NIM from A to Z in AIX 5L

- Configuring NIM - illustrated
- Sample best practices
- NIM case scenarios

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Note: Before using this information and the product it supports, read the information in “Notices” on page ix.

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This edition applies to AIX 5L V5.3 Technology Level 5, Cluster Systems Management (CSM) V1.5.1, and IBM Director V5.1.

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Preface

This IBM® Redbooks® publication will help the AIX® 5L™ technical community, and in particular system administrators who are well versed in the concepts and terminology of the AIX Operating System, to understand the benefits of implementing a Network Installation Manager (NIM) environment in their data center. The book applies to AIX 5L V5.3 Technology Level 5, Cluster Systems Management (CSM) V1.5.1, and IBM Director V5.1.

The concept of a cluster (that is, at least two IBM System p™ machines connected through a network) presents the challenge of installing, maintaining, updating and backing up the various participants in the cluster. NIM, a critical feature of AIX, can perform these tasks for your System p server farm. Using NIM, you can install or upgrade many IBM System p machines and LPARs with the same (or different) images at the same time.

This publication complements the information found in IBM technical AIX 5L manuals, and will be most useful as a reference guide.

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Chapter 1. Introduction

This chapter explains why it is beneficial to use Network Installation Manager (NIM) in your AIX 5L environment. The information in this section is aimed at AIX 5L systems administrators who are well versed in the concepts and terminology of the AIX operating system, but who also want to understand the benefits of implementing a Network Installation Manager (NIM) environment in their data center.

The concept of a cluster (that is, at least two IBM @server machines connected through a network) has existed for several years. Using a cluster implies the need for installing, maintaining, updating, and backing up the different participants of the cluster. NIM performs all of these tasks and is now a crucial feature of the AIX 5L operating system, and an important part of any IBM eServer server farm. For sites that are looking for the most efficient way of installing and/or upgrading their AIX 5L servers, NIM provides an excellent method for performing these activities and more.

The chapter covers the following topics:

- Using Network Installation Manager
- Benefits and features of NIM
- Overview of the book
- Description of the test scenarios
1.1 Using Network Installation Manager

What is Network Installation Manager (NIM), and why should you consider using it? NIM is a client/server application which uses object oriented technology. It provides an environment to install and manage AIX filesets on machines over the network. NIM provides an easy and efficient way for you to perform various installation and software maintenance tasks over several network types (such as Ethernet). Here are some examples:

- When you have more than two IBM eServer machines in your AIX 5L environment, you are working with a cluster, so you may be seeking a way to install and upgrade your IBM @server systems without the need for multiple CD-ROMs and tapes.
- You may be seeking a way to manage AIX 5L software installations and upgrades remotely, without actual physical access to the hardware.
- You may seeking a standard method for maintaining several AIX 5L operating systems images across many IBM @server systems.

For all these scenarios, NIM is the tool of choice.

You could also use NIM on a large IBM @server machine, such as a p590 or p595 partitioned in several LPARs, using dedicated or virtual I/O resources. Even though a CD/DVD drive may be available to the CEC, installing and maintaining several partitions by passing along the CD/DVD drive from one LPAR to another may be time-consuming and prone to human error (incorrect software selection, for example). By using one LPAR as a NIM server and installing the other LPARs in the same CEC over a virtual network, you can save time and decrease the chance of installing incorrect or incomplete software.

1.1.1 Benefits and features of NIM

Here are some of the benefits and features offered by NIM:

- It is free! The NIM package is included in the AIX 5L CDs. There is no additional cost required for this package.
- NIM allows system administrators to install, upgrade, back up and maintain AIX 5L systems remotely. There is no need to use CDs or tapes. Physical access to the systems is no longer required (except perhaps during initial installation; in that case, Cluster Systems Management (CSM) can help—in conjunction with NIM—with the installation of remote systems, so refer to “Overview of Cluster Systems Management” on page 560).
Multiple machines can be installed or maintained at the same time. For example, you may choose to install a specific group of systems, while at the same time apply the latest fixes to another specific group of machines.

Multiple AIX 5L versions, Maintenance Levels (MLs) or Technology Levels (TLs) can be used in the same NIM environment. This is known as coexistence.

Disaster recovery - local systems can be recovered quickly with NIM. In many cases, a system can be recovered in as little as 15 to 30 minutes. At disaster recovery sites, NIM can be deployed to quickly recover system images to disaster recovery systems without the need for AIX CDs or mksysb backup tapes.

Systems can be installed with standard and consistent AIX 5L operating system images. By defining a standard operating environment (SOE) for your AIX 5L system images, systems can be customized to meet your specific needs and maintain a level of consistency across all AIX 5L servers.

This makes administering multiple servers much easier because the administrator deals with a similar environment (for example, the same LPPs, tools, man pages, file system/logical volume naming, utilities, and so on) across all systems.

Using this SOE image also means new system builds can be accomplished quickly using very little customization or manual labor. In some cases, new builds can be completed in under 30 minutes.

Recovering a system backup (mksysb) from tape can be difficult when booting from CD media. You must boot off media that is at the same level as the backup (for example, AIX 5L base install CDs). If the CD media is not at an equal to or higher Technology Level than the level of the backup image being installed from tape, then unpredictable results might occur. As a result, every time a new Technology Level is released and applied to your machine, it is also necessary to immediately obtain the latest install media for that level of AIX 5L at the corresponding Technology Level.

However, if you use NIM to install, back up and recover your systems there is no need to rely on CDs or tapes to recover your system. Machines can be recovered easily using a network boot image at the correct level for that system.

It is possible to create bootable CD media from the source system, but this can be a time-consuming task involving CD/DVD media and may require additional manual tasks for handling the media (for example, sending it offsite). You can avoid this challenge by taking advantage of the flexibility of NIM.

Cloning systems is another excellent feature of NIM which can assist you in moving from one server to another, or even from one site to another site. By
taking a backup of your operating system image, you can use NIM to reinstall this image onto another machine, potentially with different hardware (for example, from an IBM @server p650 to a IBM System p p595, which may even reside at a different physical location).

You may want to do this for several reasons, for example moving to new hardware, cloning a system to test an upgrade, or moving a server to a new data center.

There are also several new cloning features with NIM on AIX 5L V5.3 and POWER5™ that can assist you even further when migrating from earlier versions of AIX (4.3.3/AIX 5L V5.1) to AIX 5L V5.3 and POWER5 hardware.

### 1.2 Overview of this book

Next, we describe both the contents of this book as well as the test environment we used for the scenarios and examples.

### 1.2.1 The contents of this book

As previously described, NIM is designed to install and maintain machines in a cluster environment. For information about the basic concepts and configuration of NIM, refer to:

- Chapter 2, “Network Installation Manager definitions and concepts” on page 7
- Chapter 3, “Basic configuration of a Network Installation Manager environment” on page 51

For information about significant improvements introduced with AIX 5L V5.3, using simple scenarios or guidelines for best practices, refer to:

- Chapter 4, “Network Installation Manager scenarios” on page 123
- Chapter 5, “Network Installation Manager best practices” on page 409

In addition to NIM, it is useful to use a single point of control (SPOC) to fully automate, control and manage your environments, and this is provided by Cluster Systems Management (CSM). You can associate CSM with NIM to perform tasks that NIM cannot handle by itself, such as hardware control. For a description of the relationship between NIM and CSM, and for details about how to configure one of the cluster machines as CSM Management Server and NIM master, refer to:

- Chapter 6, “Cluster Systems Management and Network Installation Manager” on page 559
For a discussion of the most common problem areas in a NIM environment, as well as a brief troubleshooting methodology, refer to:

- Chapter 7, “Basic NIM problem determination and tuning” on page 565

For general guidelines about backing up and restoring a NIM master, and for information about NIM usage in other environments, such as automatic provisioning (Tivoli Provisioning Manager) and System i™, refer to:

- Appendix A, “General LPAR sizing and creation with mig2p5 tools” on page 615
- Appendix B, “Automatic provisioning NIM and Tivoli Provisioning Manager” on page 629
- Appendix C, “NIM and System i operating system installation for an AIX 5L LPAR” on page 639

1.2.2 Test environment

In order to illustrate the advantages of using NIM to install and maintain machines in a cluster environment, we have documented various scenarios. To run these scenarios, we used different IBM System p machines, as shown in Figure 1-1 on page 6.

Our environment consisted of:

- A partitionable IBM @server p670 (POWER4™) with its own HMC used for testing basic NIM operations such as:
  - Backup and restore of the NIM master
  - High availability NIM
  - AIX migrations
  - Secure NIM
  - and so forth
- A partitionable IBM System p p521 and IBM System p p520 with their respective HMCs, used for testing the VIO server features:
  - Micro-partitioning and virtual I/O resources
  - Backup and restore of the VIO server
- An IBM @server p615 used as a NIM master and server
Figure 1-1  ITSO test environment diagram
Network Installation Manager definitions and concepts

This chapter presents NIM basic terminology and definitions, and also covers the basic concepts of a Network Installation Manager (NIM) environment.

These topics are also examined in AIX 5L V5.3 Installation and Migration, SC23-4887. However, having a practical understanding of NIM terminology and concepts is key to deploying and using a NIM environment to its full potential, so this chapter provides detailed explanations of these topics. The following topics are covered:

- Basic NIM configuration
- NIM terminology
- How a NIM environment works
- How to choose a NIM master
- Easy steps to start with NIM
- Easy steps to maintain a NIM environment
- What is new in NIM for AIX 5L
2.1 Basic NIM configuration

In the following sections, we describe the basic NIM configuration. After providing a general overview of what is behind NIM, we define the key terminology used in a NIM environment, and finish by presenting a basic setup of a NIM environment.

The NIM application
As previously mentioned, NIM is a client/server application which uses object oriented technology. It provides an environment to install and manage AIX filesets (base operating system, Maintenance Levels, individual fixes, and so on) on machines over the network. Here we describe an overview of what NIM needs to work properly, and how NIM uses its different components.

2.1.1 NIM overview

A basic NIM environment consists of several IBM System p machines (at least two) connected via a TCP/IP network. A physical network can be shared by several NIM environments, therefore the machines attached to the same physical network can be part of several NIM environments.

**Note:** A NIM environment is a logical group of machines, and multiple NIM environments can share the same TCP/IP network. However, one machine can be part of only one NIM environment a time, and there can be only one active NIM master per environment.

The machines (or clients) can be standalone systems, LPARs, diskless, and dataless clients (also known as “thin clients”). The machines can be controlled by one (or more) Hardware Service Console (better known as a Hardware Management Console, or HMC), or be standalone machines without a HMC.

Your first task is to determine which machine or LPAR will be the NIM master. This machine will need some disk space, a good network connection and spare CPU cycles; more details about these considerations are provided later in this chapter. The other machines (or LPARs) are then considered potential NIM clients.

Next, you must decide which machines will serve the NIM resources. In complex environments (those with multiple clients or a complex network), “stuffing” all resources on the same machine (the NIM master) may result in having it become a bottleneck, or—even worse—a security exposure. You can avoid this situation by distributing NIM resources on several other standalone machines or LPARs (see “Resources class” on page 14 for further details).
Finally, there are three basic machine roles in a NIM environment: the master, the client (NIM “machine”), and the resource server. The resource server can be either the NIM master or a standalone machine (a system that has its own local copy of the AIX operating system).

**Note:** The master and client (machines) can be explicitly defined via SMIT menus. However, the resource server is actually tied to the concept of NIM resource, and it cannot be explicitly defined as an entity through SMIT.

Figure 2-1 gives a general picture of two NIM environments sharing the same physical network. We can easily recognize the three machine categories (master, client and resource server) and two NIM environments. Also, two machines are not yet part of a NIM environment.

![Diagram of NIM environments](image)

*Figure 2-1   NIM environment overview*

Your starting point, as mentioned, is to decide which machine is the master. Refer to 2.1.4, “NIM master selection” on page 26 for general information about how to choose this machine.
NIM terminology
Next, we provide definitions of NIM terminology to help you understand the naming conventions used in this book.

**Master**
Master refers the machine where you set up and maintain your NIM environment. You can also initiate installations from here (push mode). It is the key piece of the NIM environment. Refer to 2.1.4, “NIM master selection” on page 26, for information about how to chose a machine to become the NIM master.

**Client**
The NIM client can be the target for NIM master-initiated operations such as installation, updates, and so forth (push mode). Also, a client can initiate its own installation or update (pull mode). A NIM client automatically becomes a resource server when it holds NIM resources.

**Resource server**
Any machine (the master or a standalone client) can be configured by the master as a server for a particular software resource. In most environments, the master is also resource server.

If other machines are already reporting to the master and they are installed (AIX), you can chose one of them to act as a resource server, thus relieving the NIM master of the heavy I/O load (disk and network). In such cases, the NIM master is only used to run administrative tasks.

**Tip:** If your environment has many nodes or consists of a complex network environment, you may want to configure standalone clients to act as resource servers, for performance and security reasons.

**Push and pull modes**
The *push* mode operation is initiated from the *master*. The *pull* mode operation is initiated from the *client*. The very first time a client is installed, only the pull mode can be used. Note the following points:

- In order for the push mode to be successful, the client must have a minimum AIX image already installed and TCP/IP configured.
- To use the pull mode, you need access to the clients’ SMS menu. For this you either need a console attached to the machine, or for HMC-managed systems, you need access to the HMC.

Figure 2-2 on page 11 illustrates the push and pull modes for NIM operations.
**NIM database**

The NIM database is stored in the AIX Object Data Management (ODM) repository on the NIM master and is divided into four classes: machines, networks, resources, groups. These classes are listed in Table 2-1.

**Table 2-1  The four NIM classes and their main used types**

<table>
<thead>
<tr>
<th>Machines</th>
<th>Network</th>
<th>Resources</th>
<th>Groups</th>
</tr>
</thead>
<tbody>
<tr>
<td>master</td>
<td>ent</td>
<td>lpp_source</td>
<td>mac_group</td>
</tr>
<tr>
<td>standalone</td>
<td>tok</td>
<td>spot</td>
<td>res_group</td>
</tr>
<tr>
<td>diskless</td>
<td>fddi</td>
<td>mksysb</td>
<td></td>
</tr>
<tr>
<td>dataless</td>
<td>atm</td>
<td>bosinst_data</td>
<td></td>
</tr>
<tr>
<td>alternate_master</td>
<td>generic</td>
<td>script</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>image_data</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>installp_bundle</td>
</tr>
</tbody>
</table>
To illustrate the contents of this NIM database, we use the `lsnim` command to extract the content (on a NIM master that is already set up and working), as shown in Example 2-1.

**Example 2-1  Output of lsnim command**

```bash
{nimmast}:/> # lsnim
master       machines       master
boot         resources       boot
nim_script   resources       nim_script
NET_EN1      networks       ent
LPP_53_ML4   resources       lpp_source
SPOT_53_ML4  resources       spot
BID_NP_HD0   resources       bosinst_data
LPAR1        machines       standalone
LPAR2        machines       standalone
LPAR3        machines       standalone
LPAR4        machines       standalone
LPAR5        machines       standalone
LPAR6        machines       standalone
LPAR123456   groups         mac_group
nimgrp       groups         mac_group
spotaix5104  resources       spot
lpp_sourceaix5204  resources       lpp_source
spotaix5204  resources       spot
AllDevicesKernels  resources       installp_bundle
```

Example 2-2 and Example 2-3 on page 13 provide details about each of the four classes represented in the NIM database. We start with the Machines class, followed by the Networks class and Resources class, and end with the Groups class.

**Machines class**

Example 2-2 gives an example of the output of the `lsnim -c machines` command.

**Example 2-2  Example of lsnim -c machines command**

```bash
{nimmast}:/> # lsnim -c machines
master       machines       master
LPAR1        machines       standalone
LPAR2        machines       standalone
LPAR3        machines       standalone
LPAR4        machines       standalone
LPAR5        machines       standalone
LPAR6        machines       standalone
LPAR123456   groups         mac_group
nimgrp       groups         mac_group
spotaix5104  resources       spot
lpp_sourceaix5204  resources       lpp_source
spotaix5204  resources       spot
AllDevicesKernels  resources       installp_bundle
```
VLPAR3       machines       standalone
VLPAR4       machines       standalone
LPAR4_p5     machines       standalone
vlpar1       machines       alternate_master
VLPAR6       machines       standalone
{nimmast}:/ #

The first column lists the NIM names; the second column lists the class name (only machines, in this example); the third column lists the type names related to this class name.

To see detailed client information, run the `lsnim -l <client_name>` command. Example 2-3 shows the output of the command `lsnim -l LPAR3`.

**Example 2-3  Output of the lsnim -l <client_name> command**

{nimmast}:/ # lsnim -l LPAR6
LPAR6:
    class          = machines
type           = standalone
connect        = shell
platform       = chrp
netboot_kernel = mp
if1            = NET_EN1 lpar6 0
cable_type1    = tp
Cstate         = ready for a NIM operation
prev_state     = in the process of booting
Mstate         = not running
cpuid          = 001A85D24C00
Cstate_result  = success
current_master = nimmast
sync_required  = yes
{nimmast}:/ #

The Cstate field determines whether the machine object is in use. If the Cstate value does not display `ready for a NIM operation`, you cannot perform any operation on this object.

**Important:** The status shown in the Mstate field may not be accurate, because it depends on whether NIM handled the latest shutdown or reboot.

**Networks class**

The network is what allows the machines in a NIM environment to communicate with each other. If the network is a simple local area network (LAN), the definition of the network object is simplified. The purpose of the network object is
to depict the network topology used by the NIM environment. Each modification made on the physical network must be reflected to the NIM database.

Example 2-4 gives an example of the output of the `lsnim -c networks` command.

**Example 2-4   Example of lsnim -c networks command**

```bash
{nimmast}:/ # lsnim -c networks
NET_EN1     networks       ent
{nimmast}:/ #
```

**Note:** NIM supports multiple network types, such as Standard Ethernet, IEEE 802.3 Ethernet, Token-Ring, FDDI, ATM, and Generic. The network type determines how certain NIM operations are handled. For example, network boot is only supported on Standard Ethernet, Token-Ring and FDDI.

In our environment we use only one network type, Standard Ethernet.

To see the details of a particular NIM network object, run the `lsnim -l <network_name>` command, as shown in Example 2-5.

**Example 2-5   Output of the lsnim -l <network_name> command**

```bash
{nimmast}:/ #
n{nimmast}:/ # lsnim -l NET_EN1
NET_EN1:
 class = networks
type = ent
 Nstate = ready for use
 prev_state = information is missing from this object's definition
 net_addr = 10.1.1.0
 snm = 255.255.255.0
{nimmast}:/ #
```

The Nstate field determines whether the network object is in use. If the Nstate value displayed is different from `ready for a NIM operation`, you cannot perform any operation on this object.

**Resources class**

A NIM resource is a pointer to a file or a directory located on a Resource Server, and the NIM Master is the default Resource Server. For example, the bosinst_data resource points to a file that contains information used to perform the installation process without requiring any manual intervention. The basic characteristics of a resource are the NIM name, the location (the location of the file or directory), and the resource server hosting the resource. Example 2-6 shows a list of resources.
Example 2-6  *lsnim* -c resources command output

```bash
{nimmast}:/ # lsnim -c resources
boot resources boot
nim_script resources nim_script
LPP_53_ML4 resources lpp_source
SPOT_53_ML4 resources spot
BID_NP_HD0 resources bosinst_data
spotaix5104 resources spot
lpp_sourceaix5204 resources lpp_source
spotaix5204 resources spot
spot5304 resources spot
lpp_sourceaix5104 resources lpp_source
lpar1nim-mksysb resources mksysb
exclude_lpar5 resources exclude_files
MK_LPAR6_AIX530403 resources mksysb
MKSYSB_VIO12_53_ML3 resources mksysb
MK_AIX5104 resources mksysb
mksysb_lpar5c resources mksysb
mksysb_lpar5d resources mksysb
AIXTFLINUX resources lpp_source
BID_NP_HD0_MKMIG resources bosinst_data
nim_move_up_bid resources bosinst_data
nim_move_up_exclude resources exclude_files
LPAR4_phys_mksysb resources mksysb
LPAR4_p5_mksysb resources mksysb
{nimmast}:/ #
```

Example 2-7 shows the details of a resource retrieved using the *lsnim* -l <resource_name> command. Notice the location and server attributes, which determine where the resource is located.

Example 2-7  Resource details

```bash
{nimmast}:/ # lsnim -l BID_NP_HD0
BID_NP_HD0:
  class       = resources
type        = bosinst_data
Rstate      = ready for use
prev_state  = unavailable for use
location    = /other_res/bid.np.hd0
alloc_count = 0
server      = master
{nimmast}:/ #
```

The location and the server are well identified. In this case, the server is the master.
**Groups class**

A *group* is a collection of either machines or resources. Only two types are available:

- `res_group`, for grouping a set of resources
- `mac_group`, for grouping a set of machines

Example 2-8 shows the output of the command `lsnim -c groups`.

**Example 2-8  Listing NIM groups**

```
{nimmast}:/{nimmast}:/ # lsnim -c groups  
LPAR123456 groups mac_group  
nimgrp groups mac_group  
res_53_ml3 groups res_group
```

### 2.1.2 How a NIM environment works

Now that you know *what* NIM consists of, you need to understand *how* NIM works—in particular, how NIM uses different components of the operating system to fulfill its duties. This section describes the most commonly used resources and their utilization. A basic diagram of how NIM installation works is shown in Figure 2-3 on page 17.

To start a machine installation, only two resources are mandatory: the LPP source (`lpp_source`), and the Shared Product Object Tree (SPOT). However, to avoid using manual intervention during the installation process, additional resources providing information for the AIX_install process can be used (that is, `bosinst_data`, `image_data`, and `script`).

**Note:** Another important attribute is `Rstate` (for “resource state”). The status shown determines whether the object is currently in use or not. If the `Rstate` is not *ready*, it cannot be used and a warning message will appear on the console.
The following list presents the basic resources needed for installing machines in your environment:

- **SPOT**
  SPOT, or Shared Product Object Tree, is a directory of code (installed filesets) that is used during client booting procedure. It is equivalent in content to the code that resides in the /usr file system on a system running AIX 5L (binary objects - executables and libraries, header files and shell scripts). This resource (directory) replaces the content of the basic ramdisk image available on installation CDs.

  **Remember:** The installation is performed over a network, and there are no AIX CDs available. Device drivers, the BOS install program, and other necessary code needed to perform a base operating system installation are found inside the SPOT.

  During the installation, the client machine NFS mounts this resource in order to access the code needed for the installation process.
The SPOT also contains the code needed to generate the boot images (kernels, which will be stored in the /tftpboot directory) that the client uses until it can manage to NFS-mount the SPOT directory.

Note: Multiple boot images can exist in the /tftpboot directory. Maintaining multiple smaller boot images helps you to save time when transferring the files via TFTP to the client.

Also, because the number of kernels (boot images) in the /tftpboot directory may increase if you add new operating system levels, we recommend that you to create a separate file system for the /tftpboot directory.

A general structure of a non-/usr SPOT directory is illustrated in Figure 2-4.

![Figure 2-4 General non-/usr SPOT structure](image)

As mentioned, the NIM database consists of several classes. Classes also consist of types. For example, the resources class consists of several resource types such as spot, lpp_source, and so on.
By running the `lsnim -t spot` command, you can list the different available SPOT resources. Output of the `lsnim -t spot` command is shown in Example 2-9.

**Example 2-9  Example of lsnim -t spot command**

```
{nimmast}:/#
{nimmast}:/# lsnim -t spot
SPOT_53_ML4 resources spot
spotaix5104 resources spot
spotaix5204 resources spot
spot5304 resources spot
{nimmast}:/#
```

Example 2-10 shows the details of a particular SPOT resource.

**Example 2-10  Details of a particular spot resource**

```
{nimmast}:/#
{nimmast}:/# lsnim -l SPOT_53_ML4
SPOT_53_ML4:
  class       = resources
  type        = spot
  plat_defined = chrp
  arch        = power
  bos_license = yes
  Rstate      = ready for use
  prev_state  = verification is being performed
  location    = /AIX53ML4/SPOT_53_ML4/usr
  version     = 5
  release     = 3
  mod         = 0
  oslevel_r   = 5300-04
  alloc_count = 1
  server      = master
  if_supported = chrp.mp ent
  Rstate_result = success
{nimmast}:/#
```
Notes:

- One of the details returned by the `oslevel -r` command by `1snim -1 <spot_resource_name>` is the AIX level. In our example, this is 5300-04. It is important to know the operating system level when you want to install a client, because the levels of the SPOT resource and mksysb resource should match.

- If the SPOT and mksysb are not at the same level, installation will only work if the SPOT is at a higher level than the mksysb. However, after the mksysb installation, the level of the system just installed will be updated to match the level of the SPOT using the `lpp_source` object, which also needs to be allocated for the installation.

- **lpp_source**
  An `lpp_source` is a directory similar to AIX install CDs. It contains AIX Licensed Program Products (LLPs) in Backup File Format (BFF) format and RPM Package Manager (RPM) filesets that you can install. For more information about RPM, see:

  `http://www.rpm.org`

General structure of the `lpp_source` directory is shown in Figure 2-5 on page 21.
Figure 2-5  lpp_source structure

Notes:
- The AIX `installp` command can handle both AIX installable package files; that is, Backup File Format (BFF) and RPM Package Manager (RPM).
- The `.toc` file (only found in directories containing BFF packages) must be kept up-to-date to reflect the latest filesets in the lpp_source.

Example 2-11 shows the various lpp_source type resources (using the `lsnim -t lpp_source` command).

Example 2-11   Example of lsnim -t lpp_source command

<table>
<thead>
<tr>
<th>Directory</th>
<th>Resources</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>lpp_source</td>
<td>resources</td>
<td>lpp_source</td>
</tr>
<tr>
<td>LPP_53_ML4</td>
<td>resources</td>
<td>lpp_source</td>
</tr>
<tr>
<td>lpp_sourceaix5204</td>
<td>resources</td>
<td>lpp_source</td>
</tr>
<tr>
<td>AIXTFLINUX</td>
<td>resources</td>
<td>lpp_source</td>
</tr>
</tbody>
</table>

{innmast}:// #
Example 2-12 shows the attributes of one of the lpp_source resource.

**Example 2-12  Details of a particular lpp_source resource**

{nimmast}:/ # lsnim -l LPP_53_ML4
LPP_53_ML4:
class = resources
type = lpp_source
arch = power
Rstate = ready for use
prev_state = ready for use
location = /AIX53ML4/LPP_53_ML4
simages = yes
alloc_count = 1
server = master
{nimmast}:/ #

**Important:** The simages attribute, when set to yes, means that the lpp_source resource contains the necessary filesets to support a base operating system type rte (for Run-Time Environment) installation. The simages attribute is set to yes for an lpp_source resource that contains a minimum set of install images (LPPs) necessary to support the creation of a SPOT resource, or to support the installation of the AIX operating system over the network.

For more information for the minimum list, refer to the following script:

/usr/lpp/bos.sysmgt/nim/methods/c_sh_lib

**mksysb**

This resource is a file containing the image of the root volume group (generated with the AIX mksysb command) of a machine. It is used to restore a machine, or to install it from scratch (also known as "cloning" a client).

A mksysb resource can be defined by first creating the mksysb image with SMIT or the mksysb command, and then defining the resource that references the backup image file.

A mksysb resource can also be defined using CLI:

nim -o define -t mksysb -a source=<client_to_backup> -a server=master -a location=<location to store file> RESOURCE_NAME

Example 2-13 shows the different mksysb resources that are part of our NIM environment.

**Example 2-13  Example of lsnim -t mksysb command**

{nimmast}:/ # lsnim -t mksysb
lpar1nim-mksysb resources mksysb
Example 2-14 shows the detail of one particular mksysb resource.

Example 2-14  Details of a particular mksysb resource

{nimmast}:/ # lsnim -l MK_LPAR6_AIX530403
MK_LPAR6_AIX530403:
  class       = resources
  type        = mksysb
  arch        = power
  Rstate      = ready for use
  prev_state  = unavailable for use
  location    = /export/images/mk_lpar6_aix530403
  version     = 5
  release     = 3
  mod         = 0
  oslevel_r   = 5300-04
  alloc_count = 0
  server      = master

{nimmast}:/ #

Note: One of the attributes shown by the lsnim -l <mksysb_resource_name> command is the AIX 5L level. This value is actually the one returned by the oslevel -r command on the client from which the image has been retrieved (5300-04, in our case).

It is important to know this value when you want to install a client because the levels of the SPOT resource and mksysb resource should match.

bosinst_data

The bosinst_data resource is a flat ASCII file similar to the bosinst.data file used for restoring system backup images from tape or CD/DVD. When you start the installation of a IBM System p machine, you will be prompted to select the console, language, installation method, the target disk(s) for rootvg, and so on. This resource comes in handy for both push or pull installation of multiple machines at the same time, because it will automate the installation process without requiring interactive answers for the installation parameters.

Example 2-15, Example 2-16 on page 24, and Example 2-17 on page 24 provide the different elements related to a bosinst_data resource.

Example 2-15  bosinst_data resources

{nimmast}:/ # lsnim -t bosinst_data
BID_NP_HD0           resources       bosinst_data
Example 2-16  Details of a bosinst_data resource

{nimmast}:/ # lsnim -l BID_NP_HD0

BID_NP_HD0:
    class       = resources
    type        = bosinst_data
    Rstate      = ready for use
    prev_state  = unavailable for use
    location    = /other_res/bid.np.hd0
    alloc_count = 0
    server      = master

{nimmast}:/ #

Example 2-17  Sample content - a bosinst.data file

control_flow:
    CONSOLE = /dev/lft0
    INSTALL_METHOD = overwrite
    PROMPT = no
    EXISTING_SYSTEM_OVERWRITE = yes
    INSTALL_X_IF_ADAPTER = yes
    RUN_STARTUP = yes
    RM_INST_ROOTS = no
    ERROR_EXIT =
    CUSTOMIZATION_FILE =
    TCB = no
    INSTALL_TYPE =
    BUNDLES =
    SWITCH_TO_PRODUCT_TAPE =
    RECOVER_DEVICES = Default
    BOSINST_DEBUG = no
    ACCEPT_LICENSES = yes
    DESKTOP = NONE
    INSTALL_DEVICES_AND_UPDATES = yes
    IMPORT_USER_VGS =
    ENABLE_64BIT_KERNEL = yes
    CREATE_JFS2_FS = yes
    ALL_DEVICES_KERNELS = yes
    GRAPHICS_BUNDLE = yes
    MOZILLA_BUNDLE = no
    KERBEROS_5_BUNDLE = no
    SERVER_BUNDLE = no
    ALT_DISK_INSTALL_BUNDLE = no
    REMOVE_JAVA_118 = no
    HARDWARE_DUMP = yes
ADD_CDE = no
ADD_GNOME = no
ADD_KDE = no
ERASE_ITERATIONS = 0
ERASE_PATTERNS =
MKSYSB_MIGRATION_DEVICE =

locale:
  BOSINST_LANG = en_US
  CULTURAL_CONVENTION = en_US
  MESSAGES = en_US
  KEYBOARD = en_US

target_disk_data:
  PVID =
  PHYSICAL_LOCATION =
  CONNECTION =
  LOCATION =
  SIZE_MB =
  HDISKNAME = hdisk0

Note: The highlighted parameters in Example 2-17 are the minimum mandatory parameters necessary to perform an installation without a manual entry.

- script
  The script resource is a file. After the BOS installation is finished on your client, you can perform customization such as file system resizing, additional user creation, and so forth. The script resource points to a file (usually a shell script) that contains all the commands needed to perform customization.

2.1.3 Before working with a NIM environment

Now that you are aware of the various components of a NIM environment, we cover the considerations needed to you build your NIM cluster.

For simplicity, we can say that NIM has two basic elements: AIX and the network. If one of them is not working properly, NIM does not function and its behavior can be erratic. Chapter 7, “Basic NIM problem determination and tuning” on page 565 describes basic problem determination scenarios. But here we introduce a few common troubleshooting examples for problems you may
encounter when working with a NIM environment, even if they are not directly related to NIM.

**Background needed**
Prior to working with NIM, you should become familiar with the environment and possess basic AIX system administration and problem determination skills in the areas of AIX 5L-related issues and network-related issues. We highlight these areas here:

**AIX 5L-related issues**
- A file system becomes full when you are creating a new lpp_source resource.
- A file system becomes full when you are creating a new mksysb resource.
- The file limit is set to 2 GB, but the actual backup file is larger (either on the NIM master or on the NIM clients to be backed up).
- A file that is part of, or configured as, a resource does not have the right permissions.
- An lpp_source’s table of contents file (.toc) file has not been updated.

**Network-related issues:**
- The physical network connection not working properly.
- Network parameters related to a specific adapter (speed, duplex) are not consistent across systems and network elements.
- Name resolution not working properly (there are duplicate addresses in the /etc/hosts file; a mix of long names and short names; and so on).

Next, we discuss a method to help you build a NIM environment.

### 2.1.4 NIM master selection

Choosing the machine that will become the NIM master is perhaps the most important step in building a reliable NIM environment. Before you start working with NIM, ensure that your network is up and running. Then, among the available machines, select the one that will become the NIM master.

To help you make this decision, you can use the following criteria:
- The machine that will become the NIM master must have AIX installed.

**Important:** The NIM master should always have the highest version of AIX installed across the entire NIM environment. Using the same AIX level for master and client is acceptable.
The NIM master machine must not be a production workload machine, because you will have to regularly shut down the NIM master machine to perform AIX upgrades.

Most people have the NIM master as a separate dedicated purpose machine or LPAR, so the maintenance of the images and its AIX version does not affect other workloads.

A micro-partition (POWER5 or above machine using a shared processor LPAR) is ideal because the NIM master does not use a lot of CPU cycles. However, others prefer to use a separate machine (perhaps a machine from previous hardware generation that is available after an upgrade) as the NIM master machine.

Some customers use the NIM master for other system administration tasks like performance monitoring, an operations Web server, and an NFS source of useful tools.

Regardless of the network complexity, the number of network adapters in your NIM environment must be planned.

Note: If you have a simple network with all machines on a single segment and a single IP address range, then only one network adapter is required.

The disk space must be estimated and compared to any existing resources. There are no official guidelines because NIM environments may vary.

Table 2-2 lists considerations for planning disk space for your NIM master. The two largest resources to consider are the lpp_source and the mksysb backups.

Keep in mind that a client can become a NIM resource server. Therefore, all disk space information related to this resource must be taken into account for the disk space planning of this machine. See Table 2-2 for average figures for the main files or directories needed by NIM.

<table>
<thead>
<tr>
<th>Item</th>
<th>Recommended size</th>
<th>Location</th>
<th>Comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>lpp_source</td>
<td>3 GB per AIX version or TL</td>
<td>Set by the</td>
<td>The size of an lpp_source for base install is less than 1 GB per AIX version or TL. It will be more if there are optional lpp_source filesets.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>administrator</td>
<td></td>
</tr>
<tr>
<td>spot</td>
<td>1 GB per AIX version or TL</td>
<td>Set by the</td>
<td>N/A</td>
</tr>
<tr>
<td></td>
<td></td>
<td>administrator</td>
<td></td>
</tr>
</tbody>
</table>
As an example, two releases of AIX (5.2 and 5.3) with three Maintenance Levels each, 10 mksysb images from production machines and three generations of these require the following disk space:

\[3 \times 6 + 1 \times 6 + 4 \times 10 \times 3 + 1 = 145 \text{ GB as a minimum}\]

After you select your NIM master machine or LPAR, you can refer to the following section for an explanation of what you need to do to set up a basic NIM environment.

### 2.1.5 Easy steps to start with NIM

In this section, we list the steps to start a NIM environment.

**Note:** At this point, no NIM definition or object has been yet created, and the objective is to install a system over the network. But first, this system has to become a client to a NIM environment. You only know that one machine will become the NIM master, and that the others will be clients.

**Step 1: Select a machine to be the master**

Refer to 2.1.4, “NIM master selection” on page 26 for guidance about making this decision.

<table>
<thead>
<tr>
<th>Item</th>
<th>Recommended size</th>
<th>Location</th>
<th>Comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>mksysb</td>
<td>4 GB</td>
<td>Set by the administrator</td>
<td>This figure is an average. Generally, the size can be between 1 GB (for a basic rte install) to 6GB or 7 GB for a running machine.</td>
</tr>
<tr>
<td>other</td>
<td>1GB</td>
<td>Set by the administrator</td>
<td>Used to put other resources, such as bosins_data, scripts and so on. The size of the basic space is negligible.</td>
</tr>
</tbody>
</table>
**Step 2: Install AIX for the NIM master**
Install a completely fresh copy of the latest AIX release and level you have, to avoid inheriting problems. It is recommended you start with the highest possible AIX level to avoid having to update it later on.

**Step 3: Check the software requirements**
The following steps are used to satisfy the minimum requirements for your NIM master:

- The level of AIX 5L that is installed on the NIM master
  
  oslevel -r or oslevel -s

- Available disk space
  
  lspv and lsattr -El hdisk*

- Network adapters
  
  lscfg and netstat -in

**Step 4: Install these NIM filesets**
The following NIM filesets must be installed:

- bos.sysmgt.nim.master
- bos.sysmgt.nim.spot

Note: The fileset bos.sysmgt.nim.spot is required when you want to allow a client server to serve SPOT resources. This fileset is optional, but should be installed if you are planning to work with thin servers (diskless or dataless clients).

- SMIT panels are shown in Example 2-18, Example 2-19 on page 30, Example 2-20 on page 31, Example 2-21 on page 32 and Example 2-22 on page 33.

In Example 2-18 we use the AIX CD for TL4 to install the NIM LPPs. We start using the smitty install_latest fastpath and select /dev/cd0 as install source, then select the NIM packages from the list.

**Example 2-18  SMIT panel to install NIM filesets**

<table>
<thead>
<tr>
<th>Install Software</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type or select values in entry fields.</td>
</tr>
<tr>
<td>Press Enter AFTER making all desired changes.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>[Entry Fields]</th>
</tr>
</thead>
<tbody>
<tr>
<td>* INPUT device / directory for software</td>
</tr>
<tr>
<td>* SOFTWARE to install</td>
</tr>
</tbody>
</table>
PREVIEW only? (install operation will NOT occur)  no +
COMMIT software updates?  yes +
SAVE replaced files?  no +
AUTOMATICALLY install requisite software?  yes +
EXTEND file systems if space needed?  yes +
OVERWRITE same or newer versions?  no +
VERIFY install and check file sizes?  no +
Include corresponding LANGUAGE filesets?  yes +
DETAILED output?  no +
Process multiple volumes?  yes +
ACCEPT new license agreements?  no +
Preview new LICENSE agreements?  no +

F1=Help   F2=Refresh   F3=Cancel   F4=List
F5=Reset   F6=Command   F7=Edit   F8=Image
F9=Shell   F10=Exit   Enter=Do

**Note:** This is a straightforward step to perform. It is a standard AIX fileset installation. The highlighted values must be entered according to your environment.

**Step 5: Configure the selected machine as a NIM master**

In our configuration we use the **smitty nimconfig** fastpath as shown in Example 2-19. Other tools, such as EZNIM, are detailed in 3.3, “EZNIM” on page 115.

**Example 2-19  SMIT panel to configure an AIX machine as a NIM master**

Configure Network Installation Manager Master Fileset

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

<table>
<thead>
<tr>
<th>[Entry Fields]</th>
</tr>
</thead>
<tbody>
<tr>
<td>* Network Name</td>
</tr>
<tr>
<td>* Primary Network Install Interface</td>
</tr>
<tr>
<td>Allow Machines to Register Themselves as Clients? [yes] +</td>
</tr>
<tr>
<td>Alternate Port Numbers for Network Communications (reserved values will be used if left blank)</td>
</tr>
<tr>
<td>Client Registration [] #</td>
</tr>
<tr>
<td>Client Communications [] #</td>
</tr>
</tbody>
</table>

F1=Help   F2=Refresh   F3=Cancel   F4=List
F5=Reset   F6=Command   F7=Edit   F8=Image
F9=Shell   F10=Exit   Enter=Do
Step 6: Creating the file systems for NIM
As explained in 2.1.2, “How a NIM environment works” on page 16, the lpp_source and the SPOT resources are directories and the related file systems must be created. Refer to Table 2-2 on page 27 for sizing information.

Step 7: Defining basic resources
First define the lpp_source resource, followed by the SPOT. The lpp_source resource is a directory containing installable filesets. Use the smitty nim_mkres fastpath, select lpp_source, and enter the required values in the input screen shown as shown in Example 2-20.

Notes:
- You can also consider creating the basic resources using the following steps: smitty nim-> Configure the NIM Environment-> configure a Basic NIM Environment (Easy Startup) to create the lpp_source and SPOT together, instead of creating individual resources.
- We suggest that you create the lpp_source first from CD, then use it to create the SPOT. This way you use the CD only once, thus reducing the time for creating the SPOT.

Example 2-20   SMIT panel to define an lpp_source resource

Define a Resource

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

[Entry Fields]
* Resource Name                  [LPP_53_ML4]
* Resource Type                  lpp_source
* Server of Resource           [master]    +
* Location of Resource          [/nim/aix53ml4/lppsour> /
[ ]   +
[cd0]   +/
[ ]
[yes]    +
[ ]

F1=Help  F2=Refresh  F3=Cancel  F4=List
F5=Reset  F6=Command  F7=Edit  F8=Image

Note: The highlighted values must be entered according to your environment.
After the lpp_source resource is created, define the SPOT resource. Use `smitty nim_mkres` and select `spot`. Then enter the information in the SMIT panel as shown in Example 2-21.

**Example 2-21   SMIT panel to define a SPOT resource**

<table>
<thead>
<tr>
<th>[Entry Fields]</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>* Resource Name</td>
<td>[SPOT_53_ML4]</td>
</tr>
<tr>
<td>* Resource Type</td>
<td>spot</td>
</tr>
<tr>
<td>* Server of Resource</td>
<td>[master] +</td>
</tr>
<tr>
<td>* Source of Install Images</td>
<td>[LPP_53_ML4] +</td>
</tr>
<tr>
<td>* Location of Resource</td>
<td>[/nim/aix53ml4/] /</td>
</tr>
<tr>
<td>Expand file systems if space needed?</td>
<td>yes +</td>
</tr>
<tr>
<td>Comments</td>
<td>[]</td>
</tr>
</tbody>
</table>

installp Flags

| COMMIT software updates? | no + |
| SAVE replaced files?     | yes + |
| AUTOMATICALLY install requisite software? | yes + |
| OVERWRITE same or newer versions? | no + |

**Step 8: Defining the client**

After the two basic resources have been defined, add the first NIM client. Use the `smitty nim_mkmac` fastpath, enter the name of the machine, and fill in the required fields in the SMIT panel as shown in Example 2-22 on page 33.

**Important:** The NIM machine name must be a resolvable IP label (usually the same as the short hostname of the machine to be added).
**Example 2-22   SMIT panel to define a NIM client**

Define a Machine

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

```
[TOP] [Entry Fields]
* NIM Machine Name     [LPAR3]
* Machine Type          [standalone]  +
* Hardware Platform Type [chrp]       +
  Kernel to use for Network Boot [mp]  +
  Communication Protocol used by client [] +
  Primary Network Install Interface
  * Cable Type             tp   +
  Network Speed Setting    []   +
  Network Duplex Setting   []   +
  * NIM Network            NET_EN1
  * Host Name               lpar3
  Network Adapter Hardware Address [0]
  Network Adapter Logical Device Name []
[MORE...4]
```

Remember that NIM programs must be able to resolve the IP labels using the /etc/hosts file or a DNS server. Refer to “Setting up IP name resolution” on page 65 for additional information.

**Step 9: Start the client installation**

At this time, because there is no mksysb resource available yet, the only way to perform a BOS install on a client is by using a Run-Time Environment (rte). Use the `smitty nim_task_inst` fastpath, then select Install the Base Operating System on Standalone Clients, the client to be installed (LPAR3), rte as installation method, and the resources (SPOT_53_ML4 and LPP_53_ML4), as shown in Example 2-23.

**Example 2-23   Starting base operating system installation on a client**

```
Install the Base Operating System on Standalone Clients

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

[TOP] [Entry Fields]
* Installation Target     LPAR3
```


Step 10: Additional checks

Perform the following checks before starting the client installation.

Verify that the bos_inst operation is correctly set up. There are three things to always check before you actually perform the installation:

- Verify that the correct entry has been added in the /etc/bootptab file.

  Example 2-24 shows, in highlighted text, the LPAR3 client entry.

Example 2-24    Content of the /etc/bootptab file

{nimmast}:/ # tail /etc/bootptab
...........
#      T179 -- (xstation only) -- XDMCP host
T180 -- (xstation only) -- enable virtual screen
lpar3:bf=/tftpboot/lpar3:ip=10.1.1.13:ht=ethernet:sa=10.1.1.1:sm=255.255.255.0:
{nimmast}:/ #  

- Verify that the boot files have been created in the /tftpboot directory. The
  /tftpboot directory must contain a boot image with the name of the client. This
  file is a symbolic link to the boot image (kernel) created from the SPOT
  resource.

  This directory also must contain a file <client_name>.info use during the
  installation to set environment variables which are used by the boot image file
  and the install scripts.

  Example 2-25 lists the files and resources in /tftpboot.

Example 2-25  Content of the /tftpboot directory

{nimmast}:/ # ls -l /tftpboot
total 151248
-rw-r--r--  1 root     system     12211712 Jun 20 15:57 AIX53_ML04_debug.chrp.mp.ent
-rw-r--r--  1 root     system     11688960 Jun 12 11:13 SPOT-VIO.chrp.mp.ent
-rw-r--r--  1 root     system     12211712 Jun 19 16:24 SPOT_53_ML4.chrp.mp.ent
-rw-r--r--  1 root     system     12211712 Jun 22 17:43 SPOT_PRUEBA.chrp.mp.ent
-lrwxrwxrwx  1 root     system           33 Jun 26 09:11 lpar3 ->
/tftpboot/SPOT_53_ML4.chrp.mp.ent
-rw-r--r--  1 root     system     1109 Jun 26 09:11 lpar3.info
-rw-r--r--  1 root     system      8162755 Jun 02 10:37 spotaix5104.chrp.mp.ent
-rw-r--r--  1 root     system      8720910 Jun 02 11:49 spotaix5204.chrp.mp.ent
{nimmast}:/ #  

- Verify that the required resources are allocated to the client and that its
  Cstate parameter has the right value. Refer to Example 2-26 for details
  related to the LPAR3 client. There is information in highlighted text that must
  be checked before starting the pull mode.

Example 2-26  Output of the lsnim -l LPAR3 command

{nimmast}:/ # lsnim -l LPAR3
LPAR3:
  class     = machines
  type      = standalone
  connect   = shell
  platform  = chrp
  netboot_kernel = mp
```plaintext
if1 = NET_EN1 lpar3 0
 cable_type1 = tp
 Cstate = BOS installation has been enabled
 prev_state = ready for a NIM operation
 Mstate = not running
 boot = boot
 lpp_source = LPP_53_ML4
 nim_script = nim_script
 spot = SPOT_53_ML4
 cpuid = 001A85D24C00
 control = master
 current_master = nimmast
 sync_required = yes
{nimmast}:/ #
```

**Step 11: Start the client installation**

To start the client installation, power on the client and go into the SMS menus. Using the console, press the 1 key during the boot sequence. For details about how to reach the SMS menu, see “SMS and console flow during NIM client installation” on page 84.

**Step 12: Redo the checks in Step 10: Additional checks**

Verify that the /etc/bootptab file no longer contains a specific line related to the machine, or a specific link into the /tftpboot directory and the Cstate of the client must be back to Ready for a NIM operation.

**2.1.6 Easy steps to maintain a NIM environment**

In this section we provide a simple example to illustrate the different steps needed to maintain a NIM environment. The starting point is a running NIM environment consisting of a master and its clients. One of the clients needs to be updated by a new fileset, a PTF (fix), or an entire Technology Level (TL, formerly known as ML).

Follow these steps:

1. Find a source to install the missing fileset on a client.
   
   Remember that you are working in a NIM environment, thus the installation package source is an lpp_source. Because NIM is able to work with multiple AIX versions and technology/Maintenance Levels, you must know the appropriate lpp_source that is used as the source of the filesets.

2. Check the AIX level of the client by using the commands `oslevel -r` and `oslevel -s`.  

---

36   NIM from A to Z in AIX 5L
3. Check whether the required fileset is part of the current lpp_source by performing the lslpp operation on an lpp_source. You can use: smitty nim -> Perform NIM Administrative Tasks -> Manage Resources, as shown in Example 2-27.

Example 2-27  An lslpp operation on an lpp_source resource

Optionally, you can update the current lpp_source if the required fileset is not present by performing the update operation on the related lpp_source resource, as shown in Example 2-28. Use smitty nim -> Perform NIM Software Installation and Maintenance Tasks -> Software Maintenance and Utilities -> Add Software to an lpp_source -> Select Target lpp_source -> Select Software Source.

Example 2-28  An update operation on an lpp_source resource
SOFTWARE Packages to Add
-OR-
INSTALLP BUNDLE containing packages to add

gencopy Flags
DIRECTORY for temporary storage during copying [/tmp]
EXTEND filesystems if space needed? yes
Process multiple volumes? no

4. Perform a push operation from your master to the client by using the following SMIT fast path:

```
smitty nim_task_inst
```

Choose Install Software. Example 2-29 shows the related SMIT panel.

**Example 2-29**  *SMIT panel to performing a fileset installation on a client*

<table>
<thead>
<tr>
<th>Install and Update Software</th>
</tr>
</thead>
<tbody>
<tr>
<td>Move cursor to desired item and press Enter.</td>
</tr>
<tr>
<td>Install the Base Operating System on Standalone Clients</td>
</tr>
<tr>
<td>Install Software</td>
</tr>
<tr>
<td>Update Installed Software to Latest Level (Update All)</td>
</tr>
<tr>
<td>Install Software Bundle</td>
</tr>
<tr>
<td>Update Software by Fix (APAR)</td>
</tr>
<tr>
<td>Install and Update from ALL Available Software</td>
</tr>
</tbody>
</table>

5. Check the result of the installation by using the following SMIT fast path (see Example 2-30):

```
smitty "nim_list_installed_sw"
```

**Example 2-30**  *SMIT panel to list the installed software on a client*

<table>
<thead>
<tr>
<th>List Installed Software</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type or select values in entry fields.</td>
</tr>
<tr>
<td>Press Enter AFTER making all desired changes.</td>
</tr>
</tbody>
</table>
2.2 What is new in NIM for AIX 5L

NIM was introduced with AIX V 4.1. NIM improvements have been added with each release of the AIX operating system. In covering the differences between versions (NIM objects, NIM application, maintenance, administration and the tools to support migration from one level to the next), we start with AIX 5L V5.1 and trace its progress up to AIX 5L V5.3. For AIX versions older than AIX 5L V5.1 refer to *NIM From A to Z in AIX 4.3*, SG24-5524.

2.2.1 NIM improvements with AIX 5L V5.1

A major improvement offered by AIX 5L V5.1 is the capability to use AIX tools to manage RPMS filesets. The basic command *installp* has been replaced by *geninstall*, and the *gencopy* command has been introduced. As a result, it is fairly easy to administer RPM packages.

2.2.2 NIM improvements with AIX 5L V5.2

This section lists the main improvements coming with AIX 5L V5.2.

- **lpp_source management tools**
  Enhancements to the management of lpp_source resources including the following:
  - The lpp_source is no longer required for mksysb installations.
  - The NIM update operation, which allows you to update an lpp_source resource by adding or removing packages. Previously, you could copy or remove packages into or from an lpp_source directory and then run the *nim -o check* command to update the lpp_source.

  SMIT allows you to add packages to the lpp_source directory through the *smitty nim_bffcreate* fast path. However, this SMIT function does not
check whether the lpp_source is allocated (or locked), nor does it update the simages attribute when finished. The update operation has been created to address this situation.

- The `lppmgr` operation is available to help you manage your lpp_source resource. The `lppmgr` facility can be used to clean an lpp_source that contains superfluous filesets.

For example, you may have loaded all eight AIX install CDs into the lpp_source, but yet do not want language support other than your own language. Or, if continuing to download ML updates into your lpp_source, you could have superseded fixes that are no longer needed.

Again, a cleanup would help to save space and time when this resource is used. If desired, you can choose to save your cleaned-up filesets by setting the save removed files field to yes as shown by Example 2-31; for example, `smitty nim --> Perform NIM Software Installation and Maintenance Tasks --> Software Maintenance and Utilities --> Eliminate Unnecessary Software Images in an lpp_source --> Select Target lpp_source`.

**Example 2-31  Example of SMIT panel for an lppmgr action**

Eliminate Unnecessary Software Images in an lpp_source

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

[Entry Fields]

<table>
<thead>
<tr>
<th>TARGET lpp_source</th>
<th>LPP_53_ML4</th>
</tr>
</thead>
<tbody>
<tr>
<td>PREVIEW only?</td>
<td>yes</td>
</tr>
<tr>
<td>REMOVE DUPLICATE software</td>
<td>yes</td>
</tr>
<tr>
<td>REMOVE SUPERSEDED updates</td>
<td>yes</td>
</tr>
<tr>
<td>REMOVE LANGUAGE software</td>
<td>yes</td>
</tr>
<tr>
<td>PRESERVE language</td>
<td>[en_US]</td>
</tr>
<tr>
<td>REMOVE NON-SIMAGES software</td>
<td>no</td>
</tr>
<tr>
<td>SAVE removed files</td>
<td>no</td>
</tr>
<tr>
<td>DIRECTORY for storing saved files</td>
<td>[]</td>
</tr>
<tr>
<td>EXTEND filesystems if space needed?</td>
<td>yes</td>
</tr>
</tbody>
</table>

- Creating resources simultaneously

Previously, when NIM ran a process that calculated and allocated file system space (such as creating an SPOT, lpp_source, and mksysb resource), no other similar operation could take place at the same time. Because these
operations calculate free space and enlarge the size of a file system, the NIM master was limited to one of these operations at a time.

Starting in AIX 5L V5.2, however, you can use NIM to simultaneously create multiple lpp-source and mksysb resources in separate file systems on the same server.

**Note:** You cannot simultaneously create multiple SPOT resources (creating a SPOT requires an installp process, and there can be only one such instance at a time), but you can simultaneously create an SPOT, an lpp_source, and mksysb resources.

The locking mechanism is set for each file system instead of each server. However, if you know that you have enough space in a file system to create multiple resources simultaneously, you can use the force option (`-F` flag) to prevent the locking mechanism from being used.

- **Resource groups**
  This allows you to create a group of resources and specify clients (or a group of clients) as default. Previously, every time a NIM operation occurred, the NIM resources had to be specified to be allocated manually. A default resource group can be created containing the required resources, so when a NIM operation is performed, the resources are already associated to the client (or the group of clients) by the default resource group.

- **Alternate disk migration installation**
  This allows the user to create a copy of rootvg to a free disk and simultaneously migrate it through NIM to a new release level. Using alternate disk migration installation over a conventional migration provides several advantages:
  - Reduced downtime
  - Quick recovery in case of migration failure
  - High degree of flexibility and customization
  - Easy configuration utilities

- **EZNIM**
  The SMIT EZNIM menu helps the system administrator by organizing the commonly used NIM operations and simplifies frequently used advanced NIM operations.

- **nim_master_setup**
  The `nim_master_setup` command performs the basic steps which are further detailed in 3.1.2, “Setting up the NIM environment” on page 59. It installs the bos.sysmgmt.nim.master fileset, configures the NIM master, and creates the resources for installation (SPOT, lpp_source), optionally including a system backup resource (mksysb). The `nim_master_setup` command uses the rootvg
volume group and creates an /export/nim file system by default. You can change these defaults using the `volume_group` and `file_system` options.

Example 2-32 shows the options available with the `nim_master_setup` command.

Example 2-32  `nim_master_setup`

```bash
# nim_master_setup
Usage nim_master_setup: Setup and configure NIM master.

nim_master_setup [-a mk_resource={yes|no}]
[-a file_system=fs_name]
[-a volume_group=vg_name]
[-a disk=disk_name]
[-a device=device]
[-B] [-v]

-B Do not create mksysb resource.
-v Enable debug output.

Default values:

mk_resource = yes
file_system = /export/nim
volume_group = rootvg
device = /dev/cd0
```

- `nim_clients_setup`

The `nim_clients_setup` command as shown in Example 2-33, is used to define your NIM clients, allocate the installation resources, and initiate a NIM BOS installation on the clients (see details in 4.3.2, “Performing a BOS installation” on page 149).

Example 2-33  `nim_clients_setup`

```bash
Usage nim_clients_setup: Setup and Initialize BOS install for NIM clients.

nim_clients_setup [-m mksysb_resource]
[-c] [-r] [-v] client_objects

-m specify mksysb resource object name -OR- absolute file path.
-c define client objects from client.defs file.
-r reboot client objects for BOS install.
-v Enables debug output.
```

**Note:** If no client object names are given, then all clients in the NIM environment are enabled for BOS installation. If the `-c` flag is used, the newly created LPARs are initialized for installation; otherwise, specified clients or all existing LPARs are initialized for installation.
2.2.3 NIM improvements with AIX 5L V5.3

This section gives general information about the improvements coming with AIX 5L V5.3. Among the improvements, nimsh and alternate NIM master are of particular importance:

- **nimsh**

  By default, the NIM environment uses rsh to communicate with your client when performing push operations. This means using the ~/.rhosts file, which may not be acceptable (as it is considered not to be secure) in certain environments.

  NIM in AIX 5L V5.3 allows an alternate communication method using nimsh. Out of the box, nimsh is also considered semi-secure, because it requires root privileges and uses the NIM master and client cpu_id to authenticate. If you require stronger security, you have the option to implement SSL with nimsh. See 5.3, “NIMSH, OpenSSL and firewall considerations” on page 424, for further details.

- **Alternate NIM master**

  NIM in AIX 5L V5.3 introduces a facility to have a backup NIM master to takeover if your primary NIM master suffers a disaster. See 4.1, “High Availability Network Installation Manager” on page 124 for details about how to set up an alternate NIM master.

- **Detailed output when creating a NIM lpp_source resource**

  Before AIX 5L V5.3, the NIM lpp_source creation did not give any information about the progress of the procedure. AIX 5L V5.3 extends the NIM lpp_source creation adding verbose output. There is a new attribute (show_progress) which has been introduced to the nim command. The NIM administrator can modify it to turn the verbose attribute on or off. Example 2-34 shows how to turn on this attribute.

  **Example 2-34  Turning on the show_progress attribute**

  ```
  nim -o define -t lpp_source ... -a show_progress=yes
  ```

- **Creating an SPOT resource from a mksysb**

  Prior to AIX 5L V5.3, the NIM SPOT resource could be created from an existing lpp_source resource or from the installation media. The disadvantage of such a generic SPOT is the amount of disk space it consumes and the long creation time.

  **Note:** A SPOT created from a mksysb can only be used for that mksysb.
The SPOT is created from the mksysb using the /usr/lib/bootpkg/bootpkg_list file that lists only the necessary files for the SPOT. The size of the SPOT created using this method is approximately 50 MB. The size of the SPOT created from the lpp_source is about 400 MB.

- **nim_move_up** command and operation

  The **nim_move_up** command enables users of existing AIX environments to take advantage of the capabilities available on new hardware (namely POWER5 servers or later). The command provides an interface that migrates an existing AIX system onto an LPAR residing on a POWER5 (or later) server.

  The level of AIX on the original machine is raised to a level that supports operation on POWER5 hardware. The original system's hardware resources are closely replicated on the equivalent POWER5 hardware. By the end of the migration, the same system is fully running on a POWER5 LPAR.

  In addition, **nim_move_up** can use the Virtual I/O capabilities of POWER5 servers by optionally migrating a client onto virtualized hardware, such as virtual disks and virtual Ethernet.

- **mksysb migration using NIM**

  mksysb migration allows you to restore the mksysb from an old system to a system that supports AIX 5.3 and then migrate the mksysb.

  Traditional migration moves the operating system of a supported hardware configuration to a newer level. A mksysb migration installation is the recommended method of installation to move unsupported hardware configurations running AIX 4.3 and later to new supported hardware running AIX 5.3.

  A mksysb migration is not intended for systems that you can migrate with a traditional migration. This method allows you to bypass the hardware limitation by restoring the mksysb on the new hardware configuration and migrate it without running AIX 4.3. The resulting system will be running the new level of AIX.

- **Restore the SPOT copy function**

  In AIX 5L V5.3, the restore SPOT copy function was reintroduced. The administrator can select the SPOT residing on the NIM server to install the BOS on the clients.

- **NIM and Service Update Management Assistant (SUMA)**; for details, see 4.10, “NIM and Service Update Management Assistant” on page 319.

- **NIM ability to restore volume groups other than the rootvg** to clients using the **nim -o restvg** operation.
- EZNIM enhancements:
  - Creates an lpp_source resource when setting up the master.
  - Adds nimsh and cryptographic authentication option when setting up the master and reinstalling the clients.
  - Adds an rte option to be selected for client reinstall.
  - Adds install options of overwrite, preservation, and migration for client reinstall.
  - Adds new options for viewing the NIM environment.

### 2.3 Planning for your NIM environment

Successfully implementing a reliable and efficient NIM environment strongly depends on the first step of this endeavor, which is planning. Performing adequate planning for your NIM environment will most likely save you from needing to rebuilding your NIM environment in case of unsatisfactory results.

Planning of your NIM environment involves the following tasks:

- Choosing your NIM master
- Defining standard and consistent naming topologies
- Sizing your NIM master
- Designing for availability

In the following sections, we explain these tasks in more detail.

#### 2.3.1 Choosing your NIM master

The first step in the planning process is choosing the NIM master. A correct decision when choosing your NIM master will contribute significantly to increasing the resiliency of your entire environment.

Start by determining what you expect NIM to provide in your environment, and what you expect the main role of the NIM master to be. From your experience with NIM, perhaps you found that you spent more time with the NIM master performing upgrades and system backups, than the initial installation of the servers. The NIM master is usually used in server's bare-metal-restore operations in case of major failures or disaster recovery (DR) scenarios.

The following tips will help you make the optimal choice of NIM master:

- In environments where NIM is needed, there usually exists a network backup server, such as IBM Tivoli Storage Manager (TSM) server. Consolidating the
backup and recovery functionality on one server offers obvious benefits. Therefore, we recommend that you install the NIM master on the same machine or LPAR as the TSM server.

- The NIM master needs to be installed with the highest AIX version in your environment, and must be maintained at the latest AIX level. This may represent a constraint to installing the NIM master on the same machine or LPAR as the TSM server.

- The NIM master must not be installed on a production machine or LPAR. And an LPAR cannot be a NIM master and a NIM client at the same time, because of AIX-level constraints.

- We recommend that the NIM master be installed on a separate physical machine from your production environment. The same recommendation applies to the TSM server.

- The NIM master needs to have reliable IP connectivity to all NIM clients.

- The NIM master needs to be implemented in a highly secure zone because, it will probably contain the system backup images of your mission-critical business application servers.

- We recommend using the NIM master to also store backup images of the NIM clients’ volume groups. These images need to be created with appropriate exclude files. Files excluded from backup may include temporary or unnecessary files.

- The NIM master needs to have access to adequate disk storage with adequate scalability.

- We have observed dependencies on certain OEM storage subsystem multipath I/O drivers. If you have a non-IBM storage subsystem that comes with a vendor-implemented multi-path driver, verify that you use the appropriate driver version for your VIOS code. Refer to the storage subsystem manufacturer’s documentation for the appropriate information.

- In a dual VIOS environment, with a large number of disks provided by different storage subsystems, when updating any of the components (VIOS version, MPIO driver, and so on), we recommend that you take one of the VIOS offline during this update procedure.

  The easiest (and safest) way to do this is by copying the LPAR profile of the VIOS and removing from this profile any adapter that is not needed during the update operation (depending on the updated component). This includes physical and virtual adapters. Then boot the VIOS for the update it with the “reduced” profile. After the update has been successfully performed, boot the VIOS with the original profile again.

  This is not a technical demand, but if you have a large number of disks or different storage subsystems, this action is highly recommended.
2.3.2 Dynamic LPAR operations

Even though Dynamic LPAR operations are faster than installing additional memory and CPUs in other architectures, these operations must be carefully planned to understand all implications, and thus minimize the time required for management operations.

Our tests have shown that Dynamic LPAR operations with CPU capacity are very fast; it may take up to a few seconds to move several processing units from one LPAR to another. However, Dynamic LPAR memory operations need more time and can even experience some variations, depending on the situation.

The amount of time required depends on the following factors:
- The system load
- The number of short-term DMA mapped pages
- The number of LMBs being moved

Refer to APAR IY97605 for more detailed information about this topic:
https://techsupport.services.ibm.com/server/aix.srcBroker

2.3.3 Defining a consistent naming convention

Defining and adhering to a consistent naming convention contributes to increasing the efficiency of the NIM environment management. We strongly recommend that you plan for and define a standard naming topology for:
- The NIM directory structure
- The NIM resources

We recommend that you define short but indicative names.

For the NIM directory structure, five main NIM-specific file systems are needed, which are to contain NIM resources directories. Two suggestions are proposed for the NIM directory and file system structure:
- The first structural suggestion, shown in Figure 2-6 on page 48, has separate file systems for each different AIX Maintenance Level or Technology Level which includes the related lpp_source and SPOT directories.

In addition to those file systems, there is a file system to store the mksysb images, another one for additional software packages, and the last one for resources related to small files like bosinst_data, script, image_data and so forth. Refer to Table 2-2 on page 27 for an estimate size.
The second structural suggestion, shown in Figure 2-7 on page 49, has a different structure: there is one file system for the lpp_source resources and one for the SPOT resources, each of them containing the different AIX Maintenance Levels or Technology Levels.

For the rest of the file systems, we suggest the same organization: one file system to store the mksysb images, another one for additional software packages and the last one for resources related to small files like bosinst_data, script, image_data and so forth. Refer to Table 2-2 on page 27 for an estimate size.
2.3.4 Sizing your NIM master

The NIM master operations do not require extensive CPU and memory resources. This is one of the reasons why we recommend that you consider consolidating it with your TSM network backup server on the same server (LPAR).

As for I/O sizing (disk, network), the NIM master requires an adequate I/O bandwidth for performing regular system backups of the NIM clients and various other administration operations. From our experience, we found that nearly all Fibre Channel host bus adapters (HBAs) are underutilized. Therefore, you probably do not need to worry about the HBAs.

The network interfaces situation could be different. Dual Gigabit Ethernet interfaces configured in an Etherchannel would be a good start for your
combined TSM and NIM servers. The disk space must be calculated during planning. Although NIM environments vary widely, Table 2-2 on page 27 provides guidelines for planning disk space for your NIM master.

### 2.3.5 Designing for availability

Due to the nature of their operation, NIM masters and resource servers are generally not considered a single point of failure for critical business operations. In most cases, the business can continue to run while the NIM master and resource servers are being recovered, provided that they can be recovered before the next system backup cycle or so.

For TSM, however, our experience is different. We implemented high availability (HA) clustered TSM servers using IBM HACMP product for good business reasons. Combining the NIM master and the TSM server on the same system could make a stronger business case to implement a high availability NIM master and TSM server.

A reasonable degree of high availability can be implemented within a single NIM master instance by implementing the following:

- Multiple (two or more) Ethernet interfaces configured in an Etherchannel. This will not only provide a seamless recovery from a network interface failure, but also will multiply the bandwidth available.
- Multiple Fibre Channel HBAs (an even number of HBAs is recommended).
- Implement a RAID5 configuration at the disk storage level, or use AIX mirroring.
- Use extra care if your NIM master uses virtual SCSI disks. (In case of a disaster, the Virtual I/O Server may need to be recovered before you can recover your NIM master—but you might want to recover the virtual I/O Server using the NIM server.)

**Note:** To minimize the impact of such a situation, we recommend that you allocate, in the VIOS, one entire disk (LUN) to the rootvg of the NIM master. (If you have the NIM repository in a different VG, you may also want to allocate an entire LUN for that, as well.)

In this way, you will be able to change the profile of the LPAR hosting the NIM server to include the physical storage (FC or SCSI) adapter that has access to the disk (LUN) defined for the NIM server, and boot the NIM server without virtual SCSI resources.
Basic configuration of a Network Installation Manager environment

This chapter explains how to set up a basic Network Installation Manager (NIM) environment. It presents the following topics:

- Setting up a basic NIM environment
  - name resolution order
  - bootp file format
  - NIM environment variables
  - NIM server options
  - NIM database
  - NIM operational log files

- Using SMIT step-by-step to set up a NIM master and install a client
- Using Web-Based System Manager to set up a NIM master and install a client
- Using EZNIM scripts to set up a NIM master and install a client
- Using the OS_install command (wrapper) to install a client

For more detailed information about planning the NIM environment, refer to 2.3, “Planning for your NIM environment” on page 45. For more detailed information
about how to use NIM to maintain and manage your AIX/Linux software environment, refer to Chapter 4, “Network Installation Manager scenarios” on page 123. For more detailed information about configuring NIM, refer to *AIX 5L Version 5.3 Installation and Migration*, SC23-4887.
3.1 Setting up a basic NIM environment

Setting up a NIM master and bringing it to use is very simple and easy. We recommend following these steps:

1. Plan the NIM environment.
2. Set up the NIM environment by implementing the plan.
3. Maintain the installed environment.

We begin here by explaining how to set up a basic NIM environment using the command line interface (CLI). Next, we show the same steps through more user-friendly interfaces, by using the `nim_master_setup` command, EZNIM, and Web-Based System Management (WSM).

If you just want to install both AIX and Linux clients, you can also use the `OS_install` command introduced with AIX 5L V5.3 Technology Level 5 (TL5).

3.1.1 Planning the NIM environment

In this section we describe a simple design for a basic NIM environment, in which the NIM master also serves as a resource server for all resources.

**Purpose**
The purpose of the basic NIM environment is to be able to install the operating system on System p logical partitions (LPARs) and physical machines using one of the following install methods:

- Fileset-based installation (Run-Time Environment - bos rte install)
- System backup-based installation, by restoring a system image created using the AIX backup procedure (mksysb).

**System resources**
The first step in setting up a new NIM environment is to obtain the appropriate computer resources. You will also need a NIM server (master) and a network environment (physical connectivity, TCP/IP configuration).

The NIM master in a LPAR environment can be a small LPAR (using dedicated or shared resources, depending on requirements and the available System p architecture). Network and disk resources can be made available to the NIM server via a virtual I/O (VIO) server.

The same NIM master can serve NIM clients residing outside the physical machine (System p) where it is allocated by using a VIO server virtual network interface, as well as NIM clients within the same physical machine using a hypervisor virtual LAN (VLAN).
The NIM server (as described in Chapter 2, “Network Installation Manager definitions and concepts” on page 7) needs at least one network interface and, depending on the planned storage repository, plenty of storage space. The amount of storage space, even for a basic NIM environment, depends on how many versions of base AIX filesets you need to copy from AIX CDs/DVDs, and the number of downloaded Technology Levels (TLs), Service Packs (SPs), Concluding Service Packs (CSPs) and additional Program Temporary Fixes (PTFs).

**Note:** In the basic NIM environment described here, we do not take into account additional storage space for other installable application software (such DB2®, WebSphere Application Server, MQ, and so forth), as well as storage space that would be needed for NIM client system backups using NIM mksysb operation.

**File system hierarchy**
For our basic NIM environment, the storage utilization will benefit from a structured file system hierarchy. It is up to you to decide which structure you want. In 2.3.3, “Defining a consistent naming convention” on page 47 and throughout the book, we present several ways to name and structure different parts of the NIM environment.

**Note:** There is no “golden rule” for naming your directory structure and resources, but the purpose of the file structure is the same: to make it easier to find, use, manage, and minimize storage redundancy in the file system storage used for the NIM environment.

Also, keep in mind that certain directory names should be kept as default (/tftpboot, for example). However, we recommend that you use a naming convention that is relevant and easy to understand in your environment.

For the basic NIM environment, you can use the following file system hierarchy:

/tftpboot This is used for storing NIM master boot images (kernels) and info files for the NIM clients.

/export/lpp_source This is used for storing versions of AIX base level filesets in specific directories; a NIM lpp_source resource represents a directory in which software installation images are stored (in BFF or RPM format). Our basic NIM environment used a minimum of one base level and one base level with applied TL and CSP for the “Maximum Stability” maintenance model (see 4.10.4, “Maintenance models” on page 332).
/export/spot

This is used for storing non-/usr Shared Product Object Three (SPOT) in individual directories (one per SPOT version). A SPOT is required to install or initialize all types of machine configurations, as well as to generate a specific kernel image used for network booting a client system. Everything that a client machine requires in a /usr file system, such as the AIX kernel, executable commands, libraries, and applications, should be included in the SPOT.

/export/images

This is used for storing system backup images. These images can be created by using the NIM mksysb operation (“pulling” a mksysb image from a NIM client), or by copying a system backup as a file from a previously created backup file, tape, or DVD. To create subdirectories during NIM mksysb creation, you must export the NIM_MKSYSB_SUBDIRS=yes variables before using the nim -o define -t mksysb command. See 4.11, “Backing up clients with NIM” on page 348, for more detailed information about this topic.

Plan to use a relevant naming convention to keep track of all NIM resources. In our example, we use a straightforward short coded UNIX-style variant. (For examples of other naming conventions, refer to 2.3.3, “Defining a consistent naming convention” on page 47 and “Directory structure setup” on page 293.)

**Note:** The /export/nim/scripts directory is used for the nim_script resource that is managed by NIM, and should not be used to store other files or scripts.

### Basic naming convention for the NIM lpp_source objects

The NIM lpp_source objects can be named in the same way for both the directory and the NIM lpp_source object.

If an lpp_source only contains update filesets, then the directory name is prefixed to reflect the type of update. If the lpp_source directory contains all the filesets needed to perform basic operating system (rte) installation (the lpp_source’s simage attribute is set to yes), then the directory name is prefixed with lpp (Licensed Program Product). The following list presents the naming convention method we used in our test:

1. `lpp<OS#>00`  
   General Availability (GA) level for AIX version `<OS#>`
2. `lpp<OS#><TL#>`  
   GA base `<OS#>` with Technology Level `<TL#>`
3. `lpp<OS#><TL#><SP#>`  
   GA base `<OS#>` with Technology Level `<TL#>` and Service Pack `<SP#>`
1pp<OS#><TL#> CSP
GA base <OS#> with Technology Level <TL#> and its
Concluding Service Pack

TL<OS#><TL#>
Technology Level <TL#> for <OS#>

SP<OS#><SP#>
Service Pack <SP#> for <OS#>

CSP<OS#><CSP#>
Concluding Service Pack <CSP#> for <OS#>

**Note:** The AIX level is shown by the `oslevel` command as four digits; for example, AIX 5.3 GA base level are shown as 5300. The two trailing digits are always zero (0) and can be omitted. The two leading digits represent the `<OS#>` in this naming scheme. However, to make the GA base level name stand out, you can keep all four digits. For example, you could suffix the name with two zeroes (00), thus `lpp53` and `spot53` would then show as `lpp5300`, and `spot5300`, respectively.

For each AIX version you must create one directory in `/export/lpp_source`, for example `/export/lpp_source/lpp53` or `/export/lpp_source/lpp5300` for the base level of AIX 5.3.

**Basic naming convention for the NIM spot objects**

The NIM spot objects can be named in a similar fashion, and based on the numbering for the corresponding NIM lpp_source, for both the directory and the NIM spot object.

- `spot<OS#>00` General Availability (GA) level for AIX version `<OS#>`
- `spot<OS#><TL#>` GA base `<OS#>` with Technology Level `<TL#>`
- `spot<OS#><TL#><SP#>` GA base `<OS#>` with Technology Level `<TL#>` and Service Pack `<SP#>`
- `spot<OS#><TL#>CSP` GA base `<OS#>` with Technology Level `<TL#>` and its Concluding Service Pack

For each AIX version plan to create one directory in `/export/spot`, such as `/export/spot/spot53` or `/export/spot/spot5300` for the base level of AIX 5.3, which is created from the corresponding NIM lpp_source, in this case the `/export/lpp_source/lpp53` or `/export/lpp_source/lpp5300`.

**Note:** We recommend that you pair the lpp_source and the SPOT versions and levels. For installing a new system, or for upgrading/migrating, you can also use SPOT resources at a lower level than the lpp_source.

However, you should check always the software levels, and *never* use an lpp_source at a lower level than the SPOT.
**Basic naming convention for the NIM mksysb objects**

For *generic* NIM mksysb images, with general pre-customization, the NIM mksysb objects and image filenames can be named in the same way as the NIM lpp_source and NIM spot previously described:

- mksysb<OS#><00> General Availability (GA) level for AIX version <OS#>
- mksysb<OS#><TL#> GA base <OS#> with Technology Level <TL#>
- mksysb<OS#><TL#><SP#> GA base <OS#> with Technology Level <TL#> and Service Pack <SP#>
- mksysb<OS#><TL#>CSP GA base <OS#> with Technology Level <TL#> and its Concluding Service Pack

For *particular* LPARs or physical machines, mksysb image files can be named in a similar way (when you plan to use these images only on the same system they were created from), using the hostname and the date when the image are created either as a prefix/suffix. The corresponding NIM object name could consist of the hostname simply suffixed or prefixed with the word mksysb or mk.

If the specific NIM mksysb objects are created only for certain maintenance tasks (when needed, and then removed), it is not necessary to include time stamp information, such as the current date. However, this can be helpful, as shown in the following examples.

- mk5305_lpar55_060618 => /export/images/lpar55/mk5305_lpar55_060618
- mksysb_lpar55 => /export/images/lpar55/lpar55_5305_18JUN06

In this case, as shown in Example 3-1, the environment variable NIM_MKSYSB_SUBDIRS is used on the NIM master for storing system backups. When this variable is set to yes, then subdirectories are used to separate NIM mksysb image files created from client machines using the nim command. The subdirectories are transparent to the user, but they provide separate locations for NFS exporting. The subdirectories are named after the NIM machines object for which they are created (the NIM name used for the source attribute).

**Example 3-1 Using the NIM_MKSYSB_SUBDIRS environment variable**

```bash
root@master:/: export NIM_MKSYSB_SUBDIRS=yes
root@master:/: nim -o define -t mksysb -a server=master -a source=LPAR55 -a mk_image=yes -a location=/export/images/lpar55_5305_18JUN06 mksysb_lpar55
```

The `nim` command will create the mksysb image file lpar55_5305_18JUN06 in the `/export/images/LPAR55` directory, and not directly in the `/export/images` directory.
Note: For additional information on mksysb image creation and usage, see 4.11, “Backing up clients with NIM” on page 348.

Basic naming convention for the NIM network objects

In order to perform certain NIM operations, the NIM master must be able to supply information necessary to configure client network interfaces. The NIM master must also be able to verify that client machines can access all the resources required to support operations. To avoid the overhead of repeatedly specifying network information for each individual client, NIM networks are used to represent the networks in a NIM environment.

The NIM network objects are named by default as net#, where # is a number starting from 1. This might be sufficient for most installations which only utilize one IP network. But when one NIM master is used to support several networks, then the NIM network objects can be named so that the IP network is included in the name, to easier identify different networks in the environment:

net_<IP#NET> Network with the IP network address included in the name in decimal form with underscore (_) replacing dots (.) since dots are not allowed to use in NIM object names.

If the network has a 24-bit mask (FF:FF:FF:0, C-class network), the IP network address would be the three first octets, such as 10.1.1. The NIM networks name could then be net_10_1_1, or net_10_1_1_0. The last 0 is used to indicate the lowest number on the IP network, which can be useful if the NIM master will serve several IP networks. Table 3-1 shows how this could be achieved by using the lowest number on the IP network.

Table 3-1 NIM networks names for IP networks using different netmasks

<table>
<thead>
<tr>
<th>Netmask (decimal dot notation)</th>
<th>NIM networks name</th>
</tr>
</thead>
<tbody>
<tr>
<td>255.255.255.0</td>
<td>net_10_1_1_0</td>
</tr>
<tr>
<td>255.255.255.128</td>
<td>net_10_1_1_0, net_10_1_1_128</td>
</tr>
<tr>
<td>255.255.255.192</td>
<td>net_10_1_1_0, net_10_1_1_64, net_10_1_1_128, ...</td>
</tr>
<tr>
<td>255.255.255.224</td>
<td>net_10_1_1_0, net_10_1_1_32, net_10_1_1_64, ...</td>
</tr>
<tr>
<td>255.255.255.240</td>
<td>net_10_1_1_0, net_10_1_1_16, net_10_1_1_32, ...</td>
</tr>
<tr>
<td>255.255.255.248</td>
<td>net_10_1_1_0, net_10_1_1_8, net_10_1_1_16, ...</td>
</tr>
</tbody>
</table>
To set up a NIM network object, the essential information is the IP network address (net_addr) and the mask (snm). Example 3-2 shows a NIM network object.

### Example 3-2 Using lsnim to display NIM network objects

```
root@master:/: lsnim -l -c networks
net_10_1_1:
  class      = networks
  type       = ent
  Nstate     = ready for use
  prev_state = information is missing from this object's definition
  net_addr   = 10.1.1.0
  snm        = 255.255.255.0
```

The prev_state (Previous State) message shown here can be ignored because this is a newly created definition.

### 3.1.2 Setting up the NIM environment

The setup of a NIM environment consists of two major steps:

- Setting up the NIM master itself and basic master customization
- Setting up the resources and object definitions for at least one lpp_source and one spot resource

#### Basic setup of the NIM master

Install and configure the designated system for the NIM master (LPAR or physical machine) with the latest AIX version and Technology Level (TL) with appropriate Service Packs (SPs); see 4.10.7, “IBM AIX Service Strategy” on page 347.

**Important:** The NIM master should always have the highest AIX version of all the machines defined (NIM clients).

**Install the bos.sysmgt.nim.master fileset**

After initial BOS installation, install the NIM master software from the bos.sysmgt.nim.master fileset.

<table>
<thead>
<tr>
<th>Netmask (decimal dot notation)</th>
<th>NIM networks name</th>
</tr>
</thead>
<tbody>
<tr>
<td>255.255.255.252</td>
<td>net_10_1_1_0, net_10_1_1_4, net_10_1_1_8, ...</td>
</tr>
</tbody>
</table>
Create the file systems used as repository for the NIM master

Create the file systems for the NIM master as Enhanced Journaled File System (JFS2). You need to calculate the sizes (see Example 3-3) based on your own NIM environment requirements.

Example 3-3 Creating basic NIM environment master file systems

```
root@master:/: crfs -v jfs2 -g rootvg -a size=64M -m /tftpboot -A yes -p rw -a logname=INLINE
root@master:/: crfs -v jfs2 -g rootvg -a size=4G -m /export/lpp_source -A yes -p rw -a logname=INLINE
root@master:/: crfs -v jfs2 -g rootvg -a size=1G -m /export/spot -A yes -p rw -a logname=INLINE
root@master:/: crfs -v jfs2 -g rootvg -a size=6G -m /export/images -A yes -p rw -a logname=INLINE
```

After creating the file systems, mount them and set the appropriate permissions, such as 600 (which means that only the owner has read and write permission).

Initialize the NIM master

Now it is time to initialize the NIM master. Note the naming of the netname attribute. Here we will use `nimconfig` command, but you can also perform this step with the SMIT nimconfig fast path.

Configuring the NIM master using the nimconfig command

Configuring the NIM master using the `nimconfig` command creates the master, boot, the first network object, nim_script with the /export/nim directory; the master (`nimesis`) daemon is also started.

As shown in Example 3-4, we do not allow NIM clients to register themselves with the NIM master. The netname attribute value is selected using the IP network address; refer to “Basic naming convention for the NIM lpp_source objects” on page 55 for more information about this topic.

Example 3-4 NIM master initialization

```
root@master:/: nimconfig -a netname=net_10_1_1 -a pif_name=en0 -a netboot_kernel=mp -a cable_type=tp -a client_reg=no

0513-071 The nimesis Subsystem has been added.
0513-071 The nimd Subsystem has been added.
0513-059 The nimesis Subsystem has been started. Subsystem PID is 491636.
```

If you plan to configure a high availability NIM environment (multiple NIM servers), use master_net as netname. This is automatically set by the `niminit` command when the attribute is_alternate is set to yes, see 4.1, “High Availability Network Installation Manager” on page 124.
Figure 3-1 shows the SMIT nimconfig fast path panel.

![Figure 3-1   SMIT nimconfig fast path](image)

Figure 3-2 shows the same SMIT panel after values are entered.

![Figure 3-2   SMIT nimconfig fast path with input](image)

After the initial setup is performed, you can use the `lsnim` command to view the newly created NIM objects, as shown in Example 3-5.

Example 3-5   The basic NIM master objects

```
root@master:/: lsnim
master     machines     master
```
The first object of the machine type is the “master” itself. The boot resource points to the /tftpboot directory and the nim_script resource points to the /export/nim/scripts directory, as shown in Example 3-6. The networks resource contains the IP information network interface on the NIM master, as shown in Example 3-2 on page 59.

Example 3-6  The basic NIM master objects

root@master:/: lsnim -l boot
boot:
  class       = resources
type        = boot
  comments    = represents the network boot resource
  Rstate      = ready for use
  location    = /tftpboot
  alloc_count = 0
  server      = master
  reserved    = yes
root@master:/: lsnim -l nim_script
nim_script:
  class       = resources
type        = nim_script
  comments    = directory for customization scripts created by NIM
  Rstate      = ready for use
  location    = /export/nim/scripts
  alloc_count = 0
  server      = master
  reserved    = yes

The NIM master configuration is stored in Object Data Manager (ODM) classes in /etc/objrepos, the nim_attr, nim_pattr and nim_object files. When a machine is added to a NIM environment (both masters and client are machines), the /etc/niminfo file is created. Example 3-7 shows the contents on the NIM master.

Example 3-7  a NIM masters /etc/niminfo file

root@master:/: cat /etc/niminfo
export NIM_NAME=master
export NIM_CONFIGURATION=master
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_MASTER_HOSTNAME=master
The value of the NIM_CONFIGURATION variable shows that this is a NIM master. For standard clients, the value will be standalone. The value of the NIM_MASTER_PORT variable represents the TCP port on which the nimesis daemon listens. The NIM_REGISTRATION_PORT (TCP port) will be used for NIM client registration, if this is enabled.

In Example 3-8, you can note the difference between a NIM master's /etc/niminfo file and a NIM client's /etc/niminfo file. The information in the file is primarily used during NIM BOS installation. The main fields that are used for nimclient calls are NIM_MASTER_HOSTNAME, NIM_MASTER_PORT, and NIM_REGISTRATION_PORT. The client's NIM name in this example is LPAR55 and its hostname is lpar55 (IP address 10.1.1.55). The NIM master's hostname is master and its IP address is 10.1.1.2.

Example 3-8 NIM client /etc/niminfo file

```bash
#------------------ Network Install Manager ---------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
export NIM_NAME=LPAR55
export NIM_HOSTNAME=lpar55
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=master
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_LICENSE_ACCEPT=yes
export RC_CONFIG=rc.bos_inst
export NIM_BOSINST_RECOVER="/../SPOT/usr/lpp/bos.sysmgt/nim/methods/c_bosinst_env -a hostname=lpar55"
export SPOT=master:/export/lpp_source/spot504/usr
export NIM_CUSTOM="/../SPOT/usr/lpp/bos.sysmgt/nim/methods/c_script -a location=master:/export/nim/scripts/LPAR55.script"
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS= "10.1.1.55:lpar55 10.1.1.2:master "
export NIM_MOUNTS=" master:/export/lpp_source/spot504:/SPOT/usr/sys/inst.images:dir "
```

Rebuilding and recovering a corrupt /etc/niminfo file

To rebuild the NIM master /etc/niminfo file, use the nimconfig command on the master with the -r flag:

```
nimconfig -r
```

To rebuild and recover a NIM client /etc/niminfo file, use the niminit command on the client:

```
niminit -a master=<MASTER_HOSTNAME> -a name=<CLIENT_NIM_NAME>
```
Specify the NIM master’s hostname or IP address, and the NIM client’s NIM name (*not* the NIM client’s hostname or IP address). As shown in Example 3-9, the NIM master is `master` and the NIM client is `lpar6`.

**Example 3-9  Initializing the NIM master**

```
root@lpar6:/: niminit -v -a master=master -a name=lpar6
```

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>niminit</td>
<td>Testing if we can access the Master @ master</td>
</tr>
<tr>
<td></td>
<td>Establishing contact with NIM master</td>
</tr>
<tr>
<td></td>
<td>Writing request to master</td>
</tr>
<tr>
<td></td>
<td>Building niminfo file</td>
</tr>
<tr>
<td></td>
<td>Granting master rhost permission</td>
</tr>
<tr>
<td></td>
<td>giving master rhost permissions</td>
</tr>
<tr>
<td></td>
<td>Adding routes from niminfo file</td>
</tr>
<tr>
<td></td>
<td>Adding entry to inittab</td>
</tr>
</tbody>
</table>

**Tip:** To convert an old NIM master into a client:

- Create a client definition on the NIM master.
- Remove the `/etc/niminfo` file (this will remove also the `nim` command from the system).
- Uninstall the `bos.sysmgmt.nim.master` fileset.
- Check whether the `bos.sysmgmt.nim.client` fileset is installed.
- Use the `niminit` command to register with the new NIM master (client registration must be enabled for this procedure to work).

In Example 3-10, the NIM master’s IP address is specified correctly, but the NIM client’s name is spelled differently from what is stored in the NIM database.

**Example 3-10  Error message when recreating the NIM client /etc/niminfo file**

```
root@lpar55:/: niminit -a master=10.1.1.2 -a name=LpAr5500
```

0042-008 NIMkid: Request denied -

The specified NIM master is not currently configured to define machines on your subnet. The machine must be defined from the master OR a network corresponding to your subnet must be defined on the master before you can add yourself as a client to this NIM environment.
Setting up IP name resolution

Host names (IP labels) used to identify the NIM clients are symbolic names and need to be resolved into IP addresses. This is done by the NIM master using a resolver subroutine (gethostbyname()). The method used by the set of resolver subroutines to resolve names depends on the local host configuration. In addition, the organization of the network determines how a resolver subroutine communicates with remote name server hosts (the hosts that resolve names for other hosts).

When creating a NIM machine object, the NIM object name is associated with a hostname. If the NIM master uses Domain Name Server (DNS) to resolve the host name to IP address mapping, the host name will be a Fully Qualified Domain Name (FQDN). Other name resolution methods include flat files (/etc/hosts) and Network Information Services (NIS).

Tip: We recommend using local name resolution (/etc/hosts), because this will avoid having NIM operation be affected by DNS or NIS service availability.

You can use several methods to ensure that the NIM masters /etc/hosts file is used before any DNS, if the /etc/resolv.conf file exists. You can include the NSORDER variable in the /etc/environment file, or you can include a specification line in either the /etc/irs.conf file or the /etc/netsvc.conf file.

Note: The settings in the /etc/netsvc.conf configuration file override the settings in the /etc/irs.conf file. The NSORDER environment variable overrides the settings in the /etc/irs.conf and the /etc/netsvc.conf files.

In Example 3-11 on page 66, Example 3-12 on page 66, and Example 3-13 on page 66, the resolver subroutine (gethostbyname()) cannot find the host name in the /etc/hosts file and continues to search for the host name in DNS.

Add the NSORDER variable declaration shown in Example 3-11 on page 66 to the /etc/environment to be effective after the next system reboot. All system software that starts at initial program load (IPL) will have the /etc/environment variables set at that time.
Example 3-11  NSORDER configuration

NSORDER=local,bind

The /etc/netsvc.conf and /etc/irs.conf files are used by the resolver routines as soon as the files exist; see Example 3-12.

Example 3-12  /etc/netsvc.conf configuration

hosts=local,bind

Notice the syntactical difference between the /etc/netsvc.conf and /etc/irs.conf files; see Example 3-13.

Example 3-13  /etc/irs.conf configuration

hosts local continue
hosts dns

Verify auxiliary services (inetd, bootpd and tftp)

The NIM master uses the bootpd (BOOT Protocol) and tftp (Trivial File Transfer Protocol) daemons (services). Both services are normally started by the inetd daemon (InterNET master daemon).

Note: For more detailed information about troubleshooting, refer to Chapter 7, "Basic NIM problem determination and tuning" on page 565.

Verify whether the inetd daemon is running by using the lssrc command, as shown in Example 3-14. Adding the -ls flags to the lssrc command also shows the services controlled by inetd and their status (in our case, we are looking for bootpd and tftp).

Example 3-14  Checking the inetd daemon with the lssrc command

root@master:/ lssrc -ls inetd
Subsystem  Group  PID  Status
inetd      tcpip  176238  active

Debug  Inactive

Signal    Purpose
SIGALRM   Establishes socket connections for failed services
SIGHUP    Rereads configuration database and reconfigures services
SIGCHLD   Restarts service in case the service dies abnormally

Service  Command  Arguments  Status
### Chapter 3. Basic configuration of a Network Installation Manager environment

<table>
<thead>
<tr>
<th>Service</th>
<th>Command</th>
<th>Arguments</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>tftp</td>
<td>/usr/sbin/tftpd</td>
<td>tftpd -n</td>
<td>active</td>
</tr>
<tr>
<td>bootps</td>
<td>/usr/sbin/bootpd</td>
<td>bootpd /etc/bootptab</td>
<td>active</td>
</tr>
<tr>
<td>xmquery</td>
<td>/usr/bin/xmtopas</td>
<td>xmtopas -p3</td>
<td>active</td>
</tr>
<tr>
<td>time</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>daytime</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>time</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>daytime</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>nttalk</td>
<td>/usr/sbin/talkd</td>
<td>talkd</td>
<td>active</td>
</tr>
<tr>
<td>exec</td>
<td>/usr/sbin/rexecd</td>
<td>rexecd</td>
<td>active</td>
</tr>
<tr>
<td>login</td>
<td>/usr/sbin/rlogind</td>
<td>rlogind</td>
<td>active</td>
</tr>
<tr>
<td>shell</td>
<td>/usr/sbin/rshd</td>
<td>rshd</td>
<td>active</td>
</tr>
<tr>
<td>telnet</td>
<td>/usr/sbin/telnetd</td>
<td>telnetd -a</td>
<td>active</td>
</tr>
<tr>
<td>ftp</td>
<td>/usr/sbin/ftpd</td>
<td>ftpd</td>
<td>active</td>
</tr>
</tbody>
</table>

The **bootpd daemon**

Verify that the `/etc/inetd.conf` file contains the line shown in Example 3-15 for the *bootpd* daemon.

**Example 3-15**  Example of `/etc/inetd.conf` configuration for bootpd

```bash
bootps dgram udp wait root /usr/sbin/bootpd bootpd /etc/bootptab
```

The corresponding line in the `/etc/services` file is for the service name to IP port mapping, as shown in Example 3-16.

**Example 3-16**  Example of `/etc/services` configuration for bootpd

```bash
bootps 67/tcp # Bootstrap Protocol Server
```

The *bootpd* daemon will also use the `/etc/bootptab` file when a NIM client is configured to be booted from the NIM master, as shown in Example 3-17.

**Example 3-17**  `/etc/bootptab` configured for network boot of a NIM client

```
lpars5:bf=/tftpboot/lpars5:ip=10.1.1.55:ht=ethernet:sa=10.1.1.2:sm=255.255.255.0:
```

The fields in the `/etc/bootptab` file are separated by a colon (:) and the attributes are separated from the assigned value by an equal sign (=). In Example 3-17, the attributes used by NIM are:

- the first field: Hostname or full domain name (for the NIM client)
- bf: Boot file name (in the NIM boot resource directory)
- ip: Host IP address (for the NIM client)
- ht: Hardware type
- sa: TFTP server IP address for the boot file
- sm: Subnet mask (for the NIM client)
Additional fields that can be used for NIM clients are:

- **gw**  Gateway IP address (for the NIM client)
- **ha**  Hardware address (MAC for the NIM client)

When the `inetd` daemon receives BOOTP requests, it will start the `bootpd` daemon. The `bootpd` daemon reads the `/etc/bootptab` configuration file, and if the request matches one of the entries, the daemon passes the boot file information to the client. The `bootpd` daemon will stay alive (in case other BOOTP requests arrive) for a while (15 minutes is the default).

Each request will be logged to the SYSLOG subsystem, depending on the verbosity/debug level set with one or more `-d` flags in the `/etc/inetd.conf` for the `bootps` services. By default, only a line indicating that the `bootpd` daemon has started will be logged. To activate info level SYSLOG messages, append `-d` to the `bootpd` service entry in `/etc/inetd.conf` and refresh `inetd`:

```
refresh -s inetd
```

**Example 3-18  Using the -d verbosity level for bootpd**

```
bootpd: reading "/etc/bootptab"
bootpd: read 1 entries from "/etc/bootptab"
bootpd: dumped 1 entries to "/etc/bootpd.dump".
bootpd: bootptab mtime is Fri Jun 16 11:38:47 2006
bootpd: Received boot request.
bootpd: request from IP addr 10.1.1.55
bootpd: found 10.1.1.55 lpar55
bootpd: bootfile = /tftpboot/lpar55
bootpd: vendor magic field is 99.130.83.99
bootpd: RFC1048 vendor data ( bp_vend[64] )
bootpd: sending RFC1048-style reply
bootpd: The following addresses are included in the bootp reply
bootpd: Client IP address (bp->bp_ciaddr) = 10.1.1.55
bootpd: Server IP address (bp->bp_siaddr) = 10.1.1.2
bootpd: Gateway IP address (bp->bp_giaddr) = 10.1.1.2
bootpd: Finished processing boot request.
```

In Example 3-18, you can see the request line, followed by a matching NIM created boot file (kernel). The reply to the client is sent including the Server and Gateway IP addresses. Sending the Client IP address might seem unnecessary, but it is also possible to only use the MAC address, without the client knowing about its IP address the first time it is activated for installation.

**The tftpd daemon**

Verify that the `/etc/inetd.conf` file contains the tftp line, as shown in Example 3-19 on page 69.
Example 3-19  tftpd configuration in /etc/inetd.conf

tftp dgram udp6 SRC nobody /usr/sbin/tftpd tftpd -n

Also check the /etc/services file for the service name and the UDP port, as shown in Example 3-20.

Example 3-20  tftpd definition in /etc/services

tftp 69/udp # Trivial File Transfer

The tftpd daemon uses the /etc/tftpaccess.ctl file to determine which directory hierarchy is allowed to share.

Because the TFTP does not specify any authentication, it is mandatory to restrict the tftpd daemons file system access to the /tftpboot directory for NIM usage. The /etc/tftpaccess.ctl file should only contain the following line if you only use tftpd for NIM purposes, as shown in Example 3-21.

Example 3-21  Sample /etc/tftpaccess.ctl

# NIM access for network boot
allow:/tftpboot

When the inetd daemon receives TFTP requests, it will start the tftpd daemon to service it, and start the transfer of the boot image file from the /tftpboot directory.

To check that the tftpd daemon is working, you can use the tftp command on the NIM master. Example 3-22 shows how to check the status of the tftpd daemon.

Example 3-22  Checking tftpd connection

root@master:/: echo "status"|tftp 0
tftp> Connected to 0.
Mode: netascii Verbose: off Tracing: off
Max-timeout: 25 seconds
tftp>root@master:/:

Example 3-23 shows how to display the contents of the /tftpboot directory.

Example 3-23  Displaying the contents of the /tftpboot directory

root@master:/: tftp -r - 0 /tftpboot
Example 3-24 shows how to display the contents of the /tftpboot/LPAR55.info file.

Example 3-24  Displaying the contents of a file using tftp

```bash
root@master:/: tftp -o - 0 /tftpboot/LPAR55.info
#------------------ Network Install Manager ---------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
export NIM_NAME=LPAR55
...
Received 1096 Bytes in 0.0 Seconds
```

If the `-v` flag is set in the `/etc/inetd.conf` file for the `tftpd` service, for each request `tftpd` will send info level SYSLOG messages. However, the default behavior is not to send messages.

The `-v` flag brings detailed information, such as IP addresses, and file transfer information. Example 3-25 shows the messages logged when the `-vi` flags are used for the `tftp` service entry in `/etc/inetd.conf`.

Example 3-25  syslogd output, using -vi verbosity level for tftpd

```
tftpd: 10.1.1.55 RRQ <file=Received, mode=/tftpboot/lpar55, recognized options: octet>
tftpd: Status Read request for 10.1.1.55: /tftpboot/lpar55
ftpd: Status Transaction completed successfully
```

In Example 3-25, you can see the request line (RRQ), followed by a match for the request with the NIM created boot file. The file is transferred in binary/octet mode to the client.

Examining the NIM log files

The `/var/adm/ras` directory contains the NIM master log files. To examine these files, you can use the `alog` command, as shown in Example 3-26. The `/usr/adm/ras/nimlog` file contains information about failed NIM operations. For more detailed information about NIM-related log files, refer to Chapter 7, “Basic NIM problem determination and tuning” on page 565.

Example 3-26  Using the alog command to view the nimlog file

```
root@master:/: alog -f /usr/adm/ras/nimlog -o
```
Basic setup of the NIM master resources

Here we discuss the basic installation resources you will need:

- The basic NIM installation resources consist of one NIM lpp_source and one spot; these are needed to perform a NIM rte installation.
- For NIM mksysb installation, the basic installation resources are one NIM mksysb and one spot.

Create a base level (GA) NIM lpp_source

To create a NIM lpp_source object, you need the GA base level AIX filesets. You can copy the AIX CD/DVD filesets to the local disk of the NIM master (or NIM resources server) in several ways.

The current standard for installation fileset directory structures requires images to be organized into subdirectories according to package type and architecture. For example, Backup File Format (BFF) fileset images reside in the installp/ppc directory. The bffcreate command is copying from a source containing this structure; the destination is required to conform to the same convention. Both the IBM AIX 5L installation CD/DVD and NIM lpp_source directories conform to this standard.

Copying AIX CD/DVD filesets can be done when creating the NIM lpp_source object using the source attribute pointing to the AIX base level installation CD/DVD, as shown in Example 3-27.

Example 3-27 Define lpp_source and copy filesets from CD

```
root@master:~/ nim -o define -t lpp_source -a server=master
-a location=/export/lpp_source/lpp5300 -a source=/dev/cd0 lpp5300

Preparing to copy install images (this will take several minutes)...
/export/lpp_source/lpp5300/sysmgtlib.libraries.apps.5.3.0.40.U
... Now checking for missing install images...
All required install images have been found. This lpp_source is now ready.
```

Copying can also be done by using the bffcreate command or the SMIT bffcreate fast path, and saving the BFF filesets, to the intended NIM lpp_source directory.

The bffcreate command can be issued from the command line as follows:

```
bffcreate -d /dev/cd0 -t /export/lpp_source/lpp5300 all
```

Figure 3-3 on page 72 shows the corresponding SMIT bffcreate fast path panel after accepting /dev/cd0 as the INPUT device.
But it is also possible to mount the CD/DVD and then copy the files manually using a copy program such as *pax* command. The *cdmount* command in Example 3-28 requires that the *cdromd* daemon (controlled by SRC) is running and that the CD is available in the CD-ROM drive.

*Example 3-28  Mounting the AIX CD and copying the files using *pax*

```bash
root@master:/: cdmount
root@master:/: pax -rw /<CD-ROM mountpoint>/installp/ppc
/export/lpp_source/lpp5300/installp/ppc
```

Make sure that the _simages_ attribute for the NIM _lpp_source_ is set to yes, as shown in Example 3-29. The _prev_state_ (Previous State) of unavailable for use can be ignored at this point, because this resource is freshly created.

*Example 3-29  Attributes of a newly created _lpp_source_*

```bash
root@master:/: lsnim -l lpp5300
lpp53:
  class        = resources
  type         = lpp_source
  arch         = power
  Rstate       = ready for use
  prev_state   = unavailable for use
  location     = /export/lpp_source/lpp5300
  simages      = yes
  alloc_count  = 0
  server       = master
```
If you copy the AIX fileset images manually with `bffcreate` or `pax`, you can create the NIM `lpp_source` object directly, as shown in Example 3-30.

**Example 3-30 Creating a NIM `lpp_source` from a directory with all AIX filesets**

```
root@master:/: nim -o define -t lpp_source -a server=master
    -a location=/export/lpp_source/lpp5300 lpp5300
```

Preparing to copy install images (this will take several minutes)...

Now checking for missing install images...
All required install images have been found. This `lpp_source` is now ready.

**Removing a NIM `lpp_source`**

To remove a NIM `lpp_source`, the object definitions will be removed but the directory and filesets will remain. The following command removes the `lpp5300` NIM object:

```
nim -o remove lpp5300
```

**Check a NIM `lpp_source`**

After adding or removing software, you must run the NIM check operation on the NIM `lpp_source`. The check operation rebuilds the table of contents (.toc) file in the `lpp_source` directory. It also determines whether all filesets are included in the resources to qualify the `lpp_source` for the `simages` attribute, which indicates whether the `lpp_source` contains the images necessary to install the Base Operating System images on a machine; see Example 3-31.

**Example 3-31 Check of a NIM `lpp_source`**

```
root@master:/: nim -Fo check lpp5304
```

**Valid NIM operations on a NIM `lpp_source`**

Use the option `-O` (upper case letter O) on the `nim` command to display operations that can be performed on a NIM `lpp_source`, as shown in Example 3-32.

**Example 3-32 Check valid NIM operations for a NIM `lpp_source`**

```
root@master:/: lsnim -O lpp5300
lpp5300:
    define  = define an object
    change  = change an object's attributes
    remove  = remove an object
    showres = show contents of a resource
    ls1pp   = list LPP information about an object
    check   = check the status of a NIM object
```
Creating a NIM spot object

A Shared Product Object Tree (SPOT) is created through an installp process, using a install source which can be either the install CD/DVD or an existing lpp_source. The SPOT is a NIM hierarchy of a /usr file system used during different NIM operations (such as installation) on a NIM client.

To reduce the overall time needed to create an SPOT resource, we recommend to use an existing lpp_source for this purpose. You can either create a "non-/usr" SPOT, or to reduce the SPOT creation time even further, you can create a "/usr" SPOT.

Even though using a /usr SPOT is a quick solution, this means that you can only have the highest AIX level in the environment for all clients. So, if you need to maintain multiple AIX levels, you need individual non-/usr SPOT resources for every AIX level.

Note: You only need to specify the top directory for the SPOT creation; the nim command will create a directory with the same name as the NIM spot object name.

Using a NIM lpp_source to create a non-/usr SPOT is recommended if the SPOT is to be used for NIM client installations and maintenance.

Example 3-33  Creating a non-/usr SPOT from a NIM lpp_source

root@master:/: nim -o define -t spot -a server=master -a location=/export/spot -a source=lpp5300 -a installp_flags=-aQg spot5300

Creating SPOT in "/export/spot" on machine "master" from "lpp5300" ...

Restoring files from BOS image. This may take several minutes ...

Installing filesets ...

Be sure to check the output from the SPOT installation to verify that all the expected software was successfully installed. You can use the NIM "showlog" operation to view the installation log file for the SPOT.

+-----------------------------------------------------------------------------+
| Pre-installation Verification...                                             |
+-----------------------------------------------------------------------------+
| Verifying selections...done                                                  |
Verifying requisites...done
Results...

FAILURES
--------
Filesets listed in this section failed pre-installation verification and will not be installed.
...

WARNINGS
--------
Problems described in this section are not likely to be the source of any immediate or serious failures, but further actions may be necessary or desired.
...

SUCCESSES
--------
Filesets listed in this section passed pre-installation verification and will be installed.

Selected Filesets
-----------------
...
  bos.mp 5.3.0.0 # Base Operating System Multip...
...
Requisites
--------
(being installed automatically; required by filesets listed above)
...
  bos.rte.boot 5.3.0.0 # Boot Commands
...
<< End of Success Section >>

FILESET STATISTICS
------------------
464 Selected to be installed, of which:
  462 Passed pre-installation verification
  2 FAILED pre-installation verification
  30 Additional requisites to be automatically installed
----
492 Total to be installed

+------------------------------------------------------------------------------------------------+
| Installing Software... |
+------------------------------------------------------------------------------------------------+

installp: APPLYING software for:
  bos.rte 5.3.0.0
In Example 3-33 on page 74, we have excluded most of the several thousand output lines of the installation process. The remainder are mostly the headers to illustrate the SPOT creation flow.

**Note:** The creation of an SPOT, by default, produces a large amount of output. We recommend that you visually scan the output to look for non-fatal errors and warnings, in order to analyze and evaluate their impact.

For more information about creating an SPOT, see “Step 7: Defining basic resources” on page 31. For more information about creating a non-/usr SPOT from a mksysb image, see 5.4.6, “SPOT creation from an existing mksysb” on page 456.

**Note:** With AIX 5300-03 ML, creating SPOT resources for AIX 4.3.3.0 and subsequent Maintenance Levels requires the environment variable INST_DEBUG to be set (export INST_DEBUG=yes).

**Recreating the NIM spot definition**

If the NIM spot definition has been lost (usually when the NIM database has been deleted or corrupted), but the SPOT directory hierarchy is left intact, you can use the command shown in Example 3-34 on page 77 to recreate the definition.

This can also be used to define the NIM spot definition if you have copied a working SPOT to create a new one, such as when using the `pax` command with the hardlink recursive write option (`pax -lrw <source> <destination>`).
Example 3-34  Recreating the NIM spot definition

root@master:/: /usr/lpp/bos.sysmgmt/nim/methods/m_mkspot -o -a server=master -a location=/export/spot -a source=no spot5300

Removing the NIM spot

To remove the NIM spot, the object definitions will be removed, and the SPOT directory hierarchy as well. The following command removes the spot5300 NIM object:

# nim -o remove spot5300

Tip: If you want to remove the NIM spot resource but you want to keep the directory structure, if the SPOT has been defined in a separate file system, simply unmount the file system and then use the preceding command.

Resetting the NIM spot

Use the reset operation to change the state of an SPOT, so NIM operations can be performed with it. A reset may be required on an SPOT if an operation was stopped before it completed successfully. The reset operation updates the resource state (Rstate) of the SPOT. After the reset operation is performed, the SPOT's Rstate is set to ready, and you can use the SPOT in subsequent NIM operations:

# nim -Fo reset spot5300

Checking the SPOT

Use the check operation to verify the usability of the SPOT in the NIM environment. The check operation rebuilds the SPOT’s network boot images, if necessary:

# nim -o check spot5300

Checking the contents of the SPOT

Use the lppchk operation to verify that software was installed successfully on a SPOT resource, as shown in Example 3-35.

Example 3-35  Checking the LPPs in a NIM spot

root@master:/: nim -o lppchk -a show_progress=yes spot5300

+-----------------------------------------------------------------------------+
Performing "lppchk" Operation
+-----------------------------------------------------------------------------+
Performing lppchk operation on machine 1 of 1: master ...

+-----------------------------------------------------------------------------+
"lppchk" Operation Summary

<table>
<thead>
<tr>
<th>Target</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>master</td>
<td>SUCCESS</td>
</tr>
</tbody>
</table>

**Valid NIM operations on a SPOT**

Use the option `-O` (upper case letter O) on the `nim` command to display operations can be performed on an SPOT; see Example 3-36.

*Example 3-36  Check valid NIM operations for an SPOT*

```
root@master:/: lsnim -O spot5300
spot5300:
  reset   = reset an object's NIM state
  define  = define an object
  change  = change an object's attributes
  remove  = remove an object
  cust    = perform software customization
  sync_roots = synchronize roots for all clients using specified SPOT
  showres = show contents of a resource
  maint   = perform software maintenance
  lslpp   = list LPP information about an object
  fix_query = perform queries on installed fixes
  showlog = display a log in the NIM environment
  check   = check the status of a NIM object
  lppchk  = verify installed filesets
```

**Remove a NIM master configuration**

To remove and redefine a NIM master's configuration, we recommend that you back up your NIM database first, using the following command:

```
/usr/lpp/bos.sysmgt/nim/methods/m_backup_db
```

*Example 3-37  Backing up a NIM master configuration*

```
root@master:/: /usr/lpp/bos.sysmgt/nim/methods/m_backup_db /tmp/nimdb_backup
a ./etc/objrepos/nim_attr 8 blocks
a ./etc/objrepos/nim_attr.vc 8 blocks
a ./etc/objrepos/nim_object 8 blocks
a ./etc/objrepos/nim_object.vc 8 blocks
a ./etc/NIM.level 1 blocks
a ./etc/niminfo 1 blocks
```

In Example 3-37, the backup data is stored in `/tmp/nimdb_backup`. Unconfigure the NIM master with the `nim` command as shown in Example 3-38 on page 79.
Example 3-38  Unconfigure the NIM master

```
root@master:/: nim -o unconfig master
0513-044 The nimesis Subsystem was requested to stop.
0513-004 The Subsystem or Group, nimd, is currently inoperative.
0513-083 Subsystem has been Deleted.
0513-083 Subsystem has been Deleted.
4 objects deleted
31 objects deleted
```

Defining NIM clients

Before any NIM operation can be performed on a NIM client, it must be defined as a NIM object (machines). The types of NIM client machines that can be managed in the NIM environment are standalone, diskless, and dataless clients.

The term “standalone” in the NIM environment means that clients are not dependent on any NIM resources for functioning. In contrast, diskless or dataless clients need certain resources; refer to 4.8, “Common Operating System Image (COSI) management” on page 298 for more information about this topic.

To create a standalone NIM client, you need the hostname and IP address associated with it. The IP address, preferably, should be on a defined NIM network (if it is not, then the network can be created when the client is defined).

In Example 3-39, the hostname is lpar55 and the NIM machine name is LPAR55 for readability and debug purposes. Only the interface (if) attribute is used in this example; other values are taken from the NIM master definition, such as platform and netboot_kernel.

Example 3-39  Create a standalone NIM client

```
root@master:/: nim -o define -t standalone -a if1="net_10_1_1 lpar55 0 ent0" LPAR55
root@master:/: lsnim -l LPAR55
LPAR55:
  class = machines
  type  = standalone
  connect = shell
  platform = chrp
  netboot_kernel = mp
  if1 = net_10_1_1 lpar55 0 ent0
  cable_type1 = N/A
  Cstate = ready for a NIM operation
  prev_state = ready for a NIM operation
  Mstate = not running
```

The if attribute stores network interface information for a NIM client, and requires a sequence number when specified, in order to distinguish between
multiple network interfaces (if1, in Example 3-39 on page 79). Because machines can have multiple network interfaces, NIM allows more than one if attribute per machine.

The value for this attribute consists of three required values and a fourth, optional, value (see Example 3-40):

Value 1 [net_10_1_1] This specifies the name of the NIM network to which this interface connects. If the name of the NIM network is unknown, then the find_net keyword can be used to match the client's IP address to a defined NIM network. If the find_net keyword is used, but NIM does not find a matching network, the optional net_definition attribute should be used to define the network, as well.

Value 2 [lpar55] This specifies the hostname associated with this interface. This hostname is resolved into an IP address on the NIM master, and will be used to set the IP address on the NIM client's interface.

Value 3 [0] This specifies the network adapter hardware MAC address of this interface. If you do not set the MAC address, you can use a value of zero (0), unless broadcasting is used for network boot of the client.

Value 4 [ent0] This specifies the logical device name of the network adapter used for this interface. If this value is not specified, NIM uses a default based on the type of network interface defined. This field is required when the client is defined on a heterogeneous network.

Example 3-40 does not have the fourth parameter of the if attribute.

**Example 3-40  Create a standalone NIM client**

```bash
root@master:/: nim -o define -t standalone -a if1="net_10_1_1 lpar55 0" LPAR55
root@master:/: lsnim -l LPAR55
LPAR55:
    class          = machines
    type           = standalone
    connect        = shell
    platform       = chrp
    netboot_kernel = mp
    if1            = net_10_1_1 lpar55 0
    cable_type1    = N/A
    Cstate         = ready for a NIM operation
    prev_state     = ready for a NIM operation
    Mstate         = not running
```
Example 3-41 shows additional machine attributes.

Example 3-41  Create a standalone NIM client

root@master:/: nim -o define -t standalone -a platform=chrp -a if1="net_10_1_1 lpar55 0 ent0" -a cable_type1=tp -a netboot_kernel=mp LPAR55
root@master:/: lsnim -l LPAR55

LPAR55:
class = machines
type = standalone
connect = shell
platform = chrp
netboot_kernel = mp
if1 = net_10_1_1 lpar55 0 ent0
cable_type1 = tp
Cstate = ready for a NIM operation
prev_state = ready for a NIM operation
Mstate = not running

Using SMIT to define NIM machines

Figure 3-4 shows the first step of the SMIT nim_mkmac fast path, if you prefer to use this method instead to create a NIM client.

Define a Machine
Type or select a value for the entry field. Press Enter AFTER making all desired changes.

* Host Name of Machine (Primary Network Install Interface)

After typing the NIM client's hostname, you will be presented with the SMIT panel shown in Figure 3-5 on page 82. You can change values here or just accept the default values. In our case we have changed the value in NIM Machine Name from the default lpar55 to LPAR55, and changed the value in Cable type from the default bnc to tp.
Removing a NIM client definition

To remove a NIM client, first the nim command removes the information from the NIM master, then it tries to remove the /etc/niminfo file from the NIM client itself; see Example 3-42.

Example 3-42 Removing a NIM client definition from the NIM master

```
root@master:/: nim -o remove LPAR55
warning: 0042-140 m_rmmac: unable to remove the /etc/niminfo file on "LPAR55"
```

The message after the command is normal when the NIM client is not reachable from the NIM master (such as when it is powered down or otherwise offline).

Installing NIM clients

You can install a NIM client by using several methods:

- Base Operating System (BOS rte) installation
- System clone installation (NIM mksysb)
- Automated customization after a generic BOS install (refer to 5.8.1, “Install time customization” on page 505 for more information about this topic)

Here we demonstrate the simple way: performing a BOS rte installation.
To perform a BOS install with NIM, you need to allocate a NIM lpp_source and a NIM spot to a NIM client, and then start the NIM rte installation. We performed these steps:

1. We used a NIM lpp_source named lpp5304 and a NIM spot named spot5304 to install a NIM client named LPAR55.
   ```
   nim -o allocate -a spot=spot5304 -a lpp_source=lpp5304 LPAR55
   ```

2. We initiated the install (if the client is already running NIM, it will also set the bootlist to network boot on the client and then reboot the client).
   ```
   nim -o bos_inst -a source=rte -a installp_flags=agX -a accept_licenses=yes LPAR55
   ```

   The source is rte for BOS install from the NIM lpp_source. Therefore, the installp_flags attribute is also used, with the Apply (a), Prereqs (g) and Expand (X) file system flags. The accept_licenses attribute must be set to yes; otherwise, the installation will fail.

If the installation is unsuccessful, you need to re-allocate the resources. However, first you will need to reset and deallocate NIM resources (in this case, with the force option):

   ```
   nim -Fo reset LPAR55
   nim -Fo deallocate -a subclass=all LPAR55
   ```

To view the progress during installation and first boot, you can use the showlog operation to the nim command:

   ```
   nim -o showlog -a log_type=boot LPAR55
   ```

**Note:** Other showlog log_type values are bosinst, devinst, nimerr, boot, niminst, script, lppchk, and alt_disk_install.

**Basic SMS menu steps**

If the NIM client is not up and running before starting the installation, you need to manually condition (that is, initiate network boot) the client machine.

Reboot the client and access the SMS menus. Set the NIM client's IP address, netmask, gateway (if any), and the IP address of the NIM master. Verify network settings by performing a PING test from the SMS menus. If this is successful, select **Network** from the Select Install/Boot Device menu.

Exit the SMS, and the network installation will start. This starts with the client looking for boot information (BOOTP), loading the kernel and the install programs (TFTP), and then NFS mounting the allocated SPOT. After the SPOT is mounted, the install process follows the same steps as a CD/DVD install.
For a more detailed description, see “SMS and console flow during NIM client installation” on page 84.

**Using SMIT to install a standalone client**

Here we list the steps you have to perform, starting from the SMIT nim_bosinst fast path panel, to install the BOS on a NIM client:

```
root@master:/: smitty nim_bosinst
Select a TARGET for the operation
Select the installation TYPE
Select the LPP_SOURCE to use for the installation
Select the SPOT to use for the installation
```

Next, you will reach the SMIT panel depicted in Figure 3-6:

```
Install the Base Operating System on Standalone Clients
Type or select values in entry fields.
Press Enter AFTER making all desired changes.

[TOP]                                                   [Entry Fields]
* Installation Target 1par55
* Installation Type rte
* SPOT 530spot_res
LPP_SOURCE [530lpp_res] +
MKSYSB

BOSINST_DATA to use during installation [] +
IMAGE_DATA to use during installation [] +
RESOLV_CONF to use for network configuration [] +
Customization SCRIPT to run after installation [] +
Customization FB Script to run at first reboot [] +
ACCEPT new license agreements? [no] +
Remain NIM client after install? [yes] +
Preserve NIM definitions for resources on [yes] +

[MORE...35]
```

**Figure 3-6** SMIT nim_bosinst fast path

At ACCEPT new license agreements? type: yes, and then press Enter. The SMIT panel should end with OK, after which the NIM client will be installed.

**SMS and console flow during NIM client installation**

At the Initial Program Load (IPL) menu, press the 1 key to access SMS Menu.
Figure 3-7 Press the 1 key to reach the SMS menu

From the Main Menu, select 2. Setup Remote IPL (Initial Program Load), as shown in Figure 3-8.

Select the desired adapter from the NIC Adapters list, in this case 1. Interpartition Logical LAN, to access the Network Parameters menu as shown in Figure 3-9 on page 86.
Figure 3-9  Interpartition logical LAN option - select 1

From the Network Parameters menu, select 1. **IP Parameters** to access the IP Parameters menu, as shown in Figure 3-10.

Figure 3-10  Network parameters options => 1

1. From the IP Parameters menu select 1. **Client IP Address**, to set the Client IP Address.
2. From the IP Parameters menu select 2. **Server IP Address**, to set the Server IP Address (NIM master).
3. From the IP Parameters menu select 3. **Gateway IP Address**. Leave it if the NIM master and client are on the same IP subnet. Otherwise, enter the default router/gateway for the Client IP Address to access the Server IP Address network.
4. From the IP Parameters menu select **4. Subnet Mask**, to set the Subnet Mask for the IP network.

5. Press **ESC** and return to the previous menu, as shown in Figure 3-11.

<table>
<thead>
<tr>
<th>IP Parameters</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Client IP Address</td>
<td>[10.1.1.55]</td>
</tr>
<tr>
<td>Server IP Address</td>
<td>[10.1.1.2]</td>
</tr>
<tr>
<td>Gateway IP Address</td>
<td>[000.000.000.000]</td>
</tr>
<tr>
<td>Subnet Mask</td>
<td>[255.255.255.000]</td>
</tr>
</tbody>
</table>

**Figure 3-11** IP parameters - select 1., 2., 3., 4., and ESC

From the Network Parameters menu, select **3. Ping Test**, as shown in Figure 3-12.

<table>
<thead>
<tr>
<th>Network Parameters</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>IP Parameters</td>
<td></td>
</tr>
<tr>
<td>Adapter Configuration</td>
<td></td>
</tr>
<tr>
<td>Ping Test</td>
<td></td>
</tr>
<tr>
<td>Advanced Setup: BOOTP</td>
<td></td>
</tr>
</tbody>
</table>

**Figure 3-12** Network parameters option - select 3
From the Network Parameters menu, select 1. **Execute Ping Test**, as shown in Figure 3-13.

![PowerPC Firmware
Version SF240_202
SMS 1.6 (c) Copyright IBM Corp. 2000,2005 All rights reserved.

---

**Ping Test**

Interpartition Logical LAN: U9131.52A.650E4DG-V4-C30-T1

Speed, Duplex: auto,auto

Client IP Address: 10.1.1.55

Server IP Address: 10.1.1.2

Gateway IP Address: 0.0.0.0

Subnet Mask: 255.255.255.000

Spanning Tree Enabled: 0

Connector Type: none

---

1. Execute Ping Test

---

Navigation keys:

M = return to Main Menu

ESC key = return to previous screen

X = eXit System Management Services

---

Type menu item number and press Enter or select Navigation key: 1

---

**Figure 3-13 Ping Test option 1**

Two screens are shown, the first one with the configuration information and the second one with the result of the ping test; see Figure 3-14.

![PowerPC Firmware
Version SF240_202
SMS 1.6 (c) Copyright IBM Corp. 2000,2005 All rights reserved.

---

$PING: args = /vdevice/l-lan@3000001e:10.1.1.2,10.1.1.55,000.000.000.000

NET: Device String - /vdevice/l-lan@3000001e

NET: Ping timeout - 10000 msec

NET: Ping string - h,10.1.1.2,10.1.1.55,000.000.000.000

PING: chosen-network-type = ethernet,auto,none,auto

PING: client IP = 10.1.1.55

PING: server IP = 10.1.1.2

PING: gateway IP = 0.0.0.0

PING: device /vdevice/l-lan@3000001e

PING: loc-code U9131.52A.650E4DG-V4-C30-T1

PING: Ready to ping:

PING: source hardware address is 1a 8c f0 0 40 1e

PING: destination hardware address is 1a 8c f0 0 30 1e

PING: source IP address is 10.1.1.55

PING: destination IP address is 10.1.1.2

---

**Figure 3-14 Ping test option 2**

Press any key to end the ping test, as shown in Figure 3-15 on page 89.
Next, press M from the Ping Test menu to return to the Main Menu; see Figure 3-16.

From the Main Menu, choose 5. Select Boot Options, as shown in Figure 3-17 on page 90.
From the Multiboot menu, choose 1. Select Install/Boot Device, as shown in Figure 3-18.

From the Select Device Type menu, select 6. Network to choose a network, as shown in Figure 3-19 on page 91.
From the NIC Adapters list, in this case, select 1. to access the Select Task menu, as shown in Figure 3-20.

From the Select Task menu, select 2. Normal Mode Boot, as shown in Figure 3-21 on page 92.
From the exit SMS menu select **1. Yes** to let the network installation begin, as shown in Figure 3-22.

Figure 3-23 on page 93 shows the installation flow which you can expect from an AIX 5L V5.3 LPAR environment. First the network boot (IPL) is initiated for the LPAR.
Next, the LPAR issues BOOTP requests to the server IP-address specified in the IP Parameters menu. It receives the BOOTP record information from /etc/bootptab on the NIM master. This record specifies the TFTP server for sending a bootable kernel. The LPAR issues TFTP requests to the server listed in the /etc/bootptab sa field from the NIM master. In Figure 3-24 we can see that the image transferred to the client is approximately 12 MB.
Then control is passed to the transferred and loaded AIX 5L kernel, as shown in Figure 3-25.

```
BOOTP R = 1  BOOTP S = 2
FILE: /tftpboot/LPAR55
FINAL Packet Count = 23852
FINAL File Size = 12211712 bytes.
load-base=0x4000
real-base=0x2000000

Elapsed time since release of system processors: 18292 mins 43 secs

Welcome to AIX.
boot image timestamp: 14:57 06/13
The current time and date: 07:38:53 06/14/2006
number of processors: 1    size of memory: 512MB
kernel size: 11008898; 32 bit kernel
```

Figure 3-25  Starting the AIX 5L kernel

In this case the installation is made using a NIM mksysb resource, as shown in Figure 3-26.

```
Installing Base Operating System

Please wait...

Approximate % tasks complete Elapsed time
% tasks complete (in minutes)

16  1  13% of mksysb data restored.
```

Figure 3-26  Installing from a mksysb resource

After installing the software, the boot image is created as shown in Figure 3-27 on page 95.
Chapter 3. Basic configuration of a Network Installation Manager environment

Figure 3-27 Creating boot image

The installation is finished and the LPAR is restarted, as shown in Figure 3-28.

Figure 3-28 Installation is finished and LPAR restarted

The newly installed kernel is loaded and the LPAR is restarted, as shown in Figure 3-29 on page 96.
3.2 Web-Based System Manager

This section describes how to configure the Network Installation Manager (NIM) master, create the basic installation resources required to install NIM client machines, and manage the resources for diskless and dataless clients using Web-Based System Management (WebSM).

For this procedure you need access from a graphical interface (GUI) such as a local X11 display or a remote X11 client.

3.2.1 Configuring a NIM master through WebSM

Use the following procedure to configure the NIM master, and create the basic installation resources using Web-Based System Management:

1. Insert the AIX 5L V5.3 (or later) Volume 1 CD into the appropriate drive of the designated master machine.

2. Start the Web-Based System Management application with the `wsm` command. You will see the screen shown in Figure 3-30 on page 97.
In the navigation area, shown in Figure 3-30, select the NIM container. If you are configuring your NIM master for the first time, you will see the screen shown in Figure 3-31.

Select **Overview and Tasks** to open the NIM tasks control panel, which is shown in Figure 3-32 on page 98.
In the NIM Tasks panel, select *Configure the Network Installation Manager environment* to start the NIM environment configuration wizard. This wizard will guide you step-by-step through the configuration of the NIM master. The first screen is shown Figure 3-33 on page 99.
Because you are configuring a NIM master, select the first option **Configure this host as a name Master** and click **Next**.

If you are configuring your NIM Master for the first time and the NIM filesets are not installed, the wizard will ask you to insert the AIX media CD in the CD or DVD drive available to the machine you are configuring; in this case, the screen shown in Figure 3-34 on page 100 will appear.
The wizard will start installing the necessary NIM filesets. The results are similar to those shown in Example 3-43.

**Example 3-43 Installing the NIM filesets - results**

```
+-----------------------------------------------------------------------------+
| Pre-installation Verification...                                            |
| +-----------------------------------------------------------------------------+
<p>| Verifying selections...done                                                  |
| Verifying requisites...done                                                 |
| Results...                                                                  |</p>
<table>
<thead>
<tr>
<th>WARNINGS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Problems described in this section are not likely to be the source of any</td>
</tr>
<tr>
<td>immediate or serious failures, but further actions may be necessary or</td>
</tr>
<tr>
<td>desired.</td>
</tr>
<tr>
<td>FILESET STATISTICS</td>
</tr>
<tr>
<td>-----------------------------</td>
</tr>
<tr>
<td>2 Selected to be installed, of which:</td>
</tr>
<tr>
<td>1 Passed pre-installation verification</td>
</tr>
<tr>
<td>1 Already installed (directly or via superseding filesets)</td>
</tr>
<tr>
<td>----</td>
</tr>
<tr>
<td>1 Total to be installed</td>
</tr>
</tbody>
</table>
:+-----------------------------------------------------------------------------+
| Summaries:                                                                  |
:+-----------------------------------------------------------------------------+
| Pre-installation Failure/Warning Summary                                    |
```
Chapter 3. Basic configuration of a Network Installation Manager environment

The next step is to configure the primary network interface of the NIM master. The screen shown in Figure 3-35 will appear, where you will define the network name. After you define the network name, press Next.

![Figure 3-35 Configuring NIM network name.](image)

After the primary NIM network interface and the NIM network name have been configured, you need to configure the NIM resources. After clicking Next (Figure 3-35), the screen shown in Figure 3-36 on page 102 allows you to choose either to configure the NIM resources automatically using the AIX defaults, or to custom configure these resources.
Figure 3-36 illustrates the selection of custom configuration (Perform additional configuration) of the NIM resources.

Press **Next** to move to the next few screens, where you can select the tasks that are expected to be performed by the NIM master, as shown in Figure 3-37 on page 103.
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Figure 3-37   NIM master tasks

The first NIM master resource to configure is the NIM lpp_source. In Figure 3-38, you configure the location and name of the NIM lpp_source to build.
After configuring the NIM lpp_source, the next step is to configure the SPOT. In the screen shown in Figure 3-39, you configure the NIM spot name and location.

![Figure 3-39 NIM master SPOT configuration](image)

After clicking **Next**, you will receive the screen shown in Figure 3-40. Here you can choose to exit the custom configuration screens, or change the configuration parameters that you have just customized.

![Figure 3-40 Exiting the NIM configuration](image)

In Figure 3-40, you can choose to exit the NIM resources customizing screens. Select **Exit Additional Configuration** and click **Next**.
In the final screen, shown in Figure 3-41, we recommend that you select **Undo the entire configuration if any part of the setup fails**.

In Figure 3-41, you can choose to view the settings you performed before you start executing the NIM environment setup.
In Figure 3-42, you can review the configuration parameters you have set up. After completing your review, click Back to return to the previous screen to start executing the setup of the NIM environment.

**Note:** This procedure produces a large amount of output, especially when creating the SPOT resource. Remember to scan through the output to look for nonfatal errors and warnings that may not be evident from a successful return code.

### 3.2.2 Configuring NIM clients using Web-Based System Management

After you complete the setup of the NIM master, the next step is to start defining the NIM clients to your NIM master.

In the Web-Based System Management main panel, click the NIM icon to open the NIM panel, then click **Overview and Tasks** to open the following screen.
In Figure 3-43, click **Add a new Machine to the Network Installation Manager environment**. This will open the dialog box shown in Figure 3-44, where you can enter the hostnames of the NIM clients.
In the **Add New Machine** dialog box shown in Figure 3-44 on page 107, add the hostnames of the NIM Clients you want to define, then click **Next**.

**Note:** The hostnames of the NIM clients you want to add must be resolvable and preferably exist in the /etc/hostname file. If these hostnames are not defined in the /etc/hostname file, you will receive an error message as shown in Figure 3-45.

![Figure 3-45  Error message when NIM client hostnames cannot be resolved](image)

After you click Next, as in Figure 3-44 on page 107, you will receive the screen shown in Figure 3-46 for each NIM client you defined. In this screen, you are required to define the attributes of the NIM client; then click **Next**.

![Figure 3-46  NIM client attributes definition](image)
After clicking Next, you will see the screen in Figure 3-47. Define the network interface and its hardware address, then click Next.

![Figure 3-47 Define network interface and hardware address](image1)

Now you see the screen shown in Figure 3-48, informing you that you completed the configuration of the NIM clients.

![Figure 3-48 Machine definition is complete](image2)

Now you need to install the BOS on these clients, as described in the next section.
3.2.3 Installing a NIM client using Web-Based System Management

After you have completed the definition of the NIM clients, you are ready to start installing them. This section illustrates the procedure of installing NIM clients using Web-Based System Management.

To install a NIM client using Web-Based System Management, click the NIM icon in the Web-Based System Management panel, then click **Overview and Tasks**. You will see the screen shown in Figure 3-49. On this screen, click **Install the Base Operating System on a Network Installation client Machine**.

![Network Installation Management (NIM)](image)

*Figure 3-49 Installing the BOS on a NIM client using WebSM*

You will see the screen shown in Figure 3-50 on page 111, which contains a list of NIM clients already defined. Select the NIM client you want to install and press **Next**.
Figure 3-50  Selecting the NIM client you want to install

Now select the installation method from the screen shown in Figure 3-51, then press Next. In this example, we chose Overwrite the existing system because we are installing an LPAR for the first time.

Figure 3-51  Choosing the installation method

Next, choose the SPOT resource you want to use for the installation. In our case, we defined only one SPOT resource, therefore we have only one option in the list shown in Figure 3-52 on page 112. In your case you might have multiple SPOT resources, according to the number of SPOT resources you defined.
Select your SPOT resource (we selected spot5304, as shown in Figure 3-52), then press Next.

The following step, shown in Figure 3-53, allows you to choose the lpp_source resource that is relevant to the operating system you are installing. Select the lpp_source resource that matches the operating system you are installing and press Next.
In Figure 3-54, you can choose to undertake a prompted or a non-prompted installation. The screen presents three options; the first and second options are for a non-prompted installation, and the third option is for a prompted installation.

Figure 3-54   Choose between a prompted or a non-prompted installation

In Figure 3-54 you can choose:

► **Select a bosinst_data resource** if you have defined this resource earlier. We recommend that you define a bosinst_data resource for the installation scenario you need.

► **Create a new bosinst_data resource** if you did not define one earlier.

► **Answer prompts at install time** if you want to define installation options manually. Installation options include the console, target LUNs or disks, and BOS Install language.

We choose *Answer prompts at install time* because we wanted to go through the installation options manually. However, for large environments, we recommend that you use a standard bosinst_data resource to maintain consistency in your environment.

The next screen, Figure 3-55 on page 114, allows you to perform further customization, such as installing additional software packages and running a customization script.
Figure 3-55  Choose the final customization of the installation process

Select the options you want and press **Next**, which will present the screen shown in Figure 3-56.

Figure 3-56  Choose the initiate reboot option

In Figure 3-56 you can choose to start the installation immediately by initiating a client reboot from the NIM master, initiate the installation at the next reboot, or initiate the reboot from the client.

We chose the option Initiate reboot and network installation now.
After you press **Next** you will reach the license agreements screen, as shown in Figure 3-57.

![License agreements screen](image)

**Figure 3-57** The accept new license agreements screen

After you accept the license agreements and press **Next**, the installation process will start according to the option you defined.

### 3.3 EZNIM

This section shows you how to use the EZNIM command scripts to configure the NIM master, create the basic installation resources required to install NIM client machines, and configure the NIM client machines. For more information about EZNIM, refer to *AIX 5L Version 5.3 Installation and Migration*, SC23-4887.

#### 3.3.1 Configuring a NIM master using nim_master_setup

The **nim_master_setup** command installs the bos.sysmgt.nim.master fileset (if it is not already installed), configures the NIM master, and creates the required resources for installation, including a **mksysb** system backup. You can also use the SMIT eznim_master_panel fast path for this task.

The default device to copy the AIX software from is `/dev/cd0`, the default volume group to create file systems in is `rootvg`, and the default file system is `/export/nim`. 
The script requires that the TCP/IP must be configured using either Token ring or an Ethernet interface. There must be 8 MB free space in the /tmp file system, and the volume group needs at least 1 GB for the NIM file system (/export/nim) and 32 MB for the /tftpboot file system. If the NIM file system or /tftpboot do not exist, they are created. The script will create a basic lpp_source, a SPOT, and a generic mksysb resource.

For batch creation of NIM clients, a simple client.defs template configuration file is also created and placed in the /export/nim directory. The client.defs file can be used by the nim_clients_setup script.

Example 3-44 assumes that all the AIX software has been saved in the /usr/sys/inst.images directory, for example by using the bffcreate command (see “Configuring the NIM master using the nimconfig command” on page 60):

```bash
# bffcreate -d /dev/cd0 -t /usr/sys/inst.images all
```

Example 3-44 Configuring the NIM master using the nim_master_setup command

```bash
root@master:/: nim_master_setup

########################################################################
#                           NIM master setup                           #
#                                                                        #
# During script execution, lpp_source and spot resource creation times  #
# may vary. To view the install log at any time during nim_master_setup, #
# run the command: tail -f /var/adm/ras/nim.setup in a separate screen. #
#                                                                        #
########################################################################

Creating image.data file...done

Device location is /dev/cd0
Resources will be defined on volume group rootvg
Resources will exist in filesystem /export/nim
Checking for backup software...already installed
Checking /tmp space requirement...done
Installing NIM master fileset...already installed
Defining NIM master...
0513-071 The nimesis Subsystem has been added.
0513-071 The nimd Subsystem has been added.
0513-059 The nimesis Subsystem has been started. Subsystem PID is 663582.
0042-001 nim: processing error encountered on "master":
  0042-023 m_chnet: "default " is not a valid NIM routing stanza

Located volume group rootvg.
Creating /export/nim filesystem...File system created successfully.
1474308 kilobytes total disk space.
New File System size is 2949120
done
Creating /tftpboot filesystem...File system created successfully.
```
Chapter 3. Basic configuration of a Network Installation Manager environment

32560 kilobytes total disk space.
New File System size is 65536
done
Checking /export/nim space requirement...done

Creating list of files to back up
Backing up 24085 files....
24085 of 24085 files backed up (100%)
0512-038 mksysb: Backup Completed Successfully.
Creating mksysb resource 5300-04master_sysb...done
Creating bosinst_data resource 5300-04bid_ow...done

Please insert AIX 5.2 product media in device /dev/cd0
If the location for AIX 5.2 product media differs from
device /dev/cd0, supply the absolute path BEFORE pressing the ENTER key.
=> /usr/sys/inst.images
Checking /export/nim space requirement...done
Creating lpp_source resource 5301pp_res...
Checking /export/nim space requirement...done
Checking /tftpboot space requirement...done
Creating spot resource 530spot_res...
Creating resource group basic_res_grp...done

The following resources now exist:

<table>
<thead>
<tr>
<th>boot</th>
<th>resources</th>
<th>boot</th>
</tr>
</thead>
<tbody>
<tr>
<td>nim_script</td>
<td>resources</td>
<td>nim_script</td>
</tr>
<tr>
<td>5300-04master_sysb</td>
<td>resources</td>
<td>mksysb</td>
</tr>
<tr>
<td>5300-04bid_ow</td>
<td>resources</td>
<td>bosinst_data</td>
</tr>
<tr>
<td>5301pp_res</td>
<td>resources</td>
<td>lpp_source</td>
</tr>
<tr>
<td>530spot_res</td>
<td>resources</td>
<td>spot</td>
</tr>
</tbody>
</table>

NIM master setup is complete - enjoy!

If you get a message stating Error creating /export/nim filesystem - Exiting, it means that there is probably not enough space available in the volume group. In most cases, if the script fails, you can re-run it without removing the created configuration.

The default NIM environment created by the nim_master_setup script is shown in Example 3-45 (AIX 5L V5.3 TL4 on a host named nimmaster).

Example 3-45   nim_master_setup NIM environment

master:
class = machines
type = master
max_nimesis_threads = 20
comments = machine which controls the NIM environment
platform = chrp
netboot_kernel = mp
if1 = master_net nimmaster 1ABCD000301E
cable_type1 = N/A
Cstate = ready for a NIM operation
prev_state =
Mstate = currently running
serves = 5300-04bid_ow
serves = 5300-04master_sysb
serves = 530lpp_res
serves = 530spot_res
serves = boot
serves = nim_script
master_port = 1058
registration_port = 1059
reserved = yes

boot:
class = resources
type = boot
comments = represents the network boot resource
Rstate = ready for use
location = /tftpboot
alloc_count = 0
server = master
reserved = yes

master_net:
class = networks
type = ent
Nstate = ready for use
prev_state = information is missing from this object's definition
net_addr = 10.1.1.0
snm = 255.255.255.0

5300-04master_sysb:
class = resources
type = mksysb
Rstate = ready for use
prev_state = unavailable for use
location = /export/nim/mksysb/generic_sysb
version = 5
release = 3
mod = 0
oslevel_r = 5300-04
alloc_count = 0
server = master

5300-04bid_ow:
class = resources
type = bosinst_data
Rstate = ready for use
prev_state = unavailable for use
location = /export/nim/5300-04biddw
alloc_count = 0
server = master

530lpp_res:
class = resources
type = lpp_source
arch = power
Rstate = ready for use
prev_state = unavailable for use
location = /export/nim/lpp_source/530lpp_res
images = yes
alloc_count = 0
server = master

530spot_res:
class = resources
type = spot
plat_defined = chrp
arch = power
Rstate = ready for use
prev_state = verification is being performed
location = /export/nim/spot/530spot_res/usr
version = 5
release = 3
mod = 0
oslevel_r = 5300-04
alloc_count = 0
server = master
Rstate_result = success
mk_netboot = yes

3.3.2 Configuring NIM clients using nim_clients_setup

In order for the nim_clients_setup script to work, the nim_master_setup script must have completed properly and there must be a NIM res_group named basic_res_grp and a client.defs file containing client definitions.

The nim_clients_setup command is used to define NIM clients, allocate the installation resources, and initiate a NIM BOS installation on the clients. You can also use the SMIT eznim_client_panel fast path.

Example 3-46 Example client.defs specification file for nim_clients_setup

```bash
# set default values
default:
    machine_type = standalone
    subnet_mask = 255.255.254.0
```
In this scenario, we use the `nimdef` command to create the NIM machines definitions using the client.defs file. The `nimdef` command can also be used to display a preview or create a script with NIM commands for later use to create the NIM machines definitions, as shown in Example 3-47.

**Example 3-47 Using nimdef to create NIM machines from a client.defs file**

```
root@master:/export/nim: nimdef -df client.defs
```

**Summary**

1. Machine will be added to the NIM environment.
1. Machine group will be created with new members.
1. Network will be added to the NIM environment automatically.
1. Network will have new NIM machine interfaces added.

```
+ nim -o define -t standalone -a if1=find_net lpar55 0 ent -a cable_type1=tp
   -anet_definition=ent 255.255.254.0 10.1.1.1 -a netboot_kernel=mp -a platform=chrp
   vlpar2
```

By adding the `-cf` flag, shown in Example 3-48, the `nimdef` command creates a Korn Shell script and displays it to the standard output.

**Example 3-48 Using the nimdef command to create a script from a client.defs file**

```
root@master:/export/nim: nimdef -cf client.defs
```

```
#!/bin/ksh
set -x
#############################################################################
#
# Summary
#
#    1  Machine will be added to the NIM environment.
#    1  Machine group will be created with new members.
#    1  Network will be added to the NIM environment automatically.
#    1  Network will have new NIM machine interfaces added.
#
#############################################################################

```

```
#############################################################################

```

```
# Commands to define new machines in the NIM environment.
```
Chapter 3. Basic configuration of a Network Installation Manager environment

#
#~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
nim -o define -t standalone -a if1="find_net lpar55 0 ent" -a cable_type1=tp
-anet_definition="ent 255.255.254.0 10.1.1.1 " -a netboot_kernel=mp -a platform=chrp vlpar2

If the basic_res_grp NIM resource has not been created by the
nim_master_setup script, it can be created manually as shown in Example 3-49:

Example 3-49   Creating basic_res_grp (manually)

root@master:/: nim -o define -t res_group -a bosinst_data=5300-04bid_ow -a
lpp_source=530lpp_res -a spot=530spot_res -a mksysb=5300-04master_sysb basic_res_grp

root@master:/: lsnim -l basic_res_grp
basic_res_grp:  
  class   = groups
  type    = res_group
  member1 = 5300-04master_sysb
  member2 = 5300-04bid_ow
  member3 = 530lpp_res
  member4 = 530spot_res

To allocate and initiate client installation, use the nim_clients_setup command. We use the nim_clients_setup command in this case is to allocate the installation resources, and initiate a NIM BOS installation on the clients.

To initiate a change of the NIM client's boot sequence to use network as the first boot device, and to reboot the client, the -r option must be used with the nim_clients_setup command; see Example 3-50.

Example 3-50   Using the nim_clients_setup script

root@master:/export/nim: nim_clients_setup -r  
nim_clients_setup
  NSORDER=local,bind

  Generating list of client objects in NIM environment...
  Locating lpar55...done

  Checking for resource group basic_res_grp...done

The NIM setup for installing the NIM client is now completed, and the client can be restarted to initiate network boot and BOS installation.

Example 3-51 on page 122 shows the NIM client object and the /etc/bootptab entry.
Example 3-51 Verifying after the nim_clients_setup script

```
root@master:/export/nim: lsnim -l vlpar2
vlpar2:
class          = machines
type           = standalone
default_res    = basic_res_grp
connect        = shell
platform       = chrp
netboot_kernel = mp
if1            = master_net lpar55 0 ent
cable_type1    = tp
Cstate         = BOS installation has been enabled
prev_state     = ready for a NIM operation
Mstate         = currently running
boot           = boot
bosinst_data   = 5300-04bid_ow
lpp_source     = 530lpp_res
mksysb         = 5300-04master_sysb
nim_script     = nim_script
spot           = 530spot_res
cpuid          = 0000C836D700
control        = master

root@master:/: grep lpar55 /etc/boottab
```
Network Installation Manager scenarios

This chapter discusses several scenarios and implementation for a Network Installation Manager (NIM) environment. Because NIM is a highly flexible, feature-rich set of tools, these scenarios are considered just a starting point to real NIM usability. Scenarios covered in this chapter describe:

- High Availability Network Installation Manager (HANIM)
- Using the OS_install command
- NIM environment with additional resource servers
- Using NIM to perform AIX migrations
- NIM mksysb migration and nim_move_up POWER5 tools
- NIM alternate disk migration
- Network Installation Manager and Linux distributions
- Thin server and Common OS Image management (COSI)
- Using HACMP with HANIM
- NIM and Service Update Management Assistant (SUMA)
- Backing up clients with NIM
- How to create bundles, BFF, and RPM packages
- NIM in a micro-partition using Virtual I/O (VIO) resources
- Setting up the VIO server and configuring the NIM master in the VIO client
- Backup and restore of the VIO Server using NIM
- Using RSCT Peer Domain with HANIM
4.1 High Availability Network Installation Manager

AIX 5L V5.3 introduced High Availability NIM (HANIM) by allowing a backup NIM master on a different machine or LPAR. The backup NIM master takes over when the primary NIM master fails. When the primary NIM master recovers, a fallback operation gives control to the primary NIM master. The failover and fallback operations are initiated by the system administrator.

Unlike a common HA environment, NIM does not perform any heartbeat, and it does not provide file system takeover. HANIM only provides a method for replicating a NIM database and resources, and a failover/fallback procedure in a coordinated manner.

In order to have the latest NIM configuration when the backup NIM master takeover, the system administrator has to perform regular synchronization of the NIM configuration from the primary master to the backup master.

The synchronization process backs up the NIM database on the primary NIM master and copies it to the backup NIM master. The backup is then restored in the backup master.

**Note:** At the time of writing, only rsh/rshd communication is supported for NIM synchronization.

To configure HANIM, use the following SMIT sequence:

```
# smitty nim
Perform NIM Administration Tasks
   Manage Alternate Master Environment

Or, you can use the smitty nim_altmstr SMIT fast path. Example 4-1 shows the SMIT screen on the Alternate NIM master Environment.

Example 4-1  SMIT screen on Alternate Master Environment

   Manage Alternate Master Environment

Move cursor to desired item and press Enter.
```

- Initialize This Machine as an Alternate Master
- Define Another Machine as an Alternate Master
- Synchronize an Alternate Master's NIM database
- Takeover control of NIM clients from an Alternate Master
- Remove an Alternate Master
4.1.1 Configuring the alternate (backup) NIM master

In our scenario we have a primary NIM master (lpar1), and we step through the configuration to create the alternate NIM master (in our case, lpar6). This is shown in Figure 4-1.

The configuration of the alternate NIM master follows a process similar to the normal NIM master setup:

1. Install the NIM master fileset on the backup NIM master server, lpar6.

   You need to install the following filesets:
   - bos.sysmgt.nim.master
   - bos.sysmgt.nim.spot

   **Note:** The bos.sysmgt.nim.spot package is optional unless you have diskless or dataless clients.

2. Configure the backup NIM master server as the NIM master.

   On the backup NIM master server (lpar6), you need to configure the NIM environment, just like in the primary NIM master server.

   # smitty nimconfig
3. Copy the lpp_source to the backup NIM master.

You need to create the same file system structure for the lpp_source as in the primary NIM master server.

Copy all the lpp_source directory to the backup NIM master:

From the Primary NIM master,

```
# cd /export/lppsource/lpp-aix5304
# find . -print | backup -iqvf- |rsh lpar6 -l root "cd /export/lppsource/lpp-aix5304 ;restore -xqvf-"
```

**Important:** We recommend that you recreate the .toc file using the `inutoc` command on the /export/lppsource/lpp-aix5304/installp/ppc directory. Also check that the files have read permission on the other user, `chmod 644`.

4. Create the lpp_source resource on lpar6 as shown in Example 4-2.

```
# smitty nim_mkres
– Select lpp_source = source device for optional product images.
```

**Note:** You might not need to create the resource. The NIM synchronization process creates the resource if the lpp_source is in place. However, we recommend that you create the resource manually in the backup NIM master.
Names of Option Packages [ ]
Show Progress [yes] +
Comments [ ]

You will need to repeat the lpp_source resource creation if you have more than one resource.

5. Create the SPOT resource on lpar6, as shown in Example 4-3.

   # smitty nim_mkres
   Select “spot = Shared Product Object Tree - equivalent to /usr file”

**Example 4-3 Creating the SPOT resource on lpar6**

**Define a Resource**

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

[Entry Fields]

* Resource Name [spot-aix5304]
* Resource Type spot
* Server of Resource [master] +
* Source of Install Images [lpp-aix5304] +
* Location of Resource [/export/spot] /
   Expand file systems if space needed? yes +
   Comments [ ]

installp Flags
COMMIT software updates? no +
SAVE replaced files? yes +
AUTOMATICALLY install requisite software? yes +
OVERWRITE same or newer versions? no +
VERIFY install and check file sizes? no +

**Note:** We recommend that you create the SPOT from the previously defined lpp_source resource, instead of letting the NIM synchronization process create the SPOT. Make sure that you use the same directory as on the primary NIM master.

6. Copy the mksysb images, bosinst.data, image.data, firstboot script, and /etc/host files. You need to copy all the images (for example, the bosinst.data, image.data first-boot script files) that belong to the NIM resources from the primary NIM master server. The NIM synchronization process creates these
resources in the backup NIM master server if the images or files exist. You also need to copy the /etc/hosts file.

4.1.2 Initialize the backup server as the alternate NIM master server

After having performed the necessary tasks in 4.1.1, “Configuring the alternate (backup) NIM master” on page 125, we can initialize the backup server as the alternate NIM master.

We initialize the alternate NIM master from the backup NIM master. This updates the NIM database on the primary NIM master and updates the backup NIM master’s /etc/niminfo file.

In our example, the backup server is lpar6. Follow the next step and refer to Example 4-4.

Start on lpar6 with the following action:

```
# smitty nim_altmstr
Initialize This Machine as an Alternate Master
```

Example 4-4 Initializing from the backup NIM master server

<table>
<thead>
<tr>
<th>Initialize This Machine as an Alternate Master</th>
</tr>
</thead>
</table>

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

* This Machine Name [lpar6]
* Primary Network Install Interface [en0] +
* Host Name of Master with which to Initialize [lpar1]

Hardware Platform Type chrp
Kernel to use for Network Boot [mp] +
Communication Protocol used to communicate with Alternate Master [] +
Comments []

Alternate Port Numbers for Network Communications
(reserved values will be used if left blank)
Client Registration [] #
Client Communications [] #

After initialization is finished, the NIM database on the primary NIM master is updated, as shown in Example 4-5 on page 129.
**Example 4-5  lsnim output on primary NIM master**

```
lpars1:/ > lsnim -c machines
master        machines       master
lpars7 machines       standalone
lpars6 machines       alternate_master

lpars1:/ > lsnim -l master
master:
    class               = machines
    type                = master
    max_nimesis_threads = 20
    if_defined          = chrp.mp.ent
    comments            = machine which controls the NIM environment
    platform            = chrp
    netboot_kernel      = mp
    if1                 = mont_net01 lpar1 0
    cable_type1         = tp
    Cstate              = ready for a NIM operation
    prev_state          = ready for a NIM operation
    Mstate              = currently running
    serves              = BOSINST-lpar7
    serves              = IMAGE-lpar7
    serves              = lpp-aix5304
    serves              = MK-lpar7
    serves              = spot-aix5304
    serves              = alt_disk_install_bnd
    serves              = boot
    serves              = nim_script
    master_port         = 1058
    registration_port   = 1059
    reserved            = yes
    is_alternate        = yes
```

The /etc/niminfo file in the lpar6 server is updated with the field export NIM_ALTERNATE_MASTER=lpar1, as shown in Example 4-6.

**Example 4-6  /etc/niminfo file in lpar6 server**

```
lpars6:/ > nimconfig
export NIM_NAME=master
export NIM_CONFIGURATION=master
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_MASTER_HOSTNAME=lpar6
export NIM_ALTERNATE_MASTER="lpar1"
```
4.1.3 Perform NIM synchronization

NIM synchronization must only be performed after you have completed the tasks described in 4.1.1, “Configuring the alternate (backup) NIM master” on page 125 and 4.1.2, “Initialize the backup server as the alternate NIM master server” on page 128. If any of the resource files are not copied to the backup NIM master server, the NIM synchronization process will not create the resource.

From the primary NIM master server (lpar1), follow these steps (refer to Example 4-7):

```
# smitty nim_altmstr
```

Synchronize an Alternate Master's NIM database
Select the Backup NIM master server

**Example 4-7  Synchronizing an alternate master's NIM database**

Synchronize an Alternate Master's NIM database

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

---

* Target Name   ![Entry Fields]  
  lpar6

---

**Note:** You need to force the synchronization. If not, the operation will not be successful because it complains that lpar6 is already a NIM master.

In the future updates, the NIM synchronization will copy the respective resource files and/or directories. For example, the lpp_source directory will be copied over to the alternate NIM master. You do not need to manually copy them over as explained in 4.1.1, “Configuring the alternate (backup) NIM master” on page 125.

Example 4-8 on page 131 shows the output when the NIM synchronization is performed. Notice that the alternate_disk_install installp_bundle resource is not created because the alternate_disk_install bundle file was not copied to the backup NIM master. To fix this, copy the alternate_disk_install bundle file to the backup NIM master and perform the NIM synchronization again.
Example 4-8  NIM synchronization output

a ./etc/objrepos/nim_attr 16 blocks.
a ./etc/objrepos/nim_attr.vc 16 blocks.
a ./etc/objrepos/nim_object 8 blocks.
a ./etc/objrepos/nim_object.vc 8 blocks.
a ./etc/NIM.level 1 blocks.
a ./etc/niminfo 2 blocks.
The original NIM database was backed up to the
following location prior to this operation:
"/export/nim/backups/lpar6.18013606082006.backup"

0513-044 The nimesis Subsystem was requested to stop.
0513-004 The Subsystem or Group, nimd, is currently inoperative.
0513-083 Subsystem has been Deleted.
0513-083 Subsystem has been Deleted.
0518-307 odmdelete: 14 objects deleted.
0518-307 odmdelete: 130 objects deleted.
Restoring the NIM database from /tmp/_nim_dir_233622/mnt0
x ./etc/NIM.level, 9 bytes, 1 media blocks.

The level of the NIM master fileset on this machine is: 5.3.0.40
The level of the NIM database backup is: 5.3.0.40
Level check is successful.

x ./etc/objrepos/nim_attr, 8192 bytes, 16 media blocks.
x ./etc/objrepos/nim_attr.vc, 8192 bytes, 16 media blocks.
x ./etc/objrepos/nim_object, 4096 bytes, 8 media blocks.
x ./etc/objrepos/nim_object.vc, 4096 bytes, 8 media blocks.
x ./etc/NIM.level, 9 bytes, 1 media blocks.
x ./etc/niminfo, 162 bytes, 1 media blocks.
0513-071 The nimesis Subsystem has been added.
0513-071 The nimd Subsystem has been added.
0513-059 The nimesis Subsystem has been started. Subsystem PID is 315556.
Finished restoring the NIM database
Updating master definition in database from lpar6definition
  Updated master attribute platform to chrp
  Updated master attribute netboot_kernel to mp
  Updated master attribute if1 to mont_net01 lpar6 000255AF6C06 ent0
  Updated master attribute cable_type1 to N/A
Finished updating master definition
Resetting machines
  Reset master
  Reset lpar7
  Reset lpar6
Finished resetting machines
Removing NIM client lpar6
Finished removing lpar6
Resetting NIM resources
Finished resetting NIM resources
Checking NIM resources
  Keeping lpp-aix5304
  Keeping spot-aix5304

Removing alt_disk_install_bnd
  0518-307 odmdelete: 1 objects deleted. from nim_attr (serves attr)
  0518-307 odmdelete: 0 objects deleted. from nim_attr (group memberships)
  0518-307 odmdelete: 6 objects deleted. from nim_attr (resource attributes)
  0518-307 odmdelete: 1 objects deleted. from nim_object (resource object)
Finished removing alt_disk_install_bnd
  Keeping MK-lpar7
  Keeping BOSINST-lpar7
  Keeping IMAGE-lpar7
Finished checking NIM resources
Checking NIM SPOTs
  checking spot-aix5304
Finished checking SPOTs
nim_master_recover Complete

Note: Never perform a NIM synchronization from the backup (alternate) NIM master—NIM synchronization must always done at the primary NIM master. Be particularly vigilant when you perform the synchronization.

We recommend that you perform the synchronization any time there is a change in the NIM database, or you can perform regular synchronization via crontab. You can add the following NIM synchronization command into the cron jobs table on lpar1 (you can use the crontab -e command).

  # nim -o sync -a force=yes lpar6

After the NIM synchronization is done, the NIM database of the backup NIM master is updated. The lpar1 is updated as the alternate NIM master.

Example 4-9 shows the lsnim output in the backup NIM master. A master_alias field is added in the NIM database of the lpar6.

Example 4-9  lsnim output from lpar6 server showing its alternate NIM master

<table>
<thead>
<tr>
<th>lpar6:/</th>
<th>lsnim -c machines</th>
<th>lpar7</th>
<th>lsnim -c machines</th>
<th>lpar1</th>
<th>lsnim -c machines</th>
</tr>
</thead>
<tbody>
<tr>
<td>master</td>
<td>machines</td>
<td>master</td>
<td>standalone</td>
<td></td>
<td>alternate_master</td>
</tr>
<tr>
<td>lpar6:/</td>
<td></td>
<td>lpar7</td>
<td></td>
<td>lpar1</td>
<td></td>
</tr>
<tr>
<td>master:</td>
<td></td>
<td>class</td>
<td>= machines</td>
<td>type</td>
<td>= master</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
max_nimesis_threads = 20
if_defined = chrp.mp.ent
comments = machine which controls the NIM environment
platform = chrp
netboot_kernel = mp
if1 = mont_net01 lpar6 0
cable_type1 = tp
Cstate = ready for a NIM operation
prev_state = ready for a NIM operation
Mstate = currently running
serves = BOSINST-lpar7
serves = IMAGE-lpar7
serves = lpp-aix5304
serves = MK-lpar7
serves = spot-aix5304
serves = boot
serves = nim_script
master_port = 1058
registration_port = 1059
reserved = yes
master_alias = lpar6

We can also see that the /etc/niminfo file in the backup NIM master is again updated, as shown in Example 4-10.

Example 4-10 /etc/niminfo file in lpar6 server after NIM synchronization

```bash
#------------------ Network Install Manager ---------------
# warning - this file contains NIM configuration information
# machine which controls the NIM environment
export NIM_NAME=master
export NIM_HOSTNAME=lpar6
export NIM_CONFIGURATION=master
export NIM_MASTER_HOSTNAME=lpar6
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS=" 10.1.1.16:lpar6 ">
export NIM_MOUNTS=""
export NIM_ALTERNATE_MASTER="lpar1"
```

## 4.1.4 NIM master takeover

If you have a problem on the primary NIM master and need to activate the alternate NIM master, you can initiate the takeover from the backup server.
From the alternate (backup) server, lpar6, follow these steps (see Example 4-11):

```
# smitty nim_altmstr
  Takeover control of NIM clients from an Alternate Master
  Select the Primary Server
```

**Example 4-11  Takeover from the backup server**

Takeover control of NIM clients from an Alternate Master
Type or select values in entry fields.
PRESS Enter AFTER making all desired changes.

<table>
<thead>
<tr>
<th>Entry Fields</th>
</tr>
</thead>
<tbody>
<tr>
<td>* Target Name</td>
</tr>
<tr>
<td>Force   yes +</td>
</tr>
</tbody>
</table>

During the takeover process, the backup server attempts to contact the NIM client to change its controlling master. The client's `/etc/niminfo` file will be updated.

The `NIM_MASTER_HOSTNAME`, `NIM_MASTER_HOSTNAME_LIST` and the `NIM_HOSTS` fields in the `/etc/niminfo` file reflect the correct NIM master that this client reports to. Example 4-12 shows the original `/etc/niminfo` file.

**Example 4-12  NIM client's original /etc/niminfo file**

```
#------------------ Network Install Manager ---------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
export NIM_NAME=lpar7
export NIM_HOSTNAME=lpar7
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=lpar1
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_MASTER_HOSTNAME_LIST="lpar1 lpar6"
export NIM_BOS_IMAGE="/SPOT/usr/sys/inst.images/installp/ppc/bos"
export NIM_BOS_FORMAT=rte
export NIM_HOSTS=" 10.1.1.74:lpar7 10.1.1.11:lpar1 "
export NIM_MOUNTS=""
```

**Note:** Remember to verify that the rsh communication between the primary and alternate master and the clients is enabled.
Example 4-13 shows the updated /etc/niminfo file after the NIM takeover. The changes are shown in bold highlighted text.

Example 4-13  Updated NIM client's /etc/niminfo file after the takeover

```
#------------------ Network Install Manager ---------------
# warning - this file contains NIM configuration information
#          and should only be updated by NIM
export NIM_NAME=lpar7
export NIM_HOSTNAME=lpar7
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=lpar6
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_MASTER_HOSTNAME_LIST="lpar6 lpar1"
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS="10.1.1.74:lpar7 10.1.1.16:lpar6 "
export NIM_MOUNTS=""
```

If the NIM client cannot be reached, the backup server updates its database with sync_required = yes. Example 4-14 shows the result when lpar6 is not able to reach lpar7 during the takeover.

Example 4-14  lsnim output with sync_required set to yes on NIM client -lpar7

```
lpar6:/ > lsnim -l lpar7
lpar7:
    class    = machines
    type     = standalone
    connect  = shell
    platform = chrp
    netboot_kernel = mp
    if1      = mont_net01 lpar7 0
    net_settings1 = 100 full
    cable_type1 = tp
    Cstate    = ready for a NIM operation
    prev_state= not running
    Mstate    = not running
    Cstate_result = reset
    current_master = lpar6
    sync_required = yes
```

The alternate (backup) server also attempts to contact the primary server and update it. However, if the primary server is unreachable, the backup server will update its database with sync_required =yes. Example 4-15 on page 136 shows the result when lpar6 is not able to reach lpar1 during the takeover. After every
NIM client has been updated without any problem (/etc/niminfo file is updated),
the backup NIM master is ready to perform NIM operations as a NIM master.

Example 4-15  Alternate NIM master lsnim output (sync_required = yes)

```
lsnim -l lpar1
lpar1:
  class = machines
  type = alternate_master
  connect = shell
  platform = chrp
  netboot_kernel = mp
  if1 = mont_net01 lpar1 0
  cable_type1 = N/A
  Cstate = ready for a NIM operation
  prev_state = ready for a NIM operation
  Mstate = currently running
  sync_required = yes
```

4.1.5  NIM master fallback

After the original (primary) NIM master has been restored for operation, you can
fall back the NIM master control from the backup (alternate) server. Follow the
same steps described in 4.1.4, “NIM master takeover” on page 133, but perform
the commands from the original (primary) NIM master.

From the original primary server, lpar1 (as shown in Example 4-16), follow these
steps:

```
# smitty nim_altmstr
  Takeover control of NIM clients from an Alternate Master
    Select the Backup Server
```

Example 4-16  Takeover control of NIM clients

```
Takeover control of NIM clients from an Alternate Master
Type or select values in entry fields.
Press Enter AFTER making all desired changes.

* Target Name       [Entry Fields]
  lpar6

Force
  yes +
```
4.2 Using the OS_install command

The OS_install command can be used to install both AIX clients and Linux clients. In order to install Linux clients, CSM must be installed on the installation server (NIM master).

**Note:** To support Linux installation using CSM, there are new NIM objects such as `linux_source` and `linux_inst`. In this initial release of Linux installation support from NIM, Linux clients will not be able to function as a NIM client in the same capacity as AIX NIM clients are able to.

Because the Linux installation mechanism depends on DHCP, a NIM standalone client that is to be installed with Linux must (in addition to what is required for AIX network installation) have specified a MAC address. In addition, the client and the master must reside in the same subnet. Also, NIM currently has no capabilities to perform additional system management or “bare-metal” installation of Linux standalone clients. After an allocation is performed, the client must be manually initiated for network installation using the boot parameters displayed after a successful allocation of a `linux_source` resource.

The supported Linux distributions for installation are Red Hat Enterprise Linux (RHEL) V3 and V4, and SUSE Linux Enterprise Server (SLES) V9. To use the OS_install command, you need to first install the libxml2 RPM and then the osinstall RPM, as shown in Example 4-17. The RPM packages are located in the RPMS/ppc directory of your NIM lpp_source.

```
# rpm -ihv libxml2-2.6.17-3.aix5.1.ppc.rpm
# rpm -ihv osinstall-1.0-1.aix5.3.noarch.rpm
```

**Example 4-17** Installed files from the osinstall RPM package

```
root@master:/: rpm -ql osinstall
/opt/osinstall/pm/OSInstall.pm
/opt/osinstall/pm/OSInstall/AIX_Resource.pm
/opt/osinstall/pm/OSInstall/Client.pm
/opt/osinstall/pm/OSInstall/Common.pm
/opt/osinstall/pm/OSInstall/Control_Host.pm
/opt/osinstall/pm/OSInstall/Linux_Resource.pm
/opt/osinstall/pm/OSInstall/OS_Resource.pm
/opt/osinstall/pm/OSInstall/Platform_Tools.pm
/opt/osinstall/pm/OSInstall/XMLHandler.pm
/opt/osinstall/schema/niml.xsd
/usr/sbin/OS_install
/usr/sbin/nimol_bootreplyd
```
You also need to have OpenSSH and OpenSSL installed on the master to perform netboot operations.

```
rpm -i openssl-0.9.7g-2.aix5.1.ppc.rpm
installp -d openssh.base all
installp -d openssh.license all
```

With the `OS_install` command, it is also possible to use W3C XML to describe the NIM environment for the client installation. The Extensible Markup Language Schema Definition (XSD) specification can be found in the `/opt/osinstall/schema/niml.xsd` file.

The network install schema consists of four fundamental elements: clients, os_resources, resource_servers, and ctrl_hosts. In addition, there are also the general osinstall_config objects.

### 4.2.1 OS_install basics

`OS_install` lets you define a client or resource, allocate resources to clients and netboot clients. You can also use the SMIT nim_linux_inst fastpath to perform Linux client installations with `OS_install`.

**Note:** The `OS_install` command uses the `/var/osinstall` directory as the root of its file system.

To get started with `OS_install`, you can use the following procedure:

1. Define installation resources.
2. Define controlling hosts for clients.
3. Define clients.
4. List defined objects.
5. Allocate resources to clients.
6. Perform netboot operations on clients.

Figure 4-2 on page 139 shows the NIM linux_source input panel for the SMIT nim_mkres fastpath selecting `linux_source` (the resource containing the Linux installation images) as the Resource Type.
4.2.2 OS_install resource definition

Defining an OS_install resource is similar to creating a SPOT or COSI; refer to “Creating a NIM spot object” on page 74 and 4.8, “Common Operating System Image (COSI) management” on page 298 for details. Before starting, however, you need to have AIX BOS filesets and AIX 5L V5.3 TL5 filesets available.

In Example 4-18, we have copied the filesets to the /export/lpp_source/lpp5305 directory. Then you need to decide on how to name your resource (in our example, we name the resource BOS5305. Then you must specify the operating system type and the version (in our case AIX and 53TL5, respectively).

To create OS_install resource objects you use the define_resource operation:

```
OS_install -o define_resource -a attr=value ... <object_name>
```

Required attributes:  type, version  
Optional attributes:  source, location, configfile

Example 4-18  OS_install define_resource operation

```
root@master:/: OS_install -o define_resource -a location=/export/lpp_source/bos5305 -a source=/export/lpp_source/lpp5305 -a type=AIX -a version=53TL5 BOS5305

mkdir /export/lpp_source/bos5305
Mon Jun 26 14:52:28 2006 Executing: (cd /export/lpp_source/lpp5305 && /usr/bin/tar -cf - .) | (cd /export/lpp_source/bos5305 && /usr/bin/tar -xf -)
```
4.2.3 OS_install controlling host definition

Every OS_install client needs a controlling host. The controlling host performs netboot operations on the client. In Example 4-19, we use the Hardware Management Console (HMC) for the logical partition (LPAR) which will be the controlling host and client, respectively. The HMC hostname is hmc5 and the client hostname is lpar55.

In Example 4-19, we define the controlling host (define_ctrl_host) to be of the type hmc, and we use ssh as the communications_method (thus the need to install ssh), and we name the controlling host HMC5.

To create OS_install controlling host objects, use the define_ctrl_host operation:

\[
\text{OS\_install} \ -\ o \ \text{define\_ctrl\_host} \ -\ a \ \text{attr=value} \ \ldots \ <\text{object\_name}>
\]

Required attributes: communication_method, hostname, type

Example 4-19  OS_install define_ctrl_host operation

```
root@master:/: OS_install -o define_ctrl_host -a type=hmc -a hostname=hmc5 -a communication_method=ssh HMC5
Mon Jun 26 14:20:02 2006 Writing HMC5 to repository
```

4.2.4 OS_install client definition

After the controlling host have been defined, we can define the clients. It is possible to define the clients first and then connect them to a controlling host.

Just as for standalone NIM machines, we need to know the IP-address (10.1.1.55), the MAC-address (22:33:80:00:AB:CD), and the NIM networks part with gateway (10.1.1.254) and subnet mask (255.255.255.0). In addition, we need information about the controlling host (HMC5), the LPAR name (lpar55), profile (normal) and managed system (IBM-595-65C5ABC).

To create OS_install client objects, you use the define_client operation as shown in Example 4-20 on page 141.

\[
\text{OS\_install} \ -\ o \ \text{define\_client} \ -\ a \ \text{attr=value} \ \ldots \ <\text{object\_name}>
\]

Required attributes: ip_addr, mac_addr, gateway, subnet_mask
Optional attributes: adapter_speed, adapter_duplex, lpar, profile, managed_system, disk_location, ctrl_host
Example 4-20  OS_install define_client operation

root@master:/: OS_install -o define_client -a ip_addr=10.1.1.55 -a mac_addr=22:33:00:AB:CD -a gateway=10.1.1.254 -a subnet_mask=255.255.255.0 -a ctrl_host=HMC5 -a lpar=lpars55 -a profile=normal -a managed_system=IBM-595-65C5ABC LPAR55

mkdir /var/osinstall
mkdir /var/osinstall/service_state
mkdir /var/osinstall/service_state/cfg_save
mkdir /var/osinstall/service_state/cfg_data
mkdir /var/osinstall/lock
Mon Jun 26 14:13:59 2006 OSInstall repository not found, create new
Mon Jun 26 14:13:59 2006 Writing LPAR55 to repository

To list OS_install objects (list mode) you use the -l flag as shown in Example 4-21.

    OS_install -l [ -v ] [ -t <object_type> | <object_name> ]

The -v option shows the XML for the object. Object types are shown in the right column in Example 4-21. Refer to 4.2.6, “OS_install XML repository” on page 143 for more detailed information about this topic.

Example 4-21  OS_install list objects

root@master:/: OS_install -l
HMC5 ctrl_host
LPAR55 client

4.2.5 OS_install resource allocation and installation

To allocate the resource to install a client using the OS_install command, use the allocate operation:

    OS_install -o allocate -a os_resource=<resource_name> <client_name>

Required attributes:   resource_name, client_name

To install a client using OS_install, use the netboot operation:

    OS_install -o netboot <client_name>

Note: Do not use the virtual terminal connection from the HMC to the LPAR, because this connection will be used by the netboot operation.

In Example 4-22 on page 142, we install the previously defined LPAR55 with AIX 5L using OS_install. We have not configured this NIM master to be able to log in to the HMC without supplying a password, so we will have to enter it at the password prompt.
The OS_install netboot uses the HMC lpar_netboot EXPECT script to restart the LPAR through the controlling host (HMC). The script is almost the same as the bos.sysmgt.nim.master script /usr/sbin/lpar_netboot.

**Note:** If you define an LPAR as an OS_install client and as a NIM client, you can then manage the LPAR by using both the nim and the OS_install commands. The OS_install netboot operation is especially useful when performing LPAR installations or reinstallations on regular NIM clients.

To monitor the netboot installation using OS_install you can use the monitor_installation operation, as shown here:

```
OS_install -o monitor_installation <client_name> [-d]
```

If you need to remove a OS_install resource or client, you can use the remove operation as shown in Example 4-23 on page 143.

```
OS_install -o remove <object_name>
```
4.2.6 OS_install XML repository

The OS_install information about each client or resource will be stored in the XML repository file /var/osinstall/xml_repos, as shown in Example 4-24.

Example 4-24 OS_install xml_repos

```xml
<?xml version="1.0"?>
<osinstall_config xmlns="http://www.ibm.com/niml" niml_version="1.0">
  <ctrl_host xmlns="http://www.ibm.com/niml" name="HMC5">
    <hostname xmlns="http://www.ibm.com/niml">hmc5</hostname>
    <type xmlns="http://www.ibm.com/niml">hmc</type>
    <commo_method xmlns="http://www.ibm.com/niml">ssh</commo_method>
  </ctrl_host>
  <client xmlns="http://www.ibm.com/niml" name="LPAR55">
    <ip_addr>10.1.1.55</ip_addr>
    <mac_addr>22:33:80:00:AB:CD</mac_addr>
    <gateway>10.1.1.254</gateway>
    <subnet_mask>255.255.255.0</subnet_mask>
    <adapter_speed>auto</adapter_speed>
    <adapter_duplex>auto</adapter_duplex>
    <partition_info lpar="lpar55" profile="normal" managed_system="IBM-595-65C5ABC"/>
    <ref_ctrl_host ctrl_host_name="HMC5"/>
  </client>
</osinstall_config>
```

Detailed messages from running the OS_install command are written to the /var/osinstall/event_log file.

4.3 NIM environment with additional resource servers

If your environment consists of multiple nodes or a complex network, you can consider configuring NIM resource servers to help offload your NIM master. As mentioned in Chapter 2, “Network Installation Manager definitions and concepts” on page 7, a NIM resource server can be any standalone client (machine) configured as a server for a particular resource (for example, lpp_source or SPOT).
Consider configuring additional resource servers in these cases:

- You have a complex environment with many nodes, and you need to offload your NIM master.

- You have a complex network with multiple LANs, routers and firewalls for simplifying network administration and security (one resource server per LAN).

- You have IBM System p5 servers with multiple partitions in each CEC, and you want to use POWER™ hypervisor-managed VLANs to offload the external (client) network. You can find specific information on NIM and VIO in 4.13, “NIM and Virtual I/O (VIO)” on page 373.

### 4.3.1 Configuring a resource server

In our scenario, we have an LPAR in the IBM @server p670 server configured as our NIM master, and two NIM clients (LPARs) in one IBM System p p520 server. The two NIM clients are VIO clients as well. We have a Shared Ethernet Adapter (SEA) configured in the VIO server to allow external network communication with the NIM master. Refer to Figure 4-3.

![Diagram of NIM master and resource server setup](image)
We configure one of the NIM clients, vlpar7_p5, as the resource server serving the SPOT and mksysb resources to the other NIM client, vlpar9_p5 (both vlpar7_p5 and vlpar9_p5 reside inside the same p5 server).

- Defining a SPOT resource in a standalone client

Before creating the SPOT, remember to allocate the disk space for the SPOT creation in the resource server, vlpar7_p5. We recommend that you create a file system for the SPOT (for example, /export/spot).

**Note:** Remember that the NIM master is able to communicate with the resource server either through `rsh` or `nimsh`. Also verify that NFS is enabled.

Steps through the SMIT to create the SPOT resource (see Example 4-25):

- From the NIM master, lpar1

  ```
  smitty nim_mkres
  Select “spot = Shared Product Object Tree - equivalent to /usr file”
  ```

**Example 4-25  Define a SPOT resource with vlpar7_p5 as the resource server**

Define a Resource

Type or select values in entry fields.

Press Enter AFTER making all desired changes.

<table>
<thead>
<tr>
<th>[Entry Fields]</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Resource Name</strong></td>
<td>[SPOT-AIX53-Clust01]</td>
</tr>
<tr>
<td><strong>Resource Type</strong></td>
<td>spot</td>
</tr>
<tr>
<td><strong>Server of Resource</strong></td>
<td>[vlpar7_p5] +</td>
</tr>
<tr>
<td><strong>Source of Install Images</strong></td>
<td>[LPPSRC-AIX53] +</td>
</tr>
<tr>
<td><strong>Location of Resource</strong></td>
<td>[/export/AIX53] /</td>
</tr>
<tr>
<td>Expand file systems if space needed?</td>
<td>yes +</td>
</tr>
<tr>
<td>Comments</td>
<td>[]</td>
</tr>
<tr>
<td><strong>installp Flags</strong></td>
<td></td>
</tr>
<tr>
<td>COMMIT software updates?</td>
<td>no +</td>
</tr>
<tr>
<td>SAVE replaced files?</td>
<td>yes +</td>
</tr>
<tr>
<td>AUTOMATICALLY install requisite software?</td>
<td>yes +</td>
</tr>
<tr>
<td>OVERWRITE same or newer versions?</td>
<td>no +</td>
</tr>
<tr>
<td>VERIFY install and check file sizes?</td>
<td>no +</td>
</tr>
</tbody>
</table>

In Example 4-25, notice that vlpar7_p5 is chosen as the Server of Resource.
In the SPOT creation process, the NIM master exports its lpp_source directory and the standalone client (resource server) NFS mounts the NIM master’s lpp_source directory.

See Example 4-26.

Example 4-26  lpp_source directory is exported and nfs mounted on resource server

From NIM master, lpar1,  
lpar1:/ > exportfs  
/export/lppsource/lppsrc-aix53 -ro,root=vlpar7_p5:,access=vlpar7_p5:

From the Resource server, vlpar7_p5,  
vlpar7_p5:/ > df

<table>
<thead>
<tr>
<th>Filesystem</th>
<th>512-blocks</th>
<th>Free</th>
<th>%Used</th>
<th>Iused</th>
<th>%Iused</th>
<th>Mounted on</th>
</tr>
</thead>
<tbody>
<tr>
<td>/dev/hd4</td>
<td>98304</td>
<td>21760</td>
<td>78%</td>
<td>1774</td>
<td>40%</td>
<td>/</td>
</tr>
<tr>
<td>/dev/hd2</td>
<td>1507328</td>
<td>134120</td>
<td>92%</td>
<td>9965</td>
<td>54%</td>
<td>/usr</td>
</tr>
<tr>
<td>/dev/hd9var</td>
<td>32768</td>
<td>16032</td>
<td>52%</td>
<td>373</td>
<td>17%</td>
<td>/var</td>
</tr>
<tr>
<td>/dev/hd3</td>
<td>65536</td>
<td>62808</td>
<td>5%</td>
<td>4</td>
<td>1%</td>
<td>/tmp</td>
</tr>
<tr>
<td>/dev/hd1</td>
<td>32768</td>
<td>32064</td>
<td>3%</td>
<td>5</td>
<td>1%</td>
<td>/home</td>
</tr>
<tr>
<td>/proc</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>/proc</td>
</tr>
<tr>
<td>/dev/hd10opt</td>
<td>98304</td>
<td>23032</td>
<td>77%</td>
<td>682</td>
<td>20%</td>
<td>/opt</td>
</tr>
<tr>
<td>/dev/spotlv</td>
<td>4194304</td>
<td>2971352</td>
<td>30%</td>
<td>16403</td>
<td>5%</td>
<td>/export/spot</td>
</tr>
<tr>
<td>/dev/imageslv</td>
<td>4194304</td>
<td>1044904</td>
<td>76%</td>
<td>10</td>
<td>1%</td>
<td>/export/images</td>
</tr>
<tr>
<td>lpar1:/export/lppsource/lppsrc-aix53</td>
<td>24379392</td>
<td>3982728</td>
<td>84%</td>
<td>3061</td>
<td>1%</td>
<td>/tmp/_nim_dir_327780/mnt0</td>
</tr>
</tbody>
</table>

After the SPOT resource is defined on the NIM master and created on the resource server, you can see that this resource defined into the NIM master’s database using lsnim -l <SPOT_name>.

Also notice the resource pointing to the resource server, as highlighted in bold font in Example 4-27.

Example 4-27  lsnim output showing SPOT resource pointing to the resource server

lpar1:/ > lsnim -c resources

boot resources boot
nim_scri resources nim_script
LPPSRC-AIX53 resources lpp_source
SPOT-AIX53 resources spot
SPOT-AIX53-Clust01 resourc spot

lpar1:/ > lsnim -l SPOT-AIX53-Clust01
SPOT-AIX53-Clust01:
    class = resources
type = spot
    plat_defined = chrp
    arch = power
Defining a mksysb resource on a standalone client

In our example, we initiated the mksysb of the NIM client (vlpar9_p5) from the NIM master. Before you perform this action, make sure you have allocated disk space for the resource server. We recommend you create another file system (for example, /export/images).

Steps through the SMIT to create the mksysb resource as shown in Example 4-28.

- From the NIM master, lpar1

  lpar1:/ > smitty nim_mkres

  - Select “mksysb = a mksysb image”

Example 4-28  Define a mksysb resource with vlpar7_p5 as the resource server

Define a Resource
Type or select values in entry fields.
Press Enter AFTER making all desired changes.

Note: Remember to have the following prerequisites in place:

- Communication between the NIM master and the resource server, as well as communication between the NIM master and the NIM client. You can use either rsh or nimsh.
- Verify that the NFS between the resource server and the NIM client is enabled.
- The ulimit is set to unlimited on both the resource server and the NIM client (for root user).
- The file system exported by the resource server is either large file enabled (JFS) or JFS2.
In the mksysb resource creation process, the vlpar7-p5 server's
/export/images directory is exported to the vlpar9_p5 server to perform the
mksysb; see Example 4-29.

**Example 4-29 /export/images directory NFS exported**

From Resource server, vlpar7_p5,
vlpar7_p5:/ > exportfs
/export/images -root=vlpar9_p5:,access=vlpar9_p5:

From NIM client, vlpar9_p5,
vlpar9_p5:/ > df

<table>
<thead>
<tr>
<th>Filesystem</th>
<th>512-blocks</th>
<th>Free</th>
<th>%Used</th>
<th>Iused</th>
<th>%Iused</th>
<th>Mounted on</th>
</tr>
</thead>
<tbody>
<tr>
<td>/dev/hd4</td>
<td>49152</td>
<td>15864</td>
<td>68%</td>
<td>1656</td>
<td>46%</td>
<td>/</td>
</tr>
<tr>
<td>/dev/hd2</td>
<td>1490944</td>
<td>144224</td>
<td>91%</td>
<td>19527</td>
<td>51%</td>
<td>/usr</td>
</tr>
<tr>
<td>/dev/hd9var</td>
<td>32768</td>
<td>15312</td>
<td>54%</td>
<td>363</td>
<td>17%</td>
<td>/var</td>
</tr>
<tr>
<td>/dev/hd3</td>
<td>65536</td>
<td>59272</td>
<td>10%</td>
<td>48</td>
<td>1%</td>
<td>/tmp</td>
</tr>
<tr>
<td>/dev/hd1</td>
<td>32768</td>
<td>32064</td>
<td>3%</td>
<td>5</td>
<td>1%</td>
<td>/home</td>
</tr>
<tr>
<td>/proc</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>/proc</td>
</tr>
<tr>
<td>/dev/hd10opt</td>
<td>81920</td>
<td>25792</td>
<td>69%</td>
<td>621</td>
<td>17%</td>
<td>/opt</td>
</tr>
<tr>
<td>vlpar7_p5:/export/images</td>
<td>4194304</td>
<td>2031472</td>
<td>52%</td>
<td>9</td>
<td>1%</td>
<td></td>
</tr>
<tr>
<td>/tmp/4056320</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

After the mksysb resource has been defined on the NIM master and created
on the resource server, you can see this resource by running (on the NIM
master) lsnim -l <mksysb_name>.

Note that the resource is pointing to the resource server; see the fields that
are highlighted in bold font in Example 4-30.

**Example 4-30 lsnim output showing mksysb resource pointing to resource server**

lpar1:/ > lsnim -c resources
boot resources boot
nim_script resources nim_script
LPPSRC-AIX53 resources lpp_source
4.3.2 Performing a BOS installation

Performing a BOS installation (rte or mksysb), for example, having the resources on the resource server, is similar to a BOS installation with all the resources on the NIM master. You just have to allocate the correct resources to perform this task. However, there are a prerequisite items that need to in place first:

- Communication between the NIM master and resource server (rsh or nimsh).
- Communication between the NIM master and the NIM client, if you need to perform a push operation (rsh or nimsh).
- NFS must be enabled between the NIM master and the NIM client—or between the resource server and the NIM client—depending on where the resource is located.
- If you have a resource server serving the SPOT resource for the NIM client, and you perform a pull BOS installation, note that the database for the bootp server in the /etc/bootptab file is in the resource server, instead of in the NIM master.

Also, when you specify the server’s IP address in the SMS menu, ensure that you specify the resource server’s IP instead of the NIM master IP.
Here we provide an example to demonstrate what happens when we perform a pull BOS installation with the resource server serving the mksysb and the SPOT resources for the NIM client:

1. Allocate the SPOT and the mksysb resources to the NIM client (vlpar9_p5).

   From the NIM master (lpar1), follow these steps through the SMIT menus:
   
   lpar1:/ > smitty nim_mac_res
   Allocate Network Install Resources

   Then select vlpar9_p5 as the target machine and MK-VLPAR9_P5 and SPOT-AIX53-Clust01 as resources.

   After the SPOT and mksysb are allocated, the image and the SPOT directories are exported from the vlpar7_p5 to vlpar9_p5 (see Example 4-31).

   Example 4-31  image and SPOT exported in vlpar7_p5

   vlpar7_p5:/ > exportfs
   /export/spot/SPOT-AIX53-Clust01/usr -ro,root=vlpar9_p5:,access=vlpar9_p5:
   /export/images/vlpar9_p5.mksysb -ro,root=vlpar9_p5:,access=vlpar9_p5:

2. Initialize the BOS installation on the NIM client (vlpar9_p5), as shown in Example 4-32.

   From the NIM master, follow these steps through the SMIT menu:
   
   lpar1:/ > smitty nim_mac_op

   Select vlpar9_p5 as the target machine and bos_inst = perform a BOS installation.

   Example 4-32  BOS installation - mksysb (pull operation)

   Perform a Network Install

   Type or select values in entry fields.
   Press Enter AFTER making all desired changes.

   [Entry Fields]
   Target Name vlpar9_p5
   Source for BOS Runtime Files mksysb +
   installp Flags [-agX]
   Fileset Names []
   Remain NIM client after install? yes +
   Initiate Boot Operation on Client? no +
   Set Boot List if Boot not Initiated on Client? no +
   Force Unattended Installation Enablement? no +
   ACCEPT new license agreements? [yes] +

   After the BOS installation is initialized, the /etc/boottab file in the vlpar7_p5 server is updated (not in the NIM master server). Observe that the server's IP
address is pointing to the vlpar7_p5's IP address instead of the NIM master's IP address, as shown in Example 4-33.

Example 4-33 /etc/booptab file in vlpar7_p5

```
#     T178 -- (xstation only) -- enable XDMCP
#     T179 -- (xstation only) -- XDMCP host
#     T180 -- (xstation only) -- enable virtual screen
vlpar9_p5:bf=/tftpboot/vlpar9_p5:ip=10.1.1.74:ht=ethernet:sa=10.1.1.72:sm=255.255.255.0:
```

Also, the NIM script is exported from the vlpar7_p5 to vlpar9_p5; see Example 4-34.

Example 4-34 nim script exported from vlpar7_p5

```
vlpars7_p5:/ > exportfs
/export/spot/SPOT-AIX53-Clust01/usr -ro,root=vlpar9_p5:,access=vlpar9_p5:
/export/images/vlpar9.mksysb -ro,root=vlpar9_p5:,access=vlpar9_p5:
/export/nim/scripts/VLPAR9_P5.script -ro,root=vlpar9_p5:,access=vlpar9_p5:
```

3. Boot the LPAR in SMS mode

Boot the LPAR in SMS mode to specify the vlpar7_p5 IP address as the server's IP address instead of the NIM master's IP address. Refer to “SMS and console flow during NIM client installation” on page 84 for more detailed information about SMS menus.

4.4 Using NIM to perform AIX migrations of NIM master and clients

In the following section we discuss using NIM to perform AIX migration of the master and the clients. In particular, we will focus on migration to AIX 5L V5.3. The main topics we cover are:

- Migrating a NIM master to AIX 5L V5.3
- Migrating a NIM client to AIX 5L V5.3

We cover the conventional method of AIX migration via NIM. Other methods of NIM migration such as using the `nimadm` tool are covered in 4.5, “NIM mksysb migration and nim_move_up POWER5 tools” on page 205. There are two new methods for AIX migration via NIM: mksysb migration and nim_move_up, which are discussed in later sections of this book as well.
Planning to migrate an AIX system (with or without NIM) requires careful planning and testing. Here we provide tips for planning a migration, including pre/post migration steps, NIM master and client requirements, disk space requirements, migration testing with NIM clones and more.

### 4.4.1 Migrating a NIM master to AIX 5L V5.3

In this section, we discuss the migration of a NIM master to AIX 5L V5.3. Although the migration of a NIM master is not performed via a NIM migration procedure, we cover the specific tasks required when upgrading a NIM master, including tips on pre-migration and post-migration tasks which will ensure a successful, functioning NIM environment.

We do not cover in detail how to perform an AIX migration via CD. This type of migration is documented in AIX 5L V5.3 Installation and Migration, SC23-4887, and there are no specific differences for a NIM master. The topics we cover here include:

- Prerequisites
- Pre-migration tasks
- Migration via CD
- Post-migration tasks
- Cleanup tasks
- Alternative migration option

**Note:** In a NIM environment, the NIM master must be running at the highest level of AIX. Therefore, it must be migrated to AIX 5L V5.3 **before** any of its clients. After it is migrated, the master will be able to serve AIX 5L V5.3 clients as well clients running earlier versions of AIX (for example, AIX V4.3, AIX V5.1 and AIX 5L V5.2).

Before migrating a NIM master, check the following:

- Obtain the latest AIX base install media plus the latest Technology Level (TL), Service Packs (SP), and Concluding Service Packs (CSP).
- Read the AIX 5L V5.3 release notes. These contain important information that you should know before starting a migration.
- Check that your client hardware supports AIX 5L V5.3. More information can be found in the release notes for AIX 5L V5.3. Release notes for AIX 5L V5.3 for example, mention that some older hardware is no longer supported (such as MCA).
- Always perform at least one test migration of the system before performing the real migration. This will verify that the AIX migration works as expected,
and will highlight any issues before they occur during a live production upgrade. Make sure you test the backout plan as well.

- Ensure that you have all the latest software levels for disk and other storage devices such as SDD, SDDPCM, and so on. Verify that you have the correct version for AIX 5L V5.3. If you are running SDD, you will need SDD for AIX 5L V5.3. After a migration to AIX 5L V5.3 you would need to remove the old version and install the correct version of SDD for AIX 5L V5.3.

- It is always a best practice to upgrade your system and adapter firmware to the latest level of microcode before performing an AIX migration. Some systems or adapters may not be supported or will not function with AIX 5L V5.3 if their microcode is not up-to-date.

In particular, check the levels of your fibre channel (if using SAN-attached storage) and network adapters (especially when using NIM). Check the IBM support Web site for the latest levels of system and adapter microcode and apply them before upgrading:


- Check the code level on your Hardware Management Console (HMC) (if applicable). Often there will be corresponding code levels when you upgrade the managed system microcode which may contain important fixes to support AIX 5L V5.3 and the latest Technology Level.

- Document the NIM master’s current configuration (for example, hardware, AIX and NIM information). You can use the `snap` and `lsnim` commands to document the NIM master’s configuration. You could also use a custom script to collect information about your system and store it in a text file. This file can be used later if you need to look back at how the system was configured before the migration.

- Back up the NIM database. You can use SMIT to back up the NIM database, or use a custom script. Back up the database before performing a mksysb; in this way, the NIM database backup will be included in the mksysb.

- Perform a mksysb of the NIM master before the migration. You can back up to tape or DVD media. If your NIM resources are kept in a separate volume group (for example, nimvg), then you should also perform a volume group backup (savevg) to tape or DVD, or use the backup tool that exists within your environment (for example, Tivoli Storage Manager).
In the following section, we look at upgrading your NIM master from AIX 5L V5.2 to AIX 5L V5.3 via CD.

Prior to migration, make sure that the following prerequisites are met:

- Ensure you have all the AIX 5L V5.3 media (CDs).
- Check that you have enough disk space to create file systems for the new AIX 5L V5.3 lpp_source and SPOT that will be created after the migration of the master.
- Check the following documentation:
  - AIX 5L Version 5.3 release notes
  - AIX 5L Version 5.3 Bonus Pack and Expansion Pack Release Notes
- Check if the hardware is supported. Only Common Hardware Reference Platform (CHRP) machines are supported under AIX 5L V5.3. Verify that the server is a CHRP machine:
  ```
  # bootinfo -p
  chrp
  ```
- Check file system space and free PPs in rootvg. Consult the AIX 5L V5.3 release notes for more information about space requirements.

Notes:

- Migration by media (CD) is the only supported way to migrate a NIM master. The NIM master will be unavailable for the duration of the migration.
- Starting with AIX 5L V5.3, there is a new NIM feature known as High Availability NIM (HANIM). HANIM will allow you to manually switch your primary master to an alternate. If downtime is an issue for your NIM master (for example, for disaster recovery purposes), then you can perform your migration without impacting your NIM clients.

After your NIM master has been migrated to AIX 5L V5.3, you will be able to take advantage of this feature for any future AIX migration (for example, AIX 5L V5.3 to AIX 5L V5.4) on the NIM master. For details, see 4.1, “High Availability Network Installation Manager” on page 124.
Run the AIX 5L V5.3 pre_migration script and review the results. The pre_migration script will verify whether your system is ready for migration. The pre_migration script can be found on the AIX 5L V5.3 base install media.

Back up the files /etc/motd and /etc/sendmail.cf. These files are replaced during a migration. Keep copies of the originals on hand so you can merge the old configuration into the newer files manually.

Back up the NIM database beforehand.

Verify that you have a CD and/or tape drive on the NIM master, because a CD drive will be required for the migration. If using DLPAR, you need to assign one CD/DVD drive dynamically for use during the migration.

Document AIX and NIM master configuration before and after. Use the lsnim and snap commands to generate and capture critical configuration information about your NIM master. This information will be useful if you encounter problems after the migration that require you to rebuild or reconfigure the system.

We cloned the NIM master (with “Remain NIM client set to no”) to another test system and performed a test migration to AIX 5L V5.3. We did not test the NIM environment as we only wanted to test and observe the AIX migration process. However, you could clone the master and configure so that it was a fully functional NIM master that could serve clients. You may even consider this as an alternate way of migrating your NIM master. For more information on cloning a system with NIM refer to 5.4, “Cloning NIM clients using mksysb” on page 451 and 5.10, “Backing up and reinstalling a NIM master” on page 537.

**Steps to migrate the NIM master to AIX 5L V5.3**

The following steps will migrate a NIM master running AIX 5L V5.2 on p670 LPAR to AIX 5L V5.3. We employ the use of an alternate disk install to provide a quick backout if the migration should fail for any reason.

After the migration is complete, we then verify the NIM master environment is usable and verify that we can still use NIM to perform a BOS install of the various versions of AIX that our environment supports (for example, AIX 4.3, AIX 5L V5.1, AIX 5L V5.2, and now AIX 5L V5.3). These are steps to follow:

1. Check for clients that have active NFS mounts from the NIM master before you start the migration.

   There have been situations where clients will hang when the NIM master is shut down and the clients’ NFS mount “disappears”. It can be difficult to force umount the NFS cross-mount on the client (it is not impossible, but it is difficult) and this may require a reboot of the client if the NIM master is unavailable for a long time.
If you are using CSM, you can use the `dsh` command to check all your systems at once for any current NFS mounts from the clients to the NIM master. In the following example, client `lpar4` has NFS-mounted `nimmast`'s `/export/images` file system. This should be unmounted prior to migrating the NIM master.

```bash
{nimmast}:#/ dsh -v mount | grep -i nfs
lpar4: nimmast /export/images /mnt nfs3 Jun 14 15:56
```

2. Document the AIX and NIM master configuration.

In our case, we use the `snap` and `lsnim` commands to document the system before the migration. The output from both commands would be stored on a system other than the NIM master. We need to be able to access the information whether or not the NIM master is up or down.

We also use a custom script to capture other configuration information we would like to see; refer to Appendix D, “Additional material” on page 643.

```bash
{nimmast}:#/ snap -ac
{nimmast}:#/ lsnim -l
{nimmast}:#/ AIXinfo -pre
```

3. Perform a NIM database backup.

In our case, we back up the NIM database via SMIT. You can also use a script if you prefer, as shown in Example 4-35. The advantage of using a script is that it can be run from root's cron every day, thus giving you several backups to chose from in case of a problem.

```bash
{nimmast}:#/ smitty nim_backup_db
Backup the NIM Database
* Filename/Device for the Backup
[ /etc/objrepos/nimdb.backup.14Jun2006.Prior_to_AIX53_Migration ] +
```

**Example 4-35  NIM database backup script**

```bash
{nimmast}:#/usr/local/bin # cat bknimdb
#!/usr/bin/ksh
#
# bknimdb - script to backup the NIM Database
#
# Description
# -----------
# This script will backup the NIM database. This backup could be used
# to recover the NIM Database should it become corrupted. The backup
# file will be named nimdb.backup.Day, where Day is the day of the week.
#
# e.g. /etc/objrepos/nimdb.backup.Mon
#
# The NIM database can be restored via procedures documented in the
# "AIX 5L Version 5.3 Installing AIX" Guide (SC23-4887-02).
```
# The restore can be done via SMIT i.e.
#
#       # smitty nim_restore_db
#

PATH=/usr/bin:/usr/sbin

# Directory where the NIM database backup will be created.
imdbdir=/etc/objrepos

# We can only run this as root.
if [ "$(id -un)" != "root" ]
then
echo "$(basename $0): must be run as user "root""
exit 1
fi

# Backup the NIM Database.
#
echo "---------------------------------------------------------"
echo "Starting NIM Database Backup on $(uname -n) at $(date)"
echo
/usr/lpp/bos.sysmgt/nim/methods/m_backup_db $nimdbdir/nimdb.backup.$(date +%a)
if [ $? -ne 0 ]
then
  echo
  echo "$(basename $0): Error in backing up NIM Database"
  echo
fi

echo
echo "Finished NIM Database Backup on $(uname -n) at $(date)"
echo "---------------------------------------------------------"

{nimmast}:/usr/local/bin # bknimdb

----------------------------------------------------------------
Starting NIM Database Backup on nimmast at Mon Jun 19 10:12:21 DFT 2006

a ./etc/objrepos/nim_attr 72 blocks.
a ./etc/objrepos/nim_attr.vc 272 blocks.
a ./etc/objrepos/nim_object 16 blocks.
a ./etc/objrepos/nim_object.vc 32 blocks.
a ./etc/NIM.level 1 blocks.
a ./etc/niminfo 1 blocks.

Finished NIM Database Backup on nimmast at Mon Jun 19 10:12:21 DFT 2006
4. Perform a mksysb of the NIM master and back up other volume groups.
   In our case, we saved a mksysb image to tape media and then performed a savevg of the NIM volume group (nimvg) to another tape media.

   ```
   {nimmast}:/# mksysb -i /dev/rmt0
   {nimmast}:/# savevg -f /dev/rmt0 nimvg
   ```

5. Install the bos.alt_disk_install filesets.
   These filesets are required so that we can use the `alt_disk_install` command to clone our rootvg before the migration; refer to Example 4-36.

   **Example 4-36 Installing the bos.alt_disk filesets**

   ```
   {nimmast}:/# smit nim_task_install
   Install and Update from ALL Available Software
   * Installation Target master
   * LPP_SOURCE lpp_sourceaix5204
   * Software to Install [bos.alt_disk_install]+
   ```

6. Un-mirror rootvg and clone to hdisk1 as shown in Example 4-37.
   In our case, we will use this rootvg clone if our migration fails and we need to go back to AIX 5L V5.2. If rootvg is mirrored, then you can later unmirror and use the spare disk for the alternate rootvg.

   If you are in a SAN environment, you can assign a LUN temporarily for the migration and use it as the alternate rootvg. The LUN could be returned some time after the migration is finished and you decide that you do not need to back out from the migration. The `-B` flag specifies that the bootlist will not be set to the alternate disk after the operation completes.

   However, make sure that your system can boot from a SAN-attached disk (LUN).

   **Example 4-37 Cloning rootvg with alt_disk_install**

   ```
   {nimmast}:/# unmirrorvg -c1 rootvg hdisk1
   {nimmast}:/# chpv -c hdisk1
   {nimmast}:/# lsvg -l hdisk1 ; migratepv hdisk1 hdisk0 (if required)
   {nimmast}:/# lsvg -p rootvg
   {nimmast}:/# bosboot -a -d /dev/hdisk0
   {nimmast}:/# bootlist -m normal hdisk0
   {nimmast}:/# bootlist -m normal -o
   ```
hdisk0
{nimmast}:/ # alt_disk_install -B -C hdisk1
Calling mkszfile to create new /image.data file.
Checking disk sizes.
Creating cloned rootvg volume group and associated logical volumes.
Creating logical volume alt_hd5.
Creating logical volume alt_hd6.
Creating logical volume alt_hd8.
Creating logical volume alt_hd4.
Creating logical volume alt_hd2.
Creating logical volume alt_hd9var.
Creating logical volume alt_hd3.
Creating logical volume alt_hd1.
Creating logical volume alt_hd10opt.
Creating /alt_inst/ file system.
Creating /alt_inst/home file system.
Creating /alt_inst/opt file system.
Creating /alt_inst/tmp file system.
Creating /alt_inst/var file system.
Generating a list of files
for backup and restore into the alternate file system...
Backing up the rootvg files and restoring them to the alternate file system...
Modifying ODM on cloned disk.
Building boot image on cloned disk.
forced unmount of /alt_inst/var
forced unmount of /alt_inst/usr
forced unmount of /alt_inst/tmp
forced unmount of /alt_inst/opt
forced unmount of /alt_inst/home
forced unmount of /alt_inst
forced unmount of /alt_inst
Changing logical volume names in volume group descriptor area.
Fixing LV control blocks...
Fixing file system superblocks...
{nimmast}:/ # lspv | grep root
hdisk0 00531d9a33ff6ab5         rootvg          active
hdisk1 00531d9a47ed2df6         altinst_rootvg  active

7. Commit all applied software before migrating; see Example 4-38.
   This will also create additional space in /usr (if there are any filesets in the
   applied state).

Example 4-38 Comitting all applied filesets

{nimmast}:/ # smit commit
* SOFTWARE name                                      [all] +
  PREVIEW only? (commit operation will NOT occur)     no +
  COMMIT requisites?                                 yes +
8. Ensure all users are logged off.

9. Perform migration installation of AIX 5L V5.3.

   We are now ready to execute the AIX migration. At this point in our case, we must go to the NIM master's console (via the HMC) and prepare to migrate via CD.

10. Insert AIX 5L V5.3 Installation CD Volume 1 into the CD drive.

11. Follow the procedure in the AIX installation and migration guide to migrate via media to AIX 5L V5.3

12. After the migration is finished, remove the AIX 5L V5.3 Installation Volume 1 CD from the CD-ROM drive.

13. Check the system configuration, for example, oslevel, disk, network, AIX error report, and so on.

14. Clean up old AIX 5.2 filesets. It may be necessary to remove old AIX 5.2 filesets after the migration.

15. Check the NIM environment.

   In our case, we perform some quick tests to verify the NIM environment after the migration. Using the `lsnim` command, we verify that the NIM database is intact. We check the state of the master and clients. We also validate some of our NIM resources.

   Check the NIM database:
   
   `{nimmast}`:/ # lsnim

   Check the status of the NIM master:
   
   `{nimmast}`:/ # lsnim -a Cstate -a Mstate master

   Check the status of a NIM client:
   
   `{nimmast}`:/ # lsnim -a Cstate -a Mstate LPAR4

   Validate the NIM resources:
   
   `{nimmast}`:/ # nim -o check LPP_52_ML8
   `{nimmast}`:/ # nim -o check SPOT_52_ML8

16. Build an AIX 5L V5.3 lpp_source and SPOT.

   You will need to insert the AIX 5L V5.3 install CD number 1 into the CD-ROM drive to build the lpp_source. After the lpp_source has been created, ensure that simages is set to yes, because this indicates whether or not it can be used for installations.
Also check for any errors, such as missing filesets when creating the SPOT. Refer to Example 4-39. For detailed information about creating an lpp_source and a SPOT, see 3.1, “Setting up a basic NIM environment” on page 53.

Example 4-39  AIX 5L V5.3 lpp_source and SPOT

{nimmast}:/ # lsnim -l LPP_53_ML4
LPP_53_ML4:
class = resources
type  = lpp_source
arch  = power
Rstate = ready for use
prev_state = verification is being performed
location = /AIX53ML4/LPP_53_ML4
simages = yes
alloc_count = 0
server = master

{nimmast}:/ # lsnim -l SPOT_53_ML4
SPOT_53_ML4:
class = resources
type = spot
plat_defined = chrp
arch = power
bos_license = yes
Rstate = ready for use
prev_state = verification is being performed
location = /AIX53ML4/SPOT_53_ML4/usr
version = 5
release = 3
mod = 0
oslevel_r = 5300-04
alloc_count = 1
server = master
if_supported = chrp.mp ent
Rstate_result = success

Validate the NIM resources:

{nimmast}:/ # nim -o check LPP_53_ML4
{nimmast}:/ # nim -o check SPOT_53_ML4

17. Using a test client (LPAR), perform a NIM BOS rte install of AIX 5L V5.3.

In our case, by performing a NIM BOS install onto our test client, we can confirm that our new AIX 5L V5.3 NIM master is functioning correctly.
18. Restore rootvg to a mirrored disk configuration.

In our case, now that our new NIM environment is functioning, we can remove the alternate rootvg disk and remirror rootvg, as shown in Example 4-40 on page 162.

Finally, reboot the system to turn off quorum for rootvg.

Example 4-40  Commands to remirror rootvg after alt_disk_install

{nimmast}:/ # alt_disk_install -X altinst_rootvg
{nimmast}:/ # extendvg rootvg hdisk1
{nimmast}:/ # mirrorvg rootvg hdisk1
{nimmast}:/ # bootlist -m normal hdisk0 hdisk1
{nimmast}:/ # bosboot -a -d /dev/hdisk0
{nimmast}:/ # bosboot -a -d /dev/hdisk1
{nimmast}:/ # shutdown -Fr

19. The NIM master is now running AIX 5L V5.3 and all NIM resources have been tested.

At this point, you are able to deploy AIX 5L V5.3 within your NIM environment.

**Backout plan for NIM master**

If there are issues with the NIM master migration, we can easily back out by rebooting the master from the alternate rootvg disk. The following procedure can be followed to boot from the cloned rootvg.

1. Set the bootlist to boot from original rootvg. First identify the alternate rootvg disk, as shown in Example 4-41.

Example 4-41  Identifying the alternate rootvg disk

{nimmast}:/ # lspv | grep altinst_rootvg
hdisk1 00531d9a47ed2df6 altinst_rootvg active

2. Verify that the bootlist is set to hdisk1, as shown in Example 4-42.

Example 4-42  Verifying the bootlist.

{nimmast}:/ # bootlist -m normal -o hdisk1

3. Reboot the server; see Example 4-43.

Example 4-43  Rebooting the system.

{nimmast}:/ # shutdown -Fr
Another way to perform the back out is to restore from the mksysb backup created prior to the migration. However, this will take more time, so the alternate disk method is the preferred way.

4. Verify the NIM environment as previously shown.

**Alternative NIM master migration approach**

An alternative migration option for a NIM master would be to build a new NIM master (at AIX 5L V5.3) on new hardware, and then migrate the NIM clients to the new master. If you have additional (newer) hardware, you could build a new AIX 5L V5.3 NIM master on this hardware and then move your existing clients to the new master at your convenience.

One advantage of this approach is that there is no downtime for the original NIM master. This is also a useful approach if your existing NIM master’s hardware does not support AIX 5L V5.3.

**4.4.2 Migrating a NIM client to AIX 5L V5.3**

In this section we discuss migrating a NIM client to AIX 5L V5.3. Topics include:

- Prerequisites
- Pre-migration tasks
- Migration via NIM
- Post Migration tasks
- Debugging a NIM migration

**Note:** In a NIM environment, as previously mentioned, the NIM master must be migrated to AIX 5L V5.3 before any of its clients. It must be running the highest operating system level. After the NIM master has been migrated, then the clients can follow.

We will discuss a conventional NIM migration which also utilizes a standard alternate disk install (that is, not nimadm) for backout.

The advantage of using NIM to migrate a client is that it does not require any installation media (such as a CD) to perform the migration. The migration is performed over the network. As a result, the administrator can perform and monitor the migration remotely and even automate the migration, if desired. Also, multiple migrations can occur simultaneously.

During a NIM migration, the system will be down for the duration of the upgrade. If downtime is an issue for your site, consider using the NIM alternate disk migration (nimadm) utility. This utility allows you to migrate on an alternate rootvg disk, and then reboot the system to restart it on the newer version of AIX,
all under the control of the NIM master. The migration can take place at your convenience and no downtime is required until the reboot is performed at an appropriate time. See 4.6, “NIM alternate disk migration” on page 261 for more detailed information about this topic.

If HACMP is used in your environment, then the downtime required can be minimized. You could execute a controlled failover of the system to a standby node first. Then you would be able to migrate the client without impacting the services that run on that system. After the migration was complete, you could execute a controlled fallback, restart your services, and then test them with AIX 5L V5.3. If there are any issues you could perform another controlled failover to the standby node (which would still be running AIX 5L V5.2). This would allow you to investigate the migration issues without impacting the applications on the system.

During the migration process, the client boots over the network from the NIM master (bootp/tftp). NFS mounts are then used to update the filesets on the client machine. The network-booted client runs in single user mode during the migration, and has only limited functionality to support the NIM migration process. As a result, client applications cannot be active during the migration.

If the migration process fails, you can either restore a mksysb backup of the client via NIM or reboot the client using the alternate rootvg disk created prior to the migration (which is our preferred method). After the restore or reboot is complete, you can try the migration again as soon as you have resolved the issues that caused the migration to fail.

We recommend that the following prerequisites be met before commencing a migration. Before migrating a client check the following:

- The NIM master must be running AIX 5L V5.3 with the latest Technology Level. See 3.1, “Setting up a basic NIM environment” on page 53 for more information.

- It is recommended (but not mandatory) that the client be running at the latest level of its current version of AIX. This way your client system will be running the latest code and will be able to take advantage of the latest features and enhancements for that version and level of AIX.

- Ensure you have enough disk space on the NIM master to back up the NIM client multiple times (for example, check space in /export/images). A mksysb backup of the NIM client will be taken before and after the migration, so there must be enough free space for the images.

- Check that your client hardware supports AIX 5L V5.3. More information about this topic can be found in the release notes for AIX 5L V5.3.
- Check that your applications are supported with AIX 5L V5.3. Use cloning if you want to test an application before performing the real migration. It may be worth putting together an application matrix for all your systems and contacting each vendor to ensure support for AIX 5L V5.3.

- Perform at least one test migration of the system before performing the real migration. This will verify that the AIX migration works as expected and will also highlight any issues before they occur during a live production upgrade. Clone the client to another test LPAR via NIM. Install the client’s mksysb but do not recover its devices (this will avoid IP address conflicts on your network). After the mksysb is restored, you can migrate it to AIX 5L V5.3 and observe and document the results.

**Note:** Make sure that you test the backout plan, as well.

- Ensure that you have all the latest software levels for disk and other storage devices such as SDD, SDDPCM, and so on. Check that you have the correct version for AIX 5L V5.3 (for example, SDD for AIX 5L V5.3).

- It is always useful to upgrade your system and adapter firmware to the latest level of microcode before performing an AIX migration. Some systems or adapters may not be supported or will not function with AIX 5L V5.3 if their microcode is not up-to-date.

  In particular, check the levels of your Fibre Channel (if using SAN disk) and Network adapters (especially when using NIM). Check the IBM support Web site for the latest levels of system and adapter microcode and apply them before upgrading.


- Check the code level on your HMC (if applicable). Often there will be corresponding code levels when you upgrade the managed system microcode. There may even be important fixes to support AIX 5L V5.3 and the latest Technology Level.

- The system to be migrated must be a valid NIM client. It must be registered with the NIM database and should have a valid /etc/niminfo file. You can use `niminit` to register the client if it is not already defined. Also check the current state and resource allocation for the client. Reset the client so it is in a clean state prior to the migration; refer to “Defining NIM clients” on page 79.

- The NIM master must be able to run remote commands on the NIM client to be migrated.

- Read the AIX 5L V5.3 release notes, which contain important information that you should know before starting a migration.
Install the bos.alt_disk_install filesets on the client if you plan on using alt_disk_install tools with the conventional NIM migration.

This is the basic process of a NIM client AIX migration:

- The client boots over the network.
- It mounts the files required for the migration from the NIM master.
- A menu will appear entitled Migration preparation menu. This confirms that you are doing a migration and not an overwrite installation.
- After the installation is underway, the BOS Installation Menu appears which displays the progress and status of the migration. At this point your old operating system is removed and replaced with the new version. Therefore, if there any problems with the migration, a restore of some kind will be required. This is why you must take a backup (or backups) of your system before starting the migration.
- File system allocation and a list of filesets to be updated is displayed next. Much of this information is also recorded on the client in the /var/adm/ras log files such as devinst.log.
- When the message: Over mounting ./ appears, it means that the migration is finished and the RAM file system is overmounted by the now-migrated root (/) file system. Final migration activities are performed, such as creating a new boot image and setting the client bootlist. The status of the migration can be monitored using the lsnim -a info clientname command.
- The NIM master is also informed of the successful migration and resets the NIM client's state (to ensure that the client does not boot from the network again by accident).
- The final step in the NIM migration process will be a reboot of the client. After the reboot is finished, your system will be up and running on AIX 5L V5.3. At this point, you should start your post-migration tasks.

Troubleshooting a NIM migration
This section describes troubleshooting steps to follow during a NIM migration, if needed.

- If the migration fails for some reason, you will probably experience a “system hang” or see an error appear in the BOS install output. You will probably need to reset the system so that you can recover.

As a result, the state of the NIM client will not be reset by the NIM master, because it never receives any indication that the migration was complete. It will be necessary to reset the NIM client in order to perform NIM operations on it in the future.
The reset of the NIM client will ensure that the state of client is cleared and that all NIM resources are deallocated. The reset can be done via SMIT or via the command line (examples are provided on the following pages).

When the client has been reset, you will be able to perform operations with it again such as retrying the migration after the reason for the failure has been resolved.

- The following log files contain useful information when troubleshooting a migration. These log files can also be view from the NIM master via the `nim showlog` operation:

  - `/var/adm/ras/conslog` - Console output log.
  - `/var/adm/ras/bootlog` - System boot log.
  - `/var/adm/ras/bosinstlog` - BOS installation log.
  - `/var/adm/ras/nim.script` - NIM script output.
  - `/var/adm/ras/nim.installp` - NIM filesets install log.
  - `/var/adm/ras/devinst.log` - Software installation log.

  ```bash
  # nim -o showlog -a log_type=bosinst LPAR4
  # nim -o showlog -a log_type=niminst LPAR4
  # nim -o showlog -a log_type=script LPAR4
  ```

- If you experience issues during a client network boot, you can try the following to troubleshoot the problem:
  - Verify that the client’s IP details in SMS are correct. Perform a manual ping test from the SMS menus.
  - Check that the adapter speed is correct. Depending on the type of adapter, it may be necessary to set the speed and duplex setting of the adapter (although some newer GB adapters are better set to auto). Incorrect speed and duplex settings can cause hard-to-find issues, in that the ping test will work but the NIM process will be very slow and may even stop half-way through what appears to be an otherwise successful install (usually during the restore base operating system stage).
  - As previously mentioned, also check the microcode levels of the network adapters to avoid any possible issues when booting over the network.

- If the migration hangs, check whether any of the following situations exist and also if any LED code is displayed that might correspond to the problem.

  - Are the file systems properly exported (NFS) on the NIM master?
  - Can the client access the file systems of the NIM master via NFS?

Refer to Chapter 7, “Basic NIM problem determination and tuning” on page 565, for more information about problem determination in a NIM environment.
4.4.3 NIM client AIX migration example

In this section, we provide an example of migrating a system running AIX 5L V5.2 on a System p670 to AIX 5L V5.3. Our NIM master is a System p615 running AIX 5L V5.3. Both are connected via Ethernet on the same VLAN. Our conventional NIM migration method will require the client to be down during the migration process, but it also employs an *alt_disk_install* (alternate disk install) procedure which will be used as a quick backout if the migration fails.

Although this method requires the most downtime when compared to NIM alternate disk migration, it is considered the most straightforward method, which involves the least amount of effort for the administrator (if planned and tested properly). Unlike nimadm migration, it also allows for TCB support (see 4.6, “NIM alternate disk migration” on page 261 for more information about nimadm TCB support).

Although our test environment uses SCSI disk, we also include tips for SAN disk environments, where appropriate.

Before starting the migration, check that the following prerequisites are met:

- NIM master already migrated to AIX 5L V5.3.
- System and adapter microcode already upgraded.

Planning for NIM client migration involves the following tasks:

- Reading the AIX 5L V5.3 release notes and checking that our applications are supported.
- Writing a plan of all the tasks (including command line) to be performed during the migration:
  - Ensuring that a backout plan exists.
  - Testing the backout plan on the test clone.
  - Making the backout plan usable by someone else in your team so that another person can execute the plan if you are unable to do so. This plan can be reused as a template for future migrations.
  - Asking a peer to review the document.
  - Documenting all known issues and any fixes required.
  - Briefly explaining what the process will be to migrate (for example, the basic flow of major events: upgrade AIX; post migration tasks; application testing; backout plan if required).
- Explaining what will be upgraded (for example, AIX, HACMP, SDD, and so on) and why it will be upgraded.
Cloning the system to be migrated onto a “test” LPAR and performing the migration.

This will allow you to review your plan and verify that the AIX migration will work. Resolve and document any issues you might encounter during the “real” migration on the production system. If required, clone the entire system (that is, rootvg, datavg, all applications, not just a mksysb restore) and perform application verification testing. Even test newer software like SDD or SDDPCM for AIX 5L V5.3. Test your backout plan on the test clone.

Determining what other software you need to upgrade

This includes newer (or correct) version of SDD, SDDPCM, Isot, nmon, SSH, SSL, rpm, HACMP, ibm2105, device filesets, and so on. It also includes all the necessary fixes to support software on AIX 5L V5.3. For example, HACMP 5.2 requires some APARs to support AIX 5L V5.3. Ask your storage administrator to ensure that the LIC level on the storage device you are running supports AIX 5L V5.3 and the newer versions of SDD or SDDPCM.

The following pre-migration tasks also need to be completed:

- Documenting the systems configuration (for example, hardware, AIX, and so on).
  - Use snap or a custom script. This is important if you run into issues and need to recover or rebuild your system.
- Running the AIX 5L V5.3 pre_migration script and reviewing the output to verify that the system is ready for a migration.
- Checking that there is sufficient disk space for the file systems in rootvg plus some free PPs (500 MB) for file system expansion if required.
- Running the blvset tool to check the AIX version label for all the disks in rootvg. Correct if necessary.
- Checking the status of the system.
  - Also look for hardware errors or other errors in the AIX error report.

**Performing the migration**

After the prerequisites have been met, the planning is complete and the pre-migration tasks have been executed successfully, the migration of the NIM client can be performed. The following steps can be used as a template for any migration plan required in the future:

1. Run the AIX 5L V5.3 pre_migration script.
   - The pre_migration script will save its output to /home file system (ensure there is sufficient space in /home). The pre_migration script can be found in the AIX 5L V5.3 SPOT on the NIM master (for example,
We will copy the script to our NIM client for execution. We also recommend that you confirm that the AIX level for all disks in rootvg is correct prior to the migration. You can use the `blvset` command to perform this task, as shown in Example 4-44.

**Example 4-44  Output from the pre_migration script and blvset tool**

```
# rcp nimmast:/AIX53ML4/SPOT_53_ML4/usr/lpp/bos/pre_migration /tmp
# chfs -a size=+1 /home
# /tmp/pre_migration

All saved information can be found in: /home/pre_migration.060309123949

Checking size of boot logical volume (hd5).

Your rootvg has mirrored logical volumes (copies greater than 1)
Recommendation: Break existing mirrors before migrating.

Listing software that will be removed from the system.

Listing configuration files that will not be merged.

Listing configuration files that will be merged.

Saving configuration files that will be merged.

Running lppchk commands. This may take awhile.

Please check /home/pre_migration.060309123949/software_file_existence_check for possible errors.

Please check /home/pre_migration.060309123949/software_checksum_verification for possible errors.

Please check /home/pre_migration.060309123949/tcbck.output for possible errors.

All saved information can be found in: /home/pre_migration.060309123949

It is recommended that you create a bootable system backup of your system before migrating.

; Run the blvset command.
; e.g. /usr/lpp/bosinst/blvset -d /dev/hdisk# -glevel  <!--should show 5.2

# /usr/lpp/bosinst/blvset -d /dev/hdisk0 -glevel 5.2
# /usr/lpp/bosinst/blvset -d /dev/hdisk1 -glevel
```
5.2

; If you do not get 5.2 from the above then run the following command on all rootvg disks.:

```
# /usr/lpp/bosinst/blvset -d /dev/hdisk# -plevel  <--enter 5.2 when prompted.
```

2. Check that there is enough disk space to meet the minimum requirements for the file systems in rootvg.

Expand file systems if required. Lack of disk space in rootvg file systems is a common cause of migration failure. The AIX 5L V5.3 release notes contain the latest information regarding requirements for disk space. Ensure you have some free physical partitions (PPs) in rootvg in case file system expansion is required during the migration; see Example 4-45.

**Example 4-45  Check free disk space requirements in rootvg file systems**

```plaintext
; Free space required for rootvg file systems.
/  16 MB
/usr 1256MB;
/var 128 MB;
/tmp 128 MB;
/opt 140 MB;
; Use df command to check free space.
# df -m
; Use lsvg command to check free PP's in rootvg.
# lsvg rootvg | grep FREE
```

3. Document the configuration of the server.

You can use the snap command (for example, snap -ac) or a custom script to collect important information about your AIX system. We use a custom script, AIXinfo, which is available in Appendix D, “Additional material” on page 643, to collect information about our system.

Regardless of the tool used, ensure that the information is stored on a system other than the system to be migrated, because it is probable that the time you need to call on this information will be the time when the client is down and you are trying to recover it. The system configuration information will not be obtainable if the system is not running.

What follows is some of the system configuration information you would collect and document before the migration.

Review `/etc/tunables/nextboot` file, as shown in Example 4-46.

**Example 4-46  Review and document `/etc/tunables`**

```plaintext
# cat /etc/tunables/nextboot
# IBM_PROLOG_BEGIN_TAG
```
Collect disk and volume group information as shown in Example 4-47. Capture this information to a file on another system for future reference.

**Example 4-47   Collect disk and volume group information**

```bash
# lsvg
# lsvg -o
# lspv
# lsvgcfg ; Optional. Only for SDD systems.
# lscfg -vpl hdisk0 ; Do this for each boot disk.
# bootinfo -b ; Determine which disk we booted off.
# hdisk0
```

Collect IP configuration information as shown in Example 4-48. Capture this information to a file on another system for future reference.
Example 4-48  Collecting network and IP information

```bash
# hostname
# host LPAR4
# ifconfig en0
# lscfg -vpl ent0 | grep Loc
# ifconfig -a
# netstat -nr
# entstat -d entX
```

Run `snap` or a script (in our case, AIXinfo) to capture information about the system as shown in Example 4-49.

Example 4-49  Using snap and a script to document the system

```bash
# snap -ac
# AIXinfo -pre
```

Check the AIX error report. If everything looks fine, then it is desirable to clear the error report and SMIT logs before the migration to avoid confusion; see Example 4-50.

Example 4-50  AIX error report status and SMIT log cleanup

```bash
# errpt
# errpt -a
# mkdir /tmp/errptlogs
# errpt > /tmp/errptlogs/errpt.out
# errpt -a >> /tmp/errptlogs/errpt.out
# errclear 0
# mkdir /tmp/smitlogs
# cd /
# cp smit.* /tmp/smitlogs/
# >smit.log
# >smit.script
# >smit.transaction
```

4. Create a mksysb backup of the system, as shown in Example 4-51 on page 174.

   How you do this depends on your environment. Client mksysb backups may be initiated from the NIM master or from the client via a script. In our environment we used a script which runs on the client to create a mksysb backup on the NIM master. Refer to 4.11, “Backing up clients with NIM” on page 348 for more information.

   Data in other volume groups also needs to be backed up with savevg or other backup tools such as Tivoli Storage Manager (TSM). We recommend using a script to back up just the structure of the volume group (savevg with all files excluded), and then using TSM to back up the data.
To recover the data volume group would then only require a recreation of the volume group structure (that is, restvg to recreate logical volumes and file systems), and then a complete restore of the data from TSM. We use a custom script in our example to back up the volume group structure; see the sysbtonim and skelvg scripts in Appendix D, “Additional material” on page 643.

Example 4-51  Creating a mksysb backup of the server before the migration

```bash
# /usr/local/bin/skelvg >> /var/log/skelvg.log 2>&1
# /usr/local/bin/sysbtonim >> /var/log/sysbtonim.log 2>&1
```

5. Install the bos.alt_disk_install filesets.

These filesets are required in order to clone the root volume group. We install the filesets on the client via NIM, as shown in Example 4-52.

Example 4-52  Installing the bos.alt* filesets via NIM

```bash
# smit nim_task_inst
```

6. Disable system monitoring.

If you have any monitoring software within your environment, remember to disable it or schedule downtime for the system. Otherwise, you may receive unwanted alerts while the system is down during the migration process.

7. Backup the /etc/motd and /etc/sendmail.cf files as shown in Example 4-53.

These files are replaced during the migration and you will lose any custom configuration in these files. Back them up to another directory on the system for easy recovery and reference, and also back them up with the backup tools within your environment. For example, the /home directory is not removed during a migration, so create a directory in /home and copy the files to that location.

Example 4-53  Backing up sendmail and other configuration files

```bash
# mkdir /home/premig
# cp -p /etc/motd /home/premig/
# cp -p /etc/sendmail.cf /home/premig/
```

8. Stop any applications running on the system.
9. Disable cron as shown in Example 4-54, to avoid the (unlikely) possibility of a cron job running and causing issues or changing data or trying to access applications that are down just prior to migrating the system.

**Example 4-54   Disabling cron before the migration**

```
# chitab "cron:23456789:off:/usr/sbin/cron"
# telinit q
```

10. Commit applied software.

Remove any efixes on the system first as shown in Example 4-55.

**Example 4-55   Commit applied software and check for efixes**

```
# emgr -P
# emgr -r -L fixid
# smit commit
```

11. In preparation for the cloning of rootvg, we first unmirror rootvg so that we can use one of the disks for the alt_disk_install operation, as shown in Example 4-56.

**Example 4-56   Unmirror rootvg**

```
# bootinfo -b
hdisk0
# unmirrorvg -c1 rootvg hdisk1
# chpv -c hdisk1
# lspv -l hdisk1 ; migratepv hdisk1 hdisk0 (if required).
# lspv -l hdisk1 ; disk should be empty now.
# reducevg rootvg hdisk1
# lsvg -p rootvg
rootvg:
PV_NAME      PV STATE  TOTAL PPs FREE PPs FREE DISTRIBUTION
hdisk0 active 521 390 104..17..61..104..104
# bosboot -a -d /dev/hdisk0
# bootlist -m normal hdisk0
# bootlist -m normal -o
hdisk0
```

12. Clone rootvg to hdisk1.

This alternate rootvg disk could be used if we need to back out our migration and go back to AIX 5L V5.2. The -B flag prevents the bootlist from being set after the alternate disk creation is finished, as shown in Example 4-57.

**Example 4-57   Cloning rootvg with alt_disk_install**

```
# alt_disk_install -B -C hdisk1
Calling mkszfile to create new /image.data file.
```
Checking disk sizes.
Creating cloned rootvg volume group and associated logical volumes.
Creating logical volume alt_hd5.
Creating logical volume alt_hd6.
Creating logical volume alt_hd8.
Creating logical volume alt_hd4.
Creating logical volume alt_hd2.
Creating logical volume alt_hd9var.
Creating logical volume alt_hd3.
Creating logical volume alt_hd1.
Creating logical volume alt_hd10opt.
Creating /alt_inst/ file system.
Creating /alt_inst/home file system.
Creating /alt_inst/opt file system.
Creating /alt_inst/tmp file system.
Creating /alt_inst/usr file system.
Creating /alt_inst/var file system.
Generating a list of files
for backup and restore into the alternate file system...
Backing-up the rootvg files and restoring them to the alternate file system...
Modifying ODM on cloned disk.
Building boot image on cloned disk.
forced unmount of /alt_inst/var
forced unmount of /alt_inst/usr
forced unmount of /alt_inst/tmp
forced unmount of /alt_inst/opt
forced unmount of /alt_inst/home
forced unmount of /alt_inst
forced unmount of /alt_inst
Changing logical volume names in volume group descriptor area.
Fixing LV control blocks...
Fixing file system superblocks...

# lspv | grep root
hdisk0 00531d9a33ff6ab5         rootvg          active
hdisk1 00531d9a47ed2df6         altinst_rootvg  active

13. Ensure all users are logged off and prevent new user logon, as shown in Example 4-58.

Example 4-58   Checking for active user sessions and preventing new logon

# w
# touch /etc/nologin

14. Set up the NIM environment for the upgrade of the NIM client.

We reset the NIM client to ensure that it is in a clean state before attempting the migration. We run a custom script (see Example 4-59 on page 177) to
reset the NIM client. The script does a force reset, deallocates resources, and clears the client’s CPU ID.

If a failure occurs during a NIM migration/installation with the message code: 0042-008 NIM has attempted to establish socket communications with a remote machine, and it has refused the connection, it means that the CPU ID attribute on the client’s machine definition may be obsolete (for example, if the machine’s system planar was recently replaced or the client definition was recently used for a NIM installation on a different system). To guarantee that this is not the case, erase the CPU ID from the machine definition.

**Notes:**
- The CPU ID of a NIM client is stored in the NIM database so that the master can perform verification that NIM client commands are coming from the machines that were originally registered as clients. A NIM administrator would not want this CPU ID validation to be performed in the following situations:
  - When the hardware of a client machine is changed, giving the client a new CPU ID
  - When a single client definition is used to install different machines, as on a preinstall assembly line

To disable client CPU ID validation, set the attribute `validate_cpuid=no` on the NIM master:

```
# nim -o change -a validate_cpuid=no master
```

- However, the value of the `validate_cpuid` attribute should not be changed while operations are being performed on NIM clients, because this could potentially disrupt client communications for active machines.

**Example 4-59  Reset the NIM client before the migration**

```
{nimmast}:~ # cat /work/nim_scripts/resetnimclient
#!/usr/bin/ksh
# Reset a NIM client.

if [[ "$1" = "" ]] ; then
  echo Please specify a NIM client to reset e.g. LPAR4.
else
  if /usr/sbin/lsnim -l $1 > /dev/null 2>&1 ; then
    /usr/sbin/nim -o reset -F $1
    /usr/sbin/nim -Fo deallocate -a subclass=all $1
    /usr/sbin/nim -Fo change -a cpuid= $1
  fi
```

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else
  echo Not a valid NIM client!
fi
fi

{nimmast}:/# /work/nim_scripts/resetnimclient LPAR4

Then we enabled a BOS installation for NIM client LPAR4 using our AIX 5L V5.3 lpp_source and SPOT. We also chose not to initiate reboot of the client now; see Example 4-60.

Example 4-60  Installing the client

{nimmast}:/# smitty nim_bosinst
Install the Base Operating System on Standalone Clients

* Installation Target       LPAR4
* Installation TYPE         rte
* SPOT                      SPOT_53_ML4
  LPP_SOURCE                [LPP_53_ML4]

ACCEPT new license agreements? [yes]
this target? [no]

Initiate reboot and installation now? [no]

We verify that the NIM resources are now setup to migrate the NIM client. We check the status of the NIM client using lsnim, ensure that the AIX 5L V5.3 lpp_source and SPOT have been allocated, confirm that the client's Cstate attribute is set to: B0S installation has been enabled, review the files in /tftpboot, and check the entry in /etc/bootptab is correct. We execute a script (chknim) to show the current status of the NIM client, as shown in Example 4-61 and Example 4-62 on page 179.

Example 4-61  Verifying the NIM client is set up to migrate - current status

{nimmast}:#/usr/local/bin # chknim LPAR4
/tftpboot files.
total 79680
-rw-r--r--  1 root system  8162755 Jun 02 10:37
  spotaix5104.chrp.mp.ent
-rw-r--r--  1 root system  8720910 Jun 02 11:49
  spotaix5204.chrp.mp.ent
-rw-r--r--  1 root system 11688960 Jun 12 11:13 SPOT-V10.chrp.mp.ent
-rw-r--r--  1 root system 12211712 Jun 13 13:13
  SPOT_53_ML4.chrp.mp.ent
-rw-r--r--  1 root system   934 Jun 15 12:10 lpar4.info
lrwxrwxrwx 1 root system 33 Jun 15 12:10 lpar4 ->
/tftpboot/SPOT_53_ML4.chrp.mp.ent

/etc/bootptab entries:
#     bs   -- boot image size
#     dt   -- old style boot switch
#    T170 -- (xstation only) -- server port number
#    T175 -- (xstation only) -- primary / secondary boot host indicator
#    T176 -- (xstation only) -- enable tablet
#    T177 -- (xstation only) -- xstation 130 hard file usage
#    T178 -- (xstation only) -- enable XDMCP
#    T179 -- (xstation only) -- XDMCP host
#    T180 -- (xstation only) -- enable virtual screen

lpar4:bf=/tftpboot/lpar4:ip=10.1.1.68:ht=ethernet:sa=10.1.1.1:sm=255.255.255.0:

nim client info:

LPAR4:
  class          = machines
  type           = standalone
  connect        = shell
  platform       = chrp
  netboot_kernel = mp
if1              = NET_EN1 lpar4 0
  cable_type1    = tp
  Cstate         = BOS installation has been enabled
  prev_state     = ready for a NIM operation
  Mstate         = currently running
  boot           = boot
  lpp_source     = LPP_53_ML4
  nim_script     = nim_script
  spot           = SPOT_53_ML4
  cpuid          = 001A85D24C00
  control        = master
  current_master = nimmast
  sync_required  = yes

Example 4-62 shows the chknim script.

Example 4-62  chknim script

  echo " /tftpboot files."
  ls -ltr /tftpboot/
  echo
  echo " /etc/bootptab entries:"
  tail /etc/bootptab
  echo
  if [[ "$1" != "" ]]
    then
      echo "NIM client info:"
1. snim -l $1
2. fi

15. Performing the AIX migration

At this point, we are ready to start the AIX migration for the client. We connect
to our HMC and open a console window for LPAR4. We configure our client
(via the SMS menus) to boot from the network.

We login as root via the console and reboot the system as shown in
Example 4-63.

**Note:** We recommend rebooting the system and checking that it
restarts successfully before the migration. This may uncover any issues
that already exist on the system but would be blamed on the migration.

*Example 4-63  Reboot the system*

```
# shutdown -Fr
```

- Press the 1 key to enter the SMS menu, as shown in Example 4-64. Once
  within the SMS menu, we can configure the clients IP details via the Remote
  Initial Program Load (IPL) setup menu.

*Example 4-64  SMS menu*

```
1 = SMS Menu                          5 = Default Boot List
6 = Stored Boot List                  8 = Open Firmware Prompt

memory      keyboard     network     scsi     speaker
```

- Select 4. Setup Remote IPL (Initial Program Load); see Example 4-65.

*Example 4-65  Setup Remote IPL*

```
pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000,2003 All rights reserved.

Main Menu
1. Select Language
2. Password Utilities NOT available in LPAR mode
3. View Error Log
4. **Setup Remote IPL (Initial Program Load)**
5. Change SCSI Settings
6. Select Console NOT available in LPAR mode
```
7. Select Boot Options

Navigation Keys:
X = eXit System Management Services

Type the number of the menu item and press Enter or select Navigation Key:

- Select the network adapter to configure; see Example 4-66.

Example 4-66  NIC selection

pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000, 2003 All rights reserved.

NIC Adapters
Device                            Slot          Hardware Address
1.  10/100 Mbps Ethernet PCI Adapt      2:U1.5-P2-I2/E1         000255afcdf7

Navigation keys:
M = return to Main Menu
ESC key = return to previous screen    X = eXit System Management Services

Type the number of the menu item and press Enter or select Navigation Key:

- Select 1. IP Parameters; see Example 4-67.

Example 4-67  IP Parameters menu

pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000, 2003 All rights reserved.

Network Parameters
10/100 Mbps Ethernet PCI Adapter II: U1.5-P2-I2/E1
1.  IP Parameters
2.  Adapter Configuration
3.  Ping Test

Navigation keys:
M = return to Main Menu
ESC key = return to previous screen    X = eXit System Management Services

Type the number of the menu item and press Enter or select Navigation Key:

- Enter the client, server and gateway IP address and the subnet mask; see Example 4-68.
Example 4-68  Configuring IP parameters

<table>
<thead>
<tr>
<th>IP Parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Client IP Address</td>
</tr>
<tr>
<td>2. Server IP Address</td>
</tr>
<tr>
<td>3. Gateway IP Address</td>
</tr>
<tr>
<td>4. Subnet Mask</td>
</tr>
</tbody>
</table>

Navigation keys:
M = return to Main Menu
ESC key = return to previous screen  X = eXit System Management Services

Type the number of the menu item and press Enter or select Navigation Key:

- Execute a Ping Test to ensure that the client can communicate with the NIM master; see Example 4-69.

Example 4-69  Selecting Ping Test menu

<table>
<thead>
<tr>
<th>Ping Test</th>
</tr>
</thead>
<tbody>
<tr>
<td>Speed, Duplex: 100, full</td>
</tr>
<tr>
<td>Client IP Address: 10.1.1.68</td>
</tr>
<tr>
<td>Server IP Address: 10.1.1.1</td>
</tr>
<tr>
<td>Gateway IP Address: 000.000.000.000</td>
</tr>
<tr>
<td>Subnet Mask IP Address: 255.255.255.000</td>
</tr>
<tr>
<td>Protocol: Standard</td>
</tr>
<tr>
<td>Spanning Tree Enabled: No</td>
</tr>
<tr>
<td>Connector Type: rj45</td>
</tr>
</tbody>
</table>

1. Execute Ping Test

Navigation keys:
M = return to Main Menu
ESC key = return to previous screen  X = eXit System Management Services

Type the number of the menu item and press Enter or select Navigation Key:

The Ping Test results are shown in Example 4-70 on page 183.
Example 4-70  Successful Ping Test output

```
| Attempting Ping... |
---------------------
PING: chosen-network-type = ethernet,100,rj45,full
PING: client    IP = 10.1.1.68
PING: server    IP = 10.1.1.1
PING: gateway   IP = 0.0.0.0
PING: device    /pci@3fffbe09000/pci@b,2/ethernet01
PING: loc-code  U1.5-P2-I2/E1

PING: Ready to ping:
PING: source hardware address is 0 2 55 af cd f7
PING: destination hardware address is 0 9 6b 2e 26 1d
PING: source IP address is 10.1.1.68
PING: destination IP address is 10.1.1.1

| Ping Success. |
----------------
```

Press any key to continue.......

▶ Exit back (use Esc) to the Main Menu; see Example 4-71.

Example 4-71  Back to SMS Main Menu

```
pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000,2003 All rights reserved.
-------------------------------------------------------------------------------
Main Menu
  1.  Select Language
  2.  Password Utilities NOT available in LPAR mode
  3.  View Error Log
  4.  Setup Remote IPL (Initial Program Load)
  5.  Change SCSI Settings
  6.  Select Console NOT available in LPAR mode
  7.  Select Boot Options
-------------------------------------------------------------------------------
Navigation Keys:
          X = eXit System Management Services
-------------------------------------------------------------------------------
Type the number of the menu item and press Enter or select Navigation Key:
```
Select 7. **Select Boot Options**; see Example 4-72.

**Example 4-72  Boot Options**

pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000,2003 All rights reserved.
-----------------------------------------------------------------------------------
Main Menu
1. Select Language
2. Password Utilities NOT available in LPAR mode
3. View Error Log
4. Setup Remote IPL (Initial Program Load)
5. Change SCSI Settings
6. Select Console NOT available in LPAR mode
7. Select Boot Options
-----------------------------------------------------------------------------------
Navigation Keys:
X = eXit System Management Services
-----------------------------------------------------------------------------------
Type the number of the menu item and press Enter or select Navigation Key:

Select 1. **Select Install or Boot Device**; see Example 4-73.

**Example 4-73  Boot Device selection**

pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000,2003 All rights reserved.
-------------------------------------------------------------------------------
1. Select Install or Boot Device
2. Configure Boot Device Order
3. Multiboot Startup <OFF>
-------------------------------------------------------------------------------
Navigation keys:
M = return to Main Menu
ESC key = return to previous screen       X = eXit System Management Services
-------------------------------------------------------------------------------
Type the number of the menu item and press Enter or select Navigation Key:

Select 6. **Network**; see Example 4-74.

**Example 4-74  Network boot selection**

pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000,2003 All rights reserved.
Select Device Type
1. Diskette
2. Tape
3. CD/DVD
4. IDE
5. Hard Drive
6. Network
7. List all Devices

-------------------------------------------------------------------------------
Navigation keys:
M = return to Main Menu
ESC key = return to previous screen X = eXit System Management Services
-------------------------------------------------------------------------------
Type the number of the menu item and press Enter or select Navigation Key:

► Select the network adapter to boot from; see Example 4-75.

Example 4-75  Ethernet device selection

pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000,2003 All rights reserved.

Select Device
Device Current Device
Number Position Name
1. 1 Ethernet ( loc=2:U1.5-P2-I2/E1 )

-------------------------------------------------------------------------------
Navigation keys:
M = return to Main Menu
ESC key = return to previous screen X = eXit System Management Services
-------------------------------------------------------------------------------
Type the number of the menu item and press Enter or select Navigation Key:

► Select 2. Normal Mode Boot; see Example 4-76.

Example 4-76  Selecting Boot Mode

pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000,2003 All rights reserved.

Select Task

Ethernet ( loc=2:U1.5-P2-I2/E1 )

1. Information
2. Normal Mode Boot
3. Service Mode Boot

Navigation keys:
M = return to Main Menu
ESC key = return to previous screen         X = eXit System Management Services

Type the number of the menu item and press Enter or select Navigation Key:

▶ Select 1. Yes; see Example 4-77.

Example 4-77 Accepting boot parameters

pSeries Firmware
Version RG050215_d79e02_regatta
SMS 1.3 (c) Copyright IBM Corp. 2000,2003 All rights reserved.

Are you sure you want to exit System Management Services?
1. Yes
2. No

Navigation Keys:
X = eXit System Management Services

Type the number of the menu item and press Enter or select Navigation Key:

▶ The system will now perform a network boot as shown in Example 4-78.

Example 4-78 System network boot

STARTING SOFTWARE
PLEASE WAIT...

BOOTP: chosen-network-type = ethernet,100,rj45,full
BOOTP: server   IP        = 10.1.1.1
BOOTP: requested filename =
BOOTP: client   IP        = 10.1.1.14
BOOTP: client   HW addr   = 0 2 55 af cd f7
BOOTP: gateway  IP        = 0.0.0.0
BOOTP: device   /pci@3fffbe09000/pci@b,2/ethernet01
BOOTP: loc-code  U1.5-P2-I2/E1
BOOTP: Cancel = ctl-C
BOOTP R = 1 BOOTP S = 1

FILE: /tftpboot/1par4
Load Addr=0x4000 Max Size=0xffffc000
FINAL Packet Count = 17034 FINAL File Size = 8720910 bytes.

Elapsed time since release of system processors: 345447 mins 24 secs

Welcome to AIX.
boot image timestamp: 09:49 06/02
The current time and date: 12:13:35 06/15/2006
number of processors: 2    size of memory: 1024Mb
boot device:
pci03fffbe09000/pci0b,2/ethernet01:speed=100,duplex=full,bootp,10.1.1.1,,10.1.1.14,10.1.1.1
closing stdin and stdout...

Tip: You also can force the system to boot from the network during next reboot with the following command:

```bash
# bootlist -m normal en0 bserver=10.1.1.1 gateway=10.1.1.1 \ 
  client=10.1.1.68
# shutdown -Fr
```

This will boot the system from the network via en0. If there are issues with the network boot, you will need to go into the SMS menus and perform a ping test to troubleshoot the problem.

- You will be prompted to define the system console for the migration as shown in Example 4-79. Type 1 and press Enter.

**Example 4-79 Defining the system console**

******** Please define the System Console. *******

Type a 1 and press Enter to use this terminal as the system console.
Pour definir ce terminal comme console systeme, appuyez sur 1 puis sur Entree.
Taste 1 und anschliessend die Eingabetaste druecken, um diese Datenstation als Systemkonsole zu verwenden.
Premere il tasto 1 ed Invio per usare questo terminal come console.
Escriba 1 y pulse Intro para utilizar esta terminal como consola del sistema.
Escriviu 1 1 i premeu Intro per utilitzar aquest terminal com a consola del sistema.
Digite um 1 e pressione Enter para utilizar este terminal como console do sistema.
1 Type 1 and press Enter to have English during install.

88 Help ?

Choice [1]:

- The menu Welcome to Base Operation System Installation and Maintenance will appear next, as shown in Example 4-80. Select 2 Change/Show Installation Settings and Install.

Example 4-80  BOS install welcome menu

Welcome to Base Operating System Installation and Maintenance

Type the number of your choice and press Enter. Choice is indicated by >>>.

>>> 1 Start Install Now with Default Settings

2 Change/Show Installation Settings and Install

3 Start Maintenance Mode for System Recovery

88 Help ?

99 Previous Menu

Choice [2]:

- The installation and settings menu appears as shown in Example 4-82 on page 189. Ensure that the Method of Installation is Migration. Check that the correct disk will be used for the migration.

For systems that boot from SAN (for example, rootvg resides on SAN disk), the hdisk numbers may not reflect the numbers recorded prior to the migration. To confirm that the correct disk is being selected for migration, confirm the LUN ID of the rootvg disk is correct.

Perform this by exiting from the Migration menu and selecting the menu New and Complete Overwrite. Then select the disks to install onto and select 77 Display Alternative Disk Attributes. This will give you the LUN ID, which you can then match against the lscfg output you captured earlier.

After confirming that the LUN ID to hdisk mapping is correct, re-enter the migration menu and continue with the migration; refer to Example 4-81 on page 189.
Example 4-81  Alternative disk attributes for LUN IDs

<table>
<thead>
<tr>
<th>Name</th>
<th>Device Adapter Connection Location or Physical Location Code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>hdisk0 ...-W500507630303427E-L40184000000000000000</td>
</tr>
<tr>
<td>2</td>
<td>hdisk4 ...-W500507630308427E-L400E4000000000000000</td>
</tr>
<tr>
<td>3</td>
<td>hdisk1 ...-W500507630303427E-L40074003000000000000</td>
</tr>
</tbody>
</table>

Select 3 More Options, as shown in Example 4-82.

Example 4-82  BOS installation settings menu

Installation and Settings

Either type 0 and press Enter to install with current settings, or type the number of the setting you want to change and press Enter.

1 System Settings:
   Method of Installation.............Migration
   Disk Where You Want to Install.....hdisk0

2 Primary Language Environment Settings (AFTER Install):
   Cultural Convention................English (United States)
   Language...........................English (United States)
   Keyboard...........................English (United States)
   Keyboard Type......................Default

3 More Options (Desktop, Security, Kernel, Software, ...)

>>> 0  Install with the settings listed above.

a. The menu shown in Example 4-83 is displayed.

Example 4-83  Select other options for the migration

1. Desktop ........................................ NONE
2. Enable Trusted Computing Base .......... No
3. Import User Volume Groups ............... Yes
4. Enable System Backups to install any System .... No
   (Install all devices and kernels)
5. Remove Java 1.1.8 Software ............. No

b. In the Migration Installation Confirmation menu, shown in Example 4-84 on page 190, select 1, “Install with current settings”.

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Example 4-84  Migration Installation Confirmation menu

Migration Installation Confirmation

Disks:  hdisk0
Cultural Convention: en_US
Language:  en_US
Keyboard:  en_US
Import User Volume Groups: yes
Enable System Backups to install any system: no
Remove Java 1.1.8 Software: no

>>> 1   Continue with Install

88  Help ?     |  WARNING: Base Operating System Installation will
99  Previous Menu  | destroy or impair recovery of SOME data on the
| destination disk hdisk0.

>>> Choice [1]:

Select 1, "Install with current settings"

c. Review the output from each selection on the confirmation menu (for
example, 1, 2, and 3) as shown in Example 4-85. (If you want to abandon
the migration for any reason you can do so at this point by selecting
option 4, which will reboot the system without migrating.)

Select 0 Continue with the migration.

Example 4-85  Migration Confirmation menu

Migration Confirmation

Either type 0 and press Enter to continue the installation, or type the number
of your choice and press Enter.

1  List the saved Base System configuration files which will not be
   merged into the system. These files are saved in /tmp/bos.
2  List the filesets which will be removed and not replaced.
3  List directories which will have all current contents removed.
4  Reboot without migrating.

Acceptance of license agreements is required before using system.
You will be prompted to accept after the system reboots.

>>> 0  Continue with the migration.
88  Help ?
+-------------------------------------------------------------------------------------------------------- WARNING:  
Selected files, directories, and filesets (installable options) from the Base System will be removed. Choose 2 or 3 for more information.

>>> Choice[0]: 1

/etc/motd
/etc/rc
/etc/tsh_profile
/sbin/rc.boot
/usr/sbin/skulker

End of list. Press Enter

>>> Choice[0]: 2

End of list. Press Enter

>>> Choice[0]: 3

/lpp/bos
/tmp
/usr/lpp/bos/bos.rte
/usr/lpp/bos/bos.rte.*
/usr/lpp/bos/deinstl

End of list. Press Enter

>>> Choice[0]: 0

Saving system configuration files in /tmp/bos...
Removing obsolete filesets, directories, and files...

Migration should now commence. Depending on your environment, the process should take from 30 to 60 minutes. The system will reboot when the migration process completes.

16. Monitor the status of the migration, as shown in Example 4-86. You can monitor the status by watching the console output via a vterm session on the HMC, or you can run the lsnim -a info command on the NIM master to view the progress of the client's migration.

Example 4-86  Monitoring the migration status of LPAR4 (partial output)

{nimmast}:/ # lsniminst LPAR4
LPAR4:
   info = LED 610: mount -r nimmast:/AIX53ML4/SPOT_53_ML4/usr /SPOT/usr
LPAR4:
   info = setting_console
LPAR4:
info = verifying_data_files
LPAR4:
  info = prompting_for_data_at_console
LPAR4:
  info = BOS install 1% complete: Importing root volume group.
LPAR4:
  info = BOS install 4% complete: Copying old files
LPAR4:
  info = BOS install 7% complete: Restoring base operating system.
LPAR4:
  info = BOS install 12% complete: Initializing disk environment.
LPAR4:
  info = BOS install 13% complete: Over mounting /.
LPAR4:
  info = BOS install 16% complete: Merging.
LPAR4:
  info = BOS install 19% complete: Installing additional software.
LPAR4:
  info = BOS install 96% complete: Initializing dump device.
LPAR4:
  info = BOS install 97% complete: Network Install Manager customization.
LPAR4:
  info = BOS install 98% complete: Creating boot image.
LPAR4:
  info = BOS install 100% complete

We ran the script shown in Example 4-87 on the NIM master. The script continuously displayed the progress of our LPAR's migration.

Example 4-87 lsniminst script

```bash
host=$1
while true
do
  lsnim -a info $host
  sleep 5
done
```

17. After the migration is finished and the client has rebooted, we check the NIM client state to ensure it has been reset correctly after the NIM migration. Notice that the current state (Cstate) is now showing: ready for a NIM operation as shown in Example 4-88.

Example 4-88 Check the NIM client status after the migration

```bash
{nimmast}:/ # lsnim -l LPAR4
LPAR4:
  class = machines
type = standalone
```
connect = shell
platform = chrp
netboot_kernel = mp
if1 = NET_EN1 lpar4 0
cable_type1 = tp
Cstate = ready for a NIM operation
prev_state = not running
Mstate = currently running
cpuid = 001A85D24C00
Cstate_result = success
current_master = nimmast
sync_required = yes

18. We check the system configuration after the migration completes; see Example 4-89.

Example 4-89   Checking the system after a migration

# oslevel -r
# oslevel -s
# instfix -i | grep AIX
# instfix -icqk ML-LEVEL | grep ":-:"
# lppchk -m3 -v
# lppchk -m3 -c
# lspv
# lsvg
# lsvg -o
# lsdev -Cc disk
# lsvg -l rootvg

19. We check the files in /var/adm/ras as shown in Example 4-90. These log files can also be viewed from the NIM master via the NIM showlog operation.

Example 4-90   Console, NIM and BOS installation/migration log files

# alog -f /var/adm/ras/conslog -o
# more /var/adm/ras/bootlog
# more /var/adm/ras/bosinstlog
# more /var/adm/ras/nim.script
# more /var/adm/ras/devinst.log.

{nimmast}:/ # nim -o showlog -a log_type=bosinst LPAR4
{nimmast}:/ # nim -o showlog -a log_type=niminst LPAR4
{nimmast}:/ # nim -o showlog -a log_type=script LPAR4

20. We restore and update the /etc/motd and /etc/sendmail.cf file, as shown in Example 4-91 on page 194.
Note: Do not simply copy the sendmail.cf file over the new one, because the configuration file changes with each version of sendmail. Review the file and determine which information needs to be migrated to the new sendmail.cf file.

Example 4-91 /etc/motd and /etc/sendmail.cf files after a migration

```bash
# cp -p /home/premig/motd /etc/motd
# vi /etc/motd
; change AIX version info etc.
# grep ^DS /home/premig/sendmail.cf
    xyz-mailserver.com
# vi /etc/sendmail.cf
; Change DS line xyz-mailserver.com
; Send a test email.
# mail -v somebody@xyzcompany.com
# mailq
# tail /var/log/maillog
```

21. We clean up any old AIX 5L V5.2 filesets, as shown in Example 4-92.

Example 4-92 Clean up AIX 5L V5.2 filesets if appropriate

```bash
# lslpp -l | grep 5.2
# smit deinstall
    Remove Installed Software

* SOFTWARE name [bos.docsearch*]
PREVIEW only? (remove operation will NOT occur) yes
REMOVE dependent software? yes
EXTEND file systems if space needed? no
DETAILED output? no
```

22. We install SDD for AIX 5L V5.3 (this is optional, and is only for systems using SDD). At this stage you would install the correct version of SDD for AIX 5L V5.3. You would need to remove the previous version for AIX 5.2 first; refer to the SDD user's guide for more information.

23. We verify that the AIX (and optionally, SDD) levels are correct, as shown in Example 4-93.

Example 4-93 Checking the AIX version and level after migration

```bash
# oslevel -s
5300-04-01
# lppchk -m3 -v
# instfix -i | grep AIX
```
All filesets for 5.3.0.0_AIX_ML were found.
All filesets for 5300-01_AIX_ML were found.
All filesets for 5300-02_AIX_ML were found.
All filesets for 5300-03_AIX_ML were found.
All filesets for 5300-04_AIX_ML were found.

```
# lslpp -1 devices.sdd*
Fileset Level State Description
-------------------------------------------------------------------
Path: /usr/lib/objrepos
devices.sdd.53.rte 1.6.0.5 COMMITTED IBM Subsystem Device Driver for AIX V53
Path: /etc/objrepos
devices.sdd.53.rte 1.6.0.5 COMMITTED IBM Subsystem Device Driver for AIX V53
```

24. We check and clean the error report. We check the AIX error report for any hardware or other issues after the migration. Everything looks fine, so we clear the errpt; see Example 4-94.

**Example 4-94 Checking the AIX error report after migration**

```
# errpt
# errpt -a
# errclear 0
```

25. Optional - SDD was upgraded, then a reboot must be performed now.

26. Optional - SDD - Verify data path's and volume groups as shown in Example 4-95. SDD will configure the altinst_rootvg volume group as a vpath device. Rectify this situation.

**Example 4-95 Check the SDD configuration after migration**

```
# datapath query adapter
# datapath query device
# datapath query wwpn
# lsvg
# lsvg -o
# lspv
# vp2hd altinst_rootvg
# rmdev -dl vpathX
```

27. We verify the IP configuration, as shown in Example 4-96.

**Example 4-96 Checking network configuration after the migration**

```
# ifconfig -a
```
28. We verify that the date, time, and certain environment variables (for example, LANG and TZ) are correct for the environment after the migration; see Example 4-97.

Example 4-97  Check environment variables and date/time after migration

```bash
# date
# echo $TZ
# echo $LANG
```

29. We upgrade SSH, SSL, lsof and nmon to the correct version for AIX 5L V5.3 (only if required).

30. We enable cron as shown in Example 4-98.

Example 4-98  Enabling cron

```bash
# chtab "cron:23456789:respawn:/usr/sbin/cron"
# telinit q
```

**Post-migration tasks**

This section describes the post-migration tasks.

1. Run the post_migration script as shown in Example 4-99. The output is saved to the /home directory. Review the files and ensure installation verification is fine.

Example 4-99  Running the post_migration script

```bash
# rcp nimmast:/AIX53ML4/SPOT_53_ML4/usr/lpp/bos/post_migration /tmp
# /tmp/post_migration
```

2. Create a mksysb backup of the client as shown in Example 4-100.

Example 4-100  Creating a mksysb backup of the client after the migration

```bash
# /usr/local/bin/sysbtonim -s rootvg >> /var/log/sysbtonim.log 2>&1
```

3. Remove the pre-migration and post-migration directories in /home.
4. Start the applications and perform verification testing.
5. Restore rootvg to a mirrored disk configuration as shown in Example 4-101. Reboot the system to turn off quorum for rootvg.

Example 4-101  Mirroring rootvg after migration

```bash
# alt_disk_install -X altinst_rootvg
```
# extendvg rootvg hdisk1
# mirrorvg rootvg hdisk1
# bosboot -a -d /dev/hdisk0
# bosboot -a -d /dev/hdisk1
# bootlist -m normal hdisk0 hdisk1
# bootlist -m normal -o
   hdisk0
   hdisk1
# shutdown -Fr

---

### Backing out a failed AIX migration

Follow the procedures in this section to back out a AIX 5L V5.3 migration. Using an alternate rootvg allows rebooting on the original disk and restarting the system with the previous version of AIX.

1. Set the bootlist to boot from original rootvg, as shown in Example 4-102.

   **Example 4-102   Setting the bootlist to the alternate rootvg**

   ```
   # lspv | grep altinst_rootvg
   hdisk1
   # bootlist -m normal hdisk1
   ```

2. Verify that the bootlist only has hdisk1, as shown in Example 4-103.

   **Example 4-103   Checking the bootlist**

   ```
   # bootlist -m normal -o
   hdisk1
   ```

3. Reboot the server, as shown in Example 4-104.

   **Example 4-104   Reboot the system**

   ```
   # shutdown -Fr
   ```

4. Restore the mksysb if issues with the alternate rootvg, or if it no longer exists. If required, restore rootvg to a mirrored disk configuration, as shown in Example 4-105. Reboot the system to turn off quorum for rootvg.

   **Example 4-105   Mirroring rootvg after migration**

   ```
   # alt_disk_install -X altinst_rootvg
   # extendvg rootvg hdisk1
   # mirrorvg rootvg hdisk1
   # bosboot -a -d /dev/hdisk0
   # bosboot -a -d /dev/hdisk1
   # bootlist -m normal hdisk0 hdisk1
   # bootlist -m normal -o
   ```
5. Reboot the server:
   
   # shutdown -Fr

6. Verify the system and start the applications.

At this point in our case, our NIM migration to AIX 5L V5.3 is now complete. Our client has been successfully upgraded from AIX 5L V5.2 to AIX 5L V5.3.

### 4.4.4 Debugging a NIM AIX migration

Enabling BOS install debug output is very useful if you need to troubleshoot a migration or installation via NIM. With debug information turned on, all the commands and the output from the installation are displayed on the console or tty. This is can be useful, because you will be able to see the commands or operations that failed and then take corrective action. Using BOS debug output can save you time in determining the root cause of a problem, and can reduce the scope of your investigation.

You will see the `showled` command and its output within the debug output. This command displays the system’s LED value at each stage of the process. This can also be useful because many known problems can be referenced by the LED value displayed when a problem occurs.

There are two methods for enabling debug output during a BOS installation or migration:

- By entering a special value at one of the installation menus (manually produce debug output).
- By using a bosinst_data resource to tell the installation program to display debug output (automatically produce debug output).

These methods are explained in more detail in the following sections.

**Manually producing debug output**

Use this procedure to produce debug output without using a bosinst_data resource. To enable debugging for the BOS installation program, start by performing all the processing you would normally do to install or migrate a client. Because you are not using a bosinst_data resource, you will be prompted to supply information about the installation to the BOS installation program, as described here.

1. Select your console.
2. Select your language.

3. The Welcome to Base Operating System Installation and Maintenance menu is displayed. Instead of selecting one of the options, type 911 at the prompt and press Enter.

4. Continue the normal procedure for selecting options and specifying data until the installation begins. Debug output will be sent to the client's display while the installation proceeds.

Automatically producing debug output

Use this procedure to produce debug output when using a bosinst_data resource.

1. To enable debugging for the BOS installation program, set the value BOSINST_DEBUG = yes in the control_flow stanza of the bosinst.data file that you are using for your bosinst_data resource.

   A minimum bosinst.data file for debugging purposes would contain the following lines:
   ```plaintext
   control_flow:
       BOSINST_DEBUG = yes
   ```

2. In addition to the processing you would normally do to install or migrate a client, include the modified bosinst_data resource as a resource for the operation.

   After the client boots over the network, it will use the bosinst_data resource to obtain settings for the installation. If the only data specified in your bosinst.data file is BOSINST_DEBUG = yes, then you will be prompted for the remaining required information before the installation will continue. Debug output will be sent to the client's display while the installation continues.

In Example 4-106, we use a combination of the script command and the vtmenu tool on the HMC to capture all of the debug output to a file for further analysis.

1. We prepare our migration for the client as shown previously.

2. We run the script command to capture session output.

   ```plaintext
   {nimmast}:~/ # cd /tmp ; script bosdebug.out
   ```

3. We connect to the HMC and run vtmenu to connect to the LPARs console (in our case, lpar4 is the system to be migrated so we entered 3 to open a virtual terminal).

   Example 4-106  Using vtmenu to open a console

   ```plaintext
   {nimmast}:/tmp # ssh hscroot@hmcvico
   [hscroot@hmcvico hscroot]$ vtmenu
   ```
Retrieving name of managed system(s) . . . vico

Partitions On Managed System: vico

1) lpar6 Running:
2) lpar5 Running:
3) lpar4 Running:
4) lpar3 Running:
5) lpar2 Running:
6) lpar1 Running:
7) lpar7 Ready:
8) lpar8 Ready:
9) lpar9 Ready:

Enter Number of Running Partition (q to quit): 3

Opening Virtual Terminal On Partition lpar4 . . .

NVTS hmcvico 9734 004*7040-671*01A85D2 1 004*7040-671*01A85D2 _VT_

AIX Version 5
Console login:

4. We start the normal network boot process. When presented with the Welcome to Base Operating System menu, we enter 911. A message appeared at the bottom of the screen letting us know that debug is enabled (for example: BOSINST_DEBUG enabled); see Example 4-107.

Example 4-107 Enabling BOS installation debug output

Welcome to Base Operating System
Installation and Maintenance

Type the number of your choice and press Enter. Choice is indicated by >>>.

>>> 1 Start Install Now with Default Settings

2 Change/Show Installation Settings and Install

3 Start Maintenance Mode for System Recovery

88 Help ?
99 Previous Menu

>>> Choice [1]: 911
Welcome to Base Operating System
Installation and Maintenance

Type the number of your choice and press Enter. Choice is indicated by >>>.

>>> 1 Start Install Now with Default Settings

2 Change/Show Installation Settings and Install

3 Start Maintenance Mode for System Recovery

BOSINST_DEBUG enabled

88 Help ?
99 Previous Menu

>>> Choice [1]:

5. We continue with the migration as normal.
6. All debug output is displayed to the screen (tty), as shown in Example 4-108.

Example 4-108  BOS debug partial output

+ [[ migrate = overwrite ]]
+ [[ migrate = erase_only ]]
+ [-z ]
+ Log Shrink It
+ + ./SPOT/usr/lpp/bosinst/bidata -i -g logical_volume_policy -f SHRINK SHR=
+ + ./SPOT/usr/lpp/bosinst/bidata -i -g image_data -f PRODUCT_TAPE
PT=yes
+ [  = yes -a yes = no ]
+ [  = yes -a 0 = 1 ]
+ return 0
+ + ./SPOT/usr/lpp/bosinst/bidata -b -g control_flow -f ENABLE_64BIT_KERNEL
ENABLE_64BIT=Default
+ + ./SPOT/usr/lpp/bosinst/bidata -b -g control_flow -f CREATE_JFS2_FS
CREATE_JFS2_FS=Default
+ bootinfo -y
+ 2> /dev/null
+ [ 64 = 64 ]
+ bootinfo -a
+ 2> /dev/null
+ [ 3 = 3 ]
+ [[ Default = [Yy][Ee][Ss] ]]
+ [[ Default = [Dd][Ee][Ff][Aa][Uu][Ll][Ll][Tt] ]]
+ [[ yes = [Yy][Ee][Ss] ]]
+ KERNEL64ENABLE=no
+ [ [ Default = [Yy][Ee][Ss] ] ]
+ [ [ Default = [Dd][Ee][Ff][Aa][Uu][Ll][Tt] ] ]
+ [ yes = yes ]
+ CREATEJFS2=no
+ Log Prepare_Target_Disks
+ typeset CURR_PVID=
+ typeset NEW_PVID=
+ typeset PAGELV=
+ typeset RLV=
+ typeset FS=
+ + Get_Primary_blv
+ typeset ERROR=eval return 1
+ typeset BLV=
+ typeset TYPE=
+ + /../SPOT/usr/lpp/bosinst/bidata -i -g lv_data -f LOGICAL_VOLUME -c LABEL -v primary_bootlv
BLV=
+ [ [ -z ] ]
+ + awk {print $1}
+ /../SPOT/usr/lpp/bosinst/bidata -i -g lv_data -f LOGICAL_VOLUME -c TYPE -v boot
BLV=hd5
+ print hd5
+ return 0
PRIMAR_Y.BLV=hd5

7. After the migration has completed successfully and the system has rebooted, we disconnect from the HMC (use ~ to close the vtmenu session).

The script command output file (bosdebug.out) in /tmp on the NIM master contains all the debug output including the showled command; see Example 4-109.

Example 4-109 Partial debug output including showled command

{nimmast}:/ # more bosdebug.out
...............
+ /../SPOT/usr/lpp/bosinst/bidata -b -g control_flow -f INSTALL_METHOD
IM=migrate
+ [ migrate = overwrite ]
+ + expr 5 + 1
PERCENT=6
+ Change_Status 6
+ return 0
+ + expr 6 + 1
PERCENT=7
+ Change_Status 7
+ return 0
```
+ [ -z ]
+ /usr/lib/methods/showled 0xA54
+ Log Restore_System
+ [ 5 -eq 5 ]
+ grep loc_lpp_src
+ lsvg -1 rootvg
+ 1> /dev/null 2>& 1
+ rc=1
+ [ 1 -eq 0 ]
+ dspmsg /../usr/lib/nls/msg/C/BosMenus.cat -s 10 59 Restoring base operating system.

.................
+ + /../SPOT/usr/lpp/bosinst/bidata -b -g control_flow -f CUSTOMIZATION_FILE
+ CF=
+ [ -z ]
+ + /../SPOT/usr/lpp/bosinst/bidata -i -g post_install_data -f BOSINST_FILE
+ CF=
+ cd /
+ [ -f /../ ]
+ [ -f ]
+ return 0
+ /usr/lib/methods/showled 0xA46
+ Finish
+ Change_Status 100
+ alog -t bosinst -q -s 16384
+ cat /../var/adm/ras/bi.log /var/adm/ras/bi.log
+ cp /../var/adm/ras/bi.log.* /var/adm/ras
+ 2> /dev/null
+ [ -z ]
+ [[ [ -s /../var/adm/ras/BosMenus.log0 ]]]
+ cp /../var/adm/ras/BosMenus.log /var/adm/ras
+ 2> /dev/null
+ mv /bosinst.data /var/adm/ras
+ 2> /dev/null
+ mv /image.data /var/adm/ras
+ 2> /dev/null
+ cp /../Ch_Stat.log /var/adm/ras
+ 2> /dev/null
+ [ = true ]
+ + pwd
+CWD=/
+ cd /tmp
+ ar x /usr/lpp/bos/liblpp.a
+ echo
+ cat bos.rte.copyright
Licensed Materials - Property of IBM
.................
```
+ ar t /usr/lpp/bos/liblpp.a
+ rm -f bos.rte.copyright bos.rte.usr.rmlist bos.rte.root.rmlist
   bos.rte.cfgfiles bos.rte.post_i bos.rte.pre_i incompat.pkgs
   productid bos.rte.inventory bos.rte.al bos.rte.size bos.rte.tcb
+ cd /
+ rm -f /liblpp.a /lpp_name /SPOT /../Update_Status.pn
+ [ -n ]
+ rm -f /var/adm/ras/bi.log
+ 1> /dev/null
+ [ 5 -eq 5 ]
+ nimclient -R success
+ nimclient -S shutdown
+ [ 5 -eq 3 ]
+ [ 5 -eq 3 ]
+ [[ 5 -eq 3 ]]
+ [[ 5 -eq 3 ]]
+ mv /SPOT.save.7242 /SPOT
+ 1> /dev/null 2>& 1
+ [ migrate = migrate -a 5.2 != 3.2 ]
+ [ -z ]
+ rm -rf /dev
+ 1> /dev/null 2>& 1
+ mkdir /dev
+ chown root.system /dev
+ chmod 775 /dev
+ cd /dev
+ restore -xqf /tmp/bos/dev.disk.bff
+ 1> /dev/null 2>& 1
+ [[ -L /tmp/bos/dev.disk.bff ]]
+ rm -f /tmp/bos/dev.disk.bff
+ [ yes = no ]
+ sync
+ sync
+ sync
+ umount -f /var
+ 2> /dev/null
+ umount -f /usr
+ 2> /dev/null
+ umount -f /
+ 2> /dev/null
+ reboot -q
Rebooting . .
4.5 NIM mksysb migration and nim_move_up POWER5 tools

Two new features for Network Installation Manager (NIM) and AIX migrations were introduced with AIX 5L V5.3. These new features are:

- mksysb migration
- nim_move_up

Both are designed to simplify and assist with the migration of older (possibly unsupported) levels of AIX running on older IBM RS/6000 or IBM eServer pSeries hardware. Both processes assist you with migrating these earlier systems to AIX 5L V5.3 on POWER5 hardware. In this section, we describe and demonstrate the features of both utilities.

4.5.1 mksysb migration

A mksysb migration can be extremely valuable when you want to move a system to a new POWER5 machine running AIX 5L V5.3. For example, you may have a lower level AIX 4.3 system running on a IBM System p 6H1 eServer that you want to move to a POWER5 LPAR on a IBM System p p595.

Given that AIX 4.3 is not supported on the POWER5 platform, in the days before “mksysb migrations”, the only course of action would have been to upgrade the AIX 4.3.3 system to AIX 5L V5.3 on the existing hardware (for example, the 6H1) and then clone the system via a mksysb to the new POWER5 LPAR. This process is now simplified with the mksysb migration.

A mksysb migration allows you to move a lower level AIX system (for example, AIX 4.3.3 or AIX 5L V5.1) to POWER5 without upgrading AIX on the existing server first. Essentially you boot AIX 5L V5.3 media (in our case, we use NIM) and recover the AIX 4.3.3 or AIX 5L V5.1 mksysb image, followed by an immediate migration to AIX 5L V5.3. This was not possible with previous versions of AIX and pSeries hardware. A mksysb migration is now the recommended way of moving unsupported hardware configurations of AIX 4.3 and AIX 5L V5.1 to new supported hardware and AIX 5L V5.3.

Of course this method is only intended for configurations that will not support a traditional migration method and bypasses the previous hardware limitation by restoring a mksysb on the new hardware and then performing the migration without needing to actually run AIX 4.3 on the new platform. Systems that can be migrated with a conventional migration should do so.
The end result is that the new system will be a clone of the existing system, but will be running AIX 5L V5.3 on a POWER5 platform. The existing system remains the same (for example, running AIX 4.3). You may choose to use this method to perform a test migration of a system and certify the applications, databases, or code against AIX 5L V5.3 on the clone before executing the real mksysb migration at some later stage.

**Requirements for a mksysb migration**

A customized bosinst.data file is required to perform a mksysb migration installation. Your customized bosinst.data file must meet the following requirements to be used with a mksysb migration:

- The file must be provided using the supplementary diskette method or using the client file method (NIM).
- A new variable called MKSYSB_MIGRATIONDEVICE must exist within the file. This variable specifies the name of the device that contains the mksysb. For a network installation, the valid value is the word network. Valid values are /dev/cddevice number for a mksysb image on a CD-DVD, and /dev/rmtdevice number for a mksysb image on tape.
- The following variables in the CONTROL_FLOW stanza must be set as follows:
  - PROMPT must be set to no.
  - INSTALL_METHOD must be set to migrate.
  - EXISTING_SYSTEM_OVERWRITE must be set to yes.
  - RECOVER_DEVICES must be set to no. A mksysb migration attempts to recover the sys0 attributed for the source system as specified in the mksysb ODM, but no other device-specific data is recovered from the source system.
  - Any user-supplied values for these variables is ignored.

The file should list the disks to be installed in the TARGET_DISK_DATA stanza to ensure that only those disks are used. A mksysb migration is a combination of an overwrite installation and a migration installation. The overwrite portion destroys all of the data on the target disks. The TARGET_DISK_DATA stanza must have enough information to clearly single out a disk. If you supply an empty TARGET_DISK_DATA stanza, the default disk for the platform is used, if available.

Example 4-110 on page 207 shows possible values for the TARGET_DISK_DATA stanza.
Example 4-110  Possible values for the TARGET_DISK_DATA stanza

Sample 1. Disk names only (two disks)

target_disk_data:
PVID =
PHYSICAL_LOCATION =
CONNECTION =
LOCATION =
SIZE_MB =
HDISKNAME = hdisk0

target_disk_data:
PVID =
PHYSICAL_LOCATION =
CONNECTION =
LOCATION =
SIZE_MB =
HDISKNAME = hdisk1

Sample 2. Physical location specified (1 disk)

target_disk_data:
PVID =
PHYSICAL_LOCATION = U0.1-P2/Z1-A8
CONNECTION =
LOCATION =
SIZE_MB =
HDISKNAME =

Sample 3. By physical volume ID (PVID)(2 disks)

target_disk_data:
PVID = 0007245fc49bfe3e
PHYSICAL_LOCATION =
CONNECTION =
LOCATION =
SIZE_MB =
HDISKNAME =
target_disk_data:
PVID = 00000000a472476f
PHYSICAL_LOCATION =
CONNECTION =
LOCATION =
SIZE_MB =
HDISKNAME =
Sample 4. By SAN disk ID (ww_name//lun_id - 2 disks)

target_disk_data:
   SAN_DISKID = 0x500507630308427e//0x4021401a00000000

target_disk_data:
   SAN_DISKID = 0x500507630303427e//0x4010400000000000

Some basic prerequisites should be met before attempting a mksysb migration. All requisite hardware, including any external devices (such as tape, CD, or DVD-ROM drives), must be physically connected.

Before you begin the installation, other users who have access to your system must be logged off. Verify that your applications run on AIX 5L V5.3. Also, verify that your applications are binary-compatible with AIX 5L V5.3. If your system is an application server, verify that there are no licensing issues. Refer to your application documentation or provider to verify on which levels of AIX your applications are supported and licensed. You can also check the AIX application availability guide at the following Web address:

   http://www.ibm.com/servers/aix/products/ibmsw/list

Verify that your hardware microcode is up-to-date. There must be adequate disk space and memory available. AIX 5L V5.3 requires 128 MB of memory and 2.2 GB of physical disk space. For additional release information, refer to AIX 5L V5.3 Release Notes at the following Web address:


Make a backup copy of your system software and data. If the source system is available, run the premigration script on it. Ignore any messages that pertain to the hardware configuration of the source system, because the migration takes place on the target system. Correct any other problems as recommended by the script.

### 4.5.2 Performing a mksysb migration with NIM

The following section describes how to perform a mksysb migration with NIM. We will migrate an AIX 5L V5.1 system currently running as an LPAR on a p670 (lpar4) to a new LPAR (vlpar4) running on a p520 with AIX 5L V5.3 (see Figure 4-4 on page 209 and Figure 4-5 on page 210).
These steps assume that the new LPAR has already been configured on the p520 prior to attempting the migration and that all hardware has been set up, configured and verified (for example, CPU, memory, hard disks, Ethernet, SCSI and/or fibre channel adapters). The new LPAR on the p520 is a micro-partition using VIO resources as shown in Figure 4-5 on page 210.
1. Preparing the system for a mksysb migration

Verify which hard disks will be used for the mksysb migration on the target system. In our test environment, we only had internal SCSI disks so we only needed to include hdisk0 and/or hdisk1 in our custom bosinst.data file. However, if you are working in a SAN disk environment it may be necessary to try and determine which disks (for example, ww_name and lun_id) will be used for rootvg in advance of the migration.
One way to do this is to NIM-install AIX 5L V5.3 onto the new system’s rootvg disks and run the commands (shown in Example 4-111) to obtain the lun_id and ww_name for each rootvg disk. This information is used to complete the SAN_DISKID tag in the custom bosinst.data.

Example 4-111  Commands to obtain the lun_id and ww_name

```
# lsattr -EH -l hdisk6 | egrep 'lun_id|ww_name'
lun_id 0x4021401a00000000 Logical Unit Number ID True
ww_name 0x500507630308427e FC World Wide Name False

# lsattr -EH -l hdisk7 | egrep 'lun_id|ww_name'
lun_id 0x4010400000000000 Logical Unit Number ID True
ww_name 0x500507630303427e FC World Wide Name False
```

Prepare the custom bosinst.data file for the mksysb migration. Edit the bosinst.data file and change the options in the bosinst.data file (as shown in Example 4-112). This file was located on our NIM master (/other_res/bid.np.hd0.mkmig). We then checked the contents of our file by using the bicheck command to ensure there were no obvious errors.

Example 4-112  Changing the bosinst.data file

```
{nimmast}:/ # vi /other_res/bid.np.hd0.mkmig

INSTALL_METHOD = migrate
PROMPT = no
EXISTING_SYSTEM_OVERWRITE = yes
RECOVER_DEVICES = no
MKSYSB_MIGRATION_DEVICE = network

target_disk_data:
PVID =
PHYSICAL_LOCATION =
CONNECTION =
LOCATION =
SIZE_MB =
HDISKNAME = hdisk0

{nimmast}:/ # /usr/lpp/bosinst/bicheck /other_res/bid.np.hd0.mkmig
{nimmast}:/ # echo $?
0
```
2. Define the custom bosinst.data file.

Example 4-113 shows how we defined the custom bosinst.data file as a NIM resource.

Example 4-113  Defining the bosinst.data file as a NIM resource

{nimmast}:/ # smit nim_mkres
bosinst_data = config file used during base system installation
* Resource Name [BID_NP_HD0_MKMIG]
* Resource Type bosinst_data
* Server of Resource [master]
* Location of Resource [/other_res/bid.np.hd0.mkmig]

3. Define the source clients AIX 5L V5.1 mksysb as a NIM mksysb resource.

We already had an existing mksysb for the client, which we then defined as a mksysb resource for use with the mksysb migration, as shown in Example 4-114.

Example 4-114  Defining the mksysb as a resource for NIM

{nimmast}:/ # smit nim_mkres
mksysb = a mksysb image
* Resource Name [lpn4-mksysb-mig]
* Resource Type mksysb
* Server of Resource [master]
* Location of Resource [/export/images/lpar4-mksysb.5104]

4. Allocate the NIM mksysb resource to the client, VLPAR4.

In Example 4-115, we allocated the mksysb resource to the target NIM client called VLPAR4.

Example 4-115  Allocating the NIM mksysb resource to the client

{nimmast}:/ # smit nim
Perform NIM Administration Tasks
Manage Machines
Manage Network Install Resource Allocation

Note: If you are in a SAN disk environment for rootvg, the stanza would look similar to the following:

```plaintext
target_disk_data:
SAN_DISKID = 0x500507630308427e/0x4021401a00000000

target_disk_data:
SAN_DISKID = 0x500507630303427e/0x4010400000000000
```
5. Prepare for the AIX migration on the target NIM client, VLPAR4.

We selected an rte install, the AIX 5L V5.3 lppsource and SPOT resources, our custom bosinst_data (BID_NP_HDO_MKMIG), and to accept the license agreements. We selected no to Initiate a reboot and installation now?, as shown in Example 4-116.

Example 4-116 Preparing the client VLPAR4 for migration

```
{nimmast}:/ # smit nim_bosinst
VLPAR4 machines standalone
lpar4-mksysb-mig mksysb

Install the Base Operating System on Standalone Clients
* Installation Target VLPAR4
* Installation TYPE rte
* SPOT SPOT_53_ML4
LPP_53_ML4 resources lpp_source
SPOT_53_ML4 resources spot

BOSINST_DATA to use during installation [BID_NP_HDO_MKMIG]
ACCEPT new license agreements? [yes]
Initiate reboot and installation now? [no]
```

6. We then checked that our target client was ready for the NIM mksysb migration process.

Example 4-117 shows the status of the NIM client, in particular the allocated bosinst_data, lpp_source, spot and mksysb resources.

Example 4-117 Status of the NIM client

```
{nimmast}:/ # lsnim -l VLPAR4
VLPAR4:
class = machines
type = standalone
platform = chrp
netboot_kernel = up
if1 = network1 LPAR4 0
cable_type1 = tp
Cstate = BOS installation has been enabled
prev_state = ready for a NIM operation
Mstate = not running
boot = boot
bosinst_data = BID_NP_HDO_MKMIG
lpp_source = LPP_53_ML4
```
7. Next, we initiated a standard (manual) network boot of the target LPAR.

The mksysb migration then proceeded as an unattended installation; that is, non-prompted. After the Installing Base Operating System screen appears, the installation continues. The progress is displayed and the percentage complete field and elapsed time is incremented to indicate the overall status of the installation.

The mksysb from the source client is restored first. After this is finished the actual migration to AIX 5L V5.3 is performed (this includes such tasks as merging configuration data, installing the base run-time environment and installing additional software).

Example 4-118 and Example 4-119 on page 215 show the output that we observed during the mksysb migration.

Note: Much of the output was removed to save space. Note that the BOS menus are disabled during the upgrade, thus the non-prompted migration. If an error occurs, the installation displays a message stating that the migration cannot continue, and 088 will be shown on the service display.

We monitored the mksysb migration status by watching the output on the console in one window (via vtmenu on the HMC; see Example 4-118) and observing the NIM installation information in another terminal, as shown in Example 4-119 on page 215 (using our custom lsniminst script that we introduced in Example 4-87 on page 192).

Example 4-118  Output of the mksysb migration

{nimmast}:/ # ssh hscroot@hmcp520
Last login: Tue May 30 15:56:55 2006 from 10.1.1.1
hscroot@hmcp520:~> vtmenu

Retrieving name of managed system(s) . . . YLI894-2-650E4DG

----------------------------------------------------------
Partitions On Managed System:  YLI894-2-650E4DG
OS/400 Partitions not listed
----------------------------------------------------------
1)    V101              Running
2)    vlpar1           Running
3)    vlpar2           Running
Enter Number of Running Partition (q to quit): 7

Opening Virtual Terminal On Partition vlpar4 . . .

Open in progress..

********************************************************
Mksysb\Migration Enabled
********************************************************

Running: Init_Target_Disks...
Running: Other_Initialization...
Running: Fill_Target_Stanzas...
Running: Check_Other_Stanzas...

Installing Base Operating System

Please wait...

<table>
<thead>
<tr>
<th>Approximate % tasks complete</th>
<th>Elapsed time (in minutes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

Example 4-119  Migration output

{nimmast}:/ # lsniminst VLPAR4
info = extract_diskette_data
info = BOS install 2% complete : Running: MnM_Restore_NIM_Required_Files...
info = BOS install 3% complete : Making paging logical volumes.
info = BOS install 3% complete : Running: MnM_Create_Rootvg_LVS...
info = BOS install 6% complete : Making file systems.
info = BOS install 6% complete : Running: MnM_Restore_NIM_Mksysb...
info = BOS install 6% complete : 4% of mksysb data restored.
info = BOS install 6% complete : 4% of mksysb data restored.
After the migration completes, the system will reboot. The target LPAR on the p520 will now be a clone of the AIX 5L V5.1 source system, but running AIX 5L V5.3. At this point, you can run the post-migration script to review the migration and perform any post-migration steps that are necessary.

As mentioned earlier, device specific configuration from the source system is not recovered from the mksysb restore (RECOVER_DEVICES was set to no in our custom bosinst.data file). Therefore, you may need to perform some configuration tasks for devices such as network adapters or volume groups (although we encourage you to automate this via a NIM first boot customization script that runs after the system reboots post-installation).

After you are satisfied that the migration has been successful, you can begin taking any action required to test your applications with AIX 5L V5.3, such as copying data across to the new system for testing.

### 4.5.3 Migrating a NIM client to a POWER5 logical partition using `nim_move_up`

The `nim_move_up` tool allows you to easily migrate a back-level AIX system onto a logical partition (LPAR) residing on a POWER5 (or newer) server. It automates much of the manual processes associated with migrating lower level systems to a current level. It is designed to simplify and assist with the migration of older (possibly unsupported) levels of AIX running on older IBM RS/6000 and IBM @server pSeries hardware. In this section, we describe and demonstrate the features of this tool.
The basic flow of a nim_move_up operation is as follows:

- A system backup (mksysb) of the original machine’s rootvg is taken.
- An LPAR is created with equivalent hardware resources on the POWER5 machine.
- The original mksysb backup is migrated to AIX 5.3.
- The migrated backup is installed onto the new LPAR on the POWER5 machine.

Before you can run the nim_move_up tool, however, the NIM master must meet the following prerequisites:

- A configured NIM master running AIX 5L V5.3 with 5300-03 or above.
- Perl 5.6 or above.
- OpenSSH (obtainable from the Linux Toolbox CD).
- At least one standalone NIM client running AIX 4.3.3.75 or above. It must be a registered NIM client and have a valid /etc/niminfo file.
- AIX product media version AIX 5L with 5200-04 or higher, or AIX 5L product media version 5.3 or higher, or equivalent lpp_source and SPOT NIM resources.

You must also have the following hardware resources in your environment:

- A POWER5 server with sufficient hardware resources to support the target clients’ equivalent POWER5 configuration.
- If virtual resources will be used to migrate the clients, an installed and configured Virtual I/O Server is required.
- An HMC controlling the POWER5 server, along with sufficient privileges to start, stop, and create LPARs.

**Note:** You will also require root user authority to run the `nim_move_up` command.

This `nim_move_up` process requires no downtime on the part of the original client. In addition, `nim_move_up` is capable of migrating a client onto virtualized hardware, such as virtual disks, using the Virtual I/O capabilities of the POWER5 server.

This migration process can be completed by the `nim_move_up` application in phases to allow more control over the process, or it can be completed all at once without any user interaction required. It is possible to migrate either a single
system (a NIM client) or a group of systems (a NIM machine group) at the same time.

After a successful nim_move_up migration, the final configuration (in terms of the NIM master, source and target clients) will be similar to the following:

- The original NIM master.
- The original (source) NIM client unchanged.
- A new (target) LPAR(s) on the POWER5 server that corresponds to the original (source) NIM client(s) and are controlled by the NIM master.
- An HMC to control the LPARs on the POWER5 servers.

The different phases of nim_move_up
The nim_move_up migration process is completed in ten phases. To allow some control over the process, each phase can be executed individually or all at once. This phased approach allows for more control (if required) over how and when the migration executes.

Phase 1. The Setup NIM resources phase creates the needed NIM resources to perform the migration steps if they do not already exist or are not provided beforehand.

Phase 2. The Pre-migration Software Assessment phase performs an assessment on each target client to determine what software is installed and can be migrated. Any software that is missing from the lpp_source will be added from the source of installation images that should be provided to nim_move_up.

Phase 3. The Client Hardware and Utilization Data Gathering phase gathers data about each target client’s hardware resources and attempts to assess how much of those resources are utilized on average over a given amount of time.

Phase 4. The p5 Resource Availability Data Gathering and Client Resource Data Translation phase searches the given managed system for available hardware resources. It uses the data gathered in the previous phase to create an equivalent LPAR configuration that utilizes the managed system’s available resources. It creates the client LPARs with virtual I/O resources instead of physical I/O resources if nim_move_up was provided a Virtual I/O Server LPAR to work with. It also creates the appropriate adapters and configuration on the Virtual I/O Server as they are needed.

Phase 5. The Create System Backups phase creates an installable image of each target client and its resources using the mksysb command.

Phase 6. The Migrate Each System Backup phase uses the nimadm command to migrate the newly-created installable images to the new level of AIX 5L.
Phase 7. The *Configure NIM Definitions of Client LPARs* phase uses the network information provided to the `nim_move_up` tool to create NIM standalone client objects for the new LPARs created in the *p5 Resource Availability Data Gathering and Client Resource Data Translation* phase. It allocates the appropriate NIM resources and runs a `bos_inst` pull operation (for example, NIM will not attempt to boot the client) on each NIM client.

Phase 8. The *Initiate LPAR Network Installations* phase reboots each LPAR via the service console (HMC) and initiates the installation.

**Note:** Phase 8. ends when the installation begins. The actual progress of the installation is not monitored.

Phase 9. The *Post-migration Software Assessment* phase assesses the overall success of the migration after each installation, and reports on any software migration issues. It may be necessary to manually correct the errors reported for filesets that fail to migrate.

Phase 10. The optional *Post-installation Customization* phase performs a NIM customization operation on each client with the values provided if an alternate lpp_source, fileset list, or customization script was provided to the `nim_move_up` application. This allows for the optional installation of additional software applications, or for any additional customization that may be needed.

*nim_move_up and the mig2p5 tools.*

The LPAR sizing and creation process is performed by a set of scripts known as the *mig2p5 tools*. These tools have been developed to work with `nim_move_up` and also for standalone use. Refer to Appendix A, “General LPAR sizing and creation with mig2p5 tools” on page 615 for more information.

**Note:** The tools described in the following list can be retrieved from the Additional materials accompanying this book.

The `nim_move_up` and `mig2p5` tools (available from Additional materials) work together in the following way (refer to Figure 4-6 on page 220):

1. Collect the source LPARs hardware configuration and CPU/memory utilization. This is performed by the `mig2p5` tools `getSrcCfg` and `getSrcUtil`.
2. Capture the target POWER5 system’s hardware configuration. The `mig2p5` tool `getTgtRsrc` performs this task.
3. Generate the target LPAR’s required configuration, based on the hardware requirements and CPU/memory utilization collected in step one. The `mig2p5` tool `genTgtCfg` executes this task.
4. Create the target LPAR on the POWER5 system via the mig2p5 tool `createTgtLPAR`.

5. A mksysb of the source system is created by `nim_move_up`.

6. The mksysb is migrated to AIX 5L V5.3 and installed to the new POWER5 LPAR via `nim_move_up`.

![Diagram showing the process of migrating a NIM client to AIX 5L V5.3](image)

**Figure 4-6** The `nim_move_up` and `mig2p5` tools operation

### 4.5.4 Example `nim_move_up` operation

In the following section, we describe how we used the `nim_move_up` tool to migrate a NIM client to AIX 5L V5.3. Our test environment consisted of an AIX 5L V5.1 LPAR (`lpar4`) on a p670, which was then migrated to an AIX 5L V5.3 LPAR on a p520.

In our environment we used virtual I/O (VIO) resources for the new POWER5 LPAR. A working VIO server had already been configured on the IBM System p p520.
In our example, we chose to execute each phase of the “move up” operation individually instead of executing them all at once. This decision was made so that we could discuss each phase in some detail.

The end result is somewhat similar to the mksysb migration. For example, the original client will be unchanged and the new LPAR will be a clone of the original, only now it is running AIX 5L V5.3 on a POWER5 server.

The big difference between the two methods is that nim_move_up automates the entire process, taking care of the creation of the client mksysb, creating the necessary NIM resources if they do not exist already, creating the LPAR definition (either with or without VIO resources), performing the AIX migration via nimadm, and finally initiating the mksysb installation to the new POWER5 LPAR.

Before commencing the nim_move_up operation, we performed several preliminary checks to confirm that our test environment met all the necessary requirements and was ready to support the migration.

1. We verified that the following software was installed at the correct levels on our NIM master.

   Confirm the version of Perl is 5.6 or later:
   
   `{nimmast}:/# lslpp -l perl.rte
   perl.rte 5.8.2.30 COMMITTED Perl Version 5 Runtime

   Confirm that OpenSSH has been installed:
   
   `{nimmast}:/# lslpp -l openssh
   openssh.base.client 4.1.0.5301 COMMITTED Open Secure Shell Commands
   openssh.base.server 4.1.0.5301 COMMITTED Open Secure Shell Server
   openssh.license 4.1.0.5301 COMMITTED Open Secure Shell License
   openssh.man.en_US 4.1.0.5301 COMMITTED Open Secure Shell

   Check what version and maintenance/Technology Level of AIX is running on the NIM master. It must be at least AIX 5L V5.3 ML3:
   
   `{nimmast}:/# oslevel -r
   5300-04

2. Confirm that the source client is running AIX 4.3 .3.75 or later:

   `{nimmast}:/# rsh lpar4 oslevel -r
   5100-04
3. Review the available CPU, memory, network and storage adapter resources on the target POWER5 system.

Ensure that there will be enough spare capacity to meet the needs of the client. This can be done via your HMC and viewing the properties of the managed system. Click on each tab (Processor, Memory, and so on) and review the current available resources. If you intended to use VIO resources, ensure that there is already a VIO server configured and running. Logon to the VIO server and review the storage availability.

4. When satisfied that the environment meets all the requirements, we start the `nim_move_up` configuration process.

We display and configure the `nim_move_up` input values. We run the `nim_move_up` command with the `-S` flag to display the current status of the operation, as shown in Example 4-120.

```
Example 4-120  `nim_move_up -S` command
{nimmast}:/ # nim_move_up -S

nim_move_up Status:
==================
Tue Jun  6 10:24:24 2006

Next phase to execute: 1 - Setup NIM Resources
```

We enter the `nim_move_up` configuration information (see Example 4-121 on page 224) based on the following information:

- Our existing NIM client is named LPAR4. If you want to migrate more than one client at a time, you need to specify a NIM machine group. For example, NIM_MAC_GRP_1.

- The new POWER5 LPAR address will be 10.1.1.65. If you have specified to migrate a NIM machine group, you must supply a sufficient range of IP addresses to cover the number of clients you intend to migrate, for example, 10.1.1.65-10.1.1.75. The /etc/hosts file should be updated with this information also.

  **Note:** Before starting a `nim_move_up` operation, you need to allocate a new IP address for each target client involved in the operation.

- Our POWER5 HMC hostname is hmcp520.

- Our managed system name is YLI894-2-650E4DG.

- The source install images are located in /moveup/AIX5304. We recommend that you set the source to something like a product DVD with all the required
software. In this way, if your lpp_source is missing any filesets that the client will attempt to migrate, it can be added to the lpp_source in phase 2. In our test environment, /moveup/AIX5304 contained a copy of the AIX 5L V5.3 install CDs.

- The location of the new NIM resources will be located in the file system /moveup. This is a file system that we created which will be used to contain any new NIM resources that nim_move_up must create. Our file system was 6G in size, but the size will depend on the number of and size of the client mksysb images and whether or not any new lppsource or SPOT resources need to be created.

- The Virtual I/O Server LPAR name will be VIO1, because we will be using VIO resources for the new POWER5 LPAR.

**Important:** Ensure that your VIO server hostname and LPAR name match in terms of upper case and lower case. During our tests we encountered the following error:

```
Tue Jun  6 11:24:55 2006 OUTPUT
(/usr/1pp/bos.sysmgt/nim/methods/getTgtRsrc): ssh hscroot@hmcp520
viosvrcmd -m YLI894-2-650E4DG -p viol -c ""lsvg""
Tue Jun  6 11:24:56 2006 OUTPUT
(/usr/1pp/bos.sysmgt/nim/methods/getTgtRsrc): Invalid volume group
HSCL8012 The partition named viol was not found. Please check your entry and retry the command.
```

Upon further investigation we found that the LPAR name for the VIO server was in upper case (for example, VIO1). However, in the nim_move_up configuration, the name had been entered in lower case. After the correct case was used, the command completed successfully:

```
hscroot@hmcp520:~> viosvrcmd -m YLI894-2-650E4DG -p VIO1 -c ""lsvg""
rootvg
rootvg_clients
```

- The LPP_SOURCE name will be LPP_53_ML4 and the SPOT name will be SPOT_53_ML4.

- We have not specified the bosinst_data resource, exclude_files resource or the Temporary Volume Group for NIMADM information. This is acceptable because nim_move_up will create the resources as required, and it will use the rootvg as the temporary volume group for the nimadm cache file systems.
Important: Ensure that you have enough space in rootvg on the NIM master for the extraction of the client mksysb plus at least 500 MB of free space for the migration tasks. For optimum performance, it is recommended that you use a different volume group that is separate from the volume group that contains the other NIM resources.

To reduce the size of the mksysb image, you can exclude files from the mksysb via an EXCLUDE_FILES resource which can be specified in the nim_move_up configuration.

Example 4-121  smit nim_move_up configuration parameters

{nimmast}:/ # smit nim_move_up

Configure nim_move_up Input Values

* Existing NIM Client or Machine Group [LPAR4]
* New LPAR IP Address [10.1.1.65]
* New LPAR Subnet Mask [255.255.255.0]
* New LPAR Default Gateway [10.1.1.1]
* Hostname of HMC [hmcp520]
* Managed System Name [YLI894-2-650E4DG]
* Source of Install Images [/moveup/AIX5304]
* Location of New NIM Resources [/moveup]
* Virtual I/O Server LPAR Name [VIO1]
* Force the Use of Physical Network Adapter? [no]
* Force the Use of Physical Storage Controller? [no]
* Accept All New License Agreements? [yes]

LPP_SOURCE Name [LPP_53_ML4]
SPOT Name [SPOT_53_ML4]
BOSINST_DATA
EXCLUDE_FILES resource
Customization SCRIPT resource
INSTALLP BUNDLE containing packages to add
FIX_BUNDLE to install
Temporary Volume Group for NIMADM
Number of Loops to Run on Client [ ]
Seconds for Each Loop [ ]

In Example 4-122 we check the current status of the nim_move_up operation, which also shows us the configuration information we just entered.

Example 4-122  Status of the nim_move_up operation

{nimmast}:/ # nim_move_up -S
nim_move_up Status:
==================
Tue Jun  6 10:41:12 2006

Next phase to execute: 1 - Setup NIM Resources

Saved parameters:
accept_licenses = yes
images = /moveup/AIX5304
hmc = hmcp520
location = /moveup
gateway = 10.1.1.1
managed_sys = YLI894-2-650E4DG
subnet_mask = 255.255.255.0
spot = SPOT_53_ML4
lpp_source = LPP_53_ML4
vioserver = VI01
target_client = LPAR4
min_ip = 10.1.1.65

We are now ready to execute phase 1 of the nim_move_up process.

Before moving onto the first phase, it is worth mentioning a few details regarding the nim_move_up configuration database and log files. All nim_move_up operations are logged to the directory /var/mig2p5.

This directory serves several purposes, as shown in Table 4-1 on page 226. It records state information so that the nim_move_up operation can remember what phases have been executed. The directory is created by the nim_move_up command and its contents are removed after nim_move_up is unconfigured. It also contains several log files which can be very helpful in troubleshooting.

With the exception of the log files and the contents of the client_data directory, the files in /var/mig2p5 can be read and modified so that nim_move_up can perform tasks that it would not do through its command line and SMIT interfaces.

Users are encouraged to manipulate the mig2p5 environment to meet any specific needs and to aid in the troubleshooting of any problems that might arise during the nim_move_up process.

However, modifying the mig2p5 environment is an advanced task and users must ensure they fully understand the changes being performed and their effect on the nim_move_up tool.
Table 4-1  Description and purpose of the files/directories in /var/mig2p5

<table>
<thead>
<tr>
<th>File/Directory</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>config_db - file</td>
<td>Contains all of the saved configuration options passed to nim_move_up.</td>
</tr>
<tr>
<td>current_phase - file</td>
<td>Contains the number of the phase that will execute next.</td>
</tr>
<tr>
<td>global_log - file</td>
<td>Contains the output of all the phases that have been run since the last time the mig2p5 directory was initialized. This log is very helpful in troubleshooting a nim_move_up failure.</td>
</tr>
<tr>
<td>client_data/ - directory</td>
<td>Contains files that are generated by nim_move_up during phases 3 and 4, in which each of the original clients’ system resources and utilization are monitored and quantified into configuration files. The available resources in the POWER5 server are also quantified into corresponding text files. All the data in these files will be taken into account when determining the hardware profile of the newly derived LPARs on the POWER5-based server.</td>
</tr>
<tr>
<td></td>
<td><strong>Note:</strong> These files are intended to be machine-readable data files for the nim_move_up command's internal use. Do not manually modify or create them yourself.</td>
</tr>
<tr>
<td>phase#/ - directory phase1-9</td>
<td>Contain data specific to the corresponding phase denoted by the number in its name (for example, phase4/). Every phase has a directory (for example, phase1, phase2, and so on).</td>
</tr>
<tr>
<td>phase#/log - file</td>
<td>A log file that contains all the output displayed during a phase’s execution. If a phase is executed multiple times (such as after an error has been corrected), all new output is appended to the log file. This log file is helpful in investigating failures related to this phase after they have occurred.</td>
</tr>
<tr>
<td>phase#/status - file</td>
<td>Indicates whether a phase has been successful or not. This file is used by nim_move_up to determine whether a subsequent phase can be run. A phase can only run if all previous phases’ status files contain the string: success. If a phase encounters an error that causes it to fail, the status file will contain the string: failure.</td>
</tr>
</tbody>
</table>
Example 4-123 shows the directory listing of /var/mig2p5 from our test system.

Example 4-123  Migration directory sample

```
{nimmast}:/var/mig2p5 $ ls -ltr
total 8
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase9
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase8
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase7
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase6
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase5
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase4
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase3
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase2
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase10
drwxr-xr-x 2 root system 256 Jun 06 16:17 phase1
-rw-r--r-- 1 root system 236 Jun 06 16:17 current_phase
drwxr-xr-x 2 root system 256 Jun 06 16:17 client_data
-rw-r--r-- 1 root system 236 Jun 06 16:20 config_db
```

At this stage, the config_db file contains our configuration information; see Example 4-124.

Example 4-124  Sample config_db file

```
{nimmast}:/var/mig2p5 # cat config_db
min_ip:10.1.1.65
subnet_mask:255.255.255.0
gateway:10.1.1.1
hmc:hmcp520
vioserver:VIO1
managed_sys:YLI894-2-650E4DG
target_client:LPAR4
location:/moveup
images:/moveup/AIX5304
accept_licenses:yes
lpp_source:LPP_53_ML4
spot:SPOT_53_ML4
```
5. Configure the SSH keys on the target HMC.

SSH keys needed to be configured on our HMC to allow for unattended remote execution of the commands from the NIM master. We executed the commands shown in Example 4-125 to configure the SSH keys for the root user on the NIM master and append the public key to the authorized_keys2 file for the hscroot user on the HMC. This allows the root user on the NIM master to run commands remotely on the HMC without entering a password. After configuring our SSH keys, we checked that we could run a command on the HMC without being prompted for a password.

Example 4-125 Configuring the SSH keys

```
{nimmast}/: # nim_move_up -K
Connecting to host hmcp520...
hscroot@hmcp520's password:
id_rsa.pub
100% 222 0.2KB/s 00:00
{nimmast}/: # ssh hscroot@hmcp520 date
Tue May 30 15:56:59 CEST 2006
```

6. Execute Phase 1 - Set up NIM resources.

In Example 4-126, we executed the `nim_move_up` command with the `-n` flag, which instructs `nim_move_up` to execute the next phase in the operation.

Example 4-126 Executing the nim_move_up -n command

```
{nimmast}/: # nim_move_up -n
Tue Jun  6 10:43:40 2006 Starting Phase 1 : Setup NIM Resources...
Tue Jun  6 10:43:41 2006 rc for /usr/sbin/nim = 0
Tue Jun  6 10:43:41 2006 rc for /usr/sbin/nim = 0
Tue Jun  6 10:43:41 2006 STATUS for phase 1: success
```

The bosinst_data and exclude_files NIM resources were created in this phase. Example 4-127 shows details of both NIM resources, the contents of the files used to create the NIM resources, and the directory structure. These resources are not removed after a `nim_move_up` operation.

Example 4-127 Details of the NIM resources

```
nim_move_up_bid
nim_move_up_bid:
class = resources
```
```plaintext
type       = bosinst_data
Rstate     = ready for use
prev_state = unavailable for use
location   = /moveup/bosinst.data
alloc_count = 0
server     = master

nim_move_up_exclude:
  class      = resources
  type       = exclude_files
  Rstate     = ready for use
  prev_state = unavailable for use
  location   = /moveup/exclude_files
  alloc_count = 0
  server     = master

{nimmast}:/ # cd /moveup
{nimmast}:/moveup # ls -ltr
  total 8
  drwxr-xr-x  2 root system          256 Jun 06 10:33 lost+found
  -rw-r--r--  1 root system          914 Jun 06 10:43 bosinst.data
  -rw-r--r--  1 root     system            0 Jun 06 10:43 exclude_files

{nimmast}:/moveup # cat bosinst.data
  CONSOLE = Default
  INSTALL_METHOD = overwrite
  PROMPT = no
  EXISTING_SYSTEM_OVERWRITE = yes
  INSTALL_X_IF_ADAPTER = yes
  RUN_STARTUP = no
  RM_INST_ROOTS = no
  ERROR_EXIT =
  CUSTOMIZATION_FILE =
  TCB = no
  INSTALL_TYPE =
  BUNDLES =
  RECOVER_DEVICES = Default
  BOSINST_DEBUG = no
  ACCEPT_LICENSES = yes
  DESKTOP = CDE
  INSTALL_DEVICES_AND_UPDATES = yes
  IMPORT_USER_VGS =
  ENABLE_64BIT_KERNEL = Default
  CREATE_JFS2_FS = Default
  ALL_DEVICES_KERNELS = yes
  GRAPHICS_BUNDLE = yes
  MOZILLA_BUNDLE = no
  KERBEROS_5_BUNDLE = no
  SERVER_BUNDLE = no
  REMOVE_JAVA_118 = no
```
Phase 2 will run next. We check the status before we execute the next step and we are informed that some pre-migration tasks will be performed, as shown in Example 4-128.

Example 4-128  Pre-migration tasks

{nimmast}:/ # nim_move_up -S
nim_move_up Status:
==================
Tue Jun  6 10:44:29 2006
Next phase to execute: 2 - Pre-Migration

Saved parameters:
accept_licenses = yes
images = /moveup/AIX5304
hmc = hmcp520
location = /moveup
gateway = 10.1.1.1
managed_sys = YLI894-2-650E4DG
subnet_mask = 255.255.255.0
spot = SPOT_53_ML4
lpp_source = LPP_53_ML4
vioserver = VI01
target_client = LPAR4
min_ip = 10.1.1.65

7. Run Phase 2 - Pre-migration.

The pre_migration script is run on the source client. Commands such as lppchk are run to assess what software is installed and which software cannot
be migrated. The pre_migration script saves its output to /home and should be reviewed prior to migrating. Any software that is missing from the lpp_source is then copied from the source installation images (in our case, /moveup/AIX5304) to the lpp_source directory (in our case, /AIX53ML4/LPP_53_ML4); see Example 4-129.

**Example 4-129  Pre-migration checks**

```bash
{nimmast}: # nim_move_up -n
Tue Jun  6 10:44:53 2006 Starting Phase 2 : Pre-Migration...
Tue Jun  6 10:44:53 2006 Running command /usr/lpp/bos.sysmgt/nim/methods/c_rsh
     lpar4 /usr/lpp/bos/pre_migration
Tue Jun 6 10:44:53 2006 OUTPUT:
All saved information can be found in: /home/pre_migration.060606104453

- Checking size of boot logical volume (hd5).
- Listing software that will be removed from the system.
- Listing configuration files that will not be merged.
- Listing configuration files that will be merged.
- Saving configuration files that will be merged.
- Running lppchk commands. This may take awhile.

Please check /home/pre_migration.060606104834/software_consistency for possible errors.

Please check /home/pre_migration.060606104834/tcbck.output for possible errors.

All saved information can be found in: /home/pre_migration.060606104834

It is recommended that you create a bootable system backup of your system before migrating.

Tue Jun 6 10:48:34 2006 Obtaining list of installed software on client LPAR4
Tue Jun 6 10:48:34 2006 Attempting to update lpp_source LPP_53_ML4 with software installed on clients.
     -t /AIX53ML4/LPP_53_ML4 -f /tmp/gcpyargs.553090
     /AIX53ML4/LPP_53_ML4/installp/ppc/printers.rte.5.3.0.30.I
     /AIX53ML4/LPP_53_ML4/installp/ppc/bos.diag.util.5.3.0.10.U
     /AIX53ML4/LPP_53_ML4/installp/ppc/bos.diag.rte.5.3.0.10.U
     /AIX53ML4/LPP_53_ML4/installp/ppc/bos.diag.com.5.3.0.10.U
```

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Example 4-130 shows the collection information on the client’s hardware and system usage.

Example 4-130  Client’s hardware and system usage information collection

{nimmast}:/ # nim_move_up -S
nim_move_up Status:
==================
Tue Jun  6 10:45:13 2006
Next phase to execute: 3 - Client Hardware and Utilization Data Gathering

Saved parameters:
  accept_licenses = yes
  images = /moveup/AIX5304
  hmc = hmcp520
  location = /moveup
  gateway = 10.1.1.1
  managed_sys = YLI894-2-650E4DG
  subnet_mask = 255.255.255.0
  spot = SPOT_53_ML4
  lpp_source = LPP_53_ML4
  vioserver = VI01
  target_client = LPAR4
  min_ip = 10.1.1.65

8. Phase 3 - Client hardware and utilization and data gathering.

This phase collects information about each client’s current hardware resources and also attempts to assess the average use of those resources (in terms of CPU and memory) over a given amount of time.

To collect usage statistics, the `vmstat` command is run on the client for a period of time based on the values we entered for “Number of Loops to Run on Client” and “Seconds for Each Loop” during the configuration stage. Changing these values will allow you to gather more data over a greater space of time, which may provide a better picture of the overall utilization of the system and can result in a better final configuration for the target LPAR on the POWER5 system.
In Example 4-131, the number of loops and seconds for each loop in the initial
nim_move_up configuration were changed to 30 loops and 3 seconds. This
means that the vmstat command will run on the client 30 times every 3
seconds.

**Example 4-131  Number of loops parameter change**

<table>
<thead>
<tr>
<th>Number of Loops to Run on Client</th>
<th>[30]#</th>
</tr>
</thead>
<tbody>
<tr>
<td>Seconds for Each Loop</td>
<td>[3]#</td>
</tr>
</tbody>
</table>

Example 4-132 shows the output the from phase 3.

**Example 4-132  Output of phase 3**

{nimmast}:/ # nim_move_up -n
Tue Jun 6 10:45:33 2006 Starting Phase 3: Client Hardware and Utilization
Data Gathering...
Tue Jun 6 10:45:33 2006 Running getSrcUtil on client LPAR4
Tue Jun 6 10:45:33 2006 Executing: /usr/lpp/bos.sysmgt/nim/methods/getSrcUtil
-s lpar4 -o /var/mig2p5/client_data/srcUtil_LPAR4
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcUtil):
The number of vmstat loops :10
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcUtil):
The Average of Active virtual pages: 127 MB
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcUtil):
The Average of Size of the free list: 582 MB
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcUtil):
The sum of the CPU %idle: 990
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcUtil):
The Average of CPU idle: 99.00
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcUtil):
The Average of CPU utilization: 1.00
Tue Jun 6 10:45:42 2006 rc for /usr/lpp/bos.sysmgt/nim/methods/getSrcUtil = 0
Tue Jun 6 10:45:42 2006 Running getSrcCfg on client LPAR4
Tue Jun 6 10:45:42 2006 Executing: /usr/lpp/bos.sysmgt/nim/methods/getSrcCfg
-s lpar4 -o /var/mig2p5/client_data/srcCfg_LPAR4 -util
/var/mig2p5/client_data/srcUtil_LPAR4
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcCfg):
INPUT:
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcCfg):
Source Hostname = lpar4
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcCfg):
File name for source configuration= /var/mig2p5/client_data/srcCfg_LPAR4
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcCfg):
File containing utilization data = /var/mig2p5/client_data/srcUtil_LPAR4
Tue Jun 6 10:45:42 2006 OUTPU (/usr/lpp/bos.sysmgt/nim/methods/getSrcCfg):
The scripts in Example 4-133 are used to collect hardware information and system usage data on the source client system.

Example 4-133 Scripts used to collect hardware and system usage information

/usr/lpp/bos.sysmgmt/nim/methods/getSrcCfg
/usr/lpp/bos.sysmgmt/nim/methods/getSrcUtil

Upon successful completion of this phase, we found the following files had been created in the /var/mig2p5/client_data directory, as shown in Example 4-134.

Example 4-134 New files created in the /var/mig2p5/client_data

{nimmast}:/var/mig2p5/client_data # ls -l
total 16
-rw-r--r-- 1 root system 62 Jun 06 10:45 srcUtil_LPAR4
-rw-r--r-- 1 root system 253 Jun 06 10:45 srcCfg_LPAR4

{nimmast}:/var/mig2p5/client_data # cat srcUtil_LPAR4
CPU UTILIZATION in % = 1
MEMORY UTILIZATION in MBs = 442

{nimmast}:/var/mig2p5/client_data # cat srcCfg_LPAR4
MACHINE = 7040-671
CPUS = PowerPC_POWER4, 1000 MHz, 2
MEMORY = 1024 MB
CPU UTILIZATION in % = 1
MEMORY UTILIZATION in MBs = 442
# VG = <vg name>,<size in MB>
VG = rootvg,17344
# NETWORK = <description>
NETWORK = 10/100 Mbps Ethernet PCI Adapter II

The files in Example 4-134 on page 234 contain the CPU and memory utilization statistics for the LPAR, and the current hardware configuration of the system. The nim_move_up operation will use these files to determine what the system configuration will need to look like on the new POWER5 LPAR.

Now, we move into the POWER5 resource availability and LPAR creation stage, as shown in Example 4-135.

Example 4-135  LPAR creation stage

{nimmast}:/ # nim_move_up -S
nim_move_up Status:
==================
Tue Jun  6 10:46:08 2006

Next phase to execute: 4 - p5 Resource Availability Data Gathering and LPAR Creation

Saved parameters:
accept_licenses = yes
images = /moveup/AIX5304
hmc = hmcp520
location = /moveup
gateway = 10.1.1.1
managed_sys = YL1894-2-650E4DG
subnet_mask = 255.255.255.0
spot = SPOT_53_ML4
lpp_source = LPP_53_ML4
vioserver = VI01
target_client = LPAR4
min_ip = 10.1.1.65

9. Phase 4 - POWER5 resource availability data gathering and LPAR creation.

In this phase, nim_move_up will examine the POWER5 system for available hardware resources. The data gathered in the previous phase is used to derive an equivalent LPAR configuration on the POWER5 system. We specified a VIO server so our target LPAR will be configured using VIO resources instead of physical I/O resources. The creation of the necessary VIO adapters, storage devices and other configuration on the VIO server is managed by the nim_move_up operation.
We execute this phase and note that there is significant amount of output, as shown in Example 4-136. This output is very useful for helping us to understand what is accomplished in this phase.

**Example 4-136  Output of phase 4**

{nimmast}:~ # nim_move_up -n
Tue Jun  6 11:30:54 2006 Starting Phase 4 : p5 Resource Availability Data Gathering and LPAR Creation...
Tue Jun  6 11:30:54 2006 Obtaining available resources on p5 server
YLI894-2-650E4DG
Tue Jun  6 11:30:54 2006 Executing: /usr/lpp/bos.sysmgt/nim/methods/getTgtRsnc
-hmc hmcp520 -u hscroot -m "YLI894-2-650E4DG" -o
"/var/mig2p5/client_data/tgtRsnc_YLI894-2-650E4DG" -viosDisk "VIO1" -viosEth "VIO1"
Tue Jun  6 11:30:54 2006 OUTPUT (/usr/lpp/bos.sysmgt/nim/methods/getTgtRsnc):
INPUT:
HMC Host = hmcp520
HMC Username = hscroot
Managed System name = YLI894-2-650E4DG
Ethernet VIO Server(s) = VIO1
Disk VIO Server(s) = VIO1
Output file = 
/var/mig2p5/client_data/tgtRsnc_YLI894-2-650E4DG
-----------------------------------------------------------------
Wed Jun  7 09:45:10 2006 Getting the type & model of the given P5 machine............
Wed Jun  7 09:45:10 2006 cmd = ssh hscroot@hmcp520 lssyscfg -m YLI894-2-650E4DG -r sys -Ftype_model
Wed Jun  7 09:45:10 2006 Type-Model = 9131-52A
-----------------------------------------------------------------
Wed Jun  7 09:45:10 2006 Getting the number of processing units in the given P5 machine........
Wed Jun  7 09:45:10 2006 cmd = ssh hscroot@hmcp520 lshwres -m YLI894-2-650E4DG -r proc --level sys -FConfigurable_sys_proc_units
Wed Jun  7 09:45:10 2006 available_proc_units = 4.0
Getting the amount of memory in MBs in the given P5 machine......
Configurable Memory = 8192
Available memory = 1248
LMB Size = 32

Getting the available physical I/O slots

Getting the volume groups info in the VIO Disk server(s)........
Command:

VIO Server = VIO1; VG = rootvg; Size = 53120MB
VIO Server = VIO1; VG = rootvg_clients; Size = 98816MB

Getting the available VLANs info in the VIO server(s)........
Command:

VIO Server = VIO1; VLAN Id = 1; Slot number = 30

Creating p5 configuration for client LPAR4

INPUT:

Source Configuration file                : /var/mig2p5/client_data/srcCfg_LPAR4

Target Machine information file          : /var/mig2p5/client_data/tgtRsrc_YLI894-2-650E4DG

Capacity equivalence maps file           : /usr/lpp/bos.sysmgt/nim/methods/capEqMaps

Target LPAR name                         : LPAR4_lpar

Name of the profile to be created in LPAR: LPAR4_profile

Target LPAR file                         : /var/mig2p5/client_data/tgtCfg_LPAR4

Use dedicated CPUs?                      : No

Use dedicated Ethernet adapters?         : No

Use dedicated Hard disks?                : No


----------------------------------------------------------------

Reading the Source Configure from the given file................

src_mem_util = 43

Machine Type-model of the source machine = 7040-671

Number of CPUs in the source machine     = 2

Amount of memory in the source machine   = 1024

Network slots in source machine          = 10/100 Mbps Ethernet PCI Adapter II


----------------------------------------------------------------
Reading the target P5 managed system configuration...............
Available processing units = 4.0
Available memory = 1248
Available memory = 1248
Storage IO slots = 21040003/none/Storage controller
Network IO slots = 21030003/none/PCI 1Gbps Ethernet Fiber 2-port:21050003/none/PCI 1Gbps Ethernet Fiber 2-port
VIO Volume groups = rootvg,VIO1,53120 rootvg_clients,VIO1,98816
VIO Hard disks =
VIO VLANs = 1,VIO1,30
src_freq = 1000, tgt_freq = 1500
----------------------------------------------------------------
Calculating the resource requirements of target LPAR............
des_procs = 0.1
des_memory = 448
New Physical io slots =
----------------------------------------------------------------
Creating the target LPAR configuration file......................
rc for /usr/lpp/bos.sysmgt/nim/methods/genTgtCfg = 0
Tue Jun 6 11:30:59 2006 Executing:
/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR -m
"/var/mig2p5/client_data/tgtRsrc_YLI894-2-650E4DG" -t
/var/mig2p5/client_data/tgtCfg_LPAR4

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): INPUT:

Tue Jun 6 11:30:59 2006 OUTPUT

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): Target LPAR configuration file = /var/mig2p5/client_data/tgtCfg_LPAR4

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): Managed system = YLI894-2-650E4DG

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): HMC Hostname = hmcp520

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): User configured for remote ssh to HMC = hscroot

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): LPAR name: LPAR4_lpar

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): Profile name: LPAR4_profile

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): Proc units: Min=0.1, Desired=0.1, Max=0.2

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): CPUs: Min=1, Desired=1, Max=1

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): Memory: Min=256, Desired=448, Max=896

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): Virtual IO VGs:

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): rootvg,17344,rootvg,VI01

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR):

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): Virtual IO VLANs:

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR): 1,VI01,30

Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgmt/nim/methods/createTgtLPAR):
Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Creating the target LPAR profile with proc units and memory......
Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command:
Tue Jun 6 11:30:59 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ssh hscroot@hmcp520 mksyscfg
    -r lpar -m YLI894-2-650E4DG -i
    name=LPAR4_lpar,profile_name=LPAR4_profile,lpar_env=aixlinux,proc_mode=shared,sharing_mode=cap,min_proc_units=0.1,desired_proc_units=0.1,max_proc_units=0.2,min_procs=1,desired_procs=1,max_procs=1,min_mem=256,desired_mem=448,max_mem=896,boot_mode=norm
Tue Jun 6 11:31:07 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
----------------------------------------------------------------
Tue Jun 6 11:31:07 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Discovering the LPAR id assigned to the above LPAR............
Tue Jun 6 11:31:07 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command:
Tue Jun 6 11:31:07 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ssh hscroot@hmcp520 lssyscfg
    -r lpar -m YLI894-2-650E4DG --filter lpar_names=LPAR4_lpar -Flpar_id
Tue Jun 6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): LPAR ID = 1
Tue Jun 6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
----------------------------------------------------------------
Tue Jun 6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Adding Physical I/O slots to the LPAR profile................
Tue Jun 6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ......No physical I/O slots to add to the LPAR profile.
Tue Jun 6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
----------------------------------------------------------------
Tue Jun 6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Adding Virtual I/O to the LPAR profile.................
Tue Jun 6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
----------------------------------------------------------------
Tue Jun 6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Getting the list of existing vscsi devices in the VIO server.....
Tue Jun 6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command:
Tue Jun  6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ssh hscroot@hmcp520 viosvrcmd
-m YLI894-2-650E4DG -p VI01 -c "lsdev -virtual"
Tue Jun  6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
-----------------------------------------------------------------
Tue Jun  6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Determining the free virtual
slot number in the VIO server........
Tue Jun  6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command:
Tue Jun  6 11:31:08 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ssh hscroot@hmcp520 lshwres
-r virtualio --rsubtype slot -m YLI894-2-650E4DG --level slot --filter
"lpar_names=VI01" -Fslot_num
Tue Jun  6 11:31:13 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
-----------------------------------------------------------------
Tue Jun  6 11:31:13 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Creating virtual scsi adapter
in the VIO server................
Tue Jun  6 11:31:13 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Adding the vscsi adapter to
the VIO server using DR operation.
Tue Jun  6 11:31:13 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command = ssh hscroot@hmcp520
chhwres -r virtualio --rsubtype scsi -m YLI894-2-650E4DG -o a -p VI01 -s 31 -a
"adapter_type=server,remote_slot_num=2,remote_lpar_name=LPAR4_lpar"
Tue Jun  6 11:31:15 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
-----------------------------------------------------------------
Tue Jun  6 11:31:15 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Getting the default and
current profile names of VIO server...
Tue Jun  6 11:31:15 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command:
Tue Jun  6 11:31:15 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ssh hscroot@hmcp520 lssyscfg
-r lpar -m YLI894-2-650E4DG --filter "$lpar_names=VI01"
-Fdefault_profile:curr_profile
Tue Jun  6 11:31:15 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
-----------------------------------------------------------------
Tue Jun  6 11:31:15 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Adding the vscsi adapter to
the default profile of VIO server....
Tue Jun  6 11:31:15 2006 OUTPUT
(/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command:
Tue Jun  6 11:31:15 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ssh hscroot@hmcp520 chsyscfg
-r prof -m YLI894-2-650E4DG -i
"name=normal,lpar_name=VIO1, virtual_scsi_adapters+=31/server/1/LPAR4_lpar/2/1"
Tue Jun  6 11:31:21 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
----------------------------------------------------------------
Tue Jun  6 11:31:21 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Configuring the virtual scsi
adapter in the VIO server...........
Tue Jun  6 11:31:21 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command:
Tue Jun  6 11:31:21 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ssh hscroot@hmcp520 viosvrcmd
-m YLI894-2-650E4DG -p VIO1 -c ""cfgdev"
Tue Jun  6 11:31:22 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ;-------------------------------------------------------------------
Tue Jun  6 11:31:22 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Determining the OS-generated
vscsi device name for the new adapter....
Tue Jun  6 11:31:22 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command:
Tue Jun  6 11:31:22 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ssh hscroot@hmcp520 viosvrcmd
-m YLI894-2-650E4DG -p VIO1 -c ""lsdev -virtual"
Tue Jun  6 11:31:23 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ;-------------------------------------------------------------------
Tue Jun  6 11:31:23 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Creating a logical volume in
the VIO server......................
Tue Jun  6 11:31:23 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Command:
Tue Jun  6 11:31:23 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): ssh hscroot@hmcp520 viosvrcmd
-m YLI894-2-650E4DG -p VIO1 -c ""mklv -lv rootvg_1 rootvg 17G"
Tue Jun  6 11:31:24 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): rootvg_1
Tue Jun  6 11:31:24 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR):
-------------------------------------------------------------------
Tue Jun  6 11:31:24 2006 OUTPUT
(~/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR): Attaching the above LV to the
vscsi device created earlier.......
In summary, Phase 4 performed the following:

- Obtained information regarding the POWER5 target system; that is, type and model, available processing units, available memory, available physical I/O slots, VIO volume group information, and VIO VLAN information.

- Created the new LPAR on the POWER5 machine such as LPAR name, name of the LPAR profile, whether or not dedicated or shared CPU was needed, whether or not physical adapters were required (that is, Ethernet, Fibre Channel, SCSI or VSCSI), LPAR profile configuration (min/desired/max for CPU and memory), virtual I/O resources on the VIO server for virtual SCSI disk, virtual Ethernet, virtual SCSI adapters and so on. Example 4-137 on page 245 shows the virtual SCSI adapter and disk resources that were created on the VIO server for the client.
Example 4-137  Virtual SCSI and disk resources created for the client

Example 4-137  Virtual SCSI and disk resources created for the client

On completion of Phase 4, a new LPAR is created on the p520. The LPAR is called LPAR4_lpar.

The following file was used by nim_move_up to automatically create the new POWER5 LPAR, as shown in Example 4-138 on page 246.
Example 4-138  File used to create the POWER 5 LPAR

{nimmast}:/var/mig2p5/client_data # cat tgtCfg_LPAR4
LPAR_NAME = LPAR4_Lpar
PROFILE_NAME = LPAR4_profile
# PROC_UNITS = <min> <desired> <max>
PROC_UNITS = 0.1 0.1 0.2
# MEMORY = <min MB> <desired MB> <max MB>
MEMORY = 256 448 896
# VIO_VG_INFO = <vgname_src>,<size in MB>,<vgname_vio>,<lpar_name>
#    Where <vgname_src> is the VG name in source machine, and
#    <vgname_vio> is the VG name in VIO server LPAR
VIO_VG_INFO = rootvg,17344,rootvg,VIO1
# VIO_VLAN_INFO = <vlan id>,<lpar name>,<slot number>
VIO_VLAN_INFO = 1,VIO1,30

The file in Example 4-139 is used to determine what resources are available on the POWER5 system.

Example 4-139  Determining the resources available on the POWER5 system

{nimmast}:/var/mig2p5/client_data # cat tgtRsrc_YLI894-2-650E4DG
MACHINE = 9131-52A
MANAGED SYSTEM = YLI894-2-650E4DG
HMC = hmcp520
HMC_SSH_USER = hscroot
AVAILABLE PROC UNITS = 4.0
CONFIGURABLE MEMORY = 8192MB
AVAILABLE MEMORY = 1248MB
LMB SIZE = 32MB
# IOSLOT = <drc_index>/<slot_pool_id>/<description>
IOSLOT = 21010002/none/Fibre Channel Serial Bus
IOSLOT = 21030003/none/PCI 1Gbps Ethernet Fiber 2-port
IOSLOT = 21040003/none/Storage controller
IOSLOT = 21050003/none/PCI 1Gbps Ethernet Fiber 2-port
IOSLOT = 21010004/none/Universal Serial Bus UHC Spec
IOSLOT = 21030004/none/Fibre Channel Serial Bus
# VIO VG = <vg name>,<lpar name>,<size in MB>
VIO VG = rootvg,VIO1,53120
VIO VG = rootvg,VIO1,98816
# VIO_VLAN = <vlan id>,<lpar name>,<slot number>
VIO_VLAN = 1,VIO1,30

10. Phase 5 - Create system backups.

The next step, shown in Example 4-140 on page 247, creates a mksysb backup of the source client.
Example 4-140  Creation of the mksysb backup

{nimmast}:/ # nim_move_up -S
nim_move_up Status:
==================
Tue Jun  6 11:32:04 2006

Next phase to execute: 5 - Create System Backups

Saved parameters:
 accept_licenses = yes
 images = /moveup/AIX5304
 hmc = hmcp520
 location = /moveup
 gateway = 10.1.1.1
 managed_sys = YL1894-2-650E4DG
 subnet_mask = 255.255.255.0
 spot = SPOT_53_ML4
 lpp_source = LPP_53_ML4
 vioserver = VIO1
 target_client = LPAR4
 min_ip = 10.1.1.65

Phase 5 execution has begun. After the mksysb for the client is finished, a new mksysb resource definition is created (in our case, LPAR4_phys_mksysb); see Example 4-141.

Example 4-141  New mksysb resource definition

{nimmast}:/ # nim_move_up -n
Tue Jun  6 11:39:20 2006 Starting Phase 5 : Create System Backups...
Tue Jun  6 11:39:20 2006 Creating mksysb for client LPAR4
+------------------------------------------------------------------+
System Backup Image Space Information

Note: Ensure that the file size limit (ulimit) for the root user on the client and the master is set to unlimited for mksysb images larger than 2 GB; for example:

# chuser fsize=-1 root
# lsuser -a fsize root
root fsize=-1
11. Phase 6 - Migrate the system backup.

In this phase, the nimadm command is executed to perform an AIX 5L V5.3 migration of each clients' mksysb image, as shown in Example 4-142.

**Example 4-142 Migration the system backups**

```
{nimmast}:/# nim_move_up -S
nim_move_up Status:
=====================
Tue Jun 6 11:41:19 2006

Next phase to execute: 6 - Migrate Each System Backup

Saved parameters:
accept_licenses = yes
images = /moveup/AIX5304
hmc = hmcp520
location = /moveup
gateway = 10.1.1.1
managed_sys = YL1894-2-650E4DG
subnet_mask = 255.255.255.0
spot = SPOT_53_ML4
```
lpp_source = LPP_53_ML4
vioserver = VIO1
target_client = LPAR4
min_ip = 10.1.1.65

Now we begin the execution of Phase 6 and monitor the output. Note that the output has been reduced to save space, as shown in Example 4-143.

Example 4-143 Execution and monitoring of phase 6

{nimmast}:/ # nim_move_up -n
Tue Jun  6 11:41:32 2006 Starting Phase 6: Migrate Each System Backup...
Tue Jun  6 11:41:32 2006 Executing: /usr/sbin/nimadm -HM -s SPOT_53_ML4 -l LPP_53_ML4
+-------------------------------------------------------------------
+-------------------------------------------------------------------
Tue Jun  6 11:41:32 2006 OUTPUT (/usr/sbin/nimadm): Determining level of the "bos.alt_disk_install.rte" fileset for "rootvg" ...
Tue Jun  6 11:41:33 2006 OUTPUT (/usr/sbin/nimadm): Determining level of the "bos.alt_disk_install.rte" fileset for SPOT NIM
Tue Jun  6 11:41:33 2006 OUTPUT (/usr/sbin/nimadm): resource "SPOT_53_ML4" ...
Tue Jun  6 11:41:36 2006 OUTPUT (/usr/sbin/nimadm): Determining level of the "bos.alt_disk_install.rte" fileset for lpp_source NIM
Tue Jun  6 11:41:36 2006 OUTPUT (/usr/sbin/nimadm): resource "LPP_53_ML4" ...
Tue Jun  6 11:41:36 2006 OUTPUT (/usr/sbin/nimadm):
+-------------------------------------------------------------------
+-------------------------------------------------------------------
Tue Jun  6 11:41:37 2006 OUTPUT (/usr/sbin/nimadm): The bos.alt_disk_install.rte fileset level for "rootvg" is 5.3.0.40
Tue Jun  6 11:41:37 2006 OUTPUT (/usr/sbin/nimadm): The bos.alt_disk_install.rte fileset level for "SPOT_53_ML4" is 5.3.0.40
Tue Jun  6 11:41:37 2006 OUTPUT (/usr/sbin/nimadm): The bos.alt_disk_install.rte fileset level for "LPP_53_ML4" is 5.3.0.40
Tue Jun  6 11:41:37 2006 rc for /usr/sbin/nimadm = 0
Tue Jun  6 11:41:37 2006 Migrating mksysb for client LPAR4
Tue Jun  6 11:41:37 2006 Executing: /usr/sbin/nimadm -s SPOT_53_ML4 -l
LPP_53_ML4 -T LPAR4_phys_mksysb -o /moveup/mksysb/LPAR4p5/LPAR4_mksysb -j
rootvg -N LPAR4_p5_mksysb -Y
Tue Jun  6 11:41:38 2006 OUTPUT (/usr/sbin/nimadm): Initializing the NIM
master.
alt_disk_migration eligibility.
Tue Jun  6 11:41:42 2006 OUTPUT (/usr/sbin/nimadm): Initializing log:
/var/adm/ras/alt_mig/LPAR4_phys_mksysb_alt_mig.log
Migration.

+-------------------------------------------------------------------

+-------------------------------------------------------------------

+-------------------------------------------------------------------

+-------------------------------------------------------------------

+-------------------------------------------------------------------
Tue Jun  6 11:41:56 2006 OUTPUT (/usr/sbin/nimadm): Syncing mksysb data to cache ...
Tue Jun  6 11:47:05 2006 OUTPUT (/usr/sbin/nimadm):
Tue Jun  6 11:47:06 2006 OUTPUT (/usr/sbin/nimadm):
+-------------------------------------------------------------------
Tue Jun  6 11:47:06 2006 OUTPUT (/usr/sbin/nimadm):
+-------------------------------------------------------------------
Tue Jun  6 11:47:06 2006 OUTPUT (/usr/sbin/nimadm): nimadm: There is no user customization script specified for this phase.
Tue Jun  6 11:47:06 2006 OUTPUT (/usr/sbin/nimadm):
Tue Jun  6 11:47:06 2006 OUTPUT (/usr/sbin/nimadm):
+-------------------------------------------------------------------
Tue Jun  6 11:47:06 2006 OUTPUT (/usr/sbin/nimadm):
+-------------------------------------------------------------------
Tue Jun  6 11:47:52 2006 OUTPUT (/usr/sbin/nimadm): Filesystem size changed to 786432
+-------------------------------------------------------------------
+-------------------------------------------------------------------
+-------------------------------------------------------------------
+-------------------------------------------------------------------
+-------------------------------------------------------------------
Tue Jun  6 12:23:07 2006 OUTPUT (/usr/sbin/nimadm): Defining NIM mksysb resource ... 
Tue Jun  6 12:23:08 2006 OUTPUT (/usr/sbin/nimadm): New NIM mksysb resource name is "LPAR4_p5_mksysb"
This phase migrates the client mksysb images to AIX 5L V5.3 using the nimadm utility.

Note: The nimadm log files are located in /var/adm/ras/nimadm.log and the /var/adm/ras/alt_mig/ directory.

12. Phase 7 - Configure NIM definitions for client LPARs.

We run the nim_move_up -S command again to review what the next phase will be; see Example 4-144. In phase 7, new NIM objects are created for each LPAR. The necessary NIM resources are allocated and a bos_inst pull operation is run on each client.

Example 4-144 Configuring NIM definitions for clients

{nimmast}:/ # nim_move_up -S
nim_move_up Status:
====================
Tue Jun  6 13:11:03 2006

Next phase to execute: 7 - Configure NIM Definitions of Client LPARs

Saved parameters:
accept_licenses = yes
images = /moveup/AIX5304
hmc = hmcp520
location = /moveup
gateway = 10.1.1.1
managed_sys = YLI894-2-650E4DG
subnet_mask = 255.255.255.0
spot = SPOT_53_ML4
lpp_source = LPP_53_ML4
vioserver = VI01
target_client = LPAR4
min_ip = 10.1.1.65
Phase 7 executes and creates NIM client definitions for the target system. A new NIM client was created named LPAR4_p5, as shown in Example 4-145 on page 254.

Example 4-145  Phase 7 execution and creation of NIM client definitions

{nimmast}:~ # nim_move_up -n
Tue Jun 6 13:12:10 2006 Starting Phase 7 : Configure NIM Definitions of Client LPARs...
Tue Jun 6 13:12:10 2006 Adding the following entry into /etc/hosts: LPAR4_p5 10.1.1.65
Tue Jun 6 13:12:10 2006 Executing: /usr/sbin/nim -o define -t standalone -a if1="find_net LPAR4_p5 0" LPAR4_p5
Tue Jun 6 13:12:20 2006 rc for /usr/sbin/nim = 0
Tue Jun 6 13:12:23 2006 rc for /usr/sbin/nim = 0
Tue Jun 6 13:12:23 2006 STATUS for phase 7: success

Note: If you do not update your /etc/hosts file with the new system's hostname and IP address, nim_move_up will do this for you; see Figure 4-7.
Chapter 4. Network Installation Manager scenarios

13. **Phase 8** - Initiate LPAR network installation.

Now it is time for us to install the new POWER5 LPARs, as shown in Example 4-146.

**Example 4-146  Initiating LPAR network installations**

```
{nimmast}:~ # nim_move_up -S
nim_move_up Status:
==================
Tue Jun 6 13:12:45 2006

Next phase to execute: 8 - Initiate LPAR Network Installations

Saved parameters:
  accept_licenses = yes
  images = /moveup/AIX5304
  hmc = hmcp520
  location = /moveup
  gateway = 10.1.1.1
```

*Figure 4-7  *nim_move_up has updated our /etc/hosts*
Example 4-147 shows the status of our new NIM client. You can see from its current state that it is now ready for a BOS installation via a mksysb (named LPAR4_p5_mksysb).

Example 4-147  Showing the status of our new NIM client

{nimmast}/:/ # lsnim -l LPAR4_p5

LPAR4_p5:
   class       = machines
   type        = standalone
   connect     = shell
   platform    = chrp
   netboot_kernel = mp
   if1         = NET_EN1 LPAR4_p5 0
   cable_type1 = N/A
   Cstate      = BOS installation has been enabled
   prev_state  = ready for a NIM operation
   Mstate      = not running
   boot        = boot
   bosinst_data = nim_move_up_bid
   mksysb      = LPAR4_p5_mksysb
   nim_script  = nim_script
   spot        = SPOT_53_ML4
   control     = master

The LPAR network installation is initiated (via the /usr/hmcrbin/lpar_netboot command on the HMC) as shown in Example 4-148. After the installation has begun, this phase is complete.

Note that the installation is not monitored by nim_move_up. We monitored the installation (by observing the output on the LPARs console and using the lsnim command) to ensure that the installation completed successfully.

Example 4-148  LPAR network installation initiated

{nimmast}/:/ # nim_move_up -n
Tue Jun  6 13:23:50 2006 Starting Phase 8 : Initiate LPAR Network Installations...
Tue Jun  6 13:23:50 2006 Executing: /usr/bin/ssh -l hscroot hmcp520
"lpar_netboot -A -D -t ent -s auto -d auto -S 10.1.1.1 -C 10.1.1.65 -G 10.1.1.1
""LPAR4_lpar"" \""LPAR4_profile"" \""YLI894-2-650E4DG""\"
14. Phase 9 - Post-migration.

Before executing Phase 9, make sure that the installation that was initiated in Phase 8 has completed successfully. If you try to execute the next phase before the installation is complete, you will receive an error message stating that the NIM client has not finished installing, as shown in Example 4-149.

Use the lsnim command to check the client status. When the installation is finished, its Cstate will show: ready for a NIM operation.

**Example 4-149 Error message if phase 8 has not completed**

{nimmast}:/ # nim_move_up -n
Tue Jun  6 13:34:08 2006 Starting Phase 9: post-migration...
Tue Jun  6 13:34:08 2006 ERROR: The NIM client LPAR4_p5 has not finished installing. Try again later.
Tue Jun  6 13:34:08 2006 STATUS for phase 9: failure

Now that our LPAR has been successfully installed, we are ready to move into Phase 9; refer to Example 4-150.

**Example 4-150 Executing phase 9**

{nimmast}:/ # nim_move_up -S
nim_move_up Status:
===================
Tue Jun  6 13:32:36 2006

Next phase to execute: 9 - post-migration

Saved parameters:
  accept_licenses = yes
  images = /moveup/AIX5304
  hmc = hmcp520
  location = /moveup
  gateway = 10.1.1.1
  managed_sys = YLI894-2-650E4DG
  subnet_mask = 255.255.255.0
  spot = SPOT_53_ML4
  lpp_source = LPP_53_ML4
  vioserver = VI01
  target_client = LPAR4
  min_ip = 10.1.1.65

The post_migration script is run on LPAR4_p5 as shown in Example 4-151.
This script runs commands such as lppchk to verify the installed filesets.
The output from the post_migration script is saved to /home and should be
reviewed after the migration completes.

Example 4-151  Post migration script execution

{nimmast}:/ # nim_move_up -n
Tue Jun  6 14:04:33 2006 Starting Phase 9: post-migration...
Tue Jun  6 14:04:33 2006 Running post_migration on client LPAR4_p5
Tue Jun  6 14:04:33 2006 Executing: /usr/lpp/bos.sysmgt/nim/methods/c_rsh
  LPAR4_p5 /usr/lpp/bos/post_migration
Tue Jun  6 14:04:33 2006 OUTPUT (/usr/lpp/bos.sysmgt/nim/methods/c_rsh):
      Running lppchk commands. This may take awhile.
      All saved information can be found in: /home/post_migration.060606140432
      rc for /usr/lpp/bos.sysmgt/nim/methods/c_rsh = 0
Tue Jun  6 14:11:20 2006 STATUS for phase 9: success

15. Phase 10 - Post-installation customization.

This phase is optional. It allows for the installation of additional software
(LPPs/filesets) or for any additional customization (using a script) that may be
needed. We did not perform any customization on the client; refer to
Example 4-152 on page 259.
Example 4-152  Post-installation and customization phase (optional)

{nimmast}:/ # nim_move_up -n
Tue Jun  6 14:16:05 2006 Starting Phase 10 : Post-Installation Customization (Optional)...
Tue Jun  6 14:16:05 2006 No customization resources provided- skipping customization.
Tue Jun  6 14:16:05 2006 STATUS for phase 10: success

All phases have now been executed. Our nim_move_up operation has completed each phase successfully. All that is left to do is unconfigure the environment in preparation for any future operations we may need to execute. This step is shown in Example 4-153.

Example 4-153  Unconfiguring and saving the environment parameters

{nimmast}:/ # nim_move_up -S
nim_move_up Status:
==================
Tue Jun  6 14:16:25 2006
All phases have executed.

Saved parameters:
accept_licenses = yes
images = /moveup/AIX5304
hmc = hmmc520
location = /moveup
gateway = 10.1.1.1
managed_sys = YLI894-2-650E4DG
subnet_mask = 255.255.255.0
spot = SPOT_53_ML4
lpp_source = LPP_53_ML4
vioserver = VI01
target_client = LPAR4
min_ip = 10.1.1.65

{nimmast}:/ # nim_move_up -n

All phases have been executed. Run nim_move_up -r to clear nim_move_up data.

{nimmast}:/ # nim_move_up -r
Reset of nim_move_up environment completed successfully.

Our goal has been achieved. We have migrated our AIX 5L V5.1 p670 LPAR to an AIX 5L V5.3 p520 LPAR (see Figure 4-8 on page 260). Although we invested a significant amount of time reviewing each phase of the nim_move_up operation, the actual time and labor required was minimal when compared to previous platform migration methods.
4.5.5  POWER5-to-POWER5 nim_move_up

It is possible to use the `nim_move_up` tool to move an existing POWER5 LPAR running AIX 5L V5.3 to another POWER5 system. At the time of writing, we needed to move AIX 5L V5.3 LPARs from one POWER5 system to another. We were able to use `nim_move_up` for this task by making some minor changes to phase 6.

Because our clients were already running AIX 5L V5.3, it was not necessary to migrate to AIX 5L V5.3 with `nim_move_up` (the migration is performed in phase 6). For example, we moved an LPAR (VLPAR1) from one p520 to another p520. In order for us to move our LPARs without performing phase 6, however, we needed to make the following changes immediately after phase 5:

1. We ensured that the string within the phase6/status file was set to: success.

---

```sh
# prtconf | head
System Model: IBM,7040-671
Machine Serial Number: 01A85D2
Processor Type: PowerPC_POWER4
Number Of Processors: 2
Processor Clock Speed: 1000 MHz
CPU Type: 64-bit
Kernel Type: 32-bit
LPAR Info: 4 lpar4
Memory Size: 1024 MB
Good Memory Size: 1024 MB

# oslevel -r
5100-04

# prtconf | head
System Model: IBM,9131-52A
Machine Serial Number: 650E4DG
Processor Type: PowerPC_POWER5
Number Of Processors: 1
Processor Clock Speed: 1499 MHz
CPU Type: 64-bit
Kernel Type: 64-bit
LPAR Info: 1 LPAR4_lpar
Memory Size: 448 MB
Good Memory Size: 448 MB

# oslevel -r
5300-04
```

Figure 4-8  Hardware configuration after nim_move_up operation
2. We changed the phase number in the current_phase file to: 7.

3. We copied the mksysb image VLPAR1_mksysb to VLPAR1_p5_mksysb (which is the name of the mksysb image that nim_move_up would have created after the migration and is required for phase 7).

Executing these changes allowed us to skip phase 6, continue with the remaining phases (for example, 7, 8, 9 and 10), and move VLPAR1 to our new p520 to a new LPAR named VLPAR1_p5.

4.6 NIM alternate disk migration

In this section, we describe the Network Installation Manager (NIM) alternate disk migration (nimadm) tool and show an example of how to use it to perform an AIX migration to AIX 5L V5.3.

The NIM alternate disk migration (nimadm) utility offers several advantages for migrating to a later level of AIX, over a conventional migration. For example, a system administrator can use nimadm to create a copy of a client's rootvg to a spare disk on the client (similar to a standard alternate disk install with alt_disk_install) and migrate the disk to a newer version or release of AIX. All of this can be done without disruption to the client (for example, there are no outages required to perform the upgrade). After the upgrade is finished, the only downtime required will be a scheduled reboot of the system.

There are several benefits to using nimadm over a standard NIM migration, such as:

► Reduced downtime for the client. The migration is executed while the system is up and running as normal. There is no disruption to any of the applications or services running on the client; therefore, the upgrade can be done at a time convenient to the administrator. At a later stage, a reboot can be scheduled in order to restart the system at the later level of AIX.

► The nimadm process is very flexible and it can be customized using some of the optional NIM customization resources such image_data, bosinst_data, pre/post_migration scripts, exclude_files, and so on.

► Quick recovery from migration failures. All changes are performed on the rootvg copy (altinst_rootvg). If there are any serious problems with the migration, the original rootvg is still available and the system has not been impacted. If a migration fails or terminates at any stage, nimadm is able to quickly recover from the event and clean up afterwards. There is little for the administrator to do except determine why the migration failed, rectify the situation, and attempt the nimadm process again. If the migration process completed but issues were discovered after the system was restarted on the
later level of AIX, then the administrator can back out easily by booting from the original rootvg disk.

The following requirements must be met before attempting to use nimadm:

1. You must have a NIM master running AIX 5L V5.1 or higher with the latest recommended AIX 5L maintenance/Technology Level or higher.

2. The NIM master must have the bos.alt_disk_install.rte fileset installed in its own rootvg and in the SPOT which will be used for the migration. Both need to be at the same level.

**Note:** It is not necessary to install the alternate disk utilities on the client.

3. The lpp_source and SPOT NIM resources that have been selected for the migration MUST match the AIX level to which you are migrating.

4. The NIM master (as always) should be at the same or higher AIX level than the level you are migrating to on the client.

5. The client system to be migrated must be at AIX 4.3.3 or higher.

6. The client must have disks large enough to clone the existing rootvg, plus an additional 500 MB of free space for the migration. This amount will depend on the client system configuration.

7. The target client must be registered with the NIM master as a standalone NIM client.

8. The NIM master must be able to execute remote commands (rsh) on the client using the rshd protocol.

9. The NIM master and client must have a minimum of 128 MB of RAM.

10. A reliable network connection between the master and client is required. A large amount of NFS and rsh traffic will occur, because the master and client will perform NFS mounts and read/write operations during the migration.

11. The client's hardware and software should support the AIX level that is being migrated to and meet the requirements of a conventional migration.

Some limitations apply when using the nimadm utility:

1. If the client's rootvg has TCB turned on, you will need to either disable it (permanently) or perform a conventional migration (for example, using CD or NIM; refer to 4.4, “Using NIM to perform AIX migrations of NIM master and clients” on page 151 for more information about this topic. This limitation exists because TCB needs to access file metadata that is not visible over NFS.

2. All NIM resources used by nimadm must be local to the NIM master.
3. The client may experience a minor performance decrease due to the increase in disk I/O and NFS activity, accompanied by some additional CPU usage from the alt_disk_install cloning.

4. NFS tuning may be required to optimize nimadm performance, especially on slow networks.

5. If configuration changes are made to the system after rootvg has been cloned, then you will need to either redo the alt_disk_install phase of the nimadm operation, or implement them manually or via a customization script after the migration.

For example, if new users are created or system tuning options are changed after the alt_disk_install is run, then you will need to ensure that these changes are performed after the migration is complete, such as user-related (/etc/passwd, /etc/group, /etc/security/passwd, and so on), and system tuning-related (such as /etc/tunables/nextboot).

### 4.6.1 Local disk caching versus NFS

Before we look at an example of using nimadm, there is one last feature we should point out. As already mentioned, nimadm uses NFS for many of the tasks during the migration. This can be a problem on slower networks because NFS writes can be very expensive. To avoid using NFS, a Local Disk Caching option exists which may provide some performance advantages.

Local disk caching allows the NIM master to avoid having to use NFS to write to the client. This can be useful if the nimadm operation is not performing well due to an NFS write bottleneck. If the Local Disk Caching function is invoked, then nimadm will create the client file systems in a volume group on the NIM master. It will then use streams (via rshd) to cache all of the data from the client to the file systems on the NIM master.

Advantages of local disk caching include the following:

1. Improved performance for nimadm operations on relatively slow networks.
2. Improved performance for nimadm operations that are bottlenecked in NFS writes.
3. Decreased CPU usage on the client.
4. Client file systems not exported.

Disadvantages of local disk caching include the following:

1. Cache file systems take up space on the NIM master. You must have enough disk space in a volume group on the NIM master to host the client’s rootvg file systems, plus some space for the migration of each client.
2. Increased CPU usage on the master.
3. Increased I/O on the master. For best performance, use a volume group on the NIM master that does not contain the NIM resources being used for the AIX migration.

In our case, we deploy Local Disk Caching in our nimadm test environment, as described in the following sections.

4.6.2 The 12 phases of nimadm migration

The nimadm command performs a migration in 12 phases. It is useful to have a good understanding of the nimadm process before performing a migration. Each phase can be executed individually using the -P flag. This can be useful if you are trying to pinpoint a problem with the process (for example, you can run each phase and analyze the result before moving onto the next step).

The nimadm phases are as follows:

- **Phase 1.** The master issues the alt_disk_install command to the client, which makes a copy of the rootvg to the target disks (this is Phase 1 of the alt_disk_install process). In this phase, altinst_rootvg (alternate rootvg) is created. If a target mksysb has been specified, the mksysb is used to create a rootvg using local disk caching on the NIM master.

- **Phase 2.** The master runs remote client commands to export all of the /alt_inst file systems to the master. The file systems are exported as read/write with root access to the master.

- **Phase 3.** The master NFS mounts the file systems exported in Phase 2. If a target mskysb has been specified, the mksysb archive is restored into the cache file systems created in Phase 2.

- **Phase 4.** If a premigration script resource has been specified, it is executed at this time.

- **Phase 5.** System configuration files are saved. Initial migration space is calculated and appropriate file system expansions are made. The bos image is restored and the device database is merged (similar to a conventional migration). All of the migration merge methods are executed, and some miscellaneous processing takes place.

- **Phase 6.** All system filesets are migrated using installp. Any required RPM images are also installed during this phase.

- **Phase 7.** If a post-migration script resource has been specified, it is executed at this time.

- **Phase 8.** The bosboot command is run to create a client boot image, which is written to the client's alternate boot logical volume (alt_hd5).

- **Phase 9.** All mounts made on the master in phase 3 are removed¹.
Phase 10. All client exports created in phase 2 are removed.

Phase 11. The alt_disk_install command is called again (phase 3 of alt_disk_install) to make final adjustments and put altinst_rootvg to sleep. The bootlist is set to the target disk (unless the -B flag is used). If an output mksysb has been specified, the cache is archived into a mksysb file, and a NIM mksysb resource created.

Phase 12. Cleanup is executed to end the migration. The client is rebooted, if the -r flag is specified.

If you are unable to meet the requirements for phases 1 to 10, then you will need to perform a conventional migration; refer to 4.4, “Using NIM to perform AIX migrations of NIM master and clients” on page 151 for more information.

Tip: The nimadm command supports migrating several clients at the same time.

4.6.3 Example nimadm migration

Example 4-154 demonstrates a typical NIM alternate disk migration. We will migrate a system from AIX 5L V5.2 to AIX 5L V5.3. This environment consists of a NIM master running AIX 5L V5.3 on a p615, and a NIM client running AIX 5L V5.2 as an LPAR on a p670. Our NIM client name is LPAR4 and the NIM master hostname is nimmast.

First, we check that our NIM master and client are ready to take part in a nimadm operation.

NIM master checklist:

Ensure that the bos.alt_disk_install.rte fileset is installed on the NIM master, and also in the SPOT that will be used for this migration.

Example 4-154   Alternate disk migration example

{nimmast}:/ # lslpp -l bos.alt_disk_install.rte
Fileset          Level  State      Description
--------------------------------------------------------------------

1 When using the Local Disk Caching option with nimadm, the following phases are modified (all other phases remain the same):
Phase 2 - The NIM master creates local cache file systems in the specified target volume group (on the NIM master).
Phase 3 - The NIM master populates the cache file systems with the client's rootvg data.
Phase 9 - The NIM master writes all the migrated data to the client's alternate rootvg.
Phase 10 - The NIM master cleans up and removes the local cache file systems.
2 See footnote1.
bos.alt_disk_install.rte 5.3.0.40 COMMITTED Alternate Disk Installation Runtime

{nimmast}/:/ # nim -o lslpp -a filesets='bos.alt_disk_install.rte' SPOT_53_ML4

<table>
<thead>
<tr>
<th>Fileset</th>
<th>Level</th>
<th>State</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Path: /usr/lib/objrepos</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>bos.alt_disk_install.rte 5.3.0.30</td>
<td>COMMITTED</td>
<td>Alternate Disk Installation Runtime</td>
<td></td>
</tr>
<tr>
<td>5.3.0.40</td>
<td>APPLIED</td>
<td>Alternate Disk Installation Runtime</td>
<td></td>
</tr>
</tbody>
</table>

Example 4-155 shows you how to install the bos.alt* filesets into the SPOT.

Example 4-155 Installing bos.alt_disk_install filesets into the SPOT

{nimmast}/:/ # smit nim_task_interface
Install and Update from ALL Available Software
SPOT_53_ML4 resources spot
LPP_53_ML4 resources lpp_source
Install and Update from ALL Available Software

* Installation Target SPOT_53_ML4
* LPP_SOURCE LPP_53_ML4
* Software to Install [bos.alt_disk_install]+

Customization SCRIPT to run after installation [] +
(not applicable to SPOTS)

Force no +

installp Flags
PREVIEW only? [no] +
COMMIT software updates? [yes] +
SAVE replaced files? [no] +
AUTOMATICALLY install requisite software? [yes] +
EXTEND filesystems if space needed? [yes] +
OVERWRITE same or newer versions? [no] +

COMMAND STATUS
Command: OK stdout: yes stderr: no

Before command completion, additional instructions may appear below.
Installing filesets ...

Be sure to check the output from the SPOT installation to verify that all the expected software was successfully installed. You can use the NIM "showlog" operation to view the installation log file for the SPOT.

+-----------------------------------------------------------------------------+
| Pre-installation Verification...                                           |
+-----------------------------------------------------------------------------+
Verifying selections...done
Verifying requisites...done
Results...

SUCESSES
-------
Filesets listed in this section passed pre-installation verification and will be installed.

Selected Filesets
-----------------
bos.alt_disk_install.boot_images 5.2.0.40  # Alternate Disk Installation ...
bos.alt_disk_install.rte 5.2.0.40          # Alternate Disk Installation ...

<< End of Success Section >>

FILESET STATISTICS
-------------------
2  Selected to be installed, of which:
   2  Passed pre-installation verification

MORE...39

NIM client check list

- Is the client at AIX 4.3.3 or higher?
- Does the client have a disk large enough to clone the existing rootvg plus ~500MB of free space for the migration?

If your rootvg is mirrored, consider breaking the mirror and using one of the disks for the alternate rootvg. In a SAN environment, consider allocating a LUN temporarily for the nimadm operation and removing it afterwards.

# lspv
hdisk0 001a8527c3dc8500  rootvg    active
hdisk1 001a071f9a12dbaf0  None
There is no need to install the `alt_disk_install` filesets on the client because the `alt_disk_install` command, which will be run on the client, will be executed from the SPOT that is mounted from the NIM master.

Is the client already registered with the NIM master as a valid NIM client? If not, the `niminit` command can be used to configure it from the client side.

Can the master execute commands on the client? In our case, yes.

```
{nimmast}:/ # rsh lpar4 oslevel -r
5200-04
```

The `~/.rhosts` file must exist on the client so that it allows the NIM master remote root access. The correct ownership and permissions must also be set; for example:

```
{nimmast}:/ # rsh lpar4 cat ~/.rhosts
nimmast root
{nimmast}:/ # rsh lpar4 ls -l ~/.rhosts
-rw-------   1 root     system           13 Jun 05 14:56 ~/.rhosts
```

Is the client TCB enabled? If it is enabled, then you have two choices:

- You can perform a conventional migration, which supports systems with TCB enabled.
- You can disable TCB permanently.

```
Important: Be aware that if you try to enable TCB again after the migration, you may encounter problems with files being deactivated, which may raise havoc with your running system.
```

Disabling TCB can be accomplished following the procedure shown in Example 4-156:

```
Example 4-156   Disabling TCB permanently

# odmget -q attribute=TCB_STATE PdAt > /tmp/odmout
data
# cd /tmp
# cat odmout
PdAt:
  uniquetype = 
  attribute = "TCB_STATE"
  deflt = "tcb_enabled"
  values = 
  width = 
  type = 
  generic = 
  rep = 
  nls_index = 0
```
# vi odmout
PdAt:
  uniquetype = ""
  attribute = "TCB_STATE"
  deflt = "tcb_disabled"
  values = ""
  width = ""
  type = ""
  generic = ""
  rep = ""
  nls_index = 0

# odmdelete -o PdAt -q attribute=TCB_STATE
0518-307 odmdelete: 1 objects deleted.

# odmget -q attribute=TCB_STATE PdAt
# odmadd /tmp/odmout
# odmget -q attribute=TCB_STATE PdAt

PdAt:
  uniquetype = ""
  attribute = "TCB_STATE"
  deflt = "tcb_disabled"
  values = ""
  width = ""
  type = ""
  generic = ""
  rep = ""
  nls_index = 0

---

**Note:** If you do not disable TCB, the nimadm process will terminate and will not perform the migration as shown in Example 4-157.

---

**Example 4-157  Message if TCB is not disabled**

{nimmast}:/ # nimadm -j nimvg -c LPAR4 -s SPOT_53_ML4 -l LPP_53_ML4 -d "hdisk1" -Y
Initializing the NIM master.
Initializing NIM client lpar4.
Verifying alt_disk_migration eligibility.
0505-193 nimadm: The client, lpar4, is TCB enabled.
You must either disable TCB or perform a conventional migration.
Cleaning up alt_disk_migration on the NIM master.

---

In our test environment, we attempted the procedure, and then re-enabled TCB after a migration as a test only. The results are shown in Example 4-158.
on page 270. It appears obvious that attempting to enable TCB again after a migration will damage your system.

**Note:** As mentioned, there is an option to perform a conventional migration, which supports systems with TCB enabled.

**Example 4-158  tcbck after a migration**

; Check all the files in the TCB database.
# tcbck -y ALL
; Check is OK.
; Migrate to AIX 5.3
; After migration attempt to enable TCB.
# odmget -q attribute=TCB_STATE PdAt > /tmp/odmout
# cd /tmp
# cat odmout
PdAt:

unique = ""
attribute = "TCB_STATE"
deflt = "tcb_disabled"
values = ""
width = ""
type = ""
generic = ""
rep = ""
nls_index = 0

# vi odmout
PdAt:

unique = ""
attribute = "TCB_STATE"
deflt = "tcb_enabled"
values = ""
width = ""
type = ""
generic = ""
rep = ""
nls_index = 0

# odmdelete -o PdAt -q attribute=TCB_STATE
0518-307 odmdelete: 1 objects deleted.

# odmget -q attribute=TCB_STATE PdAt
# odmadd /tmp/odmout
# odmget -q attribute=TCB_STATE PdAt

PdAt:

unique = ""
attribute = "TCB_STATE"
deflt = "tcb_enabled"
values = ""
width = ""
type = ""
generic = ""
rep = ""
nls_index = 0

; Check all the files in the TCB database.
# tcbck -y ALL
3001-023 The file /usr/sbin/mirscan has the wrong file mode.
3001-028 The file /usr/sbin/mirscan has the wrong checksum value.
3001-049 The file /usr/sbin/mirscan has the wrong file size.
3001-023 The file /usr/sbin/mklvcopy has the wrong file mode.
3001-028 The file /usr/sbin/mklvcopy has the wrong checksum value.
3001-049 The file /usr/sbin/mklvcopy has the wrong file size.

..............
; Lot's of tcbck errors are reported.
; Now a lot of system commands no longer function.
# lsv
ksh: lsv: 0403-006 Execute permission denied.
; Permissions on lot's of files/commands have changed. For example:
---------- 1 root system 26538 Aug 25 2005 varyonvg
---------- 1 root system 27744 Aug 25 2005 lsv
---------- 1 root system 10216 Aug 25 2005 lchangelv
---------- 1 root system 13506 Aug 25 2005 lresynclv
---------- 1 root system 19070 Aug 25 2005 lchangelv
---------- 1 root system 38796 Aug 28 2005 mklv
---------- 1 root system 14418 Sep 01 2005 lscons
---------- 1 root system 113686 Sep 01 2005 restbyname
---------- 1 root system 15720 Sep 01 2005 swcons
; A mksysb restore may be required to resolve this situation.

We are now ready to migrate our client from AIX 5L V5.2 ML4 to AIX 5L V5.3 TL4. Our nimadm operation will be performed as shown in Example 4-159.

Example 4-159 nimadm operation
{nimmast}:/ # smit nimadm
Perform NIM Alternate Disk Migration

* Target NIM Client [LPAR4] +
* NIM LPP_SOURCE resource [LPP_53_ML4] +
* NIM SPOT resource [SPOT_53_ML4] +
* Target Disk(s) to install [hdisk1]
  DISK CACHE volume group name [nimvg] +

NIM IMAGE_DATA resource [] +

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As mentioned, we chose to use the Local Disk Caching option for this migration. The options/flags we supplied to the `nimadm` command are explained in Table 3-1.

**Note:** You may want to consider using at least a custom BOSINST_DATA resource with `nimadm`. This will give you greater control over the migration process.

For example, you can change `ALL_DEVICES KERNELS` from the default of `yes` to `no`, which will only install the devices and kernel type for your system configuration, thus reducing the number of filesets installed and the time taken to perform the migration.

To execute the operation from the command line:

```
{nimmast}:/ # nimadm -j nimvg -c LPAR4 -s SPOT_53_ML4 -l LPP_53_ML4 -d "hdisk1" -Y
```

**Table 4-2 The nimadm flags used in our example**

<table>
<thead>
<tr>
<th>Flag</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>-j</code></td>
<td>This flag, followed by a volume group name, will instruct the nimadm operation to create file systems on the specified volume group (on the NIM master). Then <code>nimadm</code> will use streams to cache all of the data from the client to these file systems.</td>
</tr>
<tr>
<td><code>-c</code></td>
<td>The name of the NIM client which will be the target of the migration operation.</td>
</tr>
<tr>
<td><code>-s</code></td>
<td>The SPOT resource to be used for the migration.</td>
</tr>
<tr>
<td><code>-l</code></td>
<td>The name of the lpp_source to be used for the migration.</td>
</tr>
</tbody>
</table>
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There are two other options which should also be considered carefully:

- The first option is whether or not you would like the bootlist on the NIM client set to the alternate disk after the migration is complete. The default action is to set the bootlist. This may be desirable if you are planning on rebooting the client soon after the upgrade.

  However, if it is not possible to reboot a short time after (for example, within the next day or so), then you may prefer not to use this approach. It is possible that if the bootlist is set and the system is left running for several days or even weeks after the migration, you may encounter a undesirable situation (for example, if the system suffers from an unscheduled outage due to a power failure or a system crash and the system comes up on the alternate disk).

  If there are any issues as a result of the AIX migration, this may cause further unscheduled downtime for the system. Most administrators would prefer to deal with these situations during a scheduled outage.

  To prevent the boot list from being set/altered after a nimadm migration, specify the -B flag.

- The second option to consider is whether or not you want the NIM client rebooted after the migration completes. The default is set to no. Depending on your environment, however, this may not be appropriate. In our example, we chose not to reboot immediately after the migration because we had

<table>
<thead>
<tr>
<th>Flag</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>-d</td>
<td>Specifies the target disks on the client which will be used to create the altinst_rootvg volume group. This volume group will be the target of the migration.</td>
</tr>
<tr>
<td>-Y</td>
<td>Specifies that any software license agreements will be accepted. Before starting a nimadm migration you will be required to accept all software license agreements for the software to be installed. This flag will automatically answer yes to all licenses.</td>
</tr>
</tbody>
</table>

**Note:** When nimadm is run via SMIT, you will notice that an undocumented flag (-H) appears in the command line (press F6).

/usr/sbin/nimadm -H -cLPAR4 -lLPP_53_ML4 -sSPOT_53_ML4 -dhdisk1 -jnimvg -Y

This -H flag is used internally (passed between the SMIT scripts to nimadm) so that nimadm knows it is called via SMIT. This will then change the way some messages appear. For example, a message such as: Choose this menu option would be shown as: use this flag for SMIT versus the command line.
applications running on the system that would have been impacted by a reboot of the system.

If you wish to reboot the client after nimadm migration, specify the -r flag.

However, it may be more appropriate for your production environment to schedule an outage at an agreed time and then to stop all applications on the server, manually set the bootlist, and reboot the client.

After the nimadm operation commences, the status of each phase will be displayed on the screen. We will pause at each phase and comment on what is happening behind the scenes.

It is possible to execute nimadm one phase at a time. You may want to do this in order to perform some troubleshooting if the process is failing. Generally speaking, however, this will not be required and you will execute all phases at once. When the process is underway, there should be no need for the administrator to intervene.

Note: All output from the nimadm operation is logged to the file /var/adm/ras/alt_mig/nim_client_name_alt_mig.log, where nim_client_name is the name of the NIM client being migrated. In our case, the name of this file was /var/adm/ras/alt_mig/LPAR4_alt_mig.log.

In Example 4-160, Phase 1 has commenced. During this phase, an alternate disk copy of the clients rootvg was created via the alt_disk_install utility.

Example 4-160 Phase 1 starts

{nimmast}:/ # nimadm -j nimvg -c LPAR4 -s SPOT_53_ML4 -l LPP_53_ML4 -d "hdisk1" -Y
Initializing the NIM master.
Initializing NIM client lpar4.
Verifying alt_disk_migration eligibility.
Initializing Log: /var/adm/ras/alt_mig/LPAR4_alt_mig.log
Starting Alternate Disk Migration.

+---------------------------------------------------------+
Executing nimadm phase 1.
+---------------------------------------------------------+
Cloning altinst_rootvg on client, Phase 1.
Client alt_disk_install command: alt_disk_copy -j -M 5.3 -P1 -d "hdisk1"
Calling mkszfile to create new /image.data file.
Checking disk sizes.
Creating cloned rootvg volume group and associated logical volumes.
Creating logical volume alt_hd5
Creating logical volume alt_hd6
Creating logical volume alt_hd8
Creating logical volume alt_hd4
Creating logical volume alt_hd2
Creating logical volume alt_hd9var
Creating logical volume alt_hd3
Creating logical volume alt_hd1
Creating logical volume alt_hd10opt
Creating /alt_inst/ file system.
Creating /alt_inst/home file system.
Creating /alt_inst/opt file system.
Creating /alt_inst/tmp file system.
Creating /alt_inst/usr file system.
Creating /alt_inst/var file system.
Generating a list of files
for backup and restore into the alternate file system...
Phase 1 complete.

In Phase 2, the NIM master creates the cache file systems in the nimvg volume

group. Some initial checks for required migration disk space were also

performed; see Example 4-161.

Example 4-161  Executing nimadm phase 2

+---------------------------------------------------------+
Executing nimadm phase 2.
+---------------------------------------------------------+
Creating nimadm cache file systems on volume group nimvg.
Checking for initial required migration space.
Creating cache file system /LPAR4_alt/alt_inst
Creating cache file system /LPAR4_alt/alt_inst/usr
Creating cache file system /LPAR4_alt/alt_inst/var
Creating cache file system /LPAR4_alt/alt_inst/tmp
Creating cache file system /LPAR4_alt/alt_inst/home
Creating cache file system /LPAR4_alt/alt_inst/opt
Creating /alt_inst/var file system.

In Phase 3, as shown in Example 4-162, the NIM master copies the NIM client's
data to the cache file systems in nimvg. We are using the Local Disk Cache

option, so this data copy is done via rsh instead of using NFS mounts of the

client's file systems to the master.

Example 4-162  Executing nimadm phase 3

+---------------------------------------------------------+
Executing nimadm phase 3.
+---------------------------------------------------------+
Syncing client data to cache...
Viewing the status of the NIM client from the NIM master shows that an alternate disk migration is being performed; see Example 4-163.

Example 4-163  Checking the status of the NIM client

```
{nimmast}:/# lsnim -l LPAR4
LPAR4:

   class          = machines
   type           = standalone
   locked         = 397474
   connect        = shell
   platform       = chrp
   netboot_kernel = mp
   if1            = NET_EN1 lpar4 0
   cable_type1    = tp
   Cstate         = alt_disk_mig operation is being performed
   prev_state     = ready for a NIM operation
   Mstate         = currently running
   lpp_source     = LPP_53_ML4
   spot           = SPOT_53_ML4
   cpuid          = 001A85D24C00
   control        = master
   Cstate_result  = success
```

In Example 4-164, we can see the cache file systems that nimadm has created to support the migration operation. Each of the /LPAR4_alt/alt_inst* file systems corresponds to the real file systems on the client’s alternate disk copy.

On the client, the file systems are also mounted with a /alt_inst prefix. The /alt_inst prefix gives these file systems a unique name, which prevents any conflict between the real and the alternate. For example, you cannot have two file systems called /usr, so the alternate is called /alt_inst/usr.

Example 4-164  Cache file system created by nimadm

```
{nimmast}:/# lsvg -l nimvg
nimvg:

   LV NAME             TYPE       LPs   PPs   PVs  LV STATE MOUNT POINT
  lppsrclv            jfs2       97    97    1    open/syncd /export/lpp_source
  loglv00             jfs2log    1     1     1    open/syncd N/A
  spotlv              jfs2       11    11    1    open/syncd /export/spot
  imageslv            jfs2       113   113   1    open/syncd /export/images
  loglv01             jfslog     1     1     1    open/syncd N/A
  lv00                jfs        1     1     1    open/syncd /LPAR4_alt/alt_inst
  lv01                jfs        17    17    1    open/syncd /LPAR4_alt/alt_inst/usr
  lv02                jfs        1     1     1    open/syncd /LPAR4_alt/alt_inst/var
  lv03                jfs        1     1     1    open/syncd /LPAR4_alt/alt_inst/tmp
  lv04                jfs        1     1     1    open/syncd /LPAR4_alt/alt_inst/home
  lv05                jfs        1     1     1    open/syncd /LPAR4_alt/alt_inst/opt
```
# lsvg -l altinst_rootvg
altinst_rootvg:

<table>
<thead>
<tr>
<th>LV NAME</th>
<th>TYPE</th>
<th>LPs</th>
<th>PPs</th>
<th>PVs</th>
<th>LV STATE</th>
<th>MOUNT POINT</th>
</tr>
</thead>
<tbody>
<tr>
<td>alt_hd5</td>
<td>boot</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>closed/syncd</td>
<td>N/A</td>
</tr>
<tr>
<td>alt_hd6</td>
<td>paging</td>
<td>8</td>
<td>8</td>
<td>1</td>
<td>closed/syncd</td>
<td>N/A</td>
</tr>
<tr>
<td>alt_hd8</td>
<td>jfslog</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>open/syncd</td>
<td>/alt_inst</td>
</tr>
<tr>
<td>alt_hd4</td>
<td>jfs</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>open/syncd</td>
<td>/alt_inst</td>
</tr>
<tr>
<td>alt_hd2</td>
<td>jfs</td>
<td>6</td>
<td>6</td>
<td>1</td>
<td>open/syncd</td>
<td>/alt_inst/usr</td>
</tr>
<tr>
<td>alt_hd9var</td>
<td>jfs</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>open/syncd</td>
<td>/alt_inst/var</td>
</tr>
<tr>
<td>alt_hd3</td>
<td>jfs</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>open/syncd</td>
<td>/alt_inst/tmp</td>
</tr>
<tr>
<td>alt_hd1</td>
<td>jfs</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>open/syncd</td>
<td>/alt_inst/home</td>
</tr>
<tr>
<td>alt_hd10opt</td>
<td>jfs</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>open/syncd</td>
<td>/alt_inst/opt</td>
</tr>
</tbody>
</table>

On the client you can see that hdisk1 now belongs to the altinst_rootvg volume group:

{lpar4}:/{lpar4}:/ # lspv

<table>
<thead>
<tr>
<th>hdisk0</th>
<th>001a85d27c3dc850</th>
<th>rootvg</th>
<th>active</th>
</tr>
</thead>
<tbody>
<tr>
<td>hdisk1</td>
<td>001a071f9a12dbaf</td>
<td>altinst_rootvg</td>
<td>active</td>
</tr>
</tbody>
</table>

In Phase 4, if a premigration script was specified to run on the client, it would be executed now. We did not execute any premigration script in our test environment; see Example 4-165.

**Example 4-165  Phase 4 pre-migration scripts execution**

```
 Executing nimadm phase 4.
 nicadm: There is no user customization script specified for this phase.
```

Phase 5 will save system configuration files and then perform an initial check for disk space required for the migration, as shown in Example 4-166. If required, then file systems will be expanded at this point. The BOS run-time environment is restored and the device database (ODM) is merged (similar to a conventional migration).

**Example 4-166  Execution of nimadm phase 5**

```
 Executing nimadm phase 5.
 Saving system configuration files.
 Checking for initial required migration space.
 Setting up for base operating system restore.
 Restoring base operating system.
 Merging system configuration files.
```
Rebuilding inventory database.
Running migration merge method: ODM_merge Config_Rules.
Running migration merge method: ODM_merge SRCextmeth.
Running migration merge method: ODM_merge SRCsubsys.
Running migration merge method: ODM_merge SWservAt.
Running migration merge method: ODM_merge pse.conf.
Running migration merge method: ODM_merge xtiso.conf.
Running migration merge method: ODM_merge PdDv.
Running migration merge method: convert_errnotify.
Running migration merge method: passwd_mig.
Running migration merge method: login_mig.
Running migration merge method: user_mrg.
Running migration merge method: secur_mig.
Running migration merge method: mkusr_mig.
Running migration merge method: group_mig.
Running migration merge method: ldapcfg_mig.
Running migration merge method: convert_errlog.
Running migration merge method: ODM_merge GAI.
Running migration merge method: ODM_merge PdAt.
Running migration merge method: merge_smit_db.
Running migration merge method: ODM_merge fix.
Running migration merge method: merge_swvpds.
Running migration merge method: SysckMerge.

The migration to AIX 5L V5.3 commences in Phase 6. All the client’s filesets on
the local cache file systems will be migrated via installp. At this point all the
activity is taking place on the NIM master, and not on the client. Output has been
removed to save space in Example 4-167.

Example 4-167 Executing nimadm phase 6 - migration commences

+-------------------------------------------------------------------------------+
| Executing nimadm phase 6.                                                     |
+-------------------------------------------------------------------------------+
| Installing and migrating software.                                           |
| Updating install utilities.                                                   |
+-------------------------------------------------------------------------------+
| Pre-installation Verification...                                             |
+-------------------------------------------------------------------------------+
| Verifying selections...done                                                  |
| Verifying requisites...done                                                  |
| Results...                                                                  |
| ....                                                                        |
| ....                                                                        |
| Checking space requirements for installp install.                             |
| Expanding /LPAR4_alt/alt_inst/usr local filesystem.                          |
| Filesystem size changed to 2097152                                          |
| Installing software with the installp installer.                             |
Pre-installation Verification...

Verifying selections...done
Verifying requisites...done
Results...

FILESET STATISTICS

709  Selected to be installed, of which:
   611  Passed pre-installation verification
   60   Replaced by superseding updates
   36   Already installed (directly or via superseding filesets)
   1    Additional requisites to be automatically installed

612  Total to be installed

install_all_updates: Checking for recommended Maintenance Level 5300-04.
install_all_updates: Executing /usr/bin/oslevel -rf, Result = 5300-04
install_all_updates: Verification completed.
install_all_updates: Log file is /var/adm/ras/install_all_updates.log
install_all_updates: Result = SUCCESS
Restoring device ODM database.

If a post-migration script was specified for the NIM client, then it will be executed in Phase 7. We did not execute any post-migration script in our example; see Example 4-168.

**Example 4-168 Executing post-migration scripts if any - phase 7**

```
+---------------------------------+
Executing nimadm phase 7.
+---------------------------------+

nimadm: There is no user customization script specified for this phase.
```

The **bosboot** command is run to create a new boot image, which is written to the clients alternate boot logical volume alt_hd5, as shown in Example 4-169.

**Example 4-169 Running the bosboot command during phase 8**

```
+---------------------------------+
Executing nimadm phase 8.
+---------------------------------+

Creating client boot image.
bosboot: Boot image is 25216 512 byte blocks.
Writing boot image to client's alternate boot disk hdisk1.
```
On the client (lpar4), we could see the alternate boot image being created by observing the current processes on the system, as shown in Example 4-170.

**Example 4-170  Alternate boot image is created**

```
{lpar4}:/ # ps -ef | grep alt_hd5
  root 188456 258226  1 10:42:37      -  0:00 /usr/bin/dd
  if=/alt_inst/usr/lpp/bos.alt_disk_install/boot_images/alt_mig.client.boot
  of=/dev/alt_hd5 seek=2
  root 258226 303174  0 10:42:37      -  0:00 ksh -c /usr/bin/dd
  if=/alt_inst/usr/lpp/bos.alt_disk_install/boot_images/alt_mig.client.boot
  of=/dev/alt_hd5 seek=2 2>&1 && echo rmc_cmd_RET0 || echo rmc_cmd_RET1
  root 274464 188456  1 10:42:37      -  0:00 /usr/bin/dd
  if=/alt_inst/usr/lpp/bos.alt_disk_install/boot_images/alt_mig.client.boot
  of=/dev/alt_hd5 seek=2
```

All the migrated data is now copied from the NIM master's local cache file to the client's alternate rootvg via `rsh`, as shown in Example 4-171.

**Example 4-171  Migrated data is now copied during nimadm phase 9**

```
+---------------------------------------------------------+
Executing nimadm phase 9.
+---------------------------------------------------------+
Adjusting client file system sizes ...                      
  Adjusting size for /
  Adjusting size for /usr
Expanding /alt_inst/usr client filesystem.                 
  Filesystem size changed to 2490368
  Adjusting size for /var
  Adjusting size for /tmp
  Adjusting size for /home
  Adjusting size for /opt
Syncing cache data to client ...                            
```

Observing the process table on the client and the master (ps -ef command) revealed the processes involved in the master-to-client data synchronization, as shown in Example 4-172.

**Note:** The `/alt_inst/alt_disk_mig_rfail log file, which captures status information regarding the syncing of the cache data to the client, can be useful for troubleshooting.

**Example 4-172  Data synchronization**

```
{lpar4}:/ # ps -ef | grep restore
```
The NIM master cleans up and removes the local cache file systems in Phase 10 because they are no longer required, as shown in Example 4-173.

Example 4-173  Cleaning up by the NIM master - *nimadm* phase 10

```
+---------------------------------------------------------+
| Executing nimadm phase 10.                              |
| Unmounting client mounts on the NIM master.             |
| forced unmount of /LPAR4_alt/alt_inst/var              |
| forced unmount of /LPAR4_alt/alt_inst/usr              |
| forced unmount of /LPAR4_alt/alt_inst/tmp              |
| forced unmount of /LPAR4_alt/alt_inst/opt              |
| forced unmount of /LPAR4_alt/alt_inst/home             |
| forced unmount of /LPAR4_alt/alt_inst                  |
| Removing nimadm cache file systems.                    |
| Removing cache file system /LPAR4_alt/alt_inst         |
| Removing cache file system /LPAR4_alt/alt_inst/usr     |
| Removing cache file system /LPAR4_alt/alt_inst/var     |
| Removing cache file system /LPAR4_alt/alt_inst/tmp     |
| Removing cache file system /LPAR4_alt/alt_inst/home    |
| Removing cache file system /LPAR4_alt/alt_inst/opt     |
+---------------------------------------------------------+
```

The *alt_disk_install* command is called again, as it was in Phase 3, to verify the altinst_rootvg and to put the volume group to sleep (for example, unmounting the /alt_inst file systems, as shown in Example 4-174). The bootlist is set to the alternate disk unless the -B flag is specified (we did not specify this flag).

Example 4-174  Verifying the alternate rootvg installation

```
+---------------------------------------------------------+
| Executing nimadm phase 11.                              |
| Cloning altinst_rootvg on client, Phase 3.              |
| Client alt_disk_install command: alt_disk_copy -j -M 5.3 -P3 -d "hdisk1"
| # Phase 3 ##############################################
| Verifying altinst_rootvg...                            |
+---------------------------------------------------------+
```
Modifying ODM on cloned disk.
forced unmount of /alt_inst/var
forced unmount of /alt_inst/usr
forced unmount of /alt_inst/tmp
forced unmount of /alt_inst/opt
forced unmount of /alt_inst/home
forced unmount of /alt_inst
forced unmount of /alt_inst

Changing logical volume names in volume group descriptor area.
Fixing LV control blocks...
Fixing file system superblocks...
Bootlist is set to the boot disk: hdisk1

In Phase 12, several cleanup tasks are performed on the NIM master and client. If the -r flag was specified with nimadm, then the NIM client would be rebooted now. We chose not to reboot, which is the default action as shown in Example 4-175.

Example 4-175  Cleaning continues on phase 12

+---------------------------------------------------------+
Executing nimadm phase 12.
+---------------------------------------------------------+
Cleaning up alt_disk_migration on the NIM master.
Cleaning up alt_disk_migration on client LPAR4.

Now that all nimadm phases have been completed successfully, we are ready to reboot our client.

After a system outage time window has been agreed upon and scheduled, all that would be required to “migrate” our system to AIX 5L V5.3 would be a reboot. The following tasks would be performed to reboot from our alternate disk:

1. After all applications have been stopped and all users logged off, confirm that the client’s bootlist is set to the alternate rootvg and reboot the system:

   {lpar4}:/ # bootlist -m normal -o
hdisk1

   {lpar4}:/ # lspv
hdisk0  001a85d27c3dc850  rootvg active
hdisk1  001a071f9a12dbaf  altinst_rootvg

   {lpar4}:/ # shutdown -Fr

2. After the reboot, confirm that the correct AIX 5L is shown (for example, AIX 5L V5.3). At this point you would perform verification testing to ensure that the system is functioning as expected; for example:

3. {lpar4}:/ # oslevel -r

4. 5300-04
5. If required, the administrator can easily back out the upgrade by booting from the original rootvg disk as shown:

```
{lpar4}:/ # bootlist -m normal hdisk0
{lpar4}:/ # lspv
hdisk0 001a85d27c3dc850 old_rootvg
hdisk1 001a071f9a12dbaf rootvg active
# bootlist -m normal -o
hdisk0 blv=hd5
{lpar4}:/ # shutdown -Fr
```

6. After the reboot, confirm that the correct version of AIX is running (for example, the version prior to the migration to AIX 5L V5.3 which was AIX 5L V5.2). Use the following command:

```
{lpar4}:/ # oslevel -r
5200-04
```

7. If required, rootvg should be remirrored after the migration. Then reboot the system to turn off quorum for rootvg.

4.6.4 Cleaning up after a failed nimadm operation

If a `nimadm` operation fails during a migration, the `nimadm` utility can take care of cleaning up the systems without user intervention. However, in some cases it may be necessary to ask `nimadm` to rerun the cleanup process. This can be done by running the `nimadm` command with the `-C` (clean up) flag, the `-F` (unlock NIM client) flag, or via SMIT, as shown in Example 4-176.

Example 4-176 Cleaning after a failed nimadm operation

```
{nimmast}:/ # smit nimadm
Clean up NIM Alternate Disk Migration

* Target NIM Client                                           [LPAR4]+
* NIM SPOT resource                                          [SPOT_53_ML4]+
Debug output?                                               no+
FORCE cleanup to reset all locks?                          yes+

COMMAND STATUS
Command: OK                stdout: yes           stderr: no

Before command completion, additional instructions may appear below.

Initializing the NIM master.
Initializing NIM client lpar4.
Cleaning up alt_disk_migration on the NIM master.
Cleaning up alt_disk_migration on client LPAR4.
Client alt_disk_install command: alt_disk_install -M all -X
```
Bootlist is set to the boot disk: hdisk0

It may also be necessary to perform other manual tasks in the event of a nimadm failure:

- Unmounting all /alt_* file systems.
- Removing the /alt_* file systems.
- Varying off the altinst_rootvg volume group.
- Removing the altinst_rootvg volume group with the `alt_disk_install -x altinst_rootvg` command.

**Important:** We recommend that you do not use `exportvg` on an alternate rootvg. Always use the `-x` option to `alt_disk_install`. Using `exportvg` may result in some required entries in `/etc/filesystems` being removed. Our tests have shown that this can and does happen.

After you are satisfied that the failed nimadm process has been successfully cleaned up, attempt the migration operation again.

### 4.7 Network Installation Manager and Linux distributions

IBM System p machines traditionally use BOOTP protocol for booting over the network. Intel®-based computers (Windows/Linux) typically use DHCP and PXE protocol.

In order to be able to serve both AIX and Linux client network installations from one network install server, DHCP must be used for both types, because BOOTP and DHCP cannot be active on the same server at the same time. This is not a problem because DHCP on AIX 5L V5.3 supports handling of BOOTP requests as well as DHCP requests. But a conversion has to be made for all existing NIM clients to use DHCP configuration files and syntax.

As with AIX 5L V5.3, RFC 2349 is implemented in the AIX 5L tftp subsystem, making it possible to use an AIX 5L server as a complete network install server for multiple platforms.

Intel clients typically use DHCP and PXE (Pre-boot eXecution Environment) for booting over the network. And because x86-based clients cannot load more than 512 kB of code in the first boot stage, we need a special kernel known as Linux PXE kernel for the initial load when installing Linux these platforms. This kernel is responsible for transferring the network install kernel (and optionally a ramdisk) via TFTP and starting the installation.
For an IBM System p using BOOTP, there is only one file to load because IBM System p hardware does not have the 512 KB limitation.

### 4.7.1 Configuring DHCP

Before starting to configure the DHCP server, make sure that the bos.net.tcp.server fileset is installed. The DHCP server configuration file is located in `/etc/dhcpsd.cnf`. This configuration example is for a netboot DHCP server only, and should not be used to serve other DHCP clients.

By default, almost all parameters in `/etc/dhcpsd.cnf` are commented out. Example 4-177 shows which parameters have to be activated to set up DHCP as a netboot server. In order for the DHCP server to start, there has to be at least one network and one subnet defined. To solve this we define a dummy network and a dummy subnet.

One of the most important parameters is `supportBOOTP`, because this will enable the DHCP server to answer BOOTP requests, and thus support installation of IBM System p servers.

**Example 4-177  Example dhcpsd.cnf**

```plaintext
numLogFiles     4
logFileSize     100
logFileName     /var/log/dhcpsd.log
logItem ACTION
logItem INFO

leaseTimeDefault -1
supportBOOTP yes

# For DHCP to start, at least one network and one subnet is required
# Dummy network
network 172.16.0.0 255.255.255.253

# Dummy subnet
subnet 172.16.0.0       172.16.0.1-172.16.0.2
```

Do not start the DHCP server daemon yet, because BOOTP must be disabled and any existing NIM clients must be converted to use DHCP syntax.

**Disabling BOOTP**

The `bootp` service is started (default) by the `inted` subsystem. To list the services `inetd` is handling, run:

```
# lssrc -ls inetd
```
If BOOTP is enabled, you should see a line starting with `bootps`. If you do, edit `/etc/inetd.conf`, and comment out the following line:

```
bootps dgram udp wait root /usr/sbin/bootpd bootpd /etc/bootptab
```

Make the `inetd` daemon be aware of the change by issuing:

```
# refresh -s inetd
```

Run `lssrc -ls inetd` again, you should not see `bootps` in the list anymore.

**Converting to DHCP**

To enable the DHCP server to handle the existing NIM clients' BOOTP requests, their definitions must be converted to use DHCP instead of BOOTP. Before this is done, however, verify that the MAC (hardware) address is in the NIM definition for all clients because this is required for DHCP; see Example 4-178.

**Example 4-178   Checking the NIM definition of lpar5304**

```
root@master:/: lsnim -l lpar5304
Lpar5304:
class          = machines
type           = standalone
connect        = shell
platform       = chrp
netboot_kernel = mp
if1            = eth_nim lpar5304 0006298426AD
cable_type1    = tp
Cstate         = ready for a NIM operation
prev_state     = ready for a NIM operation
Mstate         = currently running
```

The MAC address shown in Example 4-178 is `0006298426AD`.

If the MAC address is not present, the client has to be updated with this information before the conversion is made. To get the MAC address of an AIX 5L client, issue the `lscfg` command (assuming `ent0` is the network install interface) as shown in Example 4-179.

**Example 4-179   Getting the MAC address of an AIX 5L client**

```
root@master:/: lscfg -vl ent0
ent0    P1/E1  IBM 10/100 Mbps Ethernet PCI Adapter (23100020)

Network Address...........0006298426AD
Displayable Message......PCI Ethernet Adapter (23100020)
Device Specific.(YL).....P1/E1
```

286   NIM from A to Z in AIX 5L
To update the client with the MAC address information, enter:

```
# nim -o change -a "if1=eth_nim lpar5304 0006298426AD" lpar5304
```

Alternatively, use SMIT to update this information (although this can be time-consuming if many clients have to be updated); see Example 4-180.

**Example 4-180  SMIT Change/Show characteristics of a machine**

<table>
<thead>
<tr>
<th>Change/Show Characteristics of a Machine</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type or select values in entry fields.</td>
</tr>
<tr>
<td>Press Enter AFTER making all desired changes.</td>
</tr>
</tbody>
</table>

```
[Entry Fields]

Machine Name                   [lpar5304]
* Hardware Platform Type       [chrp] +
* Kernel to use for Network Boot [mp] +
Machine Type                   standalone
Network Install Machine State  currently running
Network Install Control State  ready for a NIM operation
Primary Network Install Interface
   Network Name                 [eth_nim]
   Host Name                    [lpar5304]
   Network Adapter Hardware Address [0006298426AD]
   Network Adapter Logical Device Name [ent]
   Cable Type                   tp +
   Network Speed Setting        [] +
   Network Duplex Setting       [] +
   IPL ROM Emulation Device     [] +/
   CPU Id                       []
   Communication Protocol used by client [shell] +
   Comments                     []

Force                           no +

F1=Help                        F2=Refresh     F3=Cancel     F4=List
F5=Reset                       F6=Command     F7=Edit       F8=Image
F9=Shell                       F10=Exit       Enter=Do
```

After all NIM clients have their MAC addresses entered into their definitions, some kind of net_boot must be activated to make NIM update the /etc/bootptab file with the information we will later convert. For our example, we will enable a DIAG boot on all NIM clients. For one client issue the following command:

```
# nim -o diag_boot -a spot=spot5304 <client>
```

If there are many clients, a simple awk script will work:

```
for i in $(lsnim -t standalone|awk '{print $1}'); do
```
nim -o diag_boot -a spot=spotxxx $i
done

This may not work if some of the clients are currently in a state preventing operations on them. In this case, reset the clients by issuing this command:

nim -Fo reset <client>

To reset all clients defined, use the following:

for i in $(lsnim -t standalone|awk '{print $1}'); do
  nim -Fo reset $i
done

Then rerun the previous command to enable DIAG boot on all clients:

# nim -o diag_boot -a spot=spot5304 <client>

After all the NIM clients are allocated for network boot, use the AIX command `bootptodhcp` (which is part of `bos.net.tcp.server` fileset) to convert the `/etc/bootptab` file to DHCP format. See the man page of `bootptodhcp` for a detailed description of parameters. For our example, we use the `-d` flag to dump the output to a file other than `/etc/dhcpsd.cnf`; for example:

```
bootptodhcp -d /tmp/my_nim_clients.dhcp
```

The file `/tmp/my_nim_clients.dhcp` looks similar to the one in Example 4-181 on page 289.

You should see a list of all your NIM clients in a similar way. The file pointed to by option `bf /tftpboot/lpar5304` does not need to exist, because NIM will create this as a symbolic link when performing an install, diag, or maintenance operation.

Now we have all our NIM clients BOOTP definitions converted to DHCP and saved in this file, which we will use in the next section.

Before we continue, however, we reset the state of the NIM clients and deallocate the resources that were allocated during our DIAG command:

Reset a single client:

```
# nim -Fo reset <client>
```

Reset all NIM clients defined:

```
for i in $(lsnim -t standalone|awk '{print $1}'); do
  nim -Fo reset $i
done
```

Deallocation of all resources from a single client:

```
# nim -o deallocate -a subclass=all <client>
```
Deallocate all resources from all NIM clients defined:

```bash
for i in $(lsnim -t standalone|awk '{print $1}'); do
nim -o deallocate -a subclass=all $i
done
```

After the resources are deallocated, no entries should exist in the `/etc/bootptab` file other than the default comments.

Note that if new NIM clients are defined, they are not automatically added to `dhcpsd.cnf`. Instead, this action has to be done manually or automated with scripts.

**Merging files**

The next step is to merge the client definitions (`/tmp/my_nim_clients.dhcp`) with the `dhcpsd` configuration file. Append this file to `/etc/dhcpsd.cnf`, as shown:

```bash
cat /tmp/my_nim_clients.dhcp >> /etc/dhcpsd.cnf
```

**Note:** Use `>>`. Otherwise, your configuration file will be overwritten.

The configuration file looks like Example 4-181.

**Example 4-181   Example dhcpsd.cnf**

```bash
numLogFiles     4
logFileSize     100
logFileName     /var/log/dhcpsd.log
logItem         ACTION
logItem         INFO

leaseTimeDefault                -1
#leaseExpireInterval    3 minutes
supportBOOTP                    yes

# For DHCP to start, at least one network and one subnet is required
# Dummy network
network 172.16.0.0 255.255.255.253

# Dummy subnet
subnet 172.16.0.0       172.16.0.1-172.16.0.2

# BOOTP CLIENT: lpar5304
client 1 0006298426AD 192.168.234.19
{
    option 1 255.255.255.0
    option sa 192.168.234.10
    option bf "/tftpboot/lpar5304"
```
Enabling DHCP
Now that BOOTP is disabled, we can safely enable the DHCP server. Because we already configured dhcpsd.cnf, all we have to do is start the server. Note that dhcpsd is controlled by srcmstr; its configuration is shown in Example 4-182.

Example 4-182  Checking the dhcpsd configuration

```
root@master:/: lssrc -s dhcpsd
Subsystem   Group            PID          Status
dhcpsd      tcpip                         inoperative
```

Start the DHCP server, as shown in Example 4-183.

Example 4-183  startsrc -s dhcpsd

```
root@master:/: startsrc -s dhcpsd
0513-059 The dhcpsd Subsystem has been started. Subsystem PID is 327750.
```

Check if the server started, as shown in Example 4-184.

Example 4-184  lssrc -s dhcpsd

```
root@master:/: lssrc -s dhcpsd
Subsystem   Group            PID          Status
dhcpsd      tcpip            327750       active
```

Check if the clients are active for DHCP netboot, as shown in Example 4-185.

Example 4-185  lssrc -ls dhcpsd

```
Log File:                      /var/log/dhcpsd.log
Log Level:                     0x8c0
Client Expire Interval:        3600
Reserve Expire Interval:       900
Bad Addr Reclaim Interval:     4294967295
Database Save Interval:        3600
 IP Address       Status    Duration  Time Stamp    Client ID
---------------  --------  --------  ------------  -------------
  172.16.0.1       Free
  172.16.0.2       Free
 192.168.234.19   Free
We can see here that our client (192.168.234.19) is activated for netboot via DHCP.

To enable the DHCP server to start at boot time, edit /etc/rc.tcpip and uncomment the line starting with: #start /usr/sbin/dhcpsd "$src_running".

NIM does not handle DHCP, so all clients will still be able to boot from DHCP (BOOTP) as long as they are defined in /etc/dhcpsd.cnf and the dhcpsd daemon is running. This is not normally a problem with IBM System p systems, because the bootlist can be altered from the SMS menu, remotely from the service processor, or by using the bootlist command (in AIX).

Intel systems, on the other hand, do not have the same flexibility, and the boot order is often fixed with the netboot device before disk in the bootlist. This can cause a problem when the system boots and finds a DHCP server responding.

To get around this problem, the dhcpsd.cnf configuration file has to be altered to prevent the client from getting a response from the server. This can be done manually by editing the configuration file, or it can be automated with scripts.

Another solution would be to stop the dhcpsd server, but this would make installations for other clients impossible as well.

**Enabling tftp**

Trivial File Transfer Protocol (TFTP) is used to fetch the actual netboot kernel from a server after the boot has completed. This is done by BOOTP (IBM System p, DHCP (pxeboot, Linux), or AIX 5L).

IBM System p can fetch the entire kernel at once, but for Intel-based systems, the size is limited to 512 KB and we need a special PXE kernel to handle the rest. Anyway, tftp has to be enabled. This is also a service provided by the inetd daemon.

Check whether tftpd is active by running the command shown in Example 4-186; look for a line starting with:

```
tftp /usr/sbin/tftpd tftpd -n active
```

<table>
<thead>
<tr>
<th>Subsystem</th>
<th>Group</th>
<th>PID</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>inetd</td>
<td>tcpip</td>
<td>147528</td>
<td>active</td>
</tr>
</tbody>
</table>

**Example 4-186  Checking whether tftpd is active (in this case, it is not active)**

```
root@master:/: lssrs -ls inetd
Subsystem  Group  PID   Status
inetd      tcpip  147528 active
Debug      Not active
Signal     Purpose
SIGALRM    Establishes socket connections for failed services.
```
SIGHUP       Rereads the configuration database and reconfigures services.

SIGCHLD      Restarts the service in case the service ends abnormally.

<table>
<thead>
<tr>
<th>Service</th>
<th>Command</th>
<th>Description</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>xmquery</td>
<td>/usr/bin/xmtopas</td>
<td>xmtopas -p3</td>
<td>active</td>
</tr>
<tr>
<td>wsmserver</td>
<td>/usr/websm/bin/wsmserver</td>
<td>wsmserver -start</td>
<td>active</td>
</tr>
<tr>
<td>time</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>daytime</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>time</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>daytime</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>ntalk</td>
<td>/usr/sbin/talkd</td>
<td>talkd</td>
<td>active</td>
</tr>
<tr>
<td>exec</td>
<td>/usr/sbin/rexecd</td>
<td>rexecd</td>
<td>active</td>
</tr>
<tr>
<td>login</td>
<td>/usr/sbin/rlogind</td>
<td>rlogind</td>
<td>active</td>
</tr>
<tr>
<td>shell</td>
<td>/usr/sbin/rshd</td>
<td>rshd</td>
<td>active</td>
</tr>
<tr>
<td>telnet</td>
<td>/usr/sbin/telnetd</td>
<td>telnetd -a</td>
<td>active</td>
</tr>
<tr>
<td>ftp</td>
<td>/usr/sbin/ftpd</td>
<td>ftpd</td>
<td>active</td>
</tr>
</tbody>
</table>

If you do not find such a line, edit /etc/inetd.conf and uncomment the line starting with #tftpd, then refresh inetd:

    refresh -s inetd

Run lssrc -1s inetd again to verify that inetd has started; see Example 4-187.

Example 4-187   Checking for tftp service (here, it is active)

```bash
root@master:/: lssrc -1s inetd
Subsystem         Group            PID          Status
inetd            tcpip            147528       active
```

Debug       Not active
Signal       Purpose
SIGALRM      Establishes socket connections for failed services.
SIGHUP       Rereads the configuration database and reconfigures services.
SIGCHLD      Restarts the service in case the service ends abnormally.

<table>
<thead>
<tr>
<th>Service</th>
<th>Command</th>
<th>Description</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>xmquery</td>
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<td>xmtopas -p3</td>
<td>active</td>
</tr>
<tr>
<td>wsmserver</td>
<td>/usr/websm/bin/wsmserver</td>
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<td>active</td>
</tr>
<tr>
<td>time</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>daytime</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>time</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>daytime</td>
<td>internal</td>
<td></td>
<td>active</td>
</tr>
<tr>
<td>ntalk</td>
<td>/usr/sbin/talkd</td>
<td>talkd</td>
<td>active</td>
</tr>
<tr>
<td>tftp</td>
<td>/usr/sbin/ftpd</td>
<td>tftpd -n</td>
<td>active</td>
</tr>
<tr>
<td>exec</td>
<td>/usr/sbin/rexecd</td>
<td>rexecd</td>
<td>active</td>
</tr>
</tbody>
</table>
Directory structure setup

In this section, we are going to concentrate on installing Fedora5 Linux on an Intel PC and on an IBM System p system. The way to do it should not differ much from other Linux distributions.

Figure 4-9 shows the directory structure that was used for the installation.

```
/   
|   
--- tftpboot   
   |   
   --- pxelinux.cfg   
   |   
   --- fedora5   
   
--- export   
   |   
   --- fedora5   
   |       
   --- i386   
   |   
   --- ppc   
   |   
   --- kickstart
```

*Figure 4-9  Directory structure*

We recommend that each Linux distribution have its own file system for the install sources, about 3 GB to 5 GB in size, depending on the distribution.

To create one file system for Fedora5/i386™ and one for Fedora5/ppc on volume group vgnim, enter:

```
crfs -v jfs2 -g vgnim -m /export/fedora5/i386 -A yes -a size=5G
crfs -v jfs2 -g vgnim -m /export/fedora5/ppc -A yes -a size=5G
mount /export/fedora5/i386
mount /export/fedora5/ppc
```
Get the PXE Linux kernel
The Linux PXE kernel can be obtained from:

http://www.kernel.org/pub/linux/utils/boot/syslinux

The actual file you need (pxelinux.0) is included in a package called syslinux. Be sure to get a stable release of syslinux; for our examples, we used version 2.00 because it seems to work well.

http://www.kernel.org/pub/linux/utils/boot/syslinux/old/syslinux-2.00.tar.gz

Unpack the needed pxeboot.0 file using the gunzip utility found on the AIX 5L Toolbox for Linux Applications.

gunzip -c syslinux-2.00.tar.gz|tar -xf - syslinux-2.00/pxelinux.0

Copy the pxelinux.0 file to the /tftpboot/pxelinux.0.200 and create a symbolic link to the pxelinux.0, as shown in Example 4-188.

Example 4-188  Creating link to copied pxelinux.0 file

root@master:/: cp syslinux-2.00/pxelinux.0 /tftpboot/pxelinux.0.200
root@master:/: cd /tftpboot
root@master:/: ln -s pxelinux.0.200 pxelinux.0
ls -l

```
total 24
-dwrxr-xr-x 2 root  system  256 Jun 12 13:50 fedora5
lrwxrwxrwx 1 root  system  10820 Jun 12 12:00 pxelinux.0.200
lrwxrwxrwx 1 root  system  10820 Jun 12 12:00 pxelinux.0.200
lrwxr-xr-x 2 root  system  256 Jun 12 12:00 pxelinux.cfg
```

Linux install source creation
Next, copy the installation files to the NIM server. Copy the whole directory structure from the installation CDs to the file system we created earlier.

For each CD (or DVD) in the distribution, assuming /cdrom is the CD mount point, execute these commands:

For Fedora5/i386:

```
mount /cdrom
cp -Rhp /cdrom/* /export/fedora5/i386
umount /cdrom
```

For Fedora5/ppc:

```
mount /cdrom
cp -Rhp /cdrom/* /export/fedora5/ppc
umount /cdrom
```
For Fedora5/i386, the netboot kernel (installer) and ramdisk are located in directory images/pxeboot on the installation CD/DVD. Because we copied the entire contents of the CD/DVD, they are now in /export/fedora5/i386/images/pxeboot.

These files needs to be copied to the /tftpboot/fedora5 directory, preferably to a name that reflects the distribution and version.

Ownership, group, and permissions should also be checked. These files will be loaded by the Linux PXE kernel, when the initial boot stage is completed; see Example 4-189.

Example 4-189 Copying the Linux distribution files

```bash
cp /export/fedora5/i386/images/pxeboot/vmlinuz /tftpboot/fedora5/vmlinuz.fc5.i386
cp /export/fedora5/i386/images/pxeboot/initrd.img /tftpboot/fedora5/initrd.fc5.i386.img
chown root.system /tftpboot/fedora5/vmlinuz.fc5.i386
chown root.system /tftpboot/fedora5/initrd.fc5.i386.img
chmod 444 /tftpboot/fedora5/vmlinuz.fc5.i386
chmod 444 /tftpboot/fedora5/initrd.fc5.i386.img
```

For Fedora/ppc clients using BOOTP, only one kernel file has to be loaded during netboot, and the name of the file is the client hostname just as with NIM. The netboot kernel file, after we copied the installation CDs/DVD, is located in /export/fedora5/ppc/images/netboot.

There are two files in this directory, ppc32.img and ppc64.img to be used for a 32-bit kernel and 64-bit kernel, respectively. One of these files (or both) needs to be copied to the /tftpboot directory, preferably to a name that reflects the distribution, version and kernel.

Also check ownership, group, and permission on the file. A symbolic link must be created from this file to the client hostname when a network installation is going to be performed; refer to Example 4-190.

Example 4-190 Copying Linux distribution files and changing ownership permissions

```bash
cp /export/fedora5/ppc/images/netboot/ppc32.img /tftpboot/ppc32.fc5.img
cp /export/fedora5/ppc/images/pxeboot/ppc64.img /tftpboot/ppc64.fc5.img
chown root.system /tftpboot/ppc32.fc5.img
chown root.system /tftpboot/ppc64.fc5.img
chmod 444 /tftpboot/ppc32.fc5.img
chmod 444 /tftpboot/ppc64.fc5.img
```

In order for clients to access the installation source over NFS, you need to export the corresponding directory; add the following lines to the /etc/exports file:

```bash
/export/fedora5/i386 -sec=sys,ro
```
/export/fedora5/ppc -sec=sys,ro

Or execute these commands:

```
mknfsexp -d /export/fedora5/i386 -B -S sys -t ro
mknfsexp -d /export/fedora5/ppc -B -S sys -t ro
```

### 4.7.2 Intel PXE configuration

When booting an Intel client with the Linux PXE kernel, a configuration file is needed on the installation server to tell the small Linux PXE kernel where to find the actual netboot kernel and ramdisk image.

**Note:** This configuration file must be located in directory /tftpboot/pxelinux.cfg.

The name of the configuration file is the client's IP-address translated to upper case hexadecimal format. For example, if our client's IP-address is 192.168.234.19, then the configuration filename would be C0A8EA13 as shown in Table 4-3.

<table>
<thead>
<tr>
<th>Decimal</th>
<th>Hexadecimal</th>
</tr>
</thead>
<tbody>
<tr>
<td>192</td>
<td>C0</td>
</tr>
<tr>
<td>168</td>
<td>A8</td>
</tr>
<tr>
<td>234</td>
<td>EA</td>
</tr>
<tr>
<td>19</td>
<td>13</td>
</tr>
</tbody>
</table>

Newer versions of the Linux PXE kernel will first look for a filename of the client's ARP type code and hardware address in lower case hexadecimal with dash (-) separators. For example, with an Ethernet (ARP type 1) adapter with address 88:99:AA:BB:CC:DD, the Linux PXE kernel will search for a filename like 01-88-99-aa-bb-cc-dd.

Refer to the documentation included with the Linux PXE kernel for more details.

We recommend that you make the configuration files a symbolic link to a filename that is easier to remember (for example fedora5.manual or fedora5.auto).

```
cd /tftpboot/pxelinux.cfg
ln -s C0A8EA13 fedora5.manual
```

The format of the configuration file for Fedora5/i386 is shown in Example 4-191.
This is a basic configuration file that simply loads the netboot kernel and the ramdisk image. The installation on the client will be manual just as if installed with a CD/DVD. Table 4-4 shows the configuration line entry and its description.

### Table 4-4  Basic configuration file line entry and its description

<table>
<thead>
<tr>
<th>Line entry</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td># Install</td>
<td>Comment</td>
</tr>
<tr>
<td>SERIAL 0 9600</td>
<td>Enables serial port to act as a console</td>
</tr>
<tr>
<td>DEFAULT fedora5</td>
<td>Sets the default command line</td>
</tr>
<tr>
<td>LABEL fedora5</td>
<td>A label of the kernel to boot</td>
</tr>
<tr>
<td>KERNEL fedora5/vmlinuz.fc5.i386</td>
<td>Kernel image to boot</td>
</tr>
<tr>
<td>APPEND root=/dev/ram console=/dev/tty1 initrd=fedora5/initrd.fc5.i386.img</td>
<td>Options appended to the kernel command line</td>
</tr>
</tbody>
</table>

It is possible to specify more options on the APPEND line; for example, to use a kickstart installation for a completely unattended installation. Detailed information about kickstart installation is beyond the scope of this book, but a sample configuration file using kickstart is provided in Example 4-192.

Example 4-192  /tftpboot/pxelinux.cfg/fedora5.auto

```
# Install
SERIAL 0 9600
DEFAULT fedora5
LABEL fedora5
KERNEL fedora5/vmlinuz.fc5.i386
APPEND root=/dev/ram console=/dev/tty1 initrd=fedora5/initrd.fc5.i386.img
ks=nfs:192.168.234.10:/export/fedora5/kickstart/kickstart.fc5.i386.fedora5 ksdevice=eth0
PROMPT 0
```

This requires a kickstart configuration file; for information on Anaconda, the Fedora Linux installer, and Kickstart, see:

http://www.fedora.redhat.com
PPC configuration

Because Fedora/ppc uses BOOTP for booting over the network, there are no configuration files to edit. When the system boots, a manual installation can be performed just as when booting with a CD/DVD.

As an alternative, kickstart can be used to automate the installation on ppc systems, but since it is currently not possible to append any command line parameters to the netboot kernel, they have to be specified at the firmware prompt. The Open Firmware prompt as shown in Example 4-193 can be accessed by pressing F8 at boot time.

Example 4-193  Open firmware prompt

```
1 = SMS Menu                             5 = Default Boot List
6 = Stored Boot List                     8 = Open Firmware Prompt

memory    keyboard    network    scsi    speaker    ok
```

```
0>boot net ks=nfs:/192.168.234.10:/export/fedora5/kickstart/kickstart.i386.fedora5
```

The installation proceeds in kickstart mode just as with the automated PXE configuration.

4.8 Common Operating System Image (COSI) management

With the emergence of IBM Virtualization Engine™, the desire to create partitions using shared processors, virtual network interfaces, virtual disks and using NIM as the focal point for system management is becoming significantly more important.

Also, the appeals to maximize hardware and software resource utilization have prompted the reuse of NIM diskless and dataless clients as a more cost-effective solution to representing the logical partition carved up from the managed system.

Diskless clients are machines without disks; dataless clients are machines that have disks, but lack the necessary information to operate independently. Neither of these types of machines have the capability to boot by themselves, and they must rely on a common boot image, along with a NIM SPOT and other file system resources that reside on some server on the network, to operate correctly. The same resources can be used among different clients.
The original concept of diskless and dataless clients for use as graphical workstations has changed. For this reason, the term “thin server” is being used to describe these types of machines because of their limited and remote resource requirement. The term “common image” is used to describe the SPOT resource used by the thin servers.

In the following section, we define this terminology in more detail.

### 4.8.1 Thin server, diskless, dataless, and Common Operating System Image

**Thin server**

As mentioned, a thin server is a machine that lacks the physical hardware or software to allow it to operate independently. This machine must rely on remote resources such as a Common OS Image (COSI) to operate correctly. The thin server will encompass both a diskless and a dataless machine.

**Diskless machine**

As mentioned, a diskless machine is a machine that lacks a physical disk and must rely on a SPOT resource, a root resource, a dump resource, and a paging resource to run. Other, optional resources that a diskless machine uses are tmp, home, and shared_home.

**Dataless machine**

A dataless machine has a physical disk, but the disk holds no local operating system. This machine must rely on a spot resource for its operating system. It also requires a root resource and a dump resource. The paging resource is not required because the local disk can be used for paging. Other, optional resources that a dataless machine uses are tmp, home, and shared_home.

**Thin server resources**

The following resources are provided by a NIM master or NIM resource server for the thin server clients to function, in either diskless or dataless mode:

**root**

This is defined as a directory that will be NFS-mounted by thin server clients for storing a client’s / (root) directories. When a client is initialized, the root resource will be populated with a client's configuration files. These configuration files are copied from the SPOT/COSI resource used by a client to boot, and as its operating system.
dump
This is defined as a directory that will be NFS-mounted by thin server clients for use as a dump device by the client for storing a client's dump files.

paging
This is defined as a directory that will be NFS-mounted by thin server clients for use as a paging device by the client.

home
This is defined as a directory that will be NFS-mounted by thin server clients for storing a client's specific /home directories.

shared_home
This is defined as a /home directory shared by all clients. All thin server clients that use a shared_home resource will mount the same directory as the /home file system.

tmp
This is defined as a directory that will be NFS-mounted by thin server clients for use as a /tmp file system on the clients.

cosi
A Common OS Image (COSI) is a repository that contains all the necessary software to bring thin server clients up to a functional state. For AIX systems, it is a Single Product Object Tree (SPOT) and provides a /usr file system.

Note: The term COSI replaces the term SPOT for the tasks of managing thin servers and common images without requiring users to understand NIM.

Thin server commands
With AIX 5L V5.3 TL5, the following new commands to manage Common OS Images and thin servers are introduced:

`mkcosi` Makes a Common Operating System Image (COSI) for use with thin servers.

`lscosi` List information related to a Common Operating System Image (COSI).

`chcosi` Change a Common Operating System Image (COSI).

`cpcosi` Clone a Common Operating System Image (COSI).

`rmcosi` Remove a Common Operating System Image (COSI).

`mkts` Make a thin server.

`swts` Switch a thin server to a different COSI.

`lsts` List information related to a thin server.

`rmts` Remove a thin server.

`dbts` Debug a thin server.

The COSI and thin server management can also be accessed through the SMIT tscosi_client fast path.
Chapter 4. Network Installation Manager scenarios

Note: The thin server commands use the NIM master database and the **nim command** can be used to manipulate the thin server NIM environments, just as if they were diskless or dataless NIM clients.

You can also use the **nim** command directly for several thin server operations such as to reboot a thin server named LPAR55 in NIM:

```bash
# nim -o reboot LPAR55
```

On a NIM COSI object, these are the operations you can perform using the **nim** command directly:

- **reset**: Reset the COSI’s NIM state
- **define**: Define a COSI
- **change**: Change a COSI’s attributes
- **remove**: Remove a COSI
- **cust**: Perform software customization
- **sync_roots**: Synchronize roots for all clients using a specified COSI
- **showres**: Show contents of a COSI
- **maint**: Perform software maintenance
- **lslpp**: List LPP information about the COSI
- **fix_query**: Perform queries on installed fixes
- **showlog**: Display a log in the NIM environment
- **check**: Check the status of the COSI
- **lppchk**: Verify installed filesets in the COSI

On a NIM thin server object, these are the operations you can perform using the **nim** command directly, depending on whether it is diskless or dataless:

- **define**: Define a diskless or dataless thin server
- **change**: Change a thin server’s attributes
- **remove**: Remove an thin server
- **allocate**: Allocate a resource for use by a thin server
- **deallocate**: Deallocate a resource
- **dkls_init**: Initialize a diskless thin server environment
- **dtls_init**: Initialize a dataless thin server environment
- **diag**: Enable a thin server to boot a diagnostic image
- **reset**: Reset a thin server’s NIM state
- **check**: Check the status of a thin server
- **reboot**: Reboot specified thin server
- **showlog**: Display a log in the NIM environment
- **dbts**: Perform a dbts operation on a thin server
- **swts**: Perform a swts operation on a thin server
4.8.2 Creating a Common OS Image

Assuming we have stored all necessary filesets for AIX 5L V5.3 with TL5 in the /usr/sys/inst.images directory, we use the `mkcosi` command to create a COSI, as shown in Example 4-194.

Example 4-194 Creating a Common Operating System Image (COSI) resource

```
root@master:/: mkcosi -s /usr/sys/inst.images -l /export/cosi cosi5305
```

Defining cosi5305_106646_1pp object...Preparing to copy install images (this will take several minutes)...

```
/export/cosi/cosi5305_106646_1pp/RPMS/ppc/cdrecord-1.9-7.aix5.2.ppc.rpm
/export/cosi/cosi5305_106646_1pp/RPMS/ppc/mkisofs-1.13-4.aix4.3.ppc.rpm
/export/cosi/cosi5305_106646_1pp/installp/ppc/xlC.aix50.8.0.0.0.I

Now checking for missing install images...
All required install images have been found. This lpp_source is now ready.
done
```

Defining cosi5305 object...
Creating SPOT in "/export/cosi" on machine "master" from "cosi5305_106646_1pp" ...

```
Restoring files from BOS image. This may take several minutes ...
Installing filesets ...

Be sure to check the output from the SPOT installation
to verify that all the expected software was successfully
installed. You can use the NIM "showlog" operation to
view the installation log file for the SPOT.
done
```

Removing cosi5305_106646_1pp object definition...done

When the `mkcosi` command starts, it creates a temporary NIM lpp_source, so we must ensure that the location file system has enough space to accommodate this requirement. Example 4-195 shows the temporary NIM lpp_source created in Example 4-194.

Example 4-195 Displaying information on temporary lpp_source for COSI creation

```
cosi5305_106646_1pp:
class       = resources
type        = lpp_source
locked      = 258218
Rstate      = unavailable for use
prev_state  =
location    = /export/cosi/cosi5305_106646_1pp
```
To display information about a COSI, we use the `lscosi` command. It has both a debugging verbose flag `-v`, and a detail verbose level flag `-l`, with levels 1, 2 and 3, to provide the user with detailed information. The `lscosi` command, with level one, is equivalent to the `lsnim` command with the `-l` flag; see Example 4-196.

**Example 4-196  Using the lscosi command**

```
root@master:/: lscosi -l1 cosi5305

cosi5305:
   class         = resources
   type          = spot
   plat_defined  = chrp
   arch          = power
   Rstate        = ready for use
   prev_state    = verification is being performed
   location      = /export/cosi/cosi5305/usr
   version       = 5
   release       = 3
   mod           = 0
   oslevel_r     = 5300-05
   alloc_count   = 1
   server        = master
   if_supported  = chrp.mp ent
   Rstate_result = success
```

To remove a COSI, use the `rmcosi` command:

```
root@master:/: rmcosi cosi5305
```

### 4.8.3 Creating a thin server

Use the `mkts` command to create resources to bring up a thin server, except the COSI, which has to be already available. The `mkts` command will initialize the thin server and create the dump, tmp, root, paging, home and shared_home NIM resources, if the resources do not exist and their respective flags were specified.

The `mkts` command uses the `/export/nim` directory to create the necessary resources for the client, and the equivalent of a dataless machine. To create a diskless thin server, use the `-l` option, as shown in Example 4-197.

**Example 4-197  Using mkts to define a thin server definition**

```
root@master:/: mkts -i 10.1.1.55 -m 255.255.255.0 -g 10.1.1.1 -c cosi5305 -l LPAR55
```
Checking /export/nim space requirement...Defining LPAR55 object...done

Installing software in the root directories of any diskless or dataless clients served by this SPOT. This may take several minutes ...

If you get a message similar to the following one, create a /export/nim file system with enough space for the NIM resources that mkts is going to create:

dspmsg: Invalid argument index in message. May need more arguments on the command line.
Checking define_ts[31]: 9.27 >
blocks^J143.70^J71.14^J21.98^J32.63^J13.13^J--^J1
7.72^J39.52^J2821.70^J1579.36 : syntax error

To display information about a thin server, use the lsts command as shown in Example 4-198. It has both a debugging flag (verbose -v), and a detail verbose level flag (-l), with levels 1, 2 and 3, to provide the user with detailed information. The lsts command, with level one, is equivalent to the lsnim command with the -l flag.

Example 4-198  Using lsts to display thin server definition

root@master:/: lsts -l1 LPAR55
LPAR55:
  class = machines
  type = dataless
  comments = dataless client defined with mkts
  platform = chrp
  netboot_kernel = mp
  if1 = net_10_1_1 lpar55 0
  cable_type1 = N/A
  Cstate = dataless install has been enabled
  prev_state =
  Mstate = currently running
  boot = boot
  dump = dump
  root = root
  spot = cosi5305
  control = master

For our thin server, the /usr-COSI (formerly known as SPOT) together with the root, dump and paging file systems have been exported (/etc/exports), and can be viewed using the exportfs command as follows:

/export/cosi/cosi5305/usr -ro,root=lpar55:,access=lpar55:
/export/nim/root/LPAR55 -root=lpar55:,access=lpar55:
/export/nim/dump/LPAR55 -root=lpar55:,access=lpar55:
/export/nim/paging/LPAR55 -root=lpar55:,access=lpar55:
And in the /etc/bootptab file, there is a created network boot entry as follows:

```
lpars:bf=/tftpboot/lpar55:ip=10.1.1.55:ht=ethernet:sa=10.1.1.2:sm=255.255.255.0:
```

<table>
<thead>
<tr>
<th>BootP R = 1 BootP S = 2</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>FILE: /tftpboot/lpar55</strong></td>
</tr>
<tr>
<td><strong>FINAL Packet Count = 24729</strong></td>
</tr>
<tr>
<td><strong>FINAL File Size = 12660736 bytes.</strong></td>
</tr>
<tr>
<td><strong>load-base=0x4000</strong></td>
</tr>
<tr>
<td><strong>real-base=0x2000000</strong></td>
</tr>
</tbody>
</table>

```
. . .
```

```
***** Please define the System Console. *****
```

```
. . .
```

```
Saving Base Customize Data to boot disk
Starting the sync daemon
Starting the error daemon
System initialization completed.
Starting Multi-user Initialization
Performing auto-varyon of Volume Groups
Activating all paging spaces
Performing all automatic mounts
```

**Figure 4-10  Booting a thin server**

Now the thin server should be up and running using the NIM resource server for each of its needed resources, as shown in Figure 4-10.

Example 4-199 shows sample commands to illustrate the file system environment in the thin server. This particular thin server is created as a diskless thin server, but it has one disk allocated even though it is not currently used.

**Example 4-199  Commands on the thin server**

```
root@master:/: rsh lpar55
```

```
*******************************************************************************
*                                                                             *
*                                                                             *
*  Welcome to AIX Version 5.3!                                               *
*                                                                             *
*                                                                             *
*  Please see the README file in /usr/lpp/bos for information pertinent to    *
*  this release of the AIX Operating System.                                 *
*                                                                             *
*                                                                             *
*******************************************************************************
```
# mount

<table>
<thead>
<tr>
<th>node</th>
<th>mounted</th>
<th>mounted over</th>
<th>vfs</th>
<th>date</th>
<th>options</th>
</tr>
</thead>
<tbody>
<tr>
<td>master</td>
<td>/export/nim/root/LPAR55 /</td>
<td>nfs3</td>
<td>Jun 27 16:04</td>
<td>rw,hard,intr,llock,acl</td>
<td></td>
</tr>
<tr>
<td>master</td>
<td>/export/cosi/cosi5305/usr /usr</td>
<td>nfs3</td>
<td>Jun 27 16:04</td>
<td>ro,hard,intr,llock,acl</td>
<td></td>
</tr>
</tbody>
</table>

# lsps -a

<table>
<thead>
<tr>
<th>Page Space</th>
<th>Physical Volume</th>
<th>Volume Group</th>
<th>Size</th>
<th>%Used</th>
<th>Active</th>
<th>Auto</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>swapnfs0</td>
<td>---</td>
<td>---</td>
<td>64MB</td>
<td>2</td>
<td>yes</td>
<td>yes</td>
<td>nfs</td>
</tr>
</tbody>
</table>

# ipl_varyon -i

<table>
<thead>
<tr>
<th>PVNAME</th>
<th>BOOT DEVICE</th>
<th>PVID</th>
<th>VOLUME GROUP ID</th>
</tr>
</thead>
<tbody>
<tr>
<td>hdisk0</td>
<td>NO</td>
<td>00cc544ecd114572000000000000000000 00cc544e00004c00</td>
<td></td>
</tr>
</tbody>
</table>

# lspv

| hdisk0 | 00cc544ecd114572 | None |

# lsvg

0516-318 lsvg: No volume groups found.

To modify the / (root) file system for the thin server shown in Example 4-199 on page 305, edit files in /export/nim/root/LPAR55 directory, and for the thin server /usr file system, edit files in the /export/cosi/cosi5305/usr directory.

4.8.4 Remove a thin server

To remove a thin server definition, use the rmts command. In Example 4-200, we first try to remove the LPAR55 thin server. Because it is not online in the first example, the command fails and we rerun it with the force flag -f.

Example 4-200 Using rmts to remove a thin server definition

```
root@master:/: rmts LPAR55
Removing LPAR55 object definition...failed
rmts: Unable to remove LPAR55.
Try using the force flag.

root@master:/: rmts -f LPAR55
Uninitializing LPAR55.
Removing LPAR55 object definition...done
```

Using the nim command operation deallocate in the following example will cause all remotely mounted resources to be removed from use by the thin server (in this case, LPAR55):

```
# nim -Fo deallocate -a subclass=all LPAR55
```
This will cause all I/O to be blocked because the NFS file systems will no longer be available.

4.9 Using HACMP with HANIM

Starting with AIX 5L V5.3, Network Installation Manager (NIM) provides an integrated high availability feature called HANIM, which is presented in 4.1, “High Availability Network Installation Manager” on page 124.

However, when using HANIM, the NIM master and the alternate NIM master are not aware of each other’s state (because there is no keep alive information between primary and alternate NIM masters). The takeover of the role as acting NIM master is based on whether or not NIM clients want to use a specific system as their NIM master. The NIM master for a NIM client is specified in the clients’ /etc/niminfo file.

In this section, we show how IBM High Availability Cluster Multi-Processing (HACMP) can be used to automate HANIM takeover operations. The HACMP configuration shown is minimal, and the purpose is to automate the start and stop of the nimesis daemon under the control of SRC, and issue the appropriate nim commands to perform a takeover of NIM clients.

Note: Because HANIM does not make use of shared storage, HACMP is not involved in any disk takeover operation.

In this section, we use the following three POWER5 logical partitions as shown in Figure 4-11 on page 308:

1par55 This is the first and original NIM master (HACMP cluster node one).
1par56 This is the first and alternate NIM master (HACMP cluster node two).
1par6 This is the first and only NIM client (already running as a NIM client to another NIM master environment).
All LPARs are configured using a VIO server for disk and network resources, and CPU micro-partitioning, as shown in Example 4-201.

Example 4-201  Basic LPAR config for HACMP HANIM examples

root@lpar56:/ lscfg -vl hdisk0
    hdisk0 U9111.520.65C544E-V6-C2-T1-L810000000000 Virtual SCSI Disk Drive

root@lpar56:/ lscfg -vl ent0
    ent0 U9111.520.65C544E-V6-C3-T1 Virtual I/O Ethernet Adapter (I-lan)

    Network Address.............223380006003
    Displayable Message.........Virtual I/O Ethernet Adapter (I-lan)
    Device Specific.(YL)........U9111.520.65C544E-V6-C3-T1

root@lpar56:/ lparstat -h
System configuration: type=Shared mode=Capped smt=On lcpu=2 mem=512 psize=2 ent=0.10
...

The HACMP configuration will only use the ent0 network virtual network adapter on the cluster nodes, and all NIM database and resource file systems will be local to each of the two cluster nodes. HANIM functionality will be used to keep the database synchronized and resources replicated.
The HACMP configuration is made using these assumptions and requirements regarding availability:

- The systems management personnel shall not have to restore and reconfigure the NIM server in case of hardware failure.
- The longest downtime for the NIM server shall be two hours.
- Hardware failures might occur during the NIM servers’ lifetime, but it is unlikely.
- Planned downtime will occur during the NIM servers’ lifetime to install new firmware or system updates.
- In case of network failure, the NIM master can fail over to the alternate master.
- There will not be any service IP address, because HANIM will manage the NIM environment.
- In case of disk failure, the NIM master can fail over to the alternate master.

Based on the assumptions and requirements, we used the following software levels: AIX 5L V5.3 TL5, RSCT 2.4.5, and HACMP 5.4 (use SUMA to download updates to AIX 5L, RSCT and HACMP, respectively).

After the NIM master completes the BOS rte install of the LPARs used in this section, they are customized with the nim commands in Example 4-202 (becoming HACMP nodes).

The NIM client name, as shown in Example 4-202, is LPAR55. First, it is defined in the acting NIM master (hostname master), then an AIX 5L V5.3 TL5 SPOT (cosi5305) and NIM lpp_source (lpp5305) are allocated, and finally the bos_inst operation is performed to reinstall the NIM client. After these steps, some additional bos filesets are installed together with the bos.sysmgt.nim.master fileset for NIM master functionality itself. Then the rsct.basic.hacmp and rsct.basic.rte and cluster.es.server filesets for HACMP are installed. The same steps are done for LPAR56.

### Example 4-202  NIM master additional software updates of HACMP nodes

```bash
root@master:/: nim -o define -t standalone -a if1="net_10_1_1 lpar55 0" LPAR55
root@master:/: nim -o allocate -a spot=cosi5305 -a lpp_source=lpp5305 LPAR55
root@master:/: nim -o bos_inst -a source=rte LPAR55
```
Now we configure HACMP, and synchronize the HACMP nodes (lpar55 and lpar56), and bring up the cluster. First we make sure that /etc/hosts on each node contain the IP-address of both HACMP cluster nodes and of the client, lpar6. For our purposes, we use the following IP-addresses:

10.1.1.55 lpar55
10.1.1.56 lpar56
10.1.1.6 lpar6

We also adds the NSORDER variable to /etc/environment to ensure that we use the local systems /etc/hosts file to resolve hostnames to IP-addresses (we could also use the /etc/netsvc.conf or /etc/irs.conf files for the same purpose, see “Setting up IP name resolution” on page 65):

NSORDER=local,bind

Because we use rsh to communicate between the HACMP cluster nodes, we update the /.rhosts and /usr/sbin/cluster/etc/rhosts file on each node. We include the IP-address of the other nodes IP-address in each file.

The /.rhosts looks like this in HACMP node lpar55:

10.1.1.56 root

And /usr/sbin/cluster/etc/rhosts on lpar55 looks like this:

10.1.1.56

The .rhosts on lpar56 looks like this:

10.1.1.55 root

And /usr/sbin/cluster/etc/rhosts on lpar56 looks like this:

10.1.1.55

We update the /usr/sbin/cluster/netmon.cf file and put IP addresses of known hosts to PING (because we only use a single network interface on each HACMP cluster node, and this will let our local node determine if it has a working network, when it cannot communicate with the other cluster node). In our case, we use the default gateway only:

10.1.1.254
HACMP configuration

Now we are ready to issue the first HACMP cluster command to initiate the HACMP cluster itself. Call it NIMESIS.

```
claddclstr -n NIMESIS
```

We continue by adding our two nodes, the NIM master (`lpar55`) and alternate NIM master (`lpar56`), picking up the communications interface (`-p`) from `/etc/hosts`:

```
clnodename -a lpar55 -p lpar55
clnodename -a lpar56 -p lpar56
```

We let HACMP collect information about disks on the nodes (but we will not use this information further):

```
clharvest_vg -w
```

Now we can create the default network and allow IP-address takeover to be performed via IP aliases (even if we will not use any specific service IP-address in the cluster):

```
c1modnetwork -a -n master_net -i ether -s 255.255.255.0 -l yes
```

We add the boot IP-addresses for each node to the HACMP `master_net` Ethernet network:

```
claddnode -a lpar55:ether:master_net::boot: -n lpar55
claddnode -a lpar56:ether:master_net::boot: -n lpar56
```

To create the HACMP resource group, for the NIM master functionality, we first create the resource group itself:

```
claddgrp -g NIMESIS -n "lpar55 lpar56" -S "OHN" -0 "FNPN" -B "NFB"
```

We create the HACMP application server for automating the HANIM takeover functionality (see “HACMP start and stop scripts for HANIM” on page 317 for more details about the scripts):

```
claddserv -s"NIMESIS" -b /local/rg/start.nimesis -e /local/rg/stop.nimesis
```

We add the HACMP application server (NIMESIS) to the HACMP resource group (NIMESIS):

```
claddres -g NIMESIS APLICATIONS=NIMESIS
```

Note: The HACMP cluster commands to create a HACMP cluster are in the `/usr/es/sbin/cluster/utilities/` directory. Include this in your path, or prefix each `cl` command shown here with the full path, or it will not work.
The additional configuration is to add the HACMP application server scripts on both nodes to be kept in sync by HACMP. This can easily be done by creating a file collection and adding the script files to this collection:

```bash
clfilecollection -o coll -a start_stop 'application start and stop scripts'
yes yes
clfilecollection -o file -a start_stop /local/rg/start.nimesis
clfilecollection -o file -a start_stop /local/rg/stop.nimesis
```

Now the cluster is configured. We just need to verify and synchronize with the peer node (lpar56) correcting minor errors if there are any; see Example 4-203.

```bash
cldare -rt -i -b -C yes
```

**Example 4-203  Partial output from cldare -rt -i -b -C yes**

The following file collections will be processed:
- start_stop
Starting file propagation to remote node lpar56.
- Successfully propagated file /local/rg/start.nimesis to node lpar56.
- Successfully propagated file /local/rg/stop.nimesis to node lpar56.
- Total number of files propagated to node lpar56: 2
- Verification to be performed on the following:
  - Cluster Topology
  - Cluster Resources
- Verification will automatically correct verification errors.

Reading Cluster Topology Configuration...
Retrieving data from available cluster nodes. This could take a few minutes....
VERIFICATION NAME: base.ver_determine_active_cluster
Thu Jun 29 16:49:13 2006

Determine if one or more nodes in the cluster are active.

... Committing any changes, as required, to all available nodes...
Verification has completed normally.

**Checking the HACMP cluster configuration**

Now we have a HACMP cluster with two nodes, one Ethernet interface each, nothing shared, and with one resource group. Example 4-204 shows our configuration displayed with the `cltopinfo` and `cllsres` commands.

**Example 4-204  HACMP cluster displayed with cltopinfo -i and cllsres**

```bash
root@lpar55:/: cltopinfo -i
IP Label Network Type Node Address If Netmask
======== ====== ==== ====== ==== =======
1par55 master_net ether 1par55 10.1.1.55 en0 255.255.255.0
1par56 master_net ether 1par56 10.1.1.56 en0 255.255.255.0
```
HANIM takeover operation

If a NIM client's /etc/niminfo file looks like the first example (lpar6, in this case), after the takeover operation is performed (from lpar55, in this case), it will be changed to look like the second example; see Example 4-205.

Example 4-205  Changes to a NIM clients /etc/niminfo file by nim -o takeover

{lpar6}: # cat /etc/niminfo
#------------------ Network Install Manager ----------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
export NIM_NAME=lpar6
export NIM_HOSTNAME=lpar6
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=lpar56
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_MASTER_HOSTNAME_LIST="lpar56 lpar55"
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS=" 10.1.1.6:lpar6 10.1.1.56:lpar56 "
export NIM_MOUNTS=""

{lpar6}: nim -o takeover lpar56

{lpar6}: # cat /etc/niminfo
#------------------ Network Install Manager ----------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
export NIM_NAME=lpar6
export NIM_HOSTNAME=lpar6
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=lpar55
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_MASTER_HOSTNAME_LIST="lpar55 lpar56"
The nim command with the takeover operation are the core of what we use in our HACMP application start script.

**Starting the HACMP HANIM cluster**

To start the HACMP HANIM cluster, you can use the SMIT clstart fast path as shown in Figure 4-12. Select the node you want to start the cluster manager on, in this case lpar55 (we prefer to start the cluster managers sequentially and one at a time, at least until the primary node is up).

![Figure 4-12   Starting HACMP cluster node](image)

After the same clstart has been performed for the second HACMP node (lpar56), we check the status of our NIMESIS resource group with the clRGinfo or clfindres commands as shown in Example 4-206.

**Example 4-206   Using clRGinfo**

```
root@lpar55:/: clRGinfo
----------------------------------------------------------------------------
Group Name     Group State                  Node
----------------------------------------------------------------------------
NIMESIS        ONLINE                       lpar55
OFFLINE                      lpar56
```

We stop the NIMESIS resource group with the clRGmove command on lpar55, as shown in Example 4-207 on page 315.
Example 4-207 Using clRGmove to stop the HANIM resource group

root@lpar55:/: clRGmove -g NIMESIS -n lpar55 -d
Attempting to bring group NIMESIS offline on node lpar55.

Waiting for the cluster to process the resource group movement request....

Waiting for the cluster to stabilize..........

Resource group movement successful.
Resource group NIMESIS is offline on node lpar55.

We start the NIMESIS resource group with the clRGmove command on lpar56, as shown in Example 4-208.

Example 4-208 Using clRGmove to start the HANIM resource group

root@lpar55:/: clRGmove -g NIMESIS -n lpar56 -u
Attempting to bring group NIMESIS online on node lpar56.

Waiting for the cluster to process the resource group movement request....

Waiting for the cluster to stabilize..........

Resource group movement successful.
Resource group NIMESIS is online on node lpar56.

We move the NIMESIS resource group with the clRGmove command from lpar56 to lpar55, as shown in Example 4-209.

Example 4-209 Using clRGmove to move the HANIM resource group

root@lpar55:/: clRGmove -g NIMESIS -n lpar55 -m
Attempting to move resource group NIMESIS to node lpar55.

Waiting for the cluster to process the resource group movement request....

Waiting for the cluster to stabilize..........

Resource group movement successful.
Resource group NIMESIS is online on node lpar55.

Checking the movement with clfindres shows the process during the movement as shown in Example 4-210.

Example 4-210 Checking HANIM resource group transfer between nodes

root@lpar55:/: clfindres
To examine how the HACMP cluster is performing, you can check the logfiles. For example, to check the /tmp/hacmp.out file on each cluster node, you can use the different `cl` commands, the `lssrc` command, or the `lsrsrs` command; Example 4-211 shows a few samples.

**Example 4-211  Examining the topology services daemon with lssrc -ls topsvcs**

```
root@lpar55:~ lssrc -ls topsvcs

Subsystem Group PID Status
  topsvcs   topsvcs 696454 active

Network Name Index Defd Mbrs St Adapter ID Group ID
   master_net_0  [0] 2 2 S 10.1.1.55 10.1.1.56
   master_net_0  [0] en0 0x44a3eff8 0x44a3f07b

HB Interval = 1.000 secs. Sensitivity = 10 missed beats
Missed HBs: Total: 0 Current group: 0
  ...
Fast Failure Detection available but off.
   Dead Man Switch Enabled:
      reset interval = 1 seconds
      trip interval = 20 seconds
   Configuration Instance = 20
  ...
User time 0 sec. System time 0 sec.
   Number of page faults: 0. Process swapped out 0 times.
   Number of nodes up: 2. Number of nodes down: 0.
```

Using the `lssrc` command to display information about the HACMP cluster manager shows the Dynamic Node Priority values (DNP) for node `lpar55` and
1par56 (in our simplified example, we do not use these features); see Example 4-212.

**Example 4-212  Examining the HACMP cluster manager with lssrc -ls clstrmgrES**

```bash
root@lpar55:/: lssrc -ls clstrmgrES
Current state: ST_STABLE
sccsid = "@(#)36   1.135.1.60   src/43haes/usr/sbin/cluster/hacmp/trd/main.C, hacmp
p.pe, 52haes_r540, r5400622c 5/30/06 17:21:27"
i_local_nodeid 0, i_local_siteid -1, my_handle 1
There are 0 events on the Ibcast queue
There are 0 events on the RM Ibcast queue
CLversion: 9
local node vrmf is 5400
cluster fix level is "0"
The following timer(s) are currently active:
The following timer(s) are currently active:
Current DNP values
DNP Values for NodeId - 1  NodeName - lpar55
    PgSpFree = 129807  PvPctBusy = 0  PctTotalTimeIdle = 99.708770
DNP Values for NodeId - 2  NodeName - lpar56
    PgSpFree = 130348  PvPctBusy = 0  PctTotalTimeIdle = 99.248557
```

**HACMP start and stop scripts for HANIM**

Now we look at our HACMP scripts, as shown in Figure 4-13 on page 318. We use one script to start our services, and one script to stop our services. Because we use HANIM, the stop part is only to stop the nimesis SRC demon (the NIM master daemon).

The start script will make sure that the nimesis SRC daemon is started and will collect some information regarding the running cluster before it issues a nim command ordering takeover from the alternate NIM master (just in case it was the acting master for the NIM clients).

We have created the /local file system on each node, and a directory called rg in this file system. We place the scripts in the /local/rg directory and make sure they are synchronized between the cluster nodes.
In both scripts, we always end with a trap to ensure we return zero (0) as the exit value. A non-zero return value from a HACMP application server will cause the HACMP resource group to fail and require recovery from script failure. We do not want that to occur, regardless of the outcome of our scripts.

The stop script will make sure that the nimesis SRC daemon is stopped as shown in Figure 4-14 on page 319.
4.10 NIM and Service Update Management Assistant

The Service Update Management Assistant (SUMA) allows system administrators to set up the capability of automating the download of maintenance fixes on a system and supports a comprehensive set of features:

- Three task actions allow for download preview, actual download of updates, or combining the download with a fix repository cleanup (utilizing `lppmgr`).
► Scheduling using **cron** allows policies to be run at various intervals in order to confirm to necessary maintenance windows.

► There is e-mail notification of update availability and task completion.

► There is support for HTTP, HTTPS, and FTP transfer protocols and proxy servers.

► Filtering options allow comparisons against an installed software inventory or a Maintenance Level.

**Important:** SUMA is a complement to the UNIX servers product family portion of the IBM Support Fix Central Web site located at:


You can use either the **suma command** or the **smit suma** fast path. The **suma command** can be found in `/usr/sbin` and the SUMA Perl libraries are in the `/usr/suma/lib/SUMA` directory. Configuration changes are saved in indexed files in the `/var/suma/data` directory. The SUMA log files can be found under the `/var/adm/ras` directory, and the basic log file is `suma.log`.

SUMA is installed as part of the base operating system of AIX 5L V5.3. Systems at AIX 5L V5.2 or AIX 5L V5.1 may need to install additional filesets in order to enable SUMA.

**Note:** You can find more information about the **suma command** at the following IBM Web sites:


**SUMA for AIX 5L V5.2 and AIX 5L V5.1**

For AIX 5L V5.2, you have to install either the 5200-05 Maintenance Level or the fixes and prerequisites shown in Table 4-5 on page 321. For AIX 5L V5.1, you have to install the fixes and prerequisites shown in Table 4-5 on page 321.
Table 4-5  SUMA for AIX 5L V5.2 and AIX 5L V5.1

<table>
<thead>
<tr>
<th>Description</th>
<th>Fileset</th>
<th>AIX 5L V5.2</th>
<th>AIX 5L V5.1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Service Update Management Assistant (SUMA)</td>
<td>bos.suma (install package)</td>
<td>5.2.0.0</td>
<td>5.1.0.0</td>
</tr>
<tr>
<td>Service Update Management Assistant (SUMA)</td>
<td>bos.suma (update package)</td>
<td>5.2.0.1</td>
<td>5.1.0.1</td>
</tr>
<tr>
<td>Perl Library Extensions</td>
<td>perl.libext (install package)</td>
<td>2.0.58.0</td>
<td>2.0.56.0</td>
</tr>
<tr>
<td>Perl Version 5 Runtime Environment</td>
<td>perl.rte (update package)</td>
<td>5.8.0.10</td>
<td>5.6.0.10</td>
</tr>
</tbody>
</table>

**SUMA network connection**

Remember that the system, in this case the NIM master, must have access to the Internet and use Internet Domain Name Service (DNS). SUMA needs to resolve the ibm.com domain and uses by default FTP (ports 20 & 21) and HTTP (port 80).

**Important:** Check that your system can resolve the names into IP addresses for the IBM support fix servers, and that you can reach them from your NIM or fix download servers.

First, use the classic ping test to the IBM support fix server; for example, with one PING only:

```
ping -c 1 www14.software.ibm.com
```

The output should look similar to Example 4-213 with: 0% packet loss.

**Example 4-213  Ping test to www14.software.ibm.com**

```
root@master:/: ping -c 1 www14.software.ibm.com
64 bytes from 9.17.252.42: icmp_seq=0 ttl=241 time=184 ms

1 packets transmitted, 1 packets received, 0% packet loss
round-trip min/avg/max = 184/184/184 ms
```

If the test is not successful, even after increasing the number of PINGs (-c 3), then check the system’s `/etc/resolv.conf` file. If it exists, it indicates the DNS servers used by the system (`ls /etc/resolv.conf or nameslv -s`).
If this file is empty or does not have a valid DNS name listed, add a nameserver entry with a valid DNS IP address to the /etc/resolv.conf file by the vi editor, the SMIT mknamerslv fast path, or the namerslv -a -i #.#.#.# command (the #.#.#.# should be your IP address for your DNS server with Internet resolution of hostnames).

**Note:** If this computer has a resolv.conf that does not allow Internet resolution of hostnames or IP addresses, contact your network administrator responsible for the network and request Internet DNS and FTP/HTTP access for the system.

The following examples show how to use the **dig**, **host** and **nslookup** commands to resolve the SUMA default FIXSERVER_URL; see Example 4-219 on page 326. The **dig** command shown in Example 4-214 requests the DNS A record.

```plaintext
Example 4-214  Checking DNS name resolution

root@master:/: dig www14.software.ibm.com A

; <<>> DiG 9.2.0 <<>> www14.software.ibm.com A
;; global options:  printcmd
;; Got answer:
;; ->>HEADER<<- opcode: QUERY, status: NOERROR, id: 42846
;; flags: qr rd ra; QUERY: 1, ANSWER: 2, AUTHORITY: 0, ADDITIONAL: 0

;; QUESTION SECTION:
;www14.software.ibm.com. IN A

;; ANSWER SECTION:

;; Query time: 3 msec
;; SERVER: 10.1.0.14#53(10.1.0.14)
;; WHEN: Tue Jun  6 12:07:01 2006
;; MSG SIZE  rcvd: 94

root@master:/: host www14.software.ibm.com

root@master:/: nslookup www14.software.ibm.com
Server: linux0.sapidi.mop.ibm.com
Address: 10.1.0.14

Non-authoritative answer:
```
Example 4-215 shows the `nslookup` command. There is an error message indicating that `nslookup` is not supported by the DNS, so use the `dig` or `host` commands instead.

Example 4-215   Error message using nslookup with some DNS servers

root@master:/: nslookup www14.software.ibm.com
*** Can't find server name for address 10.1.0.14:Non-existent host/domain
*** Can't find server name for address 10.2.0.14:Non-existent host/domain
*** Default servers are not available

4.10.1 Using SUMA

Before starting to use SUMA, you should know:

- *Which* systems you want to update
- *Why* you want to update these systems
- *What* software you want to update
- *When* you want to update which systems

Using SUMA should make it easier to keep system software updates current. However, it is not a recommended best practice to constantly be on the latest level of the operating system, unless it is absolutely necessary.

To understand what to download with SUMA, or from the IBM support fix central Web site, as well as the meaning of the new IBM service terminology for AIX 5L (TL, ML, CSP or SP), refer to 4.10.7, “IBM AIX Service Strategy” on page 347.

Performing software maintenance with SUMA allows you to automate download directly to the NIM master. However, it will *not* automatically create new (or update) either lpp_source or SPOT; this has still to be done manually.

For those who want to delay their adoption of a new Technology Level (TL) by a period of six to eight months, but take advantage of the latest tested group of PTFs available in a Concluding Service Pack (CSP), the Maximum Stability maintenance model for AIX may be appropriate. For more information on the practical handling of the model with SUMA, see “Maximum Stability maintenance model” on page 333.

The appropriate usage is to download updates using SUMA and then update the appropriate NIM lpp_source from the updates in the SUMA directory.
manually newly updated lpp_source can then be used to update the associated spot.

**Important:** Do not use basic SUMA to download directly to a NIM lpp_source directory. The SUMA FilterDir parameter assists in not having to download into the lpp_source directly. The niminv command with the fixget option has the same risk of downloading directly to the NIM lpp_source directory. Refer to “The niminv command” on page 342 for more detailed information.

To obtain the latest fixes, you can use the niminv command for NIM machines or NIM lpp_source objects, or the compare_report command for non-NIM systems.

For more detailed comparisons of the installed software (that is, what is available from your own NIM server lpp_source, and what is available from the IBM Support Fix Central Web site), refer to 4.10.6, “Checking whether a system has all available updates installed” on page 341.

### 4.10.2 Settings for SUMA

You can view and configure the global configuration settings for SUMA with either the suma command and the -D flag, or through the SMIT suma_config fastpath. Example 4-216 shows the default display.

**Example 4-216 View the SUMA global configuration settings**

```
root@master:/: suma -D
  DisplayName=
  Action=Download
  RqType=Security
  RqName=
  RqLevel=
  PreCoreqs=y
  Ifreqs=y
  Supersedes=n
  ResolvePE=IfAvailable
  Repeats=y
  DLTarget=/usr/sys/inst.images
  NotifyEmail=root
  FilterDir=/usr/sys/inst.images
  FilterML=
  FilterSysFile=localhost
  MaxDLSize=-1
  Extend=y
```
In the following examples, we assume that the /export/lpp_suma file system has been created\(^3\), and that different downloads are kept in separate directories under this file system mountpoint, such as the directory /export/lpp_suma/5304 used for AIX 5L V5.3 TL04.

We want this to be reflected in the SUMA configuration, and we use the `suma` command with the `-D` flag and `-a attribute=value` to change specific attribute values, as shown in Example 4-218.

Example 4-217 shows the attribute `FilterSysFile` is set to `/dev/null` as the new default value. The `/dev/null` will prevent SUMA from filtering against the software inventory of the system that you are running on. The default download directory (DLTarget) and the default filter directory (FilterDir) are both set to /export/lpp_suma. In our scenario, this file system will only contain update level-specific directories, but by setting the defaults in this way, it saves on typing when using SMIT to create or execute SUMA tasks.

```
Example 4-217  Update the SUMA global configuration settings

root@master:/: suma -D -a DLTarget='/export/lpp_suma' -a FilterDir='/export/lpp_suma' -a FilterSysFile='/dev/null'
```

Example 4-217 can also be done through the SMIT suma_config_base fastpath. To set the value to /export/lpp_suma/5304 in SMIT, the path is already prepended and we only have to type: 5304. By using FilterDir, we can perform downloads to the same directory and if the update is already there, it will not be downloaded again.

```
Example 4-218  View the SUMA global configuration settings, after change

root@master:/: suma -D

DisplayName=
Action=Download
RqType=Security
RqName=
RqLevel=
PreCoreqs=y
Ifreqs=y
Supersedes=n
ResolvePE=IfAvailable
Repeats=y
DLTarget=/export/lpp_suma
NotifyEmail=root
```

\(^3\) crfs -v jfs2 -g rootvg -a size=1G -m /export/lpp_suma -A yes -p rw -a agblksize=4096 -a logname=INLINE && mount /export/lpp_suma
You can view and configure the general task settings for SUMA with either the `suma` command and the `-c` flag, or through the SMIT `suma_task_defaults` fastpath. Example 4-219 shows the default display.

**Example 4-219  View the SUMA general task settings**

```
root@master:/: suma -c
```

```
FIXSERVER_PROTOCOL=http
DOWNLOAD_PROTOCOL=ftp
DL_TIMEOUT_SEC=180
DL_RETRY=1
MAX_CONCURRENT_DOWNLOADS=5
HTTP_PROXY=
HTTPS_PROXY=
FTP_PROXY=
SCREEN_VERBOSE=LVL_INFO
NOTIFY_VERBOSE=LVL_INFO
LOGFILE_VERBOSE=LVL_VERBOSE
MAXLOGSIZE_MB=1
REMOVE_CONFLICTING_UPDATES=yes
REMOVE_DUP_BASE_LEVELS=yes
REMOVE_SUPERSEDE=yes
TMPDIR=/var/suma/tmp
FIXSERVER_URL=www14.software.ibm.com/webapp/set2/fixget
```

To change the general task configuration, we can use the `suma` command with the `-c` and `-a attribute=value` flags to change specific attribute values.

To change the download protocol from FTP to HTTP, issue the following `suma` command shown in Example 4-220.

**Example 4-220  Update the SUMA general task settings**

```
root@master:/: suma -c -a DOWNLOAD_PROTOCOL='http'
```

This setting can be helpful if you are constrained behind a firewall that only permits outgoing and returning HTTP traffic.
4.10.3 SUMA tasks

Example 4-221 shows how to create and execute a SUMA task to download all updates from 5300-00 to the latest. It downloads into the /export/lpp_suma/5304 directory and only downloads filesets that are not already there. First, we create the 5304 directory in the /export/lpp_suma file system.

Example 4-221  Creating a SUMA task for downloading a TL

```
root@master:/: mkdir /export/lpp_suma/5304
root@master:/: suma -wx -a DisplayName='5304' -a FilterML='5300-00'
               -a DLTarget='/export/lpp_suma/5304' -a FilterDir='/export/lpp_suma/5304'
```

**Note:** In Example 4-221, in order to download the Technology Level (TL) requested, the RqType needs to be set to TL, and set RqName=5300-04. If the FilterDir parameter is left blank, it defaults to the same value as the DLTarget.

Example 4-221 can also be done through the SMIT suma_task_new fastpath. First, we create directory 5304 in the /export/lpp_suma file system, if it has not been created already.

**Important:** The directory used for any SUMA task must exist prior to scheduling or executing the task. Otherwise, the task will not be accepted and you will get an error message similar to the following:

```
/export/lpp_suma/5304 must be an existing absolute path.
0500-049 The task is not valid.
```

To view all saved SUMA tasks, use the -l flag to the suma command as shown in Example 4-222 with one task defined.

Example 4-222  View defined SUMA tasks

```
root@master:/: suma -l
1:
   DisplayName=5304
   Action=Download
   RqType=Security
   RqName=
   RqLevel=
   PreCoreqs=y
   Ifreqs=y
   Supersedes=n
   ResolvePE=IfAvailable
   Repeats=y
   DLTarget=/export/lpp_suma/5304
```
Example 4-222 on page 327 can also be done through the SMIT suma_task fastpath and then View All SUMA Tasks.

To execute a saved SUMA tasks, use the -x flag to the suma command as shown in Example 4-223, which starts the first task from Example 4-222 on page 327.

Example 4-223 View execute a saved SUMA task

root@master:/: suma -x 1

Example 4-223 can also be done through SMIT using the fastpath smit suma_task_edit -> Execute Now (Do Not Save Changes).

From cron, to unschedule a saved SUMA task, add the -u flag to the suma command as shown in Example 4-224, which removes the first task from Example 4-222 on page 327.

Example 4-224 Unscheduling a SUMA task

root@master:/: suma -u 1

Example 4-224 can also be done using the SMIT suma_task_delete fastpath and setting Retain task data for future use to yes.

To delete a saved SUMA task, add the -d flag to the suma command as shown in Example 4-225, which removes the first task from Example 4-222 on page 327.

Example 4-225 View a saved SUMA task

root@master:/: suma -d 1

Example 4-225 can also be done using the SMIT suma_task_delete fast path and setting Retain task data for future use? to no.

Checking for a new Technology Level monthly

This task checks monthly for a new specified Technology Level (TL). Because a TL is released approximately every six months, a monthly check may be
You may schedule a SUMA task with a command similar to the one shown in Example 4-226 to check monthly (for example, on the first of every month at 00:30) whether a new TL has been released. The scheduling information (-s) is in crontab format (Minute Hour Day_of_month Month Weekday) for the root user. The Repeats field should be set to y in order for the system to make monthly checks for the SP. After the SP is found, the task is deleted. If Repeats is set to n, then only a single check would occur before deleting the task. An e-mail notification will be sent with the results of the check, in this case to the root user at the localhost system. A TL or ML must be in the form xxxx-xx; for example, 5300-05, as shown in Example 4-226.

Example 4-226   Creating and scheduling a task that checks monthly for a new TL

root@master:~: mkdir /export/lpp_suma/5305
root@master:~: suma –s “30 0 1 * *” –a Action=Preview –a RqType=ML –a RqName=5300-05 –a FilterML=5300-04 –a Repeats=y -a DLTarget='/export/lpp_suma/5305' –a NotifyEmail="root@localhost"

This command performs a preview (no download will occur) to check whether TL 5300-05 has been released. The FilterML setting specifies that the client already has filesets in the 5300-04 level. If 5300-05 has been released, the notification e-mail contains the list of filesets in the TL 5300-05 that was (or would be) downloaded.

If you only want to execute the query right away, and do not want to save or schedule it, use the -s flag. If 5300-05 is not yet available, the e-mail notification will contain a message similar to: Invalid requested ML level:V530005, as shown in Example 4-227.

Example 4-227   Executing a task that downloads a specific new TL

root@master:~: suma –x –a RqType=ML –a RqName=5300-05 –a FilterML=5300-04 -a DLTarget='/export/lpp_suma/5305'

0500-018 An internet request failed.
0500-014 The fix server responded with the following error condition: 204|Invalid requested ML level:V530005.
You may also elect to automatically download the filesets in this TL by setting Action equal to Download instead of Preview as in the Example 4-226 on page 329. In this case, the filesets will only be downloaded, but no installation will occur.

**Checking and downloading a new Concluding Service Pack**

This task checks weekly for a new specified Concluding Service Pack (CSP). CSPs are available shortly after a new TL is released. They contain all fixes for highly pervasive, critical, or security-related issues for the previous TL, but may also contain fixes from the newly released TL that fall into these categories. Therefore, a CSP will contain a very small subset of service that was just released as a part of a new TL.

A CSP must be in the form xxxx-xx-CSP (for example, 5300-04-CSP). Example 4-228 shows a scheduled SUMA task check monthly (for example, on the first of every month at 00:30) to see whether a new TL has been released. The scheduling information (-s) is in crontab format (Minute Hour Day_of_month Month Weekday) for the root user.

The Repeats field should be set to y in order for the system to make monthly checks for the SP. After the SP is found, the task is deleted. If Repeats is set to n, then only a single check would occur before deleting the task. An e-mail notification will be sent with the results of the check, in this case to the root user at the localhost system. The FilterML setting specifies that the client already has filesets in the 5300-04 level.

**Example 4-228  Task that checks monthly for a new CSP**

```
root@master:/: mkdir /export/lpp_suma/530004
root@master:/: suma -s "30 0 1 * *" -a Action=Preview -a RqType=SP
- a RqName=5300-04-CSP -a FilterML=5300-04 -a Repeats=y
- a DLTarget='/export/lpp_suma/530004' -a NotifyEmail="root@localhost"
```

0500-018 An internet request failed.
0500-014 The fix server responded with the following error condition:
   204 Invalid requested ML level:5300-04-CSP.

If 5300-04-CSP is not yet available, the e-mail notification will contain a message similar to: Invalid requested ML level:V5300-04-CSP, as shown in Example 4-228 on page 330.
Checking and downloading a new Service Pack

This task checks weekly for a new specified Service Pack (SP), because SPs are expected to be released approximately every 4 to 6 weeks between TLs, which are released twice a year. An SP must be in the form xxxx-xx-xx (for example, 5300-04-03 as shown in Example 4-229). The FilterML setting specifies that the client already has filesets in the 5300-04 level. Remember that a Service Pack is just a tested group of PTFs; refer to 4.10.7, “IBM AIX Service Strategy” on page 347 for more detailed information about this topic.

Note: Example 4-229 shows a one-time execution to check and download a new service pack.

Example 4-229  Executing a task that downloads a specific new SP

```
root@master:/: mkdir /export/lpp_suma/5304
root@master:/: suma -x -a RqType=SP -a RqName=5300-04-03
-a FilterML=5300-04 -a DLTarget='/export/lpp_suma/5304'
-a FilterDir='/export/lpp_suma/5304'

****************************************
Performing preview download.
****************************************
Download SKIPPED:   bos.64bit.5.3.0.41.bff
Download SKIPPED:   bos.adt.include.5.3.0.42.bff
Download SKIPPED:   bos.adt.prof.5.3.0.43.bff
Download SKIPPED:   bos.mp.5.3.0.43.bff
Download SKIPPED:   bos.mp64.5.3.0.43.bff
...  
Download SUCCEEDED: /export/lpp_suma/5304/installp/ppc/bos.rte.aio.5.3.0.41.bff
...  
Summary:
  61 downloaded
  0 failed
  9 skipped
```

Downloading the latest security fixes monthly

This task creates and schedules the download of the latest security fixes monthly, starting from ML 5300-00 (FilterML) using the /export/lpp_suma/security directory. The scheduling information (-s) is in crontab format (Minute Hour Day_of_month Month Weekday) for the root user. In Example 4-230, it is scheduled for the first of every month at 00:30, just after midnight, and the request type (RqType) is Security.
Example 4-230  Task that downloads the latest security fixes monthly

root@master:/: mkdir /export/lpp_suma/security
root@master:/: suma -s "30 0 1 * *" -a RqType=Security -a DisplayName="Monthly Security Fixes" -a DLTarget='/export/lpp_suma/security' -a FilterML='5300-00' -a FilterDir='/export/lpp_suma/security'

Checking and downloading a specific APAR once a week
To create and schedule a task that checks for a specific APAR once a week, and then when it is available, to download it and e-mail that it has done so, you can refer to Example 4-231. The Repeats field should be set to y in order for the system to make weekly checks for an APAR. After the APAR is found, the task is deleted. If Repeats is set to n, only a single check would occur before deleting the task. An -email notification will be sent with the results of the check, in this case to the root user at the localhost system.

Example 4-231  Task that checks and downloads a specific APAR

root@master:/: mkdir /export/lpp_suma/apar
root@master:/: suma -s "0 3 * * 4" -a RqType=APAR -a RqName=IY12345 -a NotifyEmail="root@localhost" -a Repeats=y -a DLTarget='/export/lpp_suma/apar' -a FilterDir='/export/lpp_suma/apar'

If you only want to execute the query right away, and not save it or schedule it, replace the -s flag with the -x flag. If the APAR is not found, the 0500-035 message will be displayed; see Example 4-232.

Example 4-232  Executing a task that checks and downloads a specific APAR

root@master:/: suma -x -a RqType=APAR -a RqName=IY12345 -a DLTarget='/export/lpp_suma/apar' -a FilterDir='/export/lpp_suma/apar'

0500-035 No fixes match your query.

4.10.4 Maintenance models

The three maintenance models (Maximum Stability, Yearly Update, and Latest Level) are recommendations based on the new IBM AIX 5L Service Strategy. For more information about this topic, see 4.10.7, “IBM AIX Service Strategy” on page 347.

In the following sections, we explain these maintenance models in greater detail.
**Maximum Stability maintenance model**

The Maximum Stability maintenance model should monitor when a Concluding Service Pack (CSP) is released; refer to 4.10.7, “IBM AIX Service Strategy” on page 347. When the CSP comes out, it should be downloaded together with the previous Technology Level (TL).

With the Maximum Stability model, you are not moving to the latest TL when it is released, and you do not have to regularly check for the release of a TL or Concluding Service Pack (CSP). It is sufficient to check monthly for a new CSP; that is, because a CSP is released approximately every six months, a monthly check may be appropriate.

We recommend that you perform the following tasks for handling the Maximum Stability maintenance model:

1. Create a specific file system or directory for the CSP with corresponding TL.
2. Download the TL and then the CSP to the new file system or directory.
3. Create a new NIM lpp_source based on the base level and adding the TL/CSP filesets.
4. Check the new NIM lpp_source for duplicates with the `lppmgr` nim operation or standalone command; refer to “Removing duplicate filesets from a NIM lpp_source directory” on page 339.
5. Create a NIM spot based on the new NIM lpp_source.

Steps 1, 3, and 5 are covered in more detail in 3.1, “Setting up a basic NIM environment” on page 53. Step 4 is shown in 4.10.5, “Removing duplicate filesets from a NIM lpp_source directory” on page 339.

**Downloading the TL and the CSP**

To check monthly whether a new CSP has been released for the next highest TL, you can schedule a SUMA task with a command similar to the one in Example 4-233 (for example, on the 15th of every month after midnight 00:01). When it is successful, an e-mail notification will be sent to the e-mail address specified in for the NotifyEmail attribute (in this case `root@localhost`), with the results of the check.

*Example 4-233  SUMA task to check for a coming CSP*

```sh
root@master:/: suma –s “1 0 15 * *” –a Action=Preview –a RqType=SP –a RqName=5300-04-CSP –a FilterML=5300-04 –a Repeats=y –a NotifyEmail=”root@localhost” –a DLTarget=/export/lpp_suma/530004

Task ID 5 created.
```
The `suma` command used in Example 4-233 on page 333 returns a SUMA task ID (in this case, #5) which can be used to perform the actual download of the task. We perform this step after we have downloaded the corresponding TL, which is shown in Example 4-234.

**Example 4-234   SUMA task to download a TL for a newly released CSP**

```
root@master:/: suma -x -a RqType=ML -a RqName=530004 -a FilterML=5300-03 -a DLTarget=/export/lpp_suma/530004
Extending the /export/lpp_suma filesystem by 194690 blocks.
Download SUCCEEDED: /export/lpp_suma/530004/installp/ppc/bos.suma.5.3.0.40.bff
...```

**Summary:**
- 225 downloaded
- 0 failed
- 32 skipped

The command in Example 4-234 downloads only TL 5300-04, but it contains all updates because the base level since each TL is cumulative. The first output line shows that the file system size was automatically increased (Extending).

After the TL is downloaded, it is time to download the CSP itself. The command in Example 4-235 could be used to download the previously scheduled task #5 for the 5300-04-CSP that had the Preview action defined to check for its release. Note that the Preview will have to be overridden with Download; otherwise, it will simply perform another preview.

**Example 4-235   SUMA task to download newly released CSP**

```
root@master:/: suma -x -a Action=Download 5
Download SUCCEEDED: /export/lpp_suma/530004/installp/ppc/bos.mp.5.3.0.43.bff
...```

**Summary:**
- 76 downloaded
- 0 failed
- 0 skipped

**Note:** With the default setting for SCREEN_VERBOSE, the messages will be the same for Download and Preview actions, but the download will only be performed when Download is specified.

At this point, we are ready to create a NIM lpp_source from the TL+CSP to use for updates or rte installation.
Creating a NIM lpp_source object with the base+TL+CSP

To use a NIM lpp_source based on GA level AIX 5L, updated with the Technology Level (TL) and its corresponding Concluding Service Pack (CSP), create a new NIM lpp_source from a GA base level NIM lpp_source.

Example 4-236, Example 4-237, and Example 4-238 show how the source attribute is set either to the NIM lpp_source name of a GA base level NIM lpp_source, or to a directory containing the Backup File Format (BFF) filesets. Example 4-236 shows how to use the NIM lpp_source name of a GA base level as a source. In this case, the source NIM lpp_source name is lpp5300.

Example 4-236   Replicating a base level lpp_source

```
root@master:/: nim -o define -t lpp_source -a server=master -a source=lpp5300 -a location=/export/lpp_source/lpp5304 lpp5304
```

Example 4-237 shows how to use the GA base level BFF fileset directory as a source; in this case, the /export/lpp_source/lpp5300/installp/ppc directory.

Example 4-237   Replicating a base level lpp_source from a directory

```
root@master:/: nim -o define -t lpp_source -a server=master -a location=/export/lpp_source/lpp5304 -a source=/export/lpp_source/lpp5300/installp/ppc lpp5304
```

We have downloaded AIX 5L V5.3 Technology Level (TL) 04 from IBM support fix central as shown in “Downloading the TL and the CSP” on page 333. To add this directory to the NIM master environment as a NIM lpp_source resource, we do not have to declare the source because it is in the install format; see “File system hierarchy” on page 54.

Example 4-238   Creating a NIM lpp_source for a Technology Level (TL) update only

```
root@master:/: nim -o define -t lpp_source -a server=master -a location=/export/lpp_suma/530004 TL5304
```

Preparing to copy install images (this will take several minutes)...

Now checking for missing install images...
warning: 0042-267 c_mk_lpp_source: The defined lpp_source does not have the "simages" attribute because one or more of the following packages are missing:
  bos
  bos.net
  bos.diag
  bos.sysmgt
  bos.terminfo
  bos.terminfo.all.data
The 0042-267 message shown in Example 4-238 on page 335 warns us that the simages attribute was not set during creation, and therefore this NIM lpp_source cannot be used for NIM rte installation. However, it can be used for other operations such as an update, which is what we want to accomplish. Before using the new TL+CSP NIM lpp_source, we check and remove duplicate filesets with the nim command and lppmgr operation, as shown in Example 4-239. See also 4.10.5, “Removing duplicate filesets from a NIM lpp_source directory” on page 339.

Example 4-239  Checking and removing duplicate filesets after updating with TL+CSP

```bash
root@master:/: nim -o lppmgr TL5304
lppmgr: Source table of contents location is /export/lpp_suma/TL530004/installp/ppc/.toc

lppmgr: Building table of contents in /export/lpp_suma/TL530004/installp/ppc ..
lppmgr: Building table of contents completed.
lppmgr: Generating duplicate list..
lppmgr: Generating base level duplicate list..

Results:
====================== start list =============================
bos.64bit.5.3.0.40.U
bos.adt.include.5.3.0.41.U
bos.adt.prof.5.3.0.41.U
bos.adt.prof.5.3.0.42.U
bos.diag.com.5.3.0.10.U
bos.diag.rte.5.3.0.10.U
bos.diag.util.5.3.0.10.U
bos.mp.5.3.0.41.U
bos.mp.5.3.0.42.U
bos.mp64.5.3.0.41.U
bos.mp64.5.3.0.42.U
...
======================== end list =============================
```

```
lppmgr: Building table of contents in /export/lpp_source/lpp5304/installp/ppc .
lppmgr: Building table of contents completed.
rm: removing /export/lpp_source/lpp5304/installp/ppc/bos.64bit.5.3.0.40.U
rm: removing /export/lpp_source/lpp5304/installp/ppc/bos.adt.include.5.3.0.41.U
rm: removing /export/lpp_source/lpp5304/installp/ppc/bos.adt.prof.5.3.0.41.U
```
In Example 4-239 on page 336, some filesets were found to be duplicated. By default, the `nim` command `lppmgr` operation removes duplicate filesets.

Our new GA base level NIM `lpp_source` can now be updated with the TL+CSP filesets. In Example 4-240, we use the NIM `lpp_source` fileset directory of the TL+CSP as the source.

Example 4-240  Updating base level `lpp_source` from a TL directory

```
root@master:/: nim -o update -a show_progress=yes -a packages=all -a source=TL5304 lpp5304
/export/lpp_source/lpp5304/installp/ppc/sysmgtlib.libraries.apps.5.3.0.40.U
/export/lpp_source/lpp5304/installp/ppc/sysmgtlib.framework.core.5.3.0.40.U
/export/lpp_source/lpp5304/installp/ppc/sysmgt.websm.apps.5.3.0.40.U
/export/lpp_source/lpp5304/installp/ppc/sysmgt.websm.rte.5.3.0.40.U
/export/lpp_source/lpp5304/installp/ppc/sysmgt.websm.icons.5.3.0.40.U
Filesystem size changed to 11993088
Inlinelog size changed to 23 MB.
```

In Example 4-240, you can see that both the filesystem and inline log sizes were changed during the NIM `lpp_source` update. After updating, it is also a good idea to check for duplicate filesets with the `nim` command and `lppmgr` operation; see 4.10.5, “Removing duplicate filesets from a NIM `lpp_source` directory” on page 339.

Example 4-241  Removing duplicates with `nim lppmgr` operation

```
root@master:/: nim -o lppmgr TL5304
lppmgr: Source table of contents location is /export/lpp_suma/530004/installp/ppc/.toc
lppmgr: Building table of contents in /export/lpp_suma/530004/installp/ppc ..
lppmgr: Building table of contents completed.
lppmgr: Generating duplicate list..
lppmgr: Generating base level duplicate list..
Results:
```
No filesets found that can be removed.

No filesets were found to be duplicated. The NIM lpp_source is now ready to be used for installing and updating NIM clients using the Maximum Stability maintenance model.

**Yearly Update maintenance model**
The Yearly Update model designed is for systems that are stable and that are planned to be only updated annually. This model shows an annual move to a new TL, and thereby skips the direct move to one of the two TLs that are released during the year (instead picking up this function when the next TL is installed, because TLs are cumulative).

In between TLs, you can use SPs, individual PTFs, and interim fixes (to address security and other issues) to maintain service on a TL for up to one year.

When moving to a new TL annually, we recommend that you install a first-half TL (for example, TL4, TL6, and so on), because it has the advantage of being a smaller release. A first-half TL (for example, TL6) will contain all the new AIX 5L software enhancements that were released with the previous TL (for example, TL5); however, TL5 will have already been in the field for six to eight months, thus allowing it to become more stable.

For examples of how to download TLs, see “Checking for a new Technology Level monthly” on page 328. For examples of how to download SPs, see “Checking and downloading a new Service Pack” on page 331.

**Latest Level maintenance model**
The Latest Level model is for new systems or hardware-upgraded systems that require a new TL, or that want to utilize new hardware or software features being introduced in a TL. This maintenance model would typically entail a move to a new TL shortly after its release.

The annual first-half TL (for example, TL4, TL6, and so on) is a smaller TL release because it is restricted to hardware features and enablement, and software service. The annual second-half TL (for example, TL5) also includes new software features, and thus will be a larger release.

In between Technology Levels (TLs), you can utilize both Service Packs (SPs) and interim fixes (to address security and other issues) in support of the current Technology Level.

For examples of how to download TLs, see “Checking for a new Technology Level monthly” on page 328. For examples of how to download SPs, see “Checking and downloading a new Service Pack” on page 331.
4.10.5 Removing duplicate filesets from a NIM lpp_source directory

Sometimes you will end up with duplicate filesets in the same directory. This can cause problems when installing and updating SPOTs or clients. These duplicates are just a waste of space, and they should be removed. This can be done when downloading filesets using SUMA to a specific directory, but if you move around filesets you need to take care of this manually. Before AIX 5L V5.3, this had to be done using customized scripts, but now it can be done with the `lppmgr` command or `lppmgr` operation with the `nim` command.

The SUMA global settings `REMOVE_CONFLICTING_UPDATES` and `REMOVE_DUP_BASE_LEVELS` will by default remove duplicate updates and base levels when downloading updates. See Example 4-219 on page 326.

To make sure that there are no duplicate filesets use the `lppmgr` command/operation to cleanup. This can be done either with the standalone command `/usr/lib/instl/lppmgr`, that can be used to check any directory containing installable filesets or using the `nim` command and `lppmgr` operation.

In Example 4-242 and Example 4-243 on page 340, we have an lpp_source named lpp5304 which contain the AIX 5L V5.3 TL04. We have after this release downloaded updates to AIX 5L V5.3 to the directory `/exports/lpp_suma/5304U`.

In the following `lppmgr` command in Example 4-242, the directory `/exports/lpp_suma/5304U` will be checked and all duplicate updates (-u) and base levels (-b) will be removed (-r).

```
/usr/lib/instl/lppmgr -d /exports/lpp_suma/5304U -rub
```

The same applies for the NIM lpp_source object lpp5304 using the `nim` command and `lppmgr` operation:

```
nim -o lppmgr -a lppmgr_flags=rub lpp5304
```

**Note:** The `lppmgr` command uses the path to the directory where the filesets are located, and the location attribute of the NIM lpp_source object is only part of this path.

Example 4-242 shows the usage of the `lppmgr` command to remove duplicate filesets from a directory. Example 4-243 on page 340 shows the same operation on the same directory, but using the `nim` command and the NIM object name for the lpp_source.

**Example 4-242 Using lppmgr command to clean up and remove duplicate filesets**

```
root@master:/: /usr/lib/instl/lppmgr -d /export/lpp_source/lpp5304/installp/ppc -rub

lppmgr: Source table of contents location is /export/lpp_source/lpp5304/installp/ppc/.toc
```
In the output, you can see the two steps of the `lppmgr` command. The first step is to find and filter. The second step is the action on the filtered filesets (in this case, remove). Example 4-243 illustrates what the report should look when all the filesets are unique in the NIM lpp_source, and there are no duplicates.

**Example 4-243 Cleaning up and removing duplicate filesets**

```
{nimmast}:/ # nim -o lppmgr -a lppmgr_flags=rub lpp5304
lppmgr: Source table of contents location is /export/lpp_source/lpp5304/installp/ppc/.toc
lppmgr: Building table of contents in /export/lpp_source/lpp5304/installp/ppc ..
lppmgr: Building table of contents completed.
lppmgr: Generating duplicate list..
lppmgr: Generating base level duplicate list..
Results:
 No filesets found that can be removed.
```
4.10.6 Checking whether a system has all available updates installed

To determine whether a particular system needs a Technology Level (TL), a Concluding Service Pack (CSP), or a Service Pack (SP), refer to 4.10.7, “IBM AIX Service Strategy” on page 347. You will obtain the most detailed information by using the new niminv command (AIX 5L V5.3 TL5) for NIM machines, or NIM lpp_source objects, and the compare_report command for installed systems.

Start with the simplest steps to check a system’s software levels by using the lslpp command, the oslevel command, and even the instfix command, as shown in Example 4-244.

You can start by using the oslevel command either with the -s flag or the -r flag, depending on your current system level. The -r option shows the recommended ML/TL, but the -s flag also shows the SP information.

Example 4-244  Examples of using the lslpp, oslevel, and uname commands

```
root@master:/: lslpp -qLc bos.rte | cut -f2-3 -d:
bos.rte:5.3.0.40

root@master:/: oslevel -r
5300-04

root@master:/: oslevel -s
5300-04-03

root@master:/: oslevel -g 5.3.0.0
Fileset                                 Actual Level        Maintenance Level
-----------------------------------------------------------------------------
bos.rte                                 5.3.0.40            5.3.0.0

root@master:/: uname  -s -v -r
AIX 3 5
```

In the oslevel command output, there are discrepancies between Actual Level and what the oslevel reports is the current level.

To obtain details about what is missing for a higher oslevel report, use the instfix command to check for the installed AIX levels, as shown in Example 4-245.

Example 4-245  Using instfix to find current software level

```
root@master:/: instfix -i|grep AIX
    All filesets for 5300-02_AIX_ML were found.
    All filesets for 5.3.0.0_AIX_ML were found.
    All filesets for 5300-01_AIX_ML were found.
```
It shows that 5300-05 is missing some filesets, because it reports: Not all filesets for 5300-05_AIX_ML were found. Thus, we use this as our next search argument with the `instfix` command to find out what is missing; see Example 4-246.

**Example 4-246 Using instfix to find missing software level**

```
root@master:/: instfix -icqk 5300-05_AIX_ML|grep ":-:"
5300-05_AIX_ML:sysmgtlib.framework.core:5.3.0.50:5.3.0.40:-:AIX 5300-05 Update
5300-05_AIX_ML:sysmgtlib.libraries.apps:5.3.0.50:5.3.0.40:-:AIX 5300-05 Update
```

This shows that two filesets were on a lower level, so we can either remove these filesets if they are unused, or update them.

**The niminv command**

With AIX 5L V5.3 TL5, the new `niminv` command is introduced. The `niminv` command can gather, conglomerate, compare, and download fixes based on the installation inventory of NIM objects.

The `niminv` command extends the functionality of the `compare_report` command to operate on several NIM objects such as machines and `lpp_sources` at the same time. The `niminv` command uses the `suma` command to download fixes from the IBM Support Fix Central, and the `geninv` command to collect software inventory information from other systems.

**Note:** “Conglomerate” means that the inventories are put together without repeats of any filesets; the default action removes any higher versions of the fileset, so only the lowest version of each fileset appears in the conglomerated list.

The `geninv` command can also be used manually to collect software inventory information from other systems using IP addresses or resolvable hostnames.

You can also use the SMIT `nim_inventory` fast path to perform `niminv` operations.

Example 4-247 on page 343 with the `niminv` command uses the `invget` operation and will collect an output file (`lslpp -L format`) in the `/export/inventory` directory with the current software levels of the NIM master.
Example 4-247 Using niminv to gather software inventory information

root@master:/: niminv -o invget -a targets=master -a location=/export/inventory
Installation Inventory for master saved to /export/inventory/inventory.master.060620140643.

Return Status = SUCCESS

Example 4-248 also uses the **invget** operation, but collects software levels from a group of NIM clients, called **nim_clients**, but currently only containing one NIM client (**lpar55**).

Example 4-248 Software inventory information for a NIM group of clients

root@master:/: niminv -o invget -a targets=nim_clients -a location=/export/inventory
Installation Inventory for lpar55 saved to /export/inventory/inventory.lpar55.060620140605.

Return Status = SUCCESS

The **niminv** command with the **invcon** operation (conglomerate) compares the levels between different systems; see Example 4-249.

Example 4-249 Software inventory information between different NIM clients

root@master:/: niminv -o invcon -a targets=master,nim_clients -a base=highest
-a location=/export/inventory

Return Status = SUCCESS

To display the fixes that can be downloaded based on the lowest installations in a conglomerate of the nim_clients group and the NIM master, use the **fixget** operation as shown in Example 4-250. The text Performing preview download indicates that the following Download SUCCEEDED did not take place.

Example 4-250 Using niminv to display available fixes

root@master:/: niminv -o fixget -a targets=master,nim_clients
*******************************************************************************
Performing preview download.
*******************************************************************************
Download SUCCEEDED: /export/lpp_suma/installp/ppc/Java14.debug.1.4.1.0.bff
Download SUCCEEDED: /export/lpp_suma/installp/ppc/Java14.debug.1.4.1.7.bff
...
Summary:
271 downloaded
0 failed
0 skipped
Return Status = SUCCESS

Example 4-251 shows the download of the latest fixes for the NIM master to a new lpp_source. The actual download will be performed with the suma command.

**Example 4-251  Using niminv to download available fixes**

```
root@master:/: niminv -o fixget -a targets=master -a download=yes -a location=/export/lpp_source/lpp5304B -a newlppname=lpp5304B
```

Download SUCCEEDED: /export/lpp_source/lpp5304B/installp/ppc/

...  
Summary:
271 downloaded  
0 failed  
0 skipped  

Return Status = SUCCESS

The niminv command will create both the location and the newlppname if they do not exist. If the niminv command is interrupted, it will perform a cleanup and remove all that was created, including the location and newlppname, giving you the following messages:

niminv: Signal received. Cleaning up.  
Return Status: FAILURE

To download the latest fixes to an existing lpp_source while filtering from the same lpp_source, see Example 4-252.

**Example 4-252  Using niminv to download available fixes**

```
root@master:/: niminv -o fixget -a targets=master -a download=yes -a lpp_source=lpp5305
```

Extending the /AIX5305 filesystem by 979890 blocks.  
Filesystem size changed to 5242880  
Inlinelog size changed to 10 MB.

Download SUCCEEDED: /AIX5305/installp/ppc/Java14.msg.ko_KR.1.4.2.0.bff

...  
Summary:
271 downloaded  
0 failed  
0 skipped  

Return Status = SUCCESS
The `niminv` command first extends the NIM `lpp_source` objects file system, and then starts the download of new filesets.

**Note:** Any filesets already contained in the destination directory will not be downloaded again.

**The `compare_report` command**

The `compare_report` command provides an easy way to check whether a specific system is at the latest level or latest Maintenance Level (ML). To determine the fixes that must be downloaded, run a comparison between the filesets installed on a standalone system and the contents of an image repository or a list of fixes available from the IBM Support Fix Central Web site.

The `compare_report` command provides the following functions:

- Compares the filesets installed on a system to a list of fixes available from the IBM Support Web site or a fix repository, such as a NIM `lpp_source`.
- Generates reports detailing which fixes are required for a system to be at the latest level or latest Maintenance Level.
- Reports can be uploaded to the “Compare report” page (select based on your desired operating system level) on the IBM Support Fix Central Web site:
  
  ```
  &release=5.3
  ```

  The fixes can then be downloaded utilizing normal Web site interfaces or using SUMA; see 4.10.2, “Settings for SUMA” on page 324. (You need to change the value for the release attribute in order to change the AIX release.)

The `compare_report` command can be used on systems that do not have access to the Internet. This prevents systems from using SUMA, which requires at least one system to have Internet access.

You can also use the SMIT `compare_report` fast path to perform `compare_report` operations.

After you download the `LatestFixData` file from the eSupport Web site, you can send this file to a system to perform an offline comparison to determine which software updates are needed to bring the system or NIM `lpp_source` to the latest level or latest ML/TL. The reports produced by `compare_report` can be uploaded to the IBM Support Fix Central Web site to request the updates to be downloaded.
To check whether a specific system is backlevel compared to what is available from the IBM Support Fix Central Web site, manually download the fileset list from:

http://www-912.ibm.com

In our case, we downloaded by using the Open Source `wget` command, as shown in Example 4-253. The file (in our example, LatestFixData53) contains a list of fixes that are in the latest maintenance package, as well as the latest available fixes that have been released after the latest maintenance package. The file can also be found using a browser on the IBM Support Fix Central Web site by selecting pSeries (Server), AIX OS (Product or fix type), Fix release information (Option), and an operating system level.

**Example 4-253  Downloading LatestFixData53 from www-912.ibm.com**

```
root@master:~ cd /tmp
   => `download?file=LatestFixData53.1'
Resolving www-912.ibm.com... 129.42.160.32
Connecting to www-912.ibm.com[129.42.160.32]:80... connected.
HTTP request sent, awaiting response... 200 OK
Length: unspecified [application/x-servicereport]

[ 46,118 ] 86.11K/s

17:27:02 (85.98 KB/s) - `download?file=LatestFixData53.1' saved [46118]
```

Compare the downloaded file from IBM with your locally installed software using the `compare_report` command or the SMIT `instolist_compare` fast path, as shown in Example 4-254.

**Example 4-254   compare_report with LatestFixData53 and local system**

```
root@master:/tmp: compare_report -s -r LatestFixData53 -l -h
#(lowerthanlatest1.rpt)
#Installed Software that is at a LOWER level
#PTF:Fileset_Name:Installed_Level:Available_Level
U487072:Java14.sdk:1.4.2.20:1.4.2.75
...
#(highert Thamaint.rpt)
#Installed Software that is at a HIGHER level than
# the latest Maintenance Level
#Fileset_Name:Installed_Level:Available_Level
bos.64bit:5.3.0.41:5.3.0.40
...
```
The files lowerthanlatest1.rpt and higherthanmaint.rpt are saved in a /tmp directory by default (this can be changed with the -t <directory> flag). They each contain a list of filesets and PTFs that are either lower than or higher than the latest ML/TL.

The Fix release information section of IBM Support Fix Central Web site allows you to upload a file that has been generated by the compare_report command.

The PTF numbers contained in the comparison report file will be used to provide the requested fixes. After uploading the file, you can download the requested fixes (PTFs) through the normal Fix Central interfaces by using the suma command or a file transfer tool such as wget.

**The wget Open Source tool**

If you do not have the wget command, you can use another tool or download it using a Web browser. Alternatively, you can install the WGET RPM package that is available from the IBM Open Source site (as shown in Example 4-255):

```bash
root@master:/: rpm -iv
```

For more information about how to use the rpm command or the IBM Open Source FTP site, refer to Linux Applications on pSeries, SG24-6033, located at:

http://www.redbooks.ibm.com/abstracts.sg246033.html

Example 4-255   Installing Open Source wget from ftp.software.ibm.com

```bash
root@master:/: wget
wget: missing URL
Usage: wget [OPTION]... [URL]...

Try `wget --help' for more options.
```

**4.10.7 IBM AIX Service Strategy**

For detailed information about this topic, refer to the following IBM Web sites:

4.10.8 IBM Support Fix Central Web site

Figure 4-15 on page 348 displays a subset of a screen from the IBM Support Fix Central Web site:

http://www.ibm.com/eserver/support/fixes/

From this site you can download TLs, SPs, CSPs, PTFs, APARs and interim fixes from this site. However, sometimes you must make a service call to IBM support to obtain specific interim fixes of PTFs.

4.11 Backing up clients with NIM

Backing up a system can be performed in all the same ways as any AIX/Linux server. But for a system that is also a NIM client, you can also back up by using
NIM to create a mksysb image. However, using NIM to create a mksysb image file must be executed from the NIM master itself (a “pull” operation). Otherwise, you will receive the following message:

0042-012 nim: this command may only be executed on a NIM master

Example 4-256 shows how the nim command is used for creating a mksysb image file named mksysb.lpar5 in the /export/images directory on the NIM master, first creating the /image.data file.

Example 4-256   Creating a mksysb from a NIM client

```bash
root@master:/: nim -o define -t mksysb -a server=master -a source=LPAR5 -a mk_image=yes -a location=/export/images/mksysb.lpar5 mksysb_lpar5
```

```
+---------------------------------------------------------------------+
| System Backup Image Space Information                             |
| (Sizes are displayed in 1024-byte blocks.)                       |
+---------------------------------------------------------------------+

Required = 868732 (848 MB)   Available = 2398052 (2342 MB)

Data compression will be used by the system backup utilities which create the system backup image. This may reduce the required space by up to 50 percent.

Creating information file (/image.data) for rootvg..

Creating list of files to back up.
Back ing up 26669 files.....
26669 of 26669 files (100%)
0512-038 savevg: Backup Completed Successfully.
```

The command executed in Example 4-256 on page 349 completed successfully, and both the specified mksysb.lpar5 image file and the mksysb_lpar5 NIM object are created.
**Note:** For naming NIM objects, using a dot (.) is unsupported. Therefore, we use an underscore ( _ ) to enhance the readability of the name. For an AIX filename, it is supported to use one or more dots or underscore signs, and we could have used the NIM object name as file system name as well.

Here we use separate signs to differentiate the name for the NIM mksysb object and the mksysb image filename. For additional naming examples, see 3.1.1, “Planning the NIM environment” on page 53.

The command breakdown for the example shown in Example 4-256 on page 349 is as follows:

- **-o define**  Specifies the operation (defining the object).
- **-t mksysb**  Specifies that the object type is mksysb.
- **-a server=master**  Specifies that the server to hold this object (the mksysb image file) is the NIM master itself.
- **-a source=LPAR5**  Specifies the NIM client to be used as the source the mksysb image, in this case, LPAR5.
- **-a mk_image=yes**  Specifies that the mksysb image file should be created.
- **-a location=/export/images/mksysb.lpar5**  Specifies the path and filename for the mksysb image file.

**mksysb_lpar5**  Specifies the NIM object name for this mksysb image.

Other attributes that can be used are (use **nim -q define -t mksysb** for the latest command option):

- **mksysb_flags**  Used to specify flags for the creation of the mksysb image file; see the mksysb command options.
- **exclude_files**  Can be used to specify the NIM object pointing to a file containing a list of file systems to exclude from the mksysb image file, like exclude.rootvg file for the mksysb command.
- **size_preview**  Used to determine the size requirement for the target mksysb image file.
- **comments**  Used to specify a description of the NIM mksysb object.
- **verbose**  Used to increase the message verbosity throughout the operation progress.
- **group**  Used to specify a NIM group to create the mksysb resource in.
### 4.11.1 Space requirements

One essential element to consider when handling mksysb images from one or several servers is the space requirement. If there is not enough space available to store the mksysb image file in the directory specified by the `location` attribute (-a location), the `nim` command will terminate and display a message similar to the output shown in Example 4-257.

**Example 4-257 Creating a mksysb from a NIM client with insufficient storage space**

0042-001 nim: processing error encountered on "master":
  0042-001 m_mkbosi: processing error encountered on "LPAR5":
  0042-210 c_mkbosi: The maximum space required for the backup is greater than the amount of free space in the target filesystem. To ignore space requirements use the "-F" flag when defining the mksysb resource.

There are several ways to calculate how much space the mksysb image file will take. One way is to let NIM calculate it by adding the `-a size_preview=yes` attribute for the mksysb image file and object creation command.

Example 4-258 shows what to expect if there is not enough space available, in which case you need to manually increase the size of the file system, or else free up some space to meet the requirements of the mksysb image file.

**Example 4-258 Determining backup image storage space requirement**

```bash
root@master:/: nim -o define -t mksysb -a server=master -a source=LPAR5 -a size_preview=yes -a mk_image=yes -a mksysb_flags=-i -a location=/export/images/mksysb.lpar5 mksysb_lpar5
```

```
+---------------------------------------------------------------------+
| System Backup Image Space Information                               |
| (Sizes are displayed in 1024-byte blocks.)                          |
+---------------------------------------------------------------------+

Required = 1132200 (1106 MB)   Available = 785232 (767 MB)
```

Data compression will be used by the system backup utilities which create the system backup image. This may reduce the required space.
The command shown in Example 4-258 reveals that there is only 767 MB of free space available at the designated location (/export/images), but the NIM required size for the mksysb image file is 1106 MB.

**Note:** The sizes calculated by the nim command are usually large because data compression is used by the system backup (which creates the system backup image). Thus, the final required space could be 50% less than the estimation.

### 4.11.2 NFS export during mksysb image file creation

During the allocation of NIM mksysb image files, only the file is exported to the NFS client. However, during mksysb creation, the parent directory is also exported. If you use that file system to create a mksysb image of a system while another system is restoring a mksysb image from that file system, you will get NFS errors.

To avoid this problem, use the NIM_MKSYSB_SUBDIRS environment variable on the NIM master, as shown in Example 4-259 on page 352.

When this variable is set to yes, then subdirectories are used to separate mksysb image files. The subdirectories are transparent to the user, but they provide separate locations for NFS exporting. The subdirectories are named after the NIM object for which they are created.

**Example 4-259** Using NIM_MKSYSB_SUBDIRS environment variable

```bash
root@master:/: export NIM_MKSYSB_SUBDIRS=yes
root@master:/: nim -o define -t mksysb -a server=master -a source=LPAR5 -a mk_image=yes -a location=/export/images/mksysb.lpar5 mksysb_lpar5
```

The command shown in Example 4-259 will create the mksysb image file in the /export/images/LPAR5 directory and not in the /export/images directory.

### 4.11.3 Exclude file for mksysb image creation

Just as with the system mksysb command, an exclude file can be used to prevent certain file systems or directories from being included in the mksysb image file creation.

First, you need to create the exclude file. The lines in this file are input to the pattern-matching conventions of the grep command to determine which files will
be excluded from the backup. For example, to exclude all the contents of the directory called temp, edit the exclude file to read as follows:

```
/temp/
```

To exclude the contents of the directory called /tmp, and avoid excluding any other directories which have /tmp in the pathname, edit the exclude file to read as follows:

```
^./tmp/
```

All files are backed up relative to the current working directory (CWD). To exclude any file or directory for which it is important to have the search match the string at the beginning of the line, use a caret (^) as the first character in the search string, followed by a dot (.), followed by the filename or directory to be excluded.

If the filename or directory being excluded is a substring of another filename or directory, use ^ (a caret followed by a dot) to indicate that the search should begin at the beginning of the line and/or use the dollar ($) sign to indicate that the search should end at the end of the line.

**Tip:** You can use the vi editor. If you are uncomfortable with this editor, you can create the first line in a new file with the echo command:

```
echo "FILESYSTEMPATTERN" > excludefilename
```

To add additional lines to the one above, use the echo command again as many times as required (note the double greater-than signs):

```
echo "FILESYSTEMPATTERN" >> excludefilename
```

After the exclude file is created, a NIM object of the exclude_files type has to be created, as shown in Example 4-260.

```
Example 4-260 Creating the exclude_files type NIM object
```

```
root@master:/: nim -o define -a verbose=2 -t exclude_files -a server=master
-a location=/export/scripts/exclude.lpar5 exclude_lpar5

m_mkres: define the exclude_lpar5 resource
  ok_to_mk_robj: server=master; location=/export/scripts/exclude.lpar5
set_Mstate: name=master
  checking for location collisions
stat_file: server=master; location=/export/scripts/exclude.lpar5;
  file must have: st_mode = 04000453330; st_vfstype = "0 3"
  stat-ing the file "/export/scripts/exclude.lpar5"
```
To use the exclude file (from the NIM object exclude_lpar5) to create a mksysb image file, use the exclude_files attribute as shown in Example 4-261.

Example 4-261 Using exclude_files when creating mksysb image files

```
root@master:/ : nim -o define -t mksysb -a server=master -a source=LPAR5
 -a mk_image=yes -a location=/export/images/mksysb.lpar5
 -a exclude_files=exclude_lpar5 mksysb_lpar5
```

+---------------------------------------------------------------------+
| System Backup Image Space Information                               |
| (Sizes are displayed in 1024-byte blocks.)                          |
+---------------------------------------------------------------------+

Required = 869048 (849 MB)  Available = 1332332 (1301 MB)

Data compression will be used by the system backup utilities which create the system backup image. This may reduce the required space by up to 50 percent.

Creating information file (/image.data) for rootvg..

Creating list of files to back up.
Back up 26665 files.....
26665 of 26665 files (100%)
0512-038 savevg: Backup Completed Successfully.

4.12 Creating bundles, BFF, and RPM packages

Starting with AIX 5L 5.1, you can install Red Hat Package Manager (RPM)-formatted and InstallShield MutliPlatform (ISMP)-formatted packages in addition to the native AIX installation Backup File Format (BFF - installp-formatted packages).

In this section, we show how to create your own BFF and RPM packages, and how to use bundles to install these onto NIM clients.

Note: The procedures can also be used for standalone systems (that is, systems not belonging to a NIM environment).

The AIX product media (CD/DVD) contains BFF and RPM packages that are installed during the base operating system (BOS) installation. The BFF packages
are located by default in the following relative path under AIX installation media or NIM lpp_source resource directories:

installp/ppc

The RPM packages are located in the following path:

RPMS/ppc

If you have media that contains ISMP packages, the packages are located in the following path:

ISMP/ppc

If you are using the geninstall command to install RPM or ISMP packages, use the prefix type to indicate to the geninstall command the type of package that you are installing. The package prefix types are the following:

- I: BFF format
- R: RPM format
- J: ISMP format
- E: Interim Fix format

For example, to install the openssl RPM package and the bos.perf BFF/installp package, type the following:

   geninstall -d /dev/cd0 R:openssl I:bos.perf

The geninstall command detects that the openssl package is an RPM package type and runs the rpm command to install the openssl package. The geninstall command then detects that bos.perf is an BFF/installp package type and runs the installp command to install the bos.perf package. The process for uninstallation is similar to the installation process.

### 4.12.1 BFF (native installp packages)

The native AIX installation Backup File Format (BFF) is sometimes referred to as the “installp” format. The mkinstallp command allows you to create your own software packages for AIX in the BFF/installp format, and can be installed or removed with the installp command.

The mkinstallp command requires files that will be packaged to be in a directory structure such that the location of the file relative to the root build directory is the same as the destination of the file after installation.

After the contents of a package are located in the correct directory structure, the mkinstallp command prompts for basic package data. This data includes the package name, requisites, descriptions of files to be packaged, and more. The mkinstallp command will then generate a template file based on responses
given by the user. To prevent command-line prompting, template files can be created and edited directly by the user and passed to the `mkinstallp` command with the `-T` flag.

To create a BFF/installp package, you can use the following procedure:
1. Create the build structure.
2. Populate the build structure with programs and files.
3. Create the packaging template file, for use by the `mkinstallp` program.
4. Create the package file with the `mkinstallp` program.

In the following sections, we describe each step in more detail.

**Creating the build structure**
We need to create the packaging buildroot directory. For our examples to create installation packages, we use the `/build` file system (directory) as the top level for our packages. We choose to use a separate file system for this purpose, and we create it as an Enhanced Journaled File System (`jfs2`):

```
crfs -v jfs2 -g rootvg -a size=120M -m /build -A yes -p rw -a
logname=INLINE
```

We mount the file system:

```
mount /build
```

We limit the access to this file system mountpoint to restrict everyone except the root user (removing read-write-execute permissions for group and others):

```
chmod go-rwx /build
```

We create a directory structure for the BFF package, with the root packaging directory of `/build/nodecust`, which will be the root (`/`) file system at install time. We will create a NIM client customization package, thus the `nodecust` name.

In the `/build` file system, we create our packages buildroot directories. In this example, we create the `nodecust` package buildroot directory:

```
mkdir -p /build/nodecust
```

Then we create subdirectories where our files will be stored. Our intention is that during the installation, specific files will be updated or replaced.

We replace the `/etc/motd` file if it already exists, and for this we create the `/etc` directory under `/build/nodecust`:

```
mkdir -p /build/nodecust/etc
```
Populating the build structure
All installed files should be put in their respective directories under the buildroot. In our example, we create an /etc/motd file under the /build/nodecust/etc directory:

```bash
banner hello world > /build/nodecust/etc/motd
```

We set the file permissions on our new version of /etc/motd file to the same as the original (read-read-read only for owner-group-others):

```bash
chmod 444 /build/nodecust/etc/motd
```

Creating the packaging template file
The `mkinstallp` template file contains specifications for the installation package. The template file can be included in the `<buildroot>` but not as part of the BFF package; refer to Figure 4-16 on page 357.

In our example, we choose to store our template file in the buildroot directory, the /build/nodecust directory (also referred to as `<buildroot>` in the following examples). The template file for this small package contains the following specification entries. We named the template file `nodecust.template` in the `<buildroot>` directory.

```plaintext
Package Name: NODECUST
Package VRMF: 1.0.0.0
Update: N
Fileset
  Fileset Name: NODECUST.rte
  Fileset VRMF: 1.0.0.0
  Fileset Description: NODECUST
  Booter required: N
  License agreement acceptance required: N
  Include license files in this package: N
  Requisites:
    ROOT Part: Y
    ROOTFiles
      /etc
      /etc/motd
    EOFileset

Figure 4-16  Example mkinstallp template file
```

We first declare the name of the package (Package Name). This will be used for creating the package file. The Fileset Name is the name is managed by the
**installp** command. It shows up in the software inventory, and it is seen by the **lslpp** command.

**Template file keywords**

Keywords with an asterisk (*) are required. It will cause **mkin** to fail if left blank or omitted in the template file. This is a list of the template file keywords:

- **Package Name**
  - Name of the package

- **Package VRMF**
  - Version, Release, Modification, and Fix level of the package

- **Update**
  - Is this an update package?

- **Fileset**
  - Start of a new Fileset
    - **Fileset Name**
      - Name of the fileset
    - **Fileset VRMF**
      - VRMF of the fileset
    - **Fileset Description**
      - Description of the fileset

- **Bosboot required**
  - Is a **bosboot** required when installing this fileset?

- **License agreement acceptance required**
  - Is license agreement acceptance required for this fileset?

- **Name of license agreement**
  - Name of the license agreement (see Note 1)

- **Include license files in this package**
  - Are the license files included in this package?

- **License file path**
  - Path of the license file(s) (see Note 2)

- **Requisites**
  - co/if/inst/pre-requisites for the fileset (see Note 3)

- **USRFiles**
  - Start of the USR part files section
    - /path/to/file
      - File path (see Note 4)
    - EOUSRFiles
      - End of the USR part files section

- **ROOT Part: [Y|N]**
  - Is there a ROOT part included in this fileset?
    - /path/to/file
      - File path (see Note 4)
    - EOROOTFiles
      - End of the ROOT part files section

- **EOFileset**
  - End of the Fileset

**Note 1:** The Name of license agreement is defined as LAR/path/to/license/agreement. License Agreement Requisite® (LAR).

The %L tag can be used in place of a hardcoded path to represent the locale of the machine that the package will be installed on. For example, if the package is installed in the en_US locale, then %L will be converted to en_US.
Creating the BFF package file

When the packaging buildroot directory structure, and after all package files are in their right places and the template file is created, you can run the `mkinstallp` command to generate the package. In our example, we specify the build directory (`-d`) and our template file (`-T`) with the `mkinstallp` command as shown in Example 4-262:

`mkinstallp -d /build/nodecust -T /build/nodecust/nodecust.template`

**Example 4-262 Creating a BFF/installp package file with mkinstallp**

root@master:/ mkinstallp -T /build/nodecust/nodecust.template -d /build/nodecust
Using /build/nodecust as the base package directory.
Cannot find /build/nodecust/.info. Attempting to create.
Using /build/nodecust/.info to store package control files.
Cleaning intermediate files from /build/nodecust/.info.

Using nodecust.template as the template file.
0503-880 mkinstallp: Warning: /etc/motd exists in another fileset on the system.
processing NODECUST 1.0.0.0 I package
processing NODECUST.rte 1.0.0.0 fileset
creating ./usr/lpp/NODECUST/liblpp.a
The `mkninstallp` command creates additional directory structure under our buildroot, BFF support files, and the BFF package file itself.

The package file is created under the `<buildroot>/tmp` directory with the package name (VRMF) and suffixed with `.bff`. The VRMF consist of four digits representing the Version, Release, Maintenance/Modification and Fix numbering. In our example, the path to the BFF file is:

```
/build/nodecust/tmp/NODECUST.1.0.0.0.bff
```

Some of the support files are found in the `<buildroot>/.info` directory, the `<buildroot>/lpp_name` package information file, the `<buildroot>/usr` directory for the `<buildroot>/usr/lpp/NODECUST/liblpp.a` archive file and the `<buildroot>/usr/lpp/NODECUST/inst_root` directory.

For additional information about the `mkninstallp` command and BFF package file format, refer to *AIX 5L Version 5.3 Commands Reference, Volume 3*, SC23-4890. Also refer to *General Programming Concepts: Writing and Debugging Programs*, SC23-4896, section “Packaging Software for Installation”.

### Examining the BFF package file

We can examine the BFF package file with the `restore` command. In Example 4-263, we use the quiet flag (`-q`) which prevents user input prompting, list (`-T`), verbose (`-v`) and device file (`-f`), and we specify the package filename.

```
Example 4-263   Examining the content of mkninstallp BFF/installp package

root@master:/build/nodecust/tmp: restore -qTv NODECUST.1.0.0.0.bff
New volume on NODECUST.1.0.0.0.bff:
Cluster 51200 bytes (100 blocks).
  Volume number 1
  Date of backup: Mon Jul  3 11:13:46 2006
  Files backed up by name
  User root
  0 ./
  166 ./lpp_name
  0 ./usr
  0 ./usr/lpp
  0 ./usr/lpp/NODECUST
  1146 ./usr/lpp/NODECUST/liblpp.a
  0 ./usr/lpp/NODECUST/inst_root
  1004 ./usr/lpp/NODECUST/inst_root/liblpp.a
  0 ./usr/lpp/NODECUST/inst_root/etc
  480 ./usr/lpp/NODECUST/inst_root/etc/motd
  0 ./etc
```
You can see that the motd file in Example 4-263 ended up under the directory 
./usr/lpp/NODECUST/inst_root/etc.

### Installing the package with `installp`

To install the package with the `installp` command, specify the package 
filename and package name (or the all keyword) as shown in Example 4-264. To 
uninstall the package, check the proper package name with `lslpp -l`, and then 
use this name with the `installp -u` command.

**Example 4-264 Installing the mkinstallp created package**

```
root@master:/build/nodecust/tmp: installp -ad NODECUST.1.0.0.0.bff NODECUST.rte
+-----------------------------------------------------------------------------+
Pre-installation Verification...
+-----------------------------------------------------------------------------+
Verifying selections...done
Verifying requisites...done
Results...

SUCCESES
-------

Filesets listed in this section passed pre-installation verification
and will be installed.

Selected Filesets
-----------------

NODECUST.rte 1.0.0.0                        # NODECUST

<< End of Success Section >>

FILESET STATISTICS
--------------------

1  Selected to be installed, of which:
    1  Passed pre-installation verification

---

1  Total to be installed

+-----------------------------------------------------------------------------+
Installing Software...
+-----------------------------------------------------------------------------+

installp: APPLYING software for:
           NODECUST.rte 1.0.0.0
Installing the package with NIM

To use the `mkminstallp` created package with NIM, it needs to be made available from a NIM `lpp_source` resource, just as any other BFF package. If you have several packages, you can create a separate NIM `lpp_source` specifically for them.

In the following examples, we assume that all packages are AIX VRMF (Version, Release, Maintenance/Modification and Fix)-independent; see Example 4-265.

Create the NIM `lpp_source` BFF/installp directory:

```
mkdir -p /export/pkgs/installp/ppc
```

Copy all `mkminstallp` created packages from their respective `<buildroot>/tmp` directory:

```
cp <buildroot>/tmp/*.bff /export/pkgs/installp/ppc
```

Create a Table of Content s (TOC) file (.toc) for the directory:

```
cd /export/pkgs/installp/ppc
inutoc .
cd -
```

Verify that the intended installation packages are accessible with the `installp` command by listing the directory TOC:

```
installp -qld /export/pkgs/installp/ppc
```

Example 4-265  `installp` command to list package directory for `mkminstallp` packages

```
root@master:/: installp -qld /export/pkgs/installp/ppc
Fileset Name      Level     I/U Q Content
```

---

sysck: 3001-036 WARNING: File /etc/motd
is also owned by fileset bos.rte.security.
Finished processing all filesets. (Total time: 1 secs).

```
+---------------------------------------------------------------+
Summaries:
+---------------------------------------------------------------+

Installation Summary
---------------------

<table>
<thead>
<tr>
<th>Name</th>
<th>Level</th>
<th>Part</th>
<th>Event</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>NODECUST.rte</td>
<td>1.0.0.0</td>
<td>USR</td>
<td>APPLY</td>
<td>SUCCESS</td>
</tr>
<tr>
<td>NODECUST.rte</td>
<td>1.0.0.0</td>
<td>ROOT</td>
<td>APPLY</td>
<td>SUCCESS</td>
</tr>
</tbody>
</table>
```
Create a NIM lpp_source resource with the nim command and define operation, as shown in Example 4-266.

**Example 4-266  The nim command and define operation for mkinstallp packages**

```
root@master:/: nim -o define -t lpp_source -a server=master -a location=/export/pkgs pkgs
```

Preparing to copy install images (this will take several minutes)...

Now checking for missing install images...

warning: 0042-267 c_mk_lpp_source: The defined lpp_source does not have the "simages" attribute because one or more of the following packages are missing:
   bos
   bos.net
   bos.diag
   bos.sysmgt
   bos.terminfo
   bos.terminfo.all.data
   devices.graphics
   devices.scsi
   devices.tty
   xlC.rte
   bos.mp
   devices.common
   bos.64bit

The warning message (0042-267) can be disregarded because we will not use this NIM lpp_source to perform BOS (base operating system) installations. We will only use it for additional software installations and updates to already-installed systems. We verify the BFF packages and the NIM lpp_source as shown in Example 4-267.

**Example 4-267  The lsnim command to display the BFF pkgs NIM lpp_source**

```
root@master:/: lsnim -l pkgs
```

```
pkgs:
  class    = resources
  type      = lpp_source
  arch      = power
  Rstate    = ready for use
  prev_state = verification is being performed
  location  = /export/pkgs
  alloc_count = 0
```
server = master

Verify that the intended installation packages are accessible with the `nim` command using the `lslpp` operation for a list of the directory TOC as shown in Example 4-268.

```
Example 4-268  The nim command and lslpp operation for mkinstallp packages

root@master:/: nim -o lslpp pkgs
NODECUST
   NODECUST.rte
```

Now the `pkgs NIM lpp_source` can be allocated to NIM clients and be used to install the `NODECUST.rte` fileset.

### 4.12.2 RPM

The RPM Package Manager (RPM) is another popular package-based installation tool, used in many Linux distributions and also introduced in AIX for installing in AIX Toolbox for Linux packages. These packages are usually files with file names suffixed with `.rpm` and installed by the `rpm` command.

http://www.rpm.org

On AIX 5L V5.3, the `rpm.rte` fileset is version 3. You will have to use the `rpm` command with the `-ba` flags to build RPM packages.

With Linux systems using version 4 of RPM, you must use the `rpmbuild` command instead.

To create an RPM package, you can use the following procedure:

1. Creating the build structure
2. Populating the build structure with programs and files
3. Creating the packaging SPEC file, for use by the `rpm` program
4. Creating the package file with the `rpm` program

We describe these steps in more detail in the following sections.

**Creating the build structure**

By default, the AIX RPM environment uses the `/opt/freeware/src/packages` directory as the top level for creating and building RPM packages. It is possible to change it to another top level, but for simplicity we choose to show the default method.
Under the /opt/freeware/src/packages directory, the subdirectories are used during different stages: during the build or the install of RPM packages:

- **BUILD** Source code hierarchy
- **SPECS** rpm SPEC specification file
- **SOURCES** gzip compressed tar archive created from the SPEC hierarchy
- **SRPMS** Source RPM package
- **RPMS/ppc** Binary RPM package for ppc architecture

We create a NIM client customization package, named NODECUST. The package will only replace the /etc/motd file.

### Populating the build structure

All files that will be installed should be put in their respective directories under <buildroot>. In our example, we create an motd file under the /opt/freeware/src/packages/BUILD/etc directory:

```
banner hello world >/opt/freeware/src/packages/BUILD/etc/motd
```

We set the file permissions on our new version of motd file to the same as the original (read-read-read only for owner-group-others):

```
chmod 444 /opt/freeware/src/packages/BUILD/etc/motd
```

From the BUILD hierarchy, we create a source file, the NODECUST-1.0-1.tar.gz file that is simply created by piping the tar archive output to gzip, and redirecting the output to the source file (as shown in Example 4-269), named according to the naming convention mentioned.

```
Example 4-269 Creating a compressed archive of BUILD directory
```

```
root@master:/: cd /opt/freeware/src/packages/BUILD
root@master:/: tar cf - | gzip -c > /opt/freeware/src/packages/SOURCES/NODECUST-1.0-1.tar.gz
```

The source and RPM package use the following basic naming convention, and expect the source file to be found in the /opt/freeware/src/packages/SOURCES directory:

```
<name>-<version>-<release>.<arch>.rpm
```

Where:

- **name** The package name
- **version** The software version
- **release** The package Release (the number of times the package has been rebuilt using the same version of the software)
arch

The architecture the package was built under, such as i686, or ppc

Creating the packaging SPEC specification file

The rpm SPEC specification file contains specifications for the installation package. The RPMs build and installation process is controlled by the SPEC file, which is the core of every RPM and SRPM (Source RPM).

By default, AIX rpm command uses the SPEC files in the /opt/freeware/src/packages/SPECS directory. For our examples, we use the SPEC file named /opt/freeware/src/packages/SPECS/NODECUST.spec as shown in Example 4-270.

Example 4-270 Sample RPM SPEC (.spec) file

<table>
<thead>
<tr>
<th>Name</th>
<th>NODECUST</th>
</tr>
</thead>
<tbody>
<tr>
<td>Summary</td>
<td>NODECUST perform local customization</td>
</tr>
<tr>
<td>Version</td>
<td>1.0</td>
</tr>
<tr>
<td>Release</td>
<td>1</td>
</tr>
<tr>
<td>Group</td>
<td>System Environment/Base</td>
</tr>
<tr>
<td>License</td>
<td>INTERNAL USE ONLY</td>
</tr>
<tr>
<td>Source</td>
<td>NODECUST-1.0-1.tar.gz</td>
</tr>
</tbody>
</table>

%description

NODECUST perform local customization

%build
%install
%files
%_builddir/etc/motd
%post

`cp %_builddir/etc/motd /etc/motd`

We declare our motd file using a macro, the %_builddir, so the file is handled and installed by the rpm command to the %_builddir/etc directory (which translates to the /opt/freeware/src/packages/BUILD/etc directory).

Note: For information on available macros on AIX, look in the /usr/opt/freeware/lib/rpm/macros file.

We declare the Source to be the NODECUST-1.0-1.tar.gz file created from our BUILD hierarchy. The motd file will be extracted from the tar.gz file into the /opt/freeware/src/packages/BUILD/etc directory.

To put our version of the motd file in the /etc directory, we use a %post stanza. We use the `cp` command to copy from the %_builddir path to the file /etc/motd.
The next step is to actually build the binary and source packages by issuing the `rpm` command as shown in Example 4-271:

```
rpm -ba <SPEC file name>
```

**Example 4-271  Creating an RPM**

```
root@master:/: rpm -ba /opt/freeware/src/packages/SPECS/NODECUST.spec  
Executing(%build): /bin/sh -e /var/opt/freeware/tmp/rpm-tmp.26112  
+ umask 022  
+ cd /opt/freeware/src/packages/BUILD  
+ exit 0  
Executing(%install): /bin/sh -e /var/opt/freeware/tmp/rpm-tmp.26112  
+ umask 022  
+ cd /opt/freeware/src/packages/BUILD  
+ exit 0  
Processing files: NODECUST-1.0-1  
Finding  Provides: (using /opt/freeware/lib/rpm/find-provides)...  
Finding  Requires: (using /opt/freeware/lib/rpm/find-requires)...  
PreReq: /bin/sh  
Wrote: /opt/freeware/src/packages/SRPMS/NODECUST-1.0-1.src.rpm  
Wrote: /opt/freeware/src/packages/RPMS/ppc/NODECUST-1.0-1.aix5.3.ppc.rpm
```

This `rpm -ba` command generates the following RPMs:

```
/opt/freeware/src/packages/SRPMS/NODECUST-1.0-1.src.rpm  
/opt/freeware/src/packages/RPMS/ppc/NODECUST-1.0-1.aix5.3.ppc.rpm
```

**Installing the package with RPM**

The RPM package can now be installed with the `-i`, `-U`, or `-F` flags of the `rpm` command. In Example 4-272, we install the RPM package with the `-ivvv` options of the `rpm` command (install and three times verbose). The `-i` flag with `rpm` will only work if the RPM is not already installed on the system. If the RPM packages are already installed, use the `-U` or `-F` flags. To uninstall the RPM, check the proper package name with `rpm -qa`, and then use this name with `rpm -e`.

**Example 4-272  Installing RPM with rpm**

```
root@master:/: rpm -ivvv /opt/freeware/src/packages/RPMS/ppc/NODECUST-1.0-1.aix5.3.ppc.rpm  
D: counting packages to install  
D: found 1 packages  
D: looking for packages to download  
D: retrieved 0 packages  
D: New Header signature  
D: Signature size: 68  
D: Signature pad : 4  
D: sigsize : 72  
D: Header + Archive: 1274  
D: expected size : 1274
```
D: opening database mode 0x102 in /var/opt/freeware/lib/rpm
D: found 0 source and 1 binary packages
D: requires: /bin/sh satisfied by db provides.
D: installing binary packages
D: New Header signature
D: Signature size: 68
D: Signature pad: 4
D: sigsize: 72
D: Header + Archive: 1274
D: expected size: 1274
D: package: NODECUST-1.0-1 files test = 0
D: file: /opt/freeware/src/packages/BUILD/etc/motd action: create
D: running preinstall script (if any)
NODECUST-1.0-1
GZDIO: 7 reads, 516 total bytes in 0.000 secs
D: running postinstall scripts (if any)
+ cp /opt/freeware/src/packages/BUILD/etc/motd /etc/motd

In the output of Example 4-272, you see the creation of the
/opt/freeware/src/packages/BUILD/etc/motd file, and the execution of our
postinstall script that copies it to /etc/motd.

**Installing the RPM package with NIM**

To use the rpm created package (or several such packages) with NIM, it needs to
be available from a NIM lpp_source resource, just as any other RPM package. If
you have several packages, create a separate NIM lpp_source for these
specifically.

In the following examples, we assume that all packages are AIX VRMF (Version,
Release, Maintenance/Modification and Fix)-independent.

Create the NIM lpp_source RPM directory:

```bash
mkdir -p /export/pkgs/RPMS/ppc
```

Copy all rpm created packages from the default <buildroot> directory:

```bash
cp /opt/freeware/src/packages/RPMS/ppc/*.rpm /export/pkgs/RPMS/ppc
```

Create a NIM lpp_source resource with the nim command and define operation
as shown in Example 4-273.

*Example 4-273  The nim command and define operation for RPM packages*

```bash
root@master:/: nim -o define -t lpp_source -a server=master -a location=/export/pkgs pkgs
```

Preparing to copy install images (this will take several minutes)...
Now checking for missing install images...

warning: 0042-267 c_mk_lpp_source: The defined lpp_source does not have the "simages" attribute because one or more of the following packages are missing:
  bos
  bos.net
  bos.diag
  bos.sysmgt
  bos.terminfo
  bos.terminfo.all.data
  devices.graphics
  devices.scsi
  devices.tty
  x1C.rte
  bos.mp
  devices.common
  bos.64bit

The warning message (0042-267) can be disregarded because we will not use this NIM lpp_source to perform BOS (base operating system) installations. We only use it for additional software installations and updates. Verify and display the RPM packages and the NIM lpp_source, as shown in Example 4-274.

Example 4-274  The lsnim command to display the RPM pkgs NIM lpp_source

root@master:/: lsnim -l pkgs
pkgs:
  class       = resources
  type        = lpp_source
  arch        = power
  Rstate      = ready for use
  prev_state  = verification is being performed
  location    = /export/pkgs
  alloc_count = 0
  server      = master

Verify that the intended installation packages are accessible with the nim command using the lslpp operation for a list of the directory TOC as shown in Example 4-275.

Example 4-275  The nim command and lslpp operation for mkinstallp packages

root@master:/: nim -o lslpp pkgs
NODECUST-1.0
Now, the pkgs NIM lpp_source can be allocated to NIM clients and used to install the NODECUST-1.0 RPM fileset.

If we use both the installp/ppc and RPMS/ppc directory, the nim command with lslpp operation will show the packages from both packaging formats as shown in Example 4-276.

Example 4-276 The nim command and lslpp operation for mkinstallp and rpm packages

```
root@master:/: nim -o lslpp pkgs
NODECUST
    NODECUST.rte
NODECUST-1.0
    NODECUST-1.0
```

**Bundles**

A NIM installp_bundle resource represents a file that contains the names of filesets that should be managed by NIM.

During an installation or maintenance operation, NIM mounts the installp_bundle file on the client machine, and make it usable for the clients local installp command. NIM automatically unmounts the resource from the client when the operation has completed.

Use any editor to create bundle files, we recommend the vi editor, which can contain comments and fileset names. Lines beginning with the pound (#) sign are recognized as comments and are ignored by the installation process.

The following are examples of predefined bundles:

- **BOS.autoi** Bundle file that BOS Auto Install product options will be installed by bos install as part of base operating system installation on all systems.

- **Server.bnd** Bundle file that contains filesets/packages that are likely to be required by Server systems.

- **Graphics.bnd** Bundle file that contains basic X11 software packages that provides support of graphical environments. Additional packages for graphical user interfaces are CDE.bnd, GNOME.bnd and KDE.bnd.

- **PerfTools.bnd** Bundle file that contains additional performance tools packages.
The system bundles are located in the `/usr/sys/inst.data/sys_bundles` directory. To list the system bundles, type the following:

```
ls /usr/sys/inst.data/sys_bundles/*.bnd
```

**Using bundles with NIM**

To create a bundle to be used as a NIM resource, create a file containing the filesets and packages to be installed. In this case we use the `/export/scripts` directory on the NIM master and call the file `nodecust.bundle`.

The file contains the package prefix type and then the package and fileset. The first line is the NODECUST.rte fileset we created in “Creating the BFF package file” on page 359 and the second line is the NODECUST-1.0 RPM package we created in “Creating the packaging SPEC specification file” on page 366; see Example 4-277.

**Example 4-277  NIM installp_bundle file**

```
I:NODECUST.rte  
R:NODECUST-1.0
```

Next, we create the NIM installp_bundle resource pointing to the bundle file with the `nim -o define` command, and with the installp_bundle type. In this case, we call our NIM resource bundle_nodecust as shown in Example 4-278.

```
nim -o define -a server=master -t installp_bundle -a
    location=/export/scripts/nodecust.bundle bundle_nodecust
```

We can examine the NIM installp_bundle resource with the `lsnim` command.

**Example 4-278  The installp_bundle NIM resource**

```
bundle_nodecust:
    class     = resources
    type      = installp_bundle
    Rstate    = ready for use
    prev_state= unavailable for use
    location  = /export/scripts/nodecust.bundle
    alloc_count= 0
    server    = master
```

**Installing NIM bundle (installp_bundle)**

To install the software specified in the bundle file, you can run the `nim` command and `cust` operation. In Example 4-279, we install the NIM bundle_nodecust on the NIM client LPAR55. Note that the installation process by default starts with the RPM packages.
Example 4-279  installp_bundle containing both BFF/installp and RPM packages

root@master:/: nim -o cust -a lpp_source=pkgs -a installp_flags=agXY -a installp_bundle=bundle_nodecust LPAR55

Validating RPM package selections ...

NODECUST

-----------------------------

Pre-installation Verification...

Verifying selections...done
Verifying requisites...done
Results...

SUCCESES

---

Filesets listed in this section passed pre-installation verification and will be installed.

Selected Filesets

--------------

NODECUST.rte 1.0.0.0 # NODECUST

<< End of Success Section >>

FILESET STATISTICS

-------------------

1 Selected to be installed, of which:
   1 Passed pre-installation verification

---

1 Total to be installed

Installing Software...

installp: APPLYING software for:

   NODECUST.rte 1.0.0.0

Finished processing all filesets.  (Total time: 1 secs).

Summaries:

Installation Summary
4.13 NIM and Virtual I/O (VIO)

If your environment has an IBM System p5 running in AIX 5L V5.3, and is connected to a Hardware Management Console (HMC), you can set up a VIO server. The VIO server provides Virtual SCSI that allows you to create more partitions (VIO clients) than the number available physical storage and network adapters in the IBM System p5 Central Electronic Complex (CEC). It also enables you to share I/O resources between partitions.

Furthermore, the VIO server provides shared Ethernet capabilities to allow multiple partitions to share Ethernet adapters if those partitions need to access the external network.

If you have an environment where most of your partitions are within a POWER5 server, you can configure the NIM master in one of the VIO clients. With this, you can configure the NIM network to allow high speed interpartition communication within the same server through the POWER Hypervisor VLAN.

4.13.1 Virtual SCSI

When you need to create multiple partitions but do not have enough SCSI/FC adapters, you can set up a VIO server to share the storage resources.

Virtual SCSI is based on a client/server model. The VIO server acts as a server owning the physical resources, and the partition is a client accessing the Virtual SCSI resources provided by the server.

For every VIO client, you need to create a dedicated virtual SCSI adapter. After it is created, you can use a VIO server’s physically-attached disks in two ways: assigning LV(s) from a VG to the VIO client; or assigning one entire LUN (hdisk) to the VIO client.

For a brief description of the Virtual SCSI server and client adapter in the Hardware Management Console (HMC), as well as the LV and disk configuration and how they are mapped to the virtual SCSI server adapter, refer to 4.13.4, “Setting up the VIO server and configuring the NIM master in the VIO client” on page 374.
In Virtual I/O server version 1.2, virtual optical devices such as DVD-ROM or DVD-RAM are also supported. You can create a virtual optical device from the physical optical device. With this virtual optical device, partitions are able to share the physical optical device in the VIO server.

### 4.13.2 Virtual Shared Ethernet

Virtual Ethernet allows interpartition communication without any physical network adapter. But if your partitions need to communicate with the external network, you need to configure a Shared Ethernet Adapter (SEA) in the VIO server. The Shared Ethernet Adapter provides the connection between the physical network with the virtual network. It enables multiple partitions to share the same physical network adapter.

### 4.13.3 Considerations when using a VIO server

We recommend that you allocate sufficient CPU resources to the VIO server or even use two VIO servers: one performing the Virtual SCSI, and the other performing the Virtual Ethernet. It is also a good idea to have VIO server redundancy so that you can perform any VIO server maintenance, should you need to bring down the VIO server during maintenance.

Refer to Chapter 5, *Advanced POWER Virtualization on IBM System p5*, SG24-7940, for more detailed information about VIO redundancy.

### 4.13.4 Setting up the VIO server and configuring the NIM master in the VIO client

This section describes the steps to set up the Virtual SCSI and Virtual Ethernet on a VIO server. We assume you already know how to create profiles in the Hardware Management Console (HMC) and set up the VIO server. The emphasis here is on Virtual SCSI and the Virtual Ethernet. Refer to *Advanced POWER Virtualization on IBM System p5*, SG24-7940, for more detailed information.

Figure 4-17 shows the disk setup of the VIO server with two VIO clients. One of the clients is configured as the NIM master.
Figure 4-17 Virtual SCSI setup

Figure 4-18 shows the VLAN configuration for the same environment (one VIO server with two VIO clients).
Setting up the VIO server profile and client profile
Here we demonstrate setting up the Virtual SCSI and the Virtual Ethernet.

1. Open the VIO server's profile. Perform the Virtual SCSI and Ethernet creation as shown in Figure 4-19 on page 376.
2. Create the Virtual SCSI in the VIO server’s profile. Click **Create server adapter...** as shown in Figure 4-20.

![Figure 4-20 Click Create server adapter...](image)

3. Specify the server’s SCSI slot ID. If you have already created an LPAR, you can enter the client partition name and its slot ID.

If not, select the setting **Any client partition can connect**. (Remember to come back to select the correct Client partition after the client partition is created.) See Figure 4-21 on page 377.

![Figure 4-21 Key in the server and client virtual SCSI ID](image)
4. Create the Virtual Ethernet on the VIO server. Click the **Ethernet** tab, then click **Create adapter...** as shown in Figure 4-22.

![Logical Partition Profile Properties: test @ SARK-520-05CS44E](image)

**Figure 4-22  Create Virtual Ethernet on VIO server**

5. Enter the Virtual SCSI slot ID and the VLAN ID.

   If you need to create a Shared Ethernet adapter to allow the partition to access the external network, select **Access external network**; see Figure 4-23 on page 378.

![Virtual Ethernet Adapter](image)

**Figure 4-23  Enter the Virtual Ethernet Slot ID and VLAN ID**

6. After completing the VIO server profile, proceed to the VIO client profile. The steps involved are very similar. Select **Create client adapter...**; Figure 4-24 illustrates the Virtual SCSI on the client.
7. When configuring the Virtual Ethernet on the VIO client, enter the Slot ID and the VLAN ID.

You do not need to select Access external network; see Figure 4-25 on page 379.

Figure 4-24 Create Virtual SCSI on VIO client

Figure 4-25 Enter Virtual Ethernet slot ID and VLAN ID
Defining the Volume Group and Logical Volumes

After defining the virtual SCSI and virtual Ethernet in the Hardware Management Console (HMC) profile, create the Volume Group (VG) and Logical Volumes (LVs) for client usage in the VIO server.

Because the NIM master requires a considerable amount of disk space, we assigned an entire hdisk and created a LV to the VIO client, which we used for our NIM master. We followed this procedure:

1. Create a VG to be partitioned into LVs for the usage of the VIO clients’ rootvg.
   For example:
   ```bash
   $ mkvg -f -vg rootvg_clients hdisk2
   ```
   If you need to extend the rootvg_clients VG, use the following command:
   ```bash
   $ extendvg -f rootvg_clients hdisk3
   ```

2. Create LVs for usage by the VIO clients.
   We created a LV on the rootvg_client VG for NIM master named rootvg_nim, and another LV for a NIM client named rootvg_lpar2; for example:
   ```bash
   $ mklv -lv rootvg_nim rootvg_clients 10G hdisk2
   $ mklv -lv rootvg_lpar2 rootvg_clients 10G hdisk2
   ```

Example 4-280 shows the details of the Volume Group configuration.

```
Example 4-280   The Volume Group information

$ lspv
NAME            PVID  VG               STATUS
hdisk0           0000c83603e569ef  rootvg     active
hdisk1           none    None           None
hdisk2           0000c836a42eeeb1  rootvg_clients active
hdisk3           0000c836a42f5b75  rootvg_clients active
hdisk4           0000c836cc576c89  None           None
```

Configuring the virtual SCSI device

Before we can create the Virtual target device, we need to identify the virtual host devices, vhosts, on the VIO server. These vhosts are the virtual SCSI server adapters. They are configured after you have defined all the virtual SCSI in the VIO server’s profile. You need to run the `cfgdev` command in the VIO server to configure these vhosts, as follows:

1. Verify the virtual host devices.

   Example 4-281 shows the command listing all the vhosts. You can see the slot ID that is assigned when you specify it in the VIO server’s profile; for example, vhost0 has the Virtual SCSI slot ID of 21.
Example 4-281  List the vhosts info

$ lsdev -virtual
name      status                  description
vhost0    Available              Virtual SCSI Server Adapter
vhost1    Available              Virtual SCSI Server Adapter

$ lsdev -vpd |grep vhost
vhost1    U9131.52A.650E4DG-V2-C22  Virtual SCSI Server Adapter
vhost0    U9131.52A.650E4DG-V2-C21  Virtual SCSI Server Adapter

2. Create Virtual Target Device mapping (VTD). See the mapping in Example 4-282.

After the hdisk, LV, and the vhosts are in place, we can create the Virtual Target devices.

For the NIM master partition using vhost0, enter:

$ mkvdev -vdev rootvg_nim -vadapter vhost0 -dev vrootvg_nim
$ mkvdev -vdev hdisk4 -vadapter vhost0 -dev vnimvg_nim

For the NIM client lpar2 using vhost1, enter:

$ mkvdev -vdev rootvg_lpar2 -vadapter vhost1 -dev vrootvg_lpar2

Example 4-282  Virtual target device mapping

$ lsmap -all
SVSA            Physloc Client Partition ID
vhost0          U9131.52A.650E4DG-V2-C21  0x00000003
VTD             vrootvg_nim
LUN             0x8100000000000000
Backing device  rootvg_nim
Physloc

VTD             vnimvg_lpar1
LUN             0x8200000000000000
Backing device  hdisk4
Physloc         U787F.001.DPM0D1L-P1-T11-L5-L0

SVSA            Physloc Client Partition ID
vhost1          U9131.52A.650E4DG-V2-C22  0x00000004
VTD             vrootvg_lpar2
LUN             0x8100000000000000
Backing device  rootvg_lpar2
Physloc
Configuring the virtual optical device

Configuring the optical device as a virtual SCSI device is similar to configuring the LV or disk as a virtual SCSI device. First, check that the physical optical device is configured in the VIO server, as shown in Example 4-283.

```
Example 4-283   List physical optical device
$ lsdev -vpd |grep cd
   cd0U787F.001.DPM0D1L-P4-D2IDE DVD-RAM Drive
```

After the physical device is available, create the virtual optical SCSI target device. In Example 4-284, the virtual optical device is assigned to the vhost0.

```
$ mkvdev -vdev cd0 -vadapter vhost0
Example 4-284   List virtual optical SCSI target device
$ lsmap -vadapter vhost0
SVSA            Physloc      Client Partition ID
vhost0          U9131.52A.650E4DG-V2-C21  0x00000003
VTD             vrootvg_nim
LUN             0x8100000000000000
Backing device  rootvg_nim
Physloc

VTD             vnimvg_lpar1
LUN             0x8200000000000000
Backing device  hdisk4
Physloc          U787F.001.DPM0D1L-P1-T11-L5-L0

VTD             vtopt0
LUN             0x8300000000000000
Backing device  cd0
Physloc          U787F.001.DPM0D1L-P4-D2

$ lsdev -vpd |grep vtopt
   vtopt0    U9131.52A.650E4DG-V2-C21-L3  Virtual Target Device - Optical
   Media
```

Note: Only one virtual target device can be created for a particular physical optical device.
Follow these steps if you need to assign the optical device to another partition.

1. Remove the existing virtual optical device on the client partition that is having the virtual optical device.

   From the VIO client, enter:
   
   ```sh
   # rmdev -dl cd0
   ```

2. Remove the virtual optical SCSI target device on the VIO server.

   From the VIO server, enter:
   
   ```sh
   $ rmvdev -vdev cd0
   ```

3. Create the virtual optical SCSI target device with the desired client's vhost adapter.

   From the VIO server, enter:
   
   ```sh
   $ mkvdev -vdev cd0 -vadapter vhost1
   ```

4. Execute the `cfgmgr` command on the new client to configure the cd0 device.

### Configuring the Shared Virtual Ethernet

If the partitions in the IBM p5 need to access the external network, you must configure the Shared Ethernet Adapter (SEA). Follow these steps to configure the SEA adapter.

1. Check the existing network adapter.

   Example 4-285 shows that we have a physical network adapter `ent0` and the Virtual Ethernet `ent1` defined, and `ent1` has slot ID 3 (C3), which is defined in the VIO server's profile.

   **Example 4-285  List network adapter**
   
   ```
   $ lsdev -type adapter
   name            status description
   ent0            Available 10/100/1000 Base-TX PCI-X Adapter(14106902)
   ent1            Available Virtual I/O Ethernet Adapter (l-lan)
   ```

   ```sh
   $ lsdev -vpd |grep ent
   Model Implementation: Multiple Processor, PCI bus
   ent1 U9131.52A.650E4DG-V2-C3-T1 Virtual I/O Ethernet Adapter (l-lan)
   ```

   ```
   ent0 U787F.001.DPM0D1L-P1-T5 10/100/1000 Base-TX PCI-X Adapter(14106902)
   ```
2. Create the Shared Ethernet Adapter.

Now we can create the Shared Ethernet Adapter using the physical Ethernet adapter ent0 and the Virtual Ethernet ent1; see Example 4-286.

$ mkvdev -sea ent0 -vadapter ent1 -default ent1 -default 1

**Example 4-286**  List the Shared Ethernet Adapter

```
$ lsdev -virtual |grep ent
ent1   Available  Virtual I/O Ethernet Adapter (l-lan)
ent2   Available  Shared Ethernet Adapter
```

```
$ lsmap -all -net
SVEA   Physloc
------- -------------------------------
ent1   U9131.52A.650E4DG-V2-C3-T1

SEA          ent2
Backing device ent0
Physloc      U787F.001.DPM0D1L-P1-T5
```

3. Configure the IP address of the Shared Ethernet adapter.

We configure the IP address on the Shared Ethernet adapter ent2:

$ mktcpip -hostname viol inetaddr 10.1.1.51 -interface en2 -start \ 
-netmask 255.255.255.0

**Installing AIX in the VIO client partition**

After assigning the disk and optical device like DVD-ROM to the client partition, bring up the partition and install the AIX operating system (OS).

After the AIX operating system installation is completed, configure the NIM master as explained in Chapter 3, “Basic configuration of a Network Installation Manager environment” on page 51. After the NIM master and NIM client is set up, install the NIM client through the NIM master.

Example 4-287 shows the Virtual devices in the client partition; in this case, the NIM master.

**Example 4-287**  List virtual SCSI disk, optical and Ethernet devices in VIO client

```
Virtual SCSI disk Information
# lscfg -vl vscsi0
  vscsi0   U9131.52A.650E4DG-V3-C2-T1  Virtual SCSI Client Adapter

Device Specific.(YL)........U9131.52A.650E4DG-V3-C2-T1
```

### Chapter 4. Network Installation Manager scenarios

#### 4.14 Backup and restore of the VIO Server using NIM

There are several ways to perform backup and restore of VIO server. You can perform this task by tape, DVD-RAM or file system. In this section, we explain how to perform the backup and restore through the NIM server.

**Note:** At the time of writing, the `installios` command on AIX only supports using VIO base media. It is not yet supported on VIO backup images.

#### 4.14.1 Backup of VIO server

We export the NIM master server's mksysb directory to the VIO server, and then perform a NFS mount of the directory, as shown in Example 4-288.

```bash
# lspv
hdisk0  0000c836a446e179  rootvg  active
hdisk1  0000c836cc576c89  nimvg  active

# lscfg -vl hdisk0
hdisk0  U9131.52A.650E4DG-V3-C2-T1-L810000000000 Virtual SCSI Disk Drive

# lscfg -vl hdisk1
hdisk1  U9131.52A.650E4DG-V3-C2-T1-L820000000000 Virtual SCSI Disk Drive

Virtual SCSI Optical device information

# lsdev -C |grep cd

cd0        Available       Virtual SCSI Optical Served by VIO Server

# lscfg -vl cd0

 Virtual SCSI Optical Served by VIO Server

cd0  U9131.52A.650E4DG-V3-C2-T1-L820000000000 Virtual SCSI Optical Served by VIO Server

Virtual Ethernet Information

# lsdev -C |grep ent0

ent0       Available       Virtual I/O Ethernet Adapter (1-lan)

# lscfg -vl ent0

 Virtual I/O Ethernet Adapter (1)

ent0  U9131.52A.650E4DG-V5-C3-T1 Virtual I/O Ethernet Adapter (1)

Network Address..............1A8CF000501E
Displayable Message........Virtual I/O Ethernet Adapter (1-lan)
Device Specific.(YL)........U9131.52A.650E4DG-V5-C3-T1
On the VIO server:

1. Create a temporary NFS mount point.
   
   $ mkdir viobackup

2. Mount the NIM master, vlpar1, in the server's mksysb directory.
   
   $ mount vlpar1:/export/images /home/padmin/viobackup

### Example 4-288  List nfs mount directory on VIO server

```
$ mount
node mounted mounted over vfs date options
---- -------- ------------- ----- ------ ----------
/dev/hd4 /       jfs2 Jun 13 09:42 rw,log=/dev/hd8
/dev/hd2 /usr    jfs2 Jun 13 09:42 rw,log=/dev/hd8
/dev/hd9var /var  jfs2 Jun 13 09:43 rw,log=/dev/hd8
/dev/hd3 /tmp    jfs2 Jun 13 09:43 rw,log=/dev/hd8
/dev/hd1 /home   jfs2 Jun 13 09:43 rw,log=/dev/hd8
/proc    /proc   procfs Jun 13 09:43 rw
/dev/hd10opt /opt jfs2 Jun 13 09:43 rw,log=/dev/hd8
vlpar1 /export/images /home/padmin/viobackup nfs3 Jun 19 17:04
```

3. Perform the VIO backup using the `backupios` command as shown in Example 4-289. The VIO.mksysb is the mksysb filename.
   
   $ backupios -file /home/padmin/viobackup/VIO.mksysb -mksysb

### Example 4-289  Backup VIO mksysb using backupios command

```
$ backupios -file /home/padmin/viobackup/VIO.mksysb -mksysb
Backup in progress. This command can take a considerable amount of time to complete, please be patient...

Creating information file (/image.data) for rootvg....

Creating list of files to back up.
Backing up 29181 files..............................
26047 of 29181 files (89%)
29181 of 29181 files (100%)
0512-038 savevg: Backup Completed Successfully.
```

**Note:** You need to specify the `-mksysb` option in the `backupios` command. This creates the mksysb image for the use of the NIM master server.

Use the `backupios` command without the `-mksysb` option only when you want install the VIO through the HMC.
We recommend that you back up the following VIO configuration information. You can use this information to restore the VIO if the mksysb restore does not perform successfully.

The information to backup is the following:

- **All physical volume groups and logical volumes devices**
  
  Commands: `lsvg ; lsvg -lv <VGname>; lspv; lspv -lv hdisk#`

- **All physical disk and virtual Logical Volumes**
  
  Command: `lsdev -type disk`

- **All physical and virtual adapters**
  
  Command: `lsdev -type adapter`

- **Mapping between physical devices / logical volume and virtual devices**
  
  Commands: `lsmap -all ; lsmap -vadapter vhost# ; lsmap -all -net`

- **Network information**
  
  Commands: `netstat -state ; netstat -num -state ; netstat -routinfo`

### 4.14.2 Restoring the VIO server

You can restore the VIO server using steps that are similar to restoring an AIX NIM client. Create a NIM mksysb resource from the image created by the `backupios` command, as described in 4.14.1, “Backup of VIO server” on page 385. Next, create the SPOT using this mksysb resource. After the mksysb and the SPOT resource are in place, you can carry out the pull BOS installation to restore the VIO server.

Follow these steps to restore the VIO server:

1. Define a mksysb resource.

   Define the mksysb resource from the `/export/images/VIO.mksysb` image as shown in Example 4-290 on page 387.

   ```
   # smitty nim_mkres
   Select “mksysb = a mksysb image”
   ```

   **Example 4-290 Define a mksysb resource**
2. Define a SPOT resource.

Define the SPOT from the mksysb resource defined in the previous step. See Example 4-291.

```
# smitty nim_mkres
Select “spot = Shared Product Object Tree - equivalent to /usr file”
```

**Example 4-291  Define SPOT resource using mksysb resource**

Define a Resource
Type or select values in entry fields.
Press Enter AFTER making all desired changes.

```
* Resource Name           [SPOT-VIO]
* Resource Type           spot
* Server of Resource      [master] +
* Source of Install Images [MK-VIO] +
* Location of Resource    [/export/spot] /
Expand file systems if space needed? yes +
Comments                   []
installp Flags
COMMIT software updates?  no +
SAVE replaced files?       yes +
AUTOMATICALLY install requisite software? yes +
OVERWRITE same or newer versions? no +
VERIFY install and check file sizes? no +
```

3. Perform the BOS installation (pull mode).

After the SPOT and the mksysb resources are in place, you can allocate both resources and perform a BOS installation through the NIM pull installation.
Refer to 3.1, “Setting up a basic NIM environment” on page 53 for information about how to create SPOT and mksysb resources and perform BOS installation.

You will receive a warning message stating that the SPOT level is older than the mksysb level, as shown in Example 4-292, which you can ignore. You are still able to use this SPOT to perform the BOS installation.

**Example 4-292  Warning message when perform BOS installation**

```
warning: 0042-360 m_bos_inst: The SPOT level is older than the mksysb level. Therefore,
the BOS installation may encounter problems.
Update the SPOT to match the mksysb level or create a
new SPOT that has the same level.
```

4. Reset the NIM BOS installation operation.

After the restoration is completed, you have to reset the NIM BOS installation operation in the NIM master as shown in Example 4-293. Follow these steps when using the SMIT menus:

```
# smitty nim
Perform NIM Administration Tasks
Manage Machines
Perform Operations on Machines
Select the Target Machine
Select “reset = reset an object’s NIM state”
```

Or, using SMIT Fast Path, execute `smitty nim_mac_op`

**Example 4-293  Reset NIM client BOS installation Operation**

```
Reset the NIM State of a Machine

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

[EntryFields]
Target Name         VI02
Deallocate All Resources?
   (removes all root data for
diskless/dataless clients)
Force               yes+
```

In the VIO server, you need to import all the other Volume Groups. The `bosinst.data` of the VIO mksysb image, the IMPORT_USER_VGS is set to no. You need to create the `bosinst_data` resource if you want to import the user VG after the NIM restoration.
Next, check the VIO configuration:

- All physical and Logical volumes created for the VIO clients are in open/synced:
  
  `lsvg -lv <VGname>`

- All the virtual devices:
  
  `lsmap -all`

- All the network configuration:
  
  `lsmap -all -net`  
  `netstat -state ; netstat -num -state ; netstat -routinfo`

After everything is in place, you can activate each VIO client.

### 4.15 Using RSCT PeerDomain with HANIM

When using HANIM (see 4.1, “High Availability Network Installation Manager” on page 124), the NIM master and the alternate NIM master are not aware of each other’s state. The takeover of the role as acting NIM master is based on whether or not NIM clients want to use a specific system as their NIM master. The NIM master for a NIM client is specified in the client’s `/etc/niminfo` file.

Here we show how RSCT PeerDomain (RPD) can be used to automate HANIM takeover operations. The purpose is only to execute the appropriate `nim` command to perform a takeover of NIM clients (change their `/etc/niminfo` file); refer to Figure 4-26 on page 391.
An **RSCT peer domain** is a cluster of nodes configured for high availability, and it uses the following:

- RSCT core cluster security services for authentication
- RSCT core Topology Services subsystem for node/network failure detection
- RSCT core Group Services subsystem for cross node/process coordination
- Resource Monitoring and Control (RMC) subsystem for coordination between the various RSCT subsystems

We use the following POWER5 logical partitions:

1par55  This will be the first and original NIM master (RPD node one).
1par56  This will be the first and alternate NIM master (RPD node two).
1par6  This will be the first and only NIM client (already running as a NIM client to another NIM master environment).

All the LPARs are configured in the same way, using VIO servers for disk and network resources, and CPU micropartitioning, as shown in Example 4-294.

**Example 4-294  Basic LPAR config for RSCT PeerDomain HANIM examples**

```bash
root@lpar56:/ lscfg -vl hdisk0
  hdisk0 U9111.520.65C544E-V6-C2-T1-L810000000000 Virtual SCSI Disk Drive

root@lpar56:/ lscfg -vl ent0
  ent0 U9111.520.65C544E-V6-C3-T1 Virtual I/O Ethernet Adapter (1-lan)
```
The node configuration will only use the ent0 network virtual network adapter on the cluster nodes, and all NIM database and resource file systems will be local to each of the two cluster nodes. HANIM functionality will be used to keep the database synchronized and resources replicated.

**Note:** In this scenario, we assume that one NIM master contain all server resources that are needed to service the network.

The RSCT PeerDomain (RPD) configuration is made using these assumptions and requirements regarding availability:

- The systems management personnel shall not have to restore and reconfigure the NIM server in case of hardware failure.
- The longest downtime for the NIM server shall be two hours.
- Hardware failures might occur during the NIM server's lifetime, but is unlikely.
- Planned downtime will occur during the NIM server's lifetime to install new firmware or system updates.
- In case of system failure of the acting NIM master, the RSCT peer will perform takeover of the NIM clients.

Based on these assumptions and requirements, we used AIX 5L V5.3 TL5 and RSCT V2.4.5 (use SUMA to download updates to AIX and RSCT respectively, see 4.10, “NIM and Service Update Management Assistant” on page 319).

After the NIM master has performed the BOS rte install of the LPARs, they are customized with the following NIM commands for the NIM clients. The NIM client name in the following examples is LPAR55 as shown in Example 4-295 on page 393. First it is defined in the current NIM master (hostname master), then an AIX 5.3 TL5 SPOT (cosi5305) and NIM lpp_source (lpp5305) are allocated. Finally, the bos_inst operation is performed to reinstall the NIM client.

After this, additional bos filesets are installed: updates to the rsct.core, together with the bos.sysmgmt.nim.master fileset for NIM master functionality itself. However, first we want to have two RPM packages installed: openssl and openssh.
The same is done for the NIM client LPAR56.

Example 4-295  NIM master additional software updates of RSCT PeerDomain nodes

root@master:/: nim -o define -t standalone -a if1="net_10_1_1 lpar55 0" LPAR55
root@master:/: nim -o allocate -a spot=cosi5305 -a lpp_source=lpp5305 LPAR55
root@master:/: nim -o bos_inst -a source=rte LPAR55
root@master:/: nim -o cust -a lpp_source=lpp5305 -a installp_flags=agXY -a
filesets="openssl-0.9.7d-2 openssh.base bos.adt.libm bos.adt.syscalls rsct.core
bos.sysmgt.nim.master" LPAR55

Now we are ready to configure the RSCT PeerDomain, and activate it. First we make sure that /etc/hosts on each node contain the IP-address of both peer nodes and of the client, lpar6. For our purposes, we use the following IP-addresses:

10.1.1.55  lpar55
10.1.1.56  lpar56
10.1.1.6   lpar6

We also add the NSORDER variable to /etc/environment to ensure that we use the local systems /etc/hosts file to resolve hostnames to IP-addresses, and log in again (we could also use the /etc/netsvc.conf or /etc/irs.conf files for the same purpose; see “Setting up IP name resolution” on page 65):

NSORDER=local,bind

RSCT PeerDomain configuration

Run the preprpnode command on both nodes. In Example 4-296 we use the -V flag only with the preprpnode command. To get more detailed output use the -T flag also.

Example 4-296  Using preprpnode for the RSCT PeerDomain

root@lpar55:/: preprpnode -V lpar55 lpar56
Beginning to prepare nodes to add to the peer domain.
Completed preparing nodes to add to the peer domain.

root@lpar56:/: preprpnode -V lpar55 lpar56
Beginning to prepare nodes to add to the peer domain.
Completed preparing nodes to add to the peer domain.

Note: RPM packages should be in the NIM lpp_source/RPMS/ppc directory (in this example, the full path to this directory on the NIM master is /export/lpp_source/lpp5305/RPMS/ppc).
Now, we create the actual RSCT PeerDomain Cluster with the `mkrpdomain` command as shown in Example 4-297. The peer domain name is NIMESIS and consisting of two nodes: lpar55 and lpar56.

**Example 4-297  Create the RSCT PeerDomain with mkrpdomain**

```
root@lpar55:/~ mkrpdomain -V NIMESIS lpar55 lpar56
Making the peer domain "NIMESIS".
Completed making the peer domain "NIMESIS".
```

We check the status of the NIMESIS cluster with the `lsrpdomain` command as shown in Example 4-298.

**Example 4-298  Checking status of RSCT PeerDomain after mkrpdomain command**

```
root@lpar55:/~ lsrpdomain
Name    OpState RSCTActiveVersion MixedVersions TSPort GSPort
NIMESIS Offline 2.4.5.2           No 12347 12348
```

Example 4-298 shows that the NIMESIS cluster is Offline, so we start it with the `startrpdomain` command as shown in Example 4-299.

**Example 4-299  Starting the RSCT PeerDomain after mkrpdomain command**

```
root@lpar55:/~ startrpdomain -V NIMESIS
Starting the peer domain "NIMESIS".
Completed starting the peer domain "NIMESIS".
```

We again check the status of the NIMESIS cluster with the `lsrpdomain` command as shown in Example 4-300.

**Example 4-300  Checking status of RSCT PeerDomain after startrpdomain command**

```
root@lpar55:/~ lsrpdomain
Name    OpState RSCTActiveVersion MixedVersions TSPort GSPort
NIMESIS Pending online 2.4.5.2           No 12347 12348
```

```
root@lpar55:/~ lsrpdomain
Name    OpState RSCTActiveVersion MixedVersions TSPort GSPort
NIMESIS Online 2.4.5.2           No 12347 12348
```

Example 4-300 shows that the NIMESIS cluster is Pending online. When we run the `lsrpdomain` command a second time, it has become Online and is ready for use. After starting the RSCT PeerDomain, it will take about a minute before it is online.
If you get the following error message when using `lsrpdomain` command, simply wait a moment and try again:

```
/usr/sbin/rsct/bin/lsrsrc-api: 2612-022 A session could not be established with the RMC daemon on "local_node".
```

Next, we use the `lsrpnode` command to check the individual status of our NIMESIS RSCT PeerDomain cluster nodes as shown in Example 4-301.

**Example 4-301  Checking status of RSCT PeerNodes after `startrpdomain` command**

```
root@lpar55:/: lsrpnode
Name   OpState RSCTVersion
lpar55 Online 2.4.5.2
lpar56 Online 2.4.5.2
```

Both are `Online` as expected, with the `rsct.core` fileset level of `2.4.5.2`. You can verify this by executing the following `lslpp` command on each node:

```
lslpp -L rsct.core.rmc
```

**Summary:** To create an RSCT PeerDomain cluster with two nodes, run the following commands:

1. `/SM590000 preprpnode node1 node2 # on node1`
2. `/SM590000 preprpnode node1 node2 # on node2`
3. `/SM590000 mkrpdomain RPD node2 node2`
4. `/SM590000 startrpdomain RPD`

### Checking the RSCT PeerDomain configuration

To check the RSCT PeerDomain configuration, we use the `lsrsrc` command to access specific RSCT resource managers (RM).

A *resource manager* is a daemon process that provides the interface between Resource Monitoring and Control subsystem (RMC) and actual physical or logical entities. Although RMC provides the basic abstractions (resource classes, resources, and attributes) for representing physical or logical entities, it does not itself represent any actual entities. A resource manager maps actual entities to RMCs abstractions. The RSCT RMC subsystem (`ctrmc`) can be monitored with the `lssrc` command. Example 4-302 shows the registered resource managers.

**Example 4-302  Listing dynamic information from the ctrmc with the lssrc (not lssrc)**

```
root@lpar55:/: lssrc -ls ctrmc
```

<table>
<thead>
<tr>
<th>Name</th>
<th>ClassKey</th>
<th>ID</th>
<th>FD</th>
<th>SHMID</th>
</tr>
</thead>
<tbody>
<tr>
<td>IBM.WLMRM</td>
<td>1</td>
<td>0</td>
<td>-1</td>
<td>-1</td>
</tr>
</tbody>
</table>
IBM.DRM                      | 1 | 1 | 26 | 3145730  
IBM.ConfigRM                | 1 | 2 | 23 |   -1      
IBM.ERRM                    | 1 | 3 | 24 |   -1      
IBM.AuditRM                 | 1 | 4 | 20 |   -1      
IBM.FSRM                    | 1 | 5 |   -1 |   -1     
IBM.HostRM                   | 1 | 6 | 19 | 3145731   
IBM.SensorRM                 | 1 | 7 |   -1 |   -1     
IBM.LPRM                    | 1 | 8 | 29 |   -1      
IBM.ServiceRM                | 1 | 9 | 27 | 3145729   
IBM.CSMAgentRM               | 1 |10 | 21 |   -1     
IBM.HacmpRgRm                | 1 |11 |   -1 |   -1     

Each resource manager represents a specific set of administrative tasks or system features. The resource manager identifies the key physical or logical entity types related to that set of administrative tasks or system features, and defines resource classes to represent those entity types.

Example 4-303 shows the current registered resource managers on one of our cluster nodes, and in the following examples we will examine the IBM.PeerDomain and IBM.PeerNode, resource managers in more detail.

Example 4-303   Listing resource managers with lsrsrc (not lssrc)

```
root@lpars55:/$ lsrsrc | pr -t -2

<table>
<thead>
<tr>
<th>class_name</th>
<th>&quot;IBM.PeerNode&quot;</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;IBM.Association&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.ATMDevice&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.AuditLog&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.AuditLogTemplate&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.Condition&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.EthernetDevice&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.EventResponse&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.FDDIDevice&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.Host&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.FileSystem&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.PagingDevice&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.PhysicalVolume&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.Processor&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.Program&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.TokenRingDevice&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.Sensor&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.Sfp&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.ServiceEvent&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.ManagementServer&quot;</td>
<td></td>
</tr>
<tr>
<td>&quot;IBM.PeerDomain&quot;</td>
<td></td>
</tr>
</tbody>
</table>
```
Using the `lsrsrc` command, we can examine both the persistent and dynamic attributes of the RMs.

The IBM.PeerDomain RM in Example 4-304 shows the persistent Name and its ActivePeerDomain called NIMESIS.

**Example 4-304  IBM.PeerDomain persistent attributes**

```bash
root@lpar55:/: lsrsrc IBM.PeerDomain
Resource Persistent Attributes for IBM.PeerDomain
resource 1:
  Name              = "NIMESIS"
  RSCTActiveVersion = "2.4.5.2"
  MixedVersions     = 0
  TSPort            = 12347
  GSPort            = 12348
  RMCPort           = 657
  ResourceClasses   = {}
  QuorumType        = 0
  ActivePeerDomain  = "NIMESIS"
```

Example 4-305 shows that the IBM.PeerDomain dynamic OpState is 1, and 1 is desirable because it means that the peer domain is online (2 means offline).

**Example 4-305  IBM.PeerDomain dynamic attributes**

```bash
root@lpar55:/: lsrsrc -A d IBM.PeerDomain
Resource Dynamic Attributes for IBM.PeerDomain
resource 1:
  OpState       = 1
  ConfigChanged = 0
  OpQuorumState = 0
```

The IBM.PeerNode RM in Example 4-306 shows the known nodes, and also shows that they belong to the ActivePeerDomain NIMESIS. The NodeList number is the sequence number for the node in the domain, and it is the same sequence on all nodes.

**Example 4-306  IBM.PeerNode persistent attributes**

```bash
root@lpar55:/: lsrsrc IBM.PeerNode
Resource Persistent Attributes for IBM.PeerNode
resource 1:
  Name               = "lpar55"
  NodeList           = {1}
  RSCTVersion        = "2.4.5.2"
  ClassVersions      = {}
  CritRsrcProtMethod = 0
  ActivePeerDomain   = "NIMESIS"
```
Example 4-307 shows that the IBM.PeerNode dynamic OpState is 1, and 1 is desirable because it means that the peer domain is online (2 means offline).

Example 4-307 IBM.PeerNode dynamic attributes

Communication groups control how RSCT core topology services “heartbeats” are performed between the communication resources within the peer domain. Each communication group corresponds to a RSCT core topology services
heartbeat ring, and identifies the attributes that control the checks between the
nodes. Now we use the environment variable CT_MANAGEMENT_SCOPE set to 2,
which will enable RSCT PeerDomain display when using the lsresrc command
as shown in Example 4-308. If it is unset, it will only show the local node
information.

Example 4-308  Using CT_MANAGEMENT_SCOPE=2 variable

```bash
root@lpar55:/: CT_MANAGEMENT_SCOPE=2 lsresrc -Ad IBM.PeerNode
Resource Dynamic Attributes for IBM.PeerNode
resource 1:
  OpState        = 1
  ConfigChanged  = 0
  CritRsrcActive = 0
resource 2:
  OpState        = 1
  ConfigChanged  = 0
  CritRsrcActive = 0
```

To examine the communication groups in our RSCT PeerDomain, we use the
lscomg command. In Example 4-309, there is only one communication group,
CG1.

Example 4-309  Checking the communication groups with lscomg

```bash
root@lpar55:/: lscomg
Name Sensitivity Period Priority Broadcast SourceRouting NIMPathName NIMParameters
CG1 4           1      1        Yes       Yes
```

To find out the interfaces used to communicate in this communication group, use
the -i flag and specify the communication group with the lscomg command. In
Example 4-310, the CG1 communication group has two members: lpar55 and
lpar56.

Example 4-310  Checking the interfaces in a communication group

```bash
root@lpar55:/: lscomg -i CG1
Name NodeName IPAddress Subnet   SubnetMask
en0 lpar56   10.1.1.56 10.1.1.0 255.255.255.0
en0 lpar55   10.1.1.55 10.1.1.0 255.255.255.0
```

We can examine the communications interfaces on our cluster nodes by using
the lsresrc command with the IBM.NetworkInterface and setting the environment
variable CT_MANAGEMENT_SCOPE to 2. This will enable RSCT PeerDomain display
when using the command. If it is unset, it will only show the local node
information. The attribute OpState should be 1, which is online; see
Example 4-311 on page 400.
**Example 4-311  Listing interfaces in a peer domain**

```
root@lpar55:/: CT_MANAGEMENT_SCOPE=2 lsrc -A d IBM.NetworkInterface
Resource Dynamic Attributes for IBM.NetworkInterface
resource 1:
  OpState     = 1
  ConfigChanged = 0
resource 2:
  OpState     = 1
  ConfigChanged = 0
```

The RSCT core topology services subsystem (cthats) can be monitored with the lssrc command, and controlled with the cthatsctrl, cthatstune, and cthactrl commands (in the /usr/sbin/rsct/bin directory).

In Example 4-312 you can see the communications group CG1 has two members (Mbrs) and the status (St) is stable (S). The connection is between 10.1.1.55 and 10.1.1.56, and it uses the local en0 TCP/IP interface for communication.

**Example 4-312  Checking cthats (topology services)**

```
root@lpar55:/: lsrc -ls cthats
Subsystem         Group            PID     Status
cthats           cthats           286832  active
Network Name   Indx Defd  Mbrs  St   Adapter ID      Group ID
CG1            [ 0] 2     2     S    10.1.1.55 10.1.1.56
CG1            [ 0] en0 0x44a4d38b 0x44a4d397
HB Interval = 1.000 secs. Sensitivity = 4 missed beats
Missed HBs: Total: 0 Current group: 0
Packets sent    : 83 ICMP 0 Errors: 0 No mbuf: 0
Packets received: 130 ICMP 0 Dropped: 0
NIM's PID: 671826
  2 locally connected Clients with PIDs:
    rmcd(565364) hagsd(544840)
    Fast Failure Detection available but off.
    Configuration Instance = 1151652855
    Daemon employs no security
    Segments pinned: Text Data.
    Text segment size: 785 KB. Static data segment size: 1526 KB.
    Dynamic data segment size: 3009. Number of outstanding malloc: 100
    User time 0 sec. System time 0 sec.
    Number of page faults: 0. Process swapped out 0 times.
    Daemon is in a refresh grace period.
    Number of nodes up: 2. Number of nodes down: 0.
```

The RSCT core group services subsystem (cthags) can be monitored with the lssrc command, and controlled with the cthagsctrl, cthagstune, and cthactrl commands.
commands (in the /usr/sbin/rsct/bin directory). In Example 4-313, you can see that the rmc_peers group is registered.

**Example 4-313  Checking cthags (group services)**

```bash
croot@lpar55:/: lssrc -ls cthags
Subsystem         Group            PID          Status
    cthags    cthags            544840       active
```

2 locally-connected clients. Their PIDs:
225376(IBM.ConfigRMD) 565364(rmcd)

HA Group Services domain information:
Domain established by node 1
Number of groups known locally: 2

<table>
<thead>
<tr>
<th>Group name</th>
<th>Number of providers</th>
<th>Number of local providers/subscribers</th>
</tr>
</thead>
<tbody>
<tr>
<td>rmc_peers</td>
<td>2</td>
<td>1</td>
</tr>
<tr>
<td>IBM.ConfigRM</td>
<td>2</td>
<td>1</td>
</tr>
</tbody>
</table>

To check the authentication and trusted host list created with the preprpnode command, you can use the ctsthl command. Example 4-314 shows our two peer nodes, lpar55 and lpar56, along with their respective IP-addresses.

**Example 4-314  Verifying ctcas trusted host list keys with ctsthl**

```bash
croot@lpar55:/: ctsthl -l
c tsthl: Contents of trusted host list file:
---------------------
Host Identity: 10.1.1.56
Identifier Generation Method: rsa512
Identifier Value:
120200d004f8e71a20d924b4da354a8ddc7698676ff82ff74000cf42e694f516a75c9dba14564b
0d9b8ec50e05b21460128bb9f05a9f461267fbb7212d7e2ddea0430103
---------------------
Host Identity: lpar55
Identifier Generation Method: rsa512
Identifier Value:
120200d004f8e71a20d924b4da354a8ddc7698676ff82ff74000cf42e694f516a75c9dba14564b
0d9b8ec50e05b21460128bb9f05a9f461267fbb7212d7e2ddea0430103
---------------------
Host Identity: 10.1.1.55
Identifier Generation Method: rsa512
Identifier Value:
120200cd29189553c272c4e02dc042ba33b80430cfd761eb4034ec70f8f4f1461a42c425c378a81
2b1ad9e9e30d2e2ef659d060ee263007906ddccc0f8e8678d94f3eb0103
---------------------
Host Identity: lpar55
Identifier Generation Method: rsa512
Identifier Value:
120200cd29189553c272c4e02dc042ba33b80430cfd761eb4034ec70f8f4f1461a42c425c378a81
```
Much of the RSCT dynamic configuration is stored under the /var/ct directory. The /var/ct/cfg/ctrmc.acls file contains the access control lists (ACL) also added by the preprnpnode command, as shown in Example 4-315.

**Example 4-315   RPD ctrmc.acls file (configured by preprnpnode command)**

```plaintext
none:root  *  rw  // give root on any node access to all
IBM.PeerDomain // Peer Domain class
root@10.1.1.55  *  rw  // cluster node
root@10.1.1.56  *  rw  // cluster node
root@lpar55  *  rw  // cluster node
root@lpar56  *  rw  // cluster node
none:any_root  *  rw  // root on any node of any cluster that this node is defined to
none:root  *  rw  // root on any node of active cluster
```

**HANIM takeover operation**

If a NIM client /etc/niminfo file looks like Example 4-316 (first part lpar6), then after the takeover operation is performed (from lpar55), it changes to look like Example 4-316 (second part lpar55).

**Example 4-316   Changes to a NIM clients /etc/niminfo file by nim -o takeover**

```plaintext
{lpar6}:/ # cat /etc/niminfo
#------------------ Network Install Manager ---------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
export NIM_NAME=lpar6
export NIM_HOSTNAME=lpar6
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=lpar56
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_MASTER_HOSTNAME_LIST="lpar56 lpar55"
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS=" 10.1.1.6:lpar6  10.1.1.56:lpar56 "
export NIM_MOUNTS=""

root@lpar55:/: nim -o takeover lpar56

{lpar6}:/ # cat /etc/niminfo
#------------------ Network Install Manager ---------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
```
export NIM_NAME=lpar6
export NIM_HOSTNAME=lpar6
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=lpar55
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_MASTER_HOSTNAME_LIST="lpar55 lpar56"
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS=" 10.1.1.6:lpar6  10.1.1.55:lpar55 "
export NIM_MOUNTS=""

The nim command with the takeover operation is the core of what we use in our takeover script shown in Figure 4-27 on page 408.

Creating a RSCT PeerDomain event detection method
Now that we have a working RSCT PeerDomain, and we know how to handle the NIM takeover operation, we can perform the steps to allow RSCT RMC event handling to perform the action for us. It involves the following steps and commands:

1. Create a program to perform actions when the intended conditions are met.
2. mkresponse - Define a program to execute.
3. mkcondition - Define a condition to monitor.
4. mkcondresp - Connect the condition with the response program.
5. startcondresp - Start monitoring the metrics in the condition.

Important: The type of condition and response we are using in this scenario with RSCT is a one-sided condition-response, and all commands must be performed on both peer nodes. However, the mkcondition command will be different between the nodes (as explained in Example 4-317).

First we create a script, /local/rg/takeover.nimesis, that will execute the nim command with the takeover operation; see Figure 4-27 on page 408. We recommend using the vi editor, both for script creation and for command line editing.

Then we define the response with the /local/rg/takeover.nimesis script, naming the response START_NIMESIS, and the action TAKEOVER. Additional actions can be added to the response with the chresponse command, but for our purposes we do not need to use this feature.

Example 4-317 Creating a response with mkresponse

root@lpar55:/ mkresponse -n TAKEOVER -s /local/rg/takeover.nimesis START_NIMESIS
Now we create the condition to evaluate. This part is where you have to find the appropriate attribute (metric) from the appropriate resource managers resource class. Use the `lsrsrc` command to find what you need.

When you know what you want to monitor, you just specify the expression to the `mkcondition` command, with the `-e` flag and the rearm expression with the `-E` flag. In our case we will monitor the `OpState` attribute in the `IBM.PeerNode` resource class for the remote peer. When it is set to 1, the peer is online, and when it is not set to 1, it is not online; that is, it can be unconfigured, pending or in some error state. However, it has to be online and nothing but online.

When we run the `mkcondition` command on our peer node `lpar55`, we use `-n lpar56`. But when we run the command on node `lpar56`, we use `-n lpar55`.

The `-n` flag specifies where the condition will be monitored, as shown in Example 4-318.

**Example 4-318  Creating a condition with mkcondition**

```
root@lpar55:~ mkcondition -mp -Sc -n "lpar56" -r IBM.PeerNode -e 'OpState <> 1'
-E 'OpState == 1' PEER_DOWN
```

```
root@lpar55:~ lscondition PEER_DOWN
Displaying condition information:
condition 1:
        Name        = "PEER_DOWN"
        Node        = "lpar56"
        MonitorStatus = "Not monitored"
        ResourceClass = "IBM.PeerNode"
        EventExpression = "OpState <> 1"
        EventDescription = ""
```
Now we have a response and we have a condition. To get the response to be performed when the condition becomes true, we need to create an association between the response and condition. This is done with the `mkcondresp` command. However, the condition will not be monitored just by creating an association, as shown Example 4-319.

**Example 4-319  Associating a condition with a response**

```bash
root@lpar55:/: mkcondresp PEER_DOWN START_NIMESIS

root@lpar55:/: lscondresp PEER_DOWN
Displaying condition with response information:
Condition   Response        Node     State
"PEER_DOWN" "START_NIMESIS" "lpar55" "Not active"
```

In order for the condition to be monitored, we start it with the `startcondresp` command as shown in Example 4-320. Now when the condition becomes true, the associated response is activated.

**Example 4-320  Starting monitoring a condition with startcondresp**

```bash
root@lpar55:/: startcondresp PEER_DOWN

root@lpar55:/: lscondresp PEER_DOWN
Displaying condition with response information:

condition-response link 1:
  Condition = "PEER_DOWN"
  Response  = "START_NIMESIS"
  Node      = "lpar55"
  State     = "Active"
```

```bash
root@lpar55:/: lsrsrc -Ad IBM.PeerNode
Resource Dynamic Attributes for IBM.PeerNode
resource 1:
  OpState        = 1
  ConfigChanged  = 0
  CritRsrcActive = 0
resource 2:
  OpState        = 1
  ConfigChanged  = 0
```
Now we have a metric that is being monitored, and when our condition is met and evaluates to true, our response is activated. This is our `takover.nimesis` script, as shown in Figure 4-27 on page 408.

To verify it, we can use the `stoprpnode` command to bring the remote node offline from our RSCT domain as shown in Example 4-321.

This will cause the `OpState` attribute in IBM.PeerNode, to change from online (1), to offline (2).

**Example 4-321 Stopping a RSCT PeerDomain node with stoprpnode**

```
root@lpar55:/: stoprpnode -V lpar56
Stopping the node(s).
Stopping these node(s) in the peer domain. lpar56
Completed stopping the node(s).
```

Now we check the status with the `lsrsrc` command as shown in Example 4-322. The first time `OpState` has changed from one (1) to six (6), then shortly after it has changed to two (2) and are offline.

We can verify that it is offline with the `lsrpnode` command, but our PeerDomain should still be active, which is seen from the output of the `lsrpdomain` command.

**Example 4-322 Checking the progress of stoprpnode of the peer node**

```
root@lpar55:/: lsrsrc -Ad IBM.PeerNode
Resource Dynamic Attributes for IBM.PeerNode
resource 1:
  OpState        = 6
  ConfigChanged  = 0
  CritRsrcActive = 0
resource 2:
  OpState        = 1
  ConfigChanged  = 0
  CritRsrcActive = 0

root@lpar55:/: lsrsrc -Ad IBM.PeerNode
Resource Dynamic Attributes for IBM.PeerNode
resource 1:
  OpState        = 1
  ConfigChanged  = 0
  CritRsrcActive = 0
resource 2:
  OpState        = 2
  ConfigChanged  = 0
```
CritRsrcActive = 0

root@lpar55:/: lsrpnode
Name OpState RSCTVersion
lpar55 Online 2.4.5.2
lpar56 Offline 2.4.5.2

root@lpar55:/: lsrpdomain
Name OpState RSCTActiveVersion MixedVersions TSPort GSPort
NIMESIS Online 2.4.5.2 No 12347 12348

When we restart the peer node, the condition will be rearmed, and ready to go again.

    startrpnode lpar56

**Takeover script for HANIM**

Now we can examine our RPD script. We use one script to start the NIM services, or rather to change the /etc/nimnfo file on the NIM clients defined in the NIM database.

The takeover script will ensure that the nimesis SRC daemon is started and will collect some information regarding the running cluster, before it will issue a nim command ordering takeover from the alternate NIM master (just in case it was the current master for the NIM clients).

We have created the /local file system on each node, and a directory called rg in this file system. We place the scripts in the /local/rg directory and make sure they are synchronized between the cluster nodes.

When activated by the Event Response Resource Manager (ERRM), the script will be supplied with several environment variables, with names starting with ERRM_.

We are mostly interested in the following: the ERRM_RSRC_CLASS_NAME, ERRM_COND_NAME and ERRM_ER_NAME to identify the RSRC RM class set by the condition, the condition name, and the event name. These variables can be used to identify in the program what condition activated it, in case the same program are used to handle several conditions.

In our case, the variables will have the following values when the script is activated as shown in Example 4-323.

*Example 4-323   ERRM environment variables*

ERRM_RSRC_CLASS_NAME=PeerNode
ERRM_COND_NAME=PEER_DOWN
ERRM_ER_NAME=START_NIMESIS
ERRM_EXPR=OpState <> 1
ERRM_VALUE=6

The ERRM_EXPR variable contains the condition expression that became true and activated the response event to start our program. The actual value of the OpState variable, at the time of setting of the trigger, is supplied in the ERRM_VALUE variable, and in our case the 6 means a transitory state from online to offline.

```bash
#!/bin/ksh
# takeover.nemesis
# Synopsis........%M%
# Author..........User01
# Created.........2006
# Version.........%2% %M% %1% (%E% %U%) %Q%
# Description.....N/A
# Input..........N/A
# Output.........Change the /etc/niminfo on all clients:
#                NIM_MASTER_HOSTNAME, NIM_MASTER_HOSTNAME_LIST and
#                NIM_HOSTS variables.
# Algorithm.......Check if nimesis are running, start it if not,
#                perform takeover regardless.
#
#*******************************************************************************
trap 'exit 0' EXIT
export PATH=/usr/bin:/usr/sbin:/usr/es/sbin/cluster/utilities
NIMESISPID=$(lssrc -s nimesis|awk '!/PID/{if (/active/) print $3}')
if [[ -z "$NIMESISPID" ]] ;then
  printf "The "nimesis" SRC will be started.\n"
  startsrc -s nimesis
  sleep 6
else
  printf "The nimesis SRC is already running "$NIMESISPID".\n"
fi
ALTERNATE_MASTER=$(lsnim -Z -t alternate_master|awk -F: '!/^#/{print $1;exit}')
printf "The NIM alternate_master is "$ALTERNATE_MASTER".\n"
[[ -z "$ALTERNATE_MASTER" ]] || nim -o takeover $ALTERNATE_MASTER
```

Figure 4-27  RSCT PeerDomain takeover.nemesis script

In the script, we end with a trap to ensure we return zero (0) as exit value.
Network Installation Manager best practices

This chapter provides examples of how to configure and use Network Installation Manager. The examples are based on best practices and on the experiences of this book's authors and contributors:

- Updating the NIM environment (lpp_source, SPOT)
- Secondary adapter
- NIMSH, OpenSSL and firewall considerations
- Cloning NIM clients using mksysb
- Using NIM to migrate systems to new hardware
- Using SAN zoning for cloning LPARs
- System maintenance for NIM clients
- Automatic scripts
- Implementing a standard operating environment for AIX 5L V5.3 systems with NIM
- How to back up and reinstall a NIM master
5.1 Updating the NIM environment (lpp_source, SPOT)

Whenever there is a need to update the Technology Level (TL) or Service Pack (SP) in any NIM client, the first thing you need to do is to update your NIM master server. After the NIM master server is updated, you will need to update the lpp_source follow by the SPOT.

**Note:** The NIM server must be at the same or higher level than the NIM clients. You need to upgrade your NIM server before upgrading your NIM client.

If your NIM environment has a mixture of TL levels, then in order to have some NIM clients at the original level, you need to keep a copy of the original lpp_source and SPOT level. These clients will still need the original level of lpp_source and SPOT.

In the next section, we describe the steps to perform the lpp_source update. In this example, we have an original lpp_source and SPOT level at TL04, and we are creating a new TL05 lpp_source and SPOT.

1. Create a new AIX 5L V5.3 TL05’s lpp_source directory, for example, /export/lppsource/lpp-aix5305, and copy the AIX 5L V5.3 TL04’s lpp_source directory into it.
   
   ```bash
   # cp -rp /export/lppsource/lpp-aix5304/* \
   /export/lppsource/lpp-aix5305
   ```

2. Create an AIX 5L V5.3 TL05 lpp_source resource from the AIX 5L V5.3 TL05 lpp_source directory, as shown in Example 5-1 on page 411. The following steps are followed when using the SMIT menus:

   ```bash
   # smitty nim
   Perform NIM Administration Tasks
   Manage Resources
   Define a Resource
   Select “lpp_source = source device for optional product images”
   ```

   Or, by using SMIT Fast Path: `smitty nim_mkres`

   **Important:** Ensure that the files in /export/lppsource/lpp-aix5304/installp/ppc have Read permission for everybody. If they do not, use the `chmod 644 *` command inside the lpp_source directory.

   Also ensure that the ownership of the files is root:system.
Example 5-1 Creating an AIX 5L V5.3 TL05 lpp_source

Define a Resource

Type or select values in entry fields. Press Enter AFTER making all desired changes.

<table>
<thead>
<tr>
<th>EntryFields</th>
</tr>
</thead>
</table>

* Resource Name | LPP-AIX5305 |
* Resource Type | lpp_source |
* Server of Resource | master |
* Location of Resource | /export/lppsource/lpp-aix5305 |
  
  Architecture of Resource
  Source of Install Images
  Names of Option Packages
  Show Progress: yes |
  Comments |

You can also use the command line as follows:

```
# nim -o define -t lpp_source -a server=master -l /
/export/lppsource/lpp-aix5305 LPP-AIX5305
```

Note: NIM updates the .toc file in <lppsource>/installp/ppc automatically. Make sure the .toc file in /export/lppsource/lpp-aix5305/installp/ppc is updated.

3. Update the TL05 to the LPP-AIX5305 resource as shown in Example 5-2. You use the NIM update operation to perform the task. This operation allows you to update or remove any packages from the lppsource resource. The next steps are followed when using the SMIT menus:

```
# smitty nim
```

Perform NIM Administration Tasks
Manage Resources
  Perform Operations on Resources
  Select LPP-AIX5305
  Select “update = add or remove software to or from an lpp_source”
  Select “Add” and enter the Software media source

Or, by using SMIT Fast Path: `smitty nim_update`

Example 5-2 Adding software to an lpp_source

Add Software to an lpp_source

Type or select values in entry fields. Press Enter AFTER making all desired changes.

[EntryFields]
TARGET lpp_source LPP-AIX5305
SOURCE of Software to Add cd0
SOFTWARE Packages to Add [all]+
-OR-
INSTALLP BUNDLE containing packages to add [] +
gencopy Flags
DIRECTORY for temporary storage during copying [/tmp]
EXTEND filesystems if space needed? yes +
Process multiple volumes? no +

You can also use the command line as follows:

# nim -o update -a packages=all -a source=/dev/cd0 LPP-AIX5305

After you have updated the TL05 lpp_source, there might be some duplicate updates. You can perform the NIM 1ppmgrp operation to remove them. This operation enables you remove any duplicate software, superseded updates, unnecessary languages, and non-simage software.

We recommend that you remove the duplicate software and any superseded updates, but that you do not remove any language software and non-simage filesets unless you are sure that they are not needed for future use. We also recommend that you perform a preview to check what software will be removed before the actual removal.

4. Remove any duplicate updates in lpp_source resource, as shown in Example 5-3.

The following steps are followed when using the SMIT menus:

# smitty nim
Perform NIM Administration Tasks
Manage Resources
Perform Operations on Resources
Select LPP_AIX5305
Select “1ppmgrp = eliminate unnecessary software images in an lpp_source”

Or, by using SMIT Fast Path: smitty nim_lppmgr

Example 5-3 Removing duplicate updates in the lpp_source

Eliminate Unnecessary Software Images in an lpp_source

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

[EntryFields]
You can also use the command line as follows:

```
# nim -o lppmgr -a lppmgr_flags="-bu -x -r -e" LPP-AIX5305
```

**Note:** Run lsnim -l LPP-AIX5305 to check the Rstate and simages. Rstate should show Ready for use and simages = yes.

Next, we need to create the AIX 5L V5.3 TL05 SPOT. We will create the SPOT using the latest LPP-AIX5305 lpp_source.

5. Create the AIX 5L V5.3 TL05's SPOT as shown in Example 5-4. The following steps are followed when using the SMIT menus:

```
# smitty nim_mkres
    Select “spot = Shared Product Object Tree - equivalent to /usr file”
```

**Example 5-4  Creating a SPOT**

```
Define a Resource

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

[Entry Fields]
[SPOT-AIX5305]

* Resource Name
* Resource Type
* Server of Resource [master] +
* Source of Install Images [LPP-AIX5305] +
* Location of Resource [/export/spot]/
EXPAND file systems if space needed? yes +
Comments []

installp Flags
COMMIT software updates? no +
SAVE replaced files? yes +
AUTOMATICALLY install requisite software? yes +
OVERWRITE same or newer versions? no +
```
After the updated lpp_source and SPOT are created, you can perform a NIM check operation to check the usability of these resources. When you perform the NIM check operation on the lpp_source resource, it rebuilds the table of contents (.toc) file in the lpp_source directory and checks whether all the necessary filesets are in the directory to qualify the lpp_source for the simage attribute.

6. Check the usability of the lpp_source and SPOT as shown in Example 5-5. The following steps are followed when using the SMIT menus:

```
# smitty nim_res_op
Select SPOT-AIX5305 or LPP-AIX5305
Select “check = check the status of a NIM object”
```

**Example 5-5  Checking the SPOT**

Check the Status of a SPOT

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

* Resource Name  SPOT-AIX5305
   Build Debug Boot Images?  no +
   Force  no +

After the lppsource and SPOT resources are updated and ready for use, you can perform software maintenance on NIM clients. Refer to “Client-initiated software maintenance tasks (“pull”)” on page 496 for details.
Chapter 5. Network Installation Manager best practices

5.2 Secondary adapter

The following section describes the secondary adapter support for the Network Installation Manager (NIM).

5.2.1 Secondary adapter support

Secondary adapter support is available for AIX 5L V5.2 or later. Prior to AIX 5L V5.2, during a NIM BOS rte installation operation, only the network adapter and interface used during BOS installation was configured. Using the NIM secondary adapter definitions, you can have additional network adapters and interfaces configured during a BOS installation or a customized installation.

The nimadapters command parses a secondary adapter stanza file to build the files required to add NIM secondary adapter definitions to the NIM environment as part of an adapter_def resource. The nimadapters command does not configure secondary adapters. The configuration takes place during a nim -o bos_inst operation or a nim -o cust operation that references the adapter_def resource.

The secondary adapter stanza file is processed by the nimadapters command and turned into a file that contains one stanza for each secondary adapter or interface on the NIM client. During a BOS installation, NIM processes this information and configures the secondary adapters. If a secondary adapter is already configured in the requested manner, NIM does not reconfigure the secondary adapter.

Note: NIM uses the /usr/lpp/bos.sysmgmt/nim/methods/c_cfpadptrs client method to configure secondary adapters.

Table 5-1 on page 416 lists the flags accepted by the nimadapters command, and the purpose of each flag.
Table 5-1  The nimadapters command options

<table>
<thead>
<tr>
<th>Flag</th>
<th>Purpose</th>
</tr>
</thead>
</table>
| -a   | Assigns the following attribute=value pairs:  
  - client=nim_client_name  
  Specifies the NIM client that will have a secondary adapter definition added or removed. This option allows you to define one secondary adapter for a client. To define multiple secondary adapters, use a stanza file.  
  - info=AttributeList  
  When previewing or defining a secondary adapter, the info attribute must be used when the client attribute is specified. AttributeList is a list of attributes separated by commas. |
| -d   | Defines secondary adapters. A Client.adapter file is created in the adapter_def location for each valid secondary adapter definition. If the nimadapters command encounters existing secondary adapter definitions for a NIM client, the existing definitions are replaced. |
| -f   | SecondaryAdapterFileName. Specifies the name of the secondary adapter file. |
| -p   | Displays a preview operation to identify any errors. This flag processes the secondary adapter file or info attribute, but does not add adapter definitions to the NIM environment. |
| -r   | Removes the secondary adapter definitions of a specific client or all the clients listed in a secondary adapter stanza file. If the client attribute or secondary adapter stanza file is not specified, then all the secondary adapter definitions in the adapter_def resource will be removed. |

Note: Before using the nimadapters command, you must configure the NIM master.

5.2.2 Working with secondary adapter file rules

The format of the secondary adapter file must comply with the following rules:
  - After the header stanza, the attribute lines format is: Attribute = Value.
  - If the value of an attribute is defined multiple times within the same stanza, only the last definition is used.
  - If an invalid attribute value or name is used, that attribute definition is ignored.
  - Each line of the file can contain only one header or attribute definition.
More than one stanza can exist in a definition file for each machine (host name).

Each stanza for a machine (host name) represents a secondary adapter definition on that NIM client. No two secondary adapter definitions for the same machine host name can have the same location or interface_name. There should be only one definition per adapter or interface on a given NIM client.

If the stanza header entry is the default keyword, this specifies to use that stanza for the purpose of defining default values.

A default value for any secondary adapter attribute can be specified. However, the netaddr and secondary_hostname attributes must be unique. Also, the location and interface_name attributes must be unique on a NIM client.

If an attribute for a secondary adapter is not specified but default value exists, the default value is used.

Default values at any location in the definition file can be specified and changed. After a default value is set, it applies to all definitions that follow.

To turn off a default value for all following machine definitions, the attribute value in a default stanza must not be set.

To turn off a default value for a single machine definition, the attribute value in the machine stanza must not be set.

Comments in a client definition file can be included. Comments begin with the number sign (#).

When parsing the definition file for header and attribute keywords and values, tab characters and spaces are ignored.

**Note:** During a `nim -o bos_inst` or `nim -o cust` operation, if NIM examines the configuration data on the client and determines that a secondary adapter is already configured with precisely the attributes requested in the adapter_def resource, this secondary adapter is not reconfigured.

### 5.2.3 Secondary adapter files

This section describes secondary adapter files.

**Using secondary adapter file keywords**

The secondary adapter file uses keywords (see Table 5-2 on page 418) to specify machine attributes.
**Using required adapter attributes**
Table 5-2 lists the required attributes used in configuring adapters.

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>machine_type</code> = secondary</td>
<td>Specifies the machine_type attribute as secondary clearly distinguishes the nimadapters input from nimdef input. If a secondary adapter’s file is mistakenly passed to the nimdef command, the error can be detected. The etherchannel option is only supported on clients running AIX 5L V5.3 or later. Stanzas with a machine_type of install are ignored.</td>
</tr>
<tr>
<td><code>netaddr</code></td>
<td>Specifies the network address for the secondary adapter.</td>
</tr>
<tr>
<td><code>interface_type</code> = en</td>
<td>Specifies the type of network interface. The network interface can be en (Ethernet interface), et (Ethernet interface), sn (switch network interface), ml (multi-link interface), or vi (virtual interface). This attribute is only supported on clients running AIX 5L V5.3 or later, and it replaces the deprecated network_type attribute.</td>
</tr>
<tr>
<td><code>subnet_mask</code></td>
<td>Specifies the subnet mask used by the secondary adapter.</td>
</tr>
</tbody>
</table>

**Using optional attributes**
Table 5-3 lists the optional secondary adapter attributes.

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>adapter_attributes</code></td>
<td>Blank-separated list of physical adapter attributes and values; for example, Attribute1=Value1 Attribute2=Value2. To see the list of attributes that can be set for the requested adapter, run the command <code>lsattr -E -1 AdapterName</code>. This attribute is only supported on clients running AIX 5L V5.3 or later.</td>
</tr>
<tr>
<td><code>interface_attributes</code></td>
<td>Blank-separated list of interface attributes and values; for example, Attribute1=Value1 Attribute2=Value2. To see the list of attributes that can be set for the requested interface, run the command <code>lsattr -E -1 InterfaceName</code>. This attribute is only supported on clients running AIX 5L V5.3 or later, and it replaces the deprecated attributes attribute.</td>
</tr>
</tbody>
</table>
### Working with deprecated attributes

Table 5-4 lists attributes that were deprecated in AIX 5L V5.3, but are still available on clients running AIX 5L V5.2 or later.

**Note:** If you have a NIM secondary adapter configuration with an AIX 5L V5.2 client, then you must use `network_type` and `attributes` because the new attributes are not supported.

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>network_type</td>
<td>Replaced by <code>interface_type</code>.</td>
</tr>
<tr>
<td>attributes</td>
<td>Replaced by <code>interface_attribute</code>.</td>
</tr>
</tbody>
</table>

**Note:** Configuring a secondary adapter sharing the same subnet with another adapter does not provide failover. Packets alternate between adapters when they are configured on the same subnet. If one of the adapters fails, the other adapter will *not* take over the failed adapter’s workload, and the subnet will have connectivity problems. Commands such as `mount` might fail if this occurs.
Sample secondary adapter file
Example 5-6 shows a sample file for the customization of a secondary adapter.

Example 5-6  Secondary adapter file sample

```plaintext
# Set default values.
default:
    machine_type  = secondary
    subnet_mask   = 255.255.240.0
    network_type  = en
    media_speed   = 100_Full_Duplex
# Define the machine "lab1"
# Take all defaults and specify 2 additional attributes.
# Unlike the case of the client definitions that are input to the
# nimdef command, the secondary adapter definition includes at least
# one required field that cannot be defaulted.
lab1:
    netaddr = 9.53.153.233
    location = P2-I1/E1
# Change the default "media_speed" attribute.
default:
    media_speed   = 100_Half_Duplex
# define the machine "test1"
# Take all defaults and include a comment.
test1:
    comments      = "This machine is a test machine."
# define a machine with a VIPA interface that uses interfaces en2 and
# en3.
lab2:
    machine_type         = secondary
    interface_type       = vi
    interface_name       = vi0
    netaddr              = 9.53.153.235
    subnet_mask          = 255.255.255.0
    secondary_hostname   = lab3
    interface_attributes = "interface_names=en2,en3"
# define a machine with an etherchannel adapter that uses the adapters
# at the following location codes P1-I4/E1 and P1/E1
lab4:
    machine_type         = etherchannel
    interface_type       = en
    interface_name       = en2
    netaddr              = 9.53.153.237
    subnet_mask          = 255.255.255.0
    multiple_physloc     = P1-I4/E1,P1/E1
# define a machine with an etherchannel adapter that uses the
# ent2 and ent3 adapters and uses mode 8023ad.
lab6:
    machine_type         = etherchannel
```

420  NIM from A to Z in AIX 5L
interface_type       = en
interface_name       = en2
netaddr              = 9.53.153.239
subnet_mask          = 255.255.255.0
adapter_attributes = "adapter_names=ent2,ent3 mode=8023ad"

---

**Working with secondary adapter definitions**

The following steps are used to accomplish common tasks working with secondary adapter definitions:

- To preview the secondary_adapters.defs client definition file, type:
  ```
  nimadapters -p -f secondary_adapters.defs adapter_def
  ```

- To add the NIM secondary adapters described in the secondary_adapters.defs secondary adapters definition file, type:
  ```
  nimadapters -d -f secondary_adapters.defs adapter_def
  ```

- To define the NIM secondary adapters for the pilsner client, type:
  ```
  nimadapters -d \
  -a info="en,P2-I1/E1,N/A,100_Full_Duplex,9.53.53.15,255.255.254.0" \ 
  -a client=pilsner adapter_def
  ```

- To remove the NIM secondary adapter definitions for a client called pilsner from the my_adapter_def resource, type:
  ```
  nimadapters -r -a client=pilsner my_adapter_def
  ```

- To remove the NIM secondary adapter definitions for clients defined in the file secondary_adapters.defs, type:
  ```
  nimadapters -r -f secondary_adapters.defs my_adapter_def
  ```

- To remove all the NIM secondary adapter definitions from the my_adapter_def resource, type:
  ```
  nimadapters -r my_adapter_def
  ```

---

### 5.2.4 Configuring a secondary adapter

This section shows a practical example of how to configure a secondary adapter. This environment comprises two machines: machine lpar2, which is the NIM master, and vlpar3, which is the client.
Defining adapter_def resource

The following procedure shows the steps executed for the creation of an adapter_def resource:

- Type smitty nim_res in the NIM master.
- Select Define a Resource from the Manage Resources SMIT panel.
- Select adapter_def from the list that shows up.
- Type the Resource Name (in this example, we choose SEC_ADAPTR).
- Type the Location of Resource (in this example, /other_res/SEC_ADAPTR).

Example 5-7  Adapter_def resource creation

| * Resource Name           | [SEC_ADAPTR]          |
| * Resource Type           | adapter_def          |
| * Server of Resource      | [master] +           |
| * Location of Resource    | [/other_res/SEC_ADAPTR] / |
| Comments                  | []                   |

Example 5-7 shows the SMIT panel used to create the adapter_def resource.

Creating a secondary adapter definition file

The following procedure shows the steps executed for the creation of an adapter definition file:

- Type smitty nim_adapt_def in the NIM master.
- Select Define Secondary Definition File from the Manage Secondary Adapter Definition Files SMIT panel.
- Select the Adapter Definition Resource for the adapter.
- Select the Client Name.
- Select the Network Address.
- Select the Interface Type.
- Select the Subnet Mask.
- The rest of the fields are blank for the purposes of this example.

Example 5-8 shows the SMIT panel used to create the adapter definition file.

Example 5-8  Adapter definition file creation

| * Adapter Definition Resource | [SEC_ADAPTR] +         |
| * Client Name                 | [VLPAR3] +             |
| Machine Type                  | secondary              |
SMIT uses the `nimadapters` command to generate the NIM secondary adapter definitions to the NIM environment as part of the `adapter_def` resource. This command can also be executed using the command line instead of SMIT, either giving the `nimadapters` command a secondary adapter stanza file or all the necessary options.

Example 5-9 shows the output of the command execution for the creation of the adapter definition file.

**Example 5-9  Adapter definition file creation output**

1 secondary adapter definition is complete. The following secondary adapter will be added to the NIM environment:

```
VLPAR3:
  hostname=VLPAR3
  machine_type=secondary
  interface_type=en
  hostaddr=10.1.1.63
  netaddr=10.1.1.75       vlpar3_en1
  subnet_mask=255.255.255.0
  adapter_attributes=secondary

Summary
1 Secondary adapter will be added to the NIM environment.
```

The VLPAR3.adapters file is created in the `/other_res/SEC_ADAPTR` directory. Example 5-10 shows the content of the adapter definition file.

**Example 5-10  Adapter definition file content**

```
VLPAR3:
  hostname=VLPAR3
  machine_type=secondary
  interface_type=en
```
NIM customization must be performed now in order to apply these definitions. Example 5-11 shows the execution of the customization to enable the secondary adapter in the client.

**Example 5-11  Client customization**

```
(root@lpar2):/ # nim -o cust -a adapter_def=SEC_ADAPTR VLPAR3
nim_name = VLPAR3
machine_type = secondary
interface_type = en
network_type =
logical_name =
location =
multiple_physloc =
secondary_hostname =
netaddr = 10.1.1.75
subnet_mask = 255.255.255.0
cable_type =
media_speed =
attributes =
interface_attributes =
adapter_attributes = secondary
bos_preconfig =
cust_preconfig =
route =
```

Could not get the current value of "secondary" for ent1. Will attempt to set "secondary".

Network device busy. Changing "ent1". Will take effect on the next reboot.

```
en1
en1 changed
```

At this point, the client vlpars is configured with two interfaces, en0 and en1. The interface en1 has been configured through NIM customization.

### 5.3 NIMSH, OpenSSL and firewall considerations

Up to the actual release, by default the Network Installation Manager (NIM) makes use of the remote shell server (rshd) when it performs remote command
execution on clients. The server provides remote execution facilities with authentication based on privileged port numbers from trusted hosts.

However, starting with AIX 5L V5.2 ML 07 and AIX 5L V5.3, a new feature called the NIM Service Handler (NIMSH) is available. This eliminates the need for classic r commands during NIM client communication. For environments where the standard rsh protocols are not considered secure enough, nimsh should be implemented. The NIM client daemon (NIMSH) uses reserved ports 3901 and 3902, and it installs as part of the bos.sysmgt.nim.client fileset.

NIMSH provides a “wrapper” for classic r commands. Only the commands registered with NIMSH (residing in /usr/lpp/bos.sysmgt/nim/methods directory) are executed as root; anything else is denied execution.

NIMSH allows you to query network machines by hostname. NIMSH processes query requests and returns NIM client configuration parameters used for defining hosts within a NIM environment. Using NIMSH, you can define NIM clients without knowing any system-specific or network-specific information.

Although NIMSH eliminates the need for rsh, in the default configuration it does not provide trusted authentication based on key encryption. To use cryptographic authentication with NIMSH, you can configure NIMSH to use OpenSSL in the NIM environment. When you install OpenSSL on a NIM client, SSL socket connections are established during NIMSH service authentication. Enabling OpenSSL provides SSL key generation and includes all cipher suites supported in SSL version 3.

There are two ports involved in NIMSH communication. These ports are referred to as the primary (port 3901) and secondary port (port 3902). The primary port listens for service requests. When a request is accepted, the primary port is used for stdin(0) and stdout(1); stderr(2) is redirected to the secondary port.

This implementation allows the NIM master connection to stay consistent with current support of client connections through rsh. Using a reserved secondary port in NIMSH allows firewall administrators to write firewall rules for accepting incoming connections on privileged ports from the secondary port. This rules can have the requirement that the originating socket address (hostname : secondary port) comes from a trusted source.

NIMSH is registered with the System Resource Controller (SRC). The SRC group name is nimclient and the subsystem defined is NIMSH. The client daemon is started by SRC when the configuration routine is run using the nimclient command.

It is possible to have a heterogeneous environment of clients using the remote shell server (rshd) and NIM Service Handler (NIMSH). However, it is not possible
to perform operations for which information is provided using NIMSH in clients that are not using NIMSH. For example, the nimquery command is not able to retrieve information from clients that are not using NIMSH.

**Note:** The NIM client daemon logs data, used only for debug purposes, in the /var/adm/ras/nimsh.log file.

### 5.3.1 Authentication process

NIMSH handles service requests similar to the way they are handled in rcmd(). The NIM master builds packets with the following data for authentication:

- Host name of NIM client.
- CPUID of NIM client.
- CPUID of NIM master.
- Return port for secondary (stderr) connection.
- Query flag.

If the Query flag is set to 1, then the nimsh daemon treats the incoming request as a client discovery for information. The following data is returned:

- Default host name obtained from inet0.
- Default route obtained from inet0.
- Network address obtained from host name.
- Network interface obtained from host name.

If the query flag is not set, then a request for service (NIM operation) is pushed by the NIM master. The nimshd daemon validates the method request as follows:

- Verify the host name of the NIM master is the recognized master host name to the client.
- Check the client CPUID passed in the authentication data. It should match the client's machine ID.
- Check the master CPUID passed in the authentication data. It should match the master's machine ID stored in the memory. It is read into the memory from the /etc/niminfo file and the mktcpip -S primary_nim_interface command outputs.
- Verify that the operation passed in the method is a method residing in the /usr/lpp/bos.sysmgt/nim/methods directory (path).
- Check for cryptographic authentication settings.

Figure 5-1 shows the connections involved in performing a NIM push operation when the client is configured to use NIMSH.
5.3.2 Setting up NIMSH

The following procedure should be used to configure existing standalone clients with NIMSH.

**Using SMIT**

Use the following SMIT menus:

```
# smitty nim_config_services
Select nimsh
```

**Or, from the command line**

The following step is done via the command line.

- Type the following command on the NIM client: `# nimclient -C`
5.3.3 Verifying NIMSH startup

Run this command to verify that the NIMSH daemon is enabled on the client:

```bash
# lssrc -s nimsh
```

The output should look similar to Example 5-12.

**Example 5-12 Verifying NIMSH startup**

<table>
<thead>
<tr>
<th>Subsystem</th>
<th>Group</th>
<th>PID</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>nimsh</td>
<td>nimclient</td>
<td>245944</td>
<td>active</td>
</tr>
</tbody>
</table>

**Note:** After NIMSH is configured on the client, you no longer need the entry for the NIM master on the ~/.rhosts file on that client because NIM no longer uses classical `r` commands to perform operations in the client.

5.3.4 Enabling cryptographic authentication

You can configure existing standalone clients to use the NIMSH communication with SSL enabled. NIM supports OpenSSL versions 0.9.6e and higher. When OpenSSL is installed, NIMSH uses SSL-encrypted certificates for authenticating the connecting NIM master.

You can install and configure the OpenSSL cryptographic software using the NIM command options. Scripts are provided for configuring OpenSSL in the NIM environment, and you can use these without any modifications. The scripts are installed as part of the bos.sysmgt.nim.client fileset and located in the /usr/samples/nim/ssl directory. The scripts are used to define SSL keys and certificates for NIM SSL usage.

Because NIM masters can support a large system environment, it is necessary to impose a hierarchy on SSL certificate and key storage structure. During NIM setup, the directory structure described in Table 5-5 on page 429 is created.

Notes:
- In order to set up NIMSH, the NIM client must already be configured, and both client and master must have AIX 5L V5.3 or later installed.
- NIMSH must be configured only in the client.
Table 5-5  Directory hierarchy on SSL certificate and key storage

<table>
<thead>
<tr>
<th>Directory</th>
<th>Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>/ssl_nimsh</td>
<td>SSL parent directory for NIM</td>
</tr>
<tr>
<td>/ssl_nimsh/configs</td>
<td>Contains scripts used to configure SSL in NIM</td>
</tr>
<tr>
<td>/ssl_nimsh/certs</td>
<td>Contains SSL certificates used during host authentication</td>
</tr>
<tr>
<td>/ssl_nims/keys</td>
<td>Contains SSL keys used during SSL protocol communication</td>
</tr>
</tbody>
</table>

The NIM SSL directory structure is considered static and you should not modify it. To change SSL certificate options, you can modify the scripts described in Table 5-6.

Table 5-6  SSL authentication configuration scripts

<table>
<thead>
<tr>
<th>Script name</th>
<th>Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>SSL_root.cnf</td>
<td>Generates Certificate Authority key for signing certificates</td>
</tr>
<tr>
<td>SSL_server.cnf</td>
<td>Generates the NIM master's certificate for distributing to clients</td>
</tr>
<tr>
<td>SSL_client.cnf</td>
<td>Generates the NIM master's local certificate for authenticating</td>
</tr>
</tbody>
</table>

Installing OpenSSL on the NIM master

OpenSSL must be installed on the NIM master in order to be able to configure SSL authentication on the NIM master.

To install the OpenSSL on the NIM master follow these steps:

- Type the smitty nim_task_inst fastpath on the NIM master.
- Select Install Software from the SMIT panel.
- Select the name of your NIM master from the list that appears.
- Select the LPP_SOURCE containing the install images for OpenSSL.
- Select the package openssl-0.9.7g on the field Software to Install.
- Select the values, for the rest of the options, which best fit your requirements.

The package version may be different. The openssl-0.9.7g package can be found on the Linux Toolbox for AIX distribution media.
Example 5-13 shows the SMIT panel used for the OpenSSL installation on the NIM master.

**Example 5-13  OpenSSL installation on the NIM master**

<table>
<thead>
<tr>
<th>* Installation Target</th>
<th>master</th>
</tr>
</thead>
<tbody>
<tr>
<td>* LPP_SOURCE</td>
<td>LPP_53_ML4</td>
</tr>
<tr>
<td>* Software to Install</td>
<td>openssl-0.9.7g &gt; +</td>
</tr>
</tbody>
</table>

Customization SCRIPT to run after installation (not applicable to SPOTs)

<table>
<thead>
<tr>
<th>Force</th>
<th>no +</th>
</tr>
</thead>
</table>

**installp Flags**

PREVIEW only? [no] +

COMMIT software updates? [yes] +

SAVE replaced files? [no] +

AUTOMATICALLY install requisite software? [yes] +

EXTEND filesystems if space needed? [yes] +

OVERWRITE same or newer versions? [no] +

VERIFY install and check file sizes? [no] +

ACCEPT new license agreements? [yes] +

(AIX V5 and higher machines and resources)

Preview new LICENSE agreements? [no] +

**Group controls (only valid for group targets):**

Number of concurrent operations [] #

Time limit (hours) [] #

Schedule a Job [no] +

YEAR [] #

MONTH [] #

DAY (1-31) [] #

HOUR (0-23) [] #

MINUTES (0-59) [] #

---

**Installing OpenSSL on the NIM client**

OpenSSL must be installed on the NIM client in order to be able to configure SSL authentication on the NIM client.

Follow these steps to configure OpenSSL on the nim client:

- Type the `smitty nim_client_inst` fast path on the NIM client.
- Select **Install Software** from the SMIT menu.
- Select the LPP_SOURCE containing the install images for OpenSSL
- Select the package **openssl-0.9.7g** on the field Software to Install.
Select the values for the rest of the options which best fit your requirements.

Example 5-14 shows the SMIT panel used for the OpenSSL installation on the NIM master.

Example 5-14  OpenSSL installation on the NIM client

* LPP_SOURCE                                           LPP_53_ML4
* Software to Install                                   [openssl-0.9.7g > +

Customization SCRIPT to run after installation          [] +
(not applicable to SPOTs)

installp Flags
PREVIEW only?                                         [no] +
Preview new LICENSE agreements?                        [no] +
ACCEPT new license agreements?                         [yes] +
COMMIT software updates?                               [yes] +
SAVE replaced files?                                   [no] +
AUTOMATICALLY install requisite software?               [yes] +
EXTEND filesystems if space needed?                    [yes] +
OVERWRITE same or newer versions?                      [no] +
VERIFY install and check file sizes?                   [no] +

SSL authentication configuration on the NIM master
The NIM master must already be configured for SSL authenticating within the NIM environment, because it is the public key server for the clients. The following procedure configures the NIM master for SSL authentication within the NIM environment.

The following sections shows how to configure SSL authentication on the NIM master using either SMIT or the command line.

Using SMIT
Follow these steps to configure SSL authentication on the NIM master:

- Type the smitty nim_ssl fast path on the NIM master.
- Set the value for Enable Cryptographic Authentication for client communication? to enable.

The output shown in Example 5-15 is obtained when enabling cryptographic authentication for client communication on the NIM master using SMIT.

Example 5-15  SSL authentication configuration on the NIM master using smit

x - /opt/freeware/lib/libssl.so.0
x - /opt/freeware/lib/libcrypto.so.0
Generating a 1024 bit RSA private key
...........................................+++++
...........................................+++++
writing new private key to '/ssl_nimsh/keys/rootkey.pem'
-----
Signature ok
subject=/C=US/ST=Texas/L=Austin/O=ibm.com/CN=Root CA
Getting Private key
Generating a 1024 bit RSA private key
...............+++++
...............+++++
writing new private key to '/ssl_nimsh/keys/clientkey.pem'
-----
Signature ok
subject=/C=US/ST=Texas/L=Austin/O=ibm.com
Getting CA Private Key
Generating a 1024 bit RSA private key
.....+++++
.....+++++
writing new private key to '/ssl_nimsh/keys/serverkey.pem'
-----
Signature ok
subject=/C=US/ST=Texas/L=Austin/O=ibm.com
Getting CA Private Key
Target "all" is up to date.

From the command line
The following command configures SSL authentication on the NIM master:

    # nimconfig -c

The output should look similar to Example 5-16.

Example 5-16  SSL authentication configuration on the NIM master

    # nimconfig -c
    NIM_MASTER_HOSTNAME=1par2
    x - /opt/freeware/lib/libssl.so.0
    x - /opt/freeware/lib/libcrypto.so.0
    Target "all" is up to date.
    Generating a 1024 bit RSA private key
    ..+++++
    .........................+++++
    writing new private key to '/ssl_nimsh/keys/rootkey.pem'
    -----  
    Signature ok
    subject=/C=US/ST=Texas/L=Austin/O=ibm.com/CN=Root CA
    Getting Private key
    Generating a 1024 bit RSA private key
writing new private key to '/ssl_nimsh/keys/clientkey.pem'
-----
Signature ok
subject=/C=US/ST=Texas/L=Austin/O=ibm.com
Getting CA Private Key
Generating a 1024 bit RSA private key

writing new private key to '/ssl_nimsh/keys/serverkey.pem'
-----
Signature ok
subject=/C=US/ST=Texas/L=Austin/O=ibm.com
Getting CA Private Key

**Note:** When cryptographic authentication is enabled, output regarding authentication is sent to the syslogd daemon.

**Enabling cryptographic authentication on the client**
The following procedure describes the steps to configure existing standalone clients to use NIMSH communication protocol with SSL enabled.

**Using SMIT**
The following are the steps while using the SMIT menus:

- Type the `smitty nim_config_services` fast path on the NIM client.
- Select `nimsh` as the Communication Protocol used by client.
- Set the value for Enable Cryptographic Authentication? to `enable`.
- Select `yes` as the option for Installing Secure Socket Layer Software, if OpenSSL is not installed on the client.
- Specify the absolute path for the RPM package, or select the `lpp_source` resource that contains the OpenSSL RPM package.

**From the command line**
The following are the steps while using the command line:

- If OpenSSL is installed on the NIM client, type the following command:
  ```bash
  # nimclient -c
  ```
- If OpenSSL is not installed on the NIM client, complete the following steps:
  - Locate the Toolbox for Linux Applications CD.
– Install OpenSSL RPM package.
– Type the following command on the NIM client after OpenSSL is installed:
  
  ```
  # nimclient -c
  ```

Example 5-17 shows the output for the command issued to enable cryptographic authentication.

**Example 5-17  Enabling cryptographic authentication via command line**

```
# nimclient -c
Received 2718 Bytes in 0.0 Seconds
0513-044 The nimsh Subsystem was requested to stop.
0513-059 The nimsh Subsystem has been started. Subsystem PID is 319594.
```

**Notes:**

- In order to enable cryptographic authentication the NIM master must already be configured for SSL authentication, and both client and master must have AIX 5L V5.3 or later installed.
- Any communication initiated from the NIM client (pull operation) reaches the NIM master on the request for services and registration ports (1058 and 1059, respectively). This communication is not encrypted.
  
For any communication initiated from the NIM master (push operations), the NIM master communicates with the NIM client using the NIMSH daemon. This allows an encrypted handshake dialog during authentication. However, data packets are not encrypted.

5.3.5 Enabling a secondary port for NIMSH communication

By default, NIMSH uses a reserved port for returning stderr output during command execution. The default setting allows administrators to specify a specific port for opening through a firewall. However, it can cause performance issues when several connections are attempted in a short amount of time.

When TCP connections are closed, the closing sockets enter TIME_WAIT state. The length of time for this state may last up to 240 seconds, depending on system settings. The secondary port option allows you to specify any specific range of ports to cycle through during NIMSH operation.

For firewalls, administrators might want to open a specific port range through the firewall, and then for each machine on the internal network, ensure that the port range on the machine coincides with the open range through the firewall. When changing the NIMSH secondary port, choose a range of ports outside of the
range used for system services. We recommend using ports 49152 through 65535.

Using SMIT to enable a secondary port
Complete these steps to configure existing standalone clients to use the NIMSH communication protocol with a secondary port range.

- Type the `smitty nim_config_services` fast path on the NIM client.
- Select `nimsh` as the Communication Protocol used by client.
- Specify a start value for the secondary port number.
- Specify an increment value for the secondary port range.

Using command line to enable a secondary port
Complete these steps to configure existing standalone clients to use the NIMSH communication protocol with a secondary port range from the command line.

- Edit the `/etc/environment` file.
- Add the variable `NIM_SECONDARY_PORT=60000:5`, to use ports 60000 - 60005 within NIMSH.
- Use the desired `nimclient` command option to restart the NIMSH daemon.

**Note:** In order to enable a secondary port, the NIM client must already be configured and both master and client must have AIX 5L V5.3 or later.

5.3.6 Disabling push operations using NIMSH

NIM clients can prohibit the NIM master from allocating resources or initiating operations by disabling push operations. When push disablement is set, NIMSH does not process any NIM operation controlled by the NIM master.

Although master control is disabled, the client can still control the allocation of NIM resources and the initiation of NIM operations. The NIM master must have push permissions to perform push operations on the NIM clients.

To configure existing standalone clients to use NIMSH communication protocol with NIM master control disabled, use the following procedures.

Using Web-Based System Management

This section describes how to use Web-Based System Management.

- From the main Web-Based System Management container, select the Software icon.
From the Software menu, select **NIM Client → Permissions**.

Select whether to grant or deny permission for the NIM master to initiate push installations.

### Using SMIT

You can use the `smit nim_perms` fast path to disable the master push permissions.

To disable the master's push permissions, enter the `smit nim_perms` fast path from the client machine and select whether to grant or deny permission for the NIM master to initiate push installations.

### Using command line

You can disable and re-enable the master push permissions from the command line.

To set control on the client to `push_off`, enter the following on the client machine:

```
nimclient -P
```

To re-enable push permission on the client, enter the following on the client machine:

```
nimclient -p
```

### 5.3.7 Disabling pull operations

You can disable pull operations (operations initiated from the NIM client) by shutting down the nimesis subsystem from SRC on the NIM master, as shown in Example 5-18. Disabling pull operations this way applies to all NIM clients.

If you need to disable pull operations for a particular NIM client, you can enable CPU validation on the NIM master and provide a non-matching CPU id for the CPU id on the NIM client object definition. For information regarding how to configure CPU validation, refer to 4.4, “Using NIM to perform AIX migrations of NIM master and clients” on page 151.

**Example 5-18  Shutting down the nimesis subsystem**

```
(root@par2):/ # stopsrc -s nimesis
0513-044 The nimesis Subsystem was requested to stop.
```
5.3.8 NIM communication within a firewall environment

NIM is unaware of any network security when it attempts to perform either a push operation or pull operation. If there is a firewall between the master/server and the client, it has to be configured to allow traffic for all the protocols involved in NIM operations.

When a network install is performed, there are several protocols involved. The following section describes steps to help firewall administrators to configure the firewalls to provide access for clients to the different resources.

Installation overview
NIM performs network installation by using a client/server model based on the bootp/tftp protocols for receiving a network boot image. After the boot image is obtained, the client requests (tftp) a configuration file (niminfo) to determine which server(s) contain the install image and other necessary install resources. The install image and resources are nfs mounted using nfsd/mountd services. After all mounts succeed, the install begins and subsequent information is sent to the NIM master via nimclient calls to the nimesis daemon (NIM).

Upon completion of install, the client sends state information to the master via nimclient calls to the nimesis daemon. The NIM master then deallocates all install resources from the client object that has completed installing. The deallocation process consists of the following tasks:

- Removing files from designated tftp directory
  - Remove niminfo file
  - Remove link to boot image
  - Remove file entry in /etc/bootptab
- Unexporting nfs resources from client
  - Remove entries from /etc/exports
  - Export remaining entries from /etc/exports
- Updating client object information in the NIM database
  - Machine state (running / not running)
  - Command result (success or failure) client state (ready for an operation)

Installation process
In this section, we describe the client-server communication during a NIM installation. A NIM master push is presented, along with specifics of the installation process.

Master-initiated installation
When a network installation is initiated from the master', the NIM master prepares resources for installation (create script files, NFS export resources,
create file entry in /etc/bootptab), and then executes an RSH command on the client to set the bootlist for install over the network interface. The client resets and attempts to boot over the network using bootp and tftp services. Figure 5-2 shows the ports and protocols involved in NIM communications.

Figure 5-2   NIM protocols

**Note:** Firewall administrators must allow traffic for the protocols involved in a NIM operation.

**Protocols involved in a NIM operation**

This section describes the protocols involved in a NIM operation.

**Remote shell (RSH)**

Remote shell requires clients to connect using source ports obtained from the reserved port range of 1023-513. Because NIM clients do not have a client service, the clients communicate by calling rcmd(), which in turn, calls rreservport() to create a TCP socket and binds a port from the privileged port range of 1023-513.
The port is determined by initializing the starting port at 1023 and attempting to bind it; if this fails, the port number is decremented and the bind to the port is reattempted. This process continues until an unused port is found or port 513 has been reached.

Upon successful binding of the source port, rcmd() allows the option of binding a secondary (auxiliary) port for any stderr. When set, reservport() is called, but this time the starting port is based on the source port that was obtained in the previous step (source - 1). After it is initialized, the process for binding is repeated and upon success, this port keeps open for any stderr received from the destination service.

NIM makes use of this option and passes return code status (in addition to error messages) over the secondary port.

**Boot protocol (BOOTP)**

The BOOTP protocol uses two reserved port numbers: BOOTP client (68) and BOOTP server (67). The client sends requests using BOOTP server as the destination port; this is usually a broadcast. The server sends replies using BOOTP client as the destination port; depending on the kernel or driver facilities in the server, this may or may not be a broadcast. The reason two reserved ports are used is to avoid “waking up” and scheduling the BOOTP server daemons, when a boot reply must be broadcast to a client.

**Trivial File Transfer Protocol (TFTP)**

The TFTP protocol uses transfer identifiers (TIDs) as ports for communication; therefore they must be between 0 and 65,535. In order to create a connection, each end of the connection chooses a TID for itself, to be used for the duration of that connection.

The TIDs chosen for a connection should be randomly chosen, so that the probability that the same number is chosen twice in immediate succession is very low. Every packet has associated with it the two TIDs of the ends of the connection, the source TID and the destination TID.

These TIDs are handed to the supporting UDP (or other datagram protocol) as the source and destination ports. A requesting host chooses its source TID as previously described, and sends its initial request to the known TID 69 decimal (105 octal) on the serving host. The response to the request, under normal operation, uses a TID chosen by the server as its source TID and the TID chosen for the previous message by the requestor as its destination TID. The two chosen TIDs are then used for the remainder of the transfer.
Network File System

The Network File System (NFS) protocol currently uses the UDP port number 2049. This is not an officially assigned port, so later versions of the protocol use the port mapping facility of Remote Procedure Call (RPC). The port mapper program maps RPC program and version numbers to transport-specific port numbers. This program makes dynamic binding of remote programs possible.

This is desirable because the range of reserved port numbers is very small and the number of potential remote programs is very large. By running only the port mapper on a reserved port (111), the port numbers of other remote programs can be ascertained by querying the port mapper.

The port mapper also aids in broadcast RPC. A given RPC program will usually have different port number bindings on different machines, so there is no way to directly broadcast to all of these programs. The port mapper, however, does have a fixed port number. So, to broadcast to a given program, the client actually sends its message to the port mapper located at the broadcast address. Each port mapper that picks up the broadcast, and then calls the local service specified by the client. When the port mapper gets the reply from the local service, it sends the reply back to the client.

Network Installation Manager

Clients communicate to the Network Installation Manager (NIM) master using TCP ports 1058 (nim) and 1059 (nimreg). During the install process, the NIM clients send status information. The information contains details specific to the install progress. This information is updated in the NIM database and actions on the master's side are handled accordingly; when necessary, resources are deallocated (unexported) and boot images are removed.

The clients do not have a registered client service, so they use rcmd() to obtain sockets based on the rules described in “Remote shell (RSH)” on page 438. The API is passed the service port of 1058 for establishing a connection to the NIM master.

The nimesis daemon runs on the NIM master and listens on the NIM service port. When a request for service is received, the nimesis daemon accepts the connection, verifies the originator, and sends an ACK signal in a similar fashion as expected by rcmd. Upon a successful connection, state information is passed and commands are placed on the client using the secondary port which has a file descriptor associated with the socket.

Because NIM clients do not have access to the NIM database, all NIM commands are interpreted on the NIM master's side and subsequent operations are placed on the client for shell execution. This detail is important to understand because clients are allowed the option of requesting NIM operations. Since
clients have no knowledge of which commands must execute per NIM operation. The requests are always sent to the NIM master (1058) and the master responds by pushing (rsh) the necessary commands on the client machines.

The registration port (1059) is used when clients attempt to add themselves to a current NIM environment. The clients use rcmd() to obtain sockets and pass the service port 1059 for establishing a connection to the NIM master. When connected, clients pass machine configuration information to the NIM master. The NIM database is updated with the newly defined client object, and rsh permissions are given to the NIM master.

5.3.9 NFS reserved ports

Usage of NFS reserved ports can be enabled within a NIM environment starting with AIX 5L V5.3 TL 05 and later. Enabling usage of NFS reserved ports forces NIM clients to use reserved ports (ports below 1024) for NFS communications to the NIM server.

Enabling usage of NFS reserved ports adds the attribute nfs_reserved_ports to the NIM master object. The value for this attribute is set to yes. All installing clients configure the nfso option nfs_use_reserved_ports setting this value to 1 within the install environment.

Any clients installed this way are also able to configure the nfso client option prior to NIM client operations. Clients participating in a NIM environment where nfs_reserved_ports is enabled are able to set the NFS client option prior to any NFS service requests.

When usage of NFS reserved ports is not enabled (which is the value by default), then NIM clients use non-reserved ports to perform NFS service requests to the NIM Server. In Example 5-19 we show the NFS traffic between a NIM client and a NIM server. It can be seen that the ports used for NFS communications are not the reserved ports. In this example our NIM server uses the IP 10.1.1.22 and the NIM client uses the IP 10.1.1.70. The netstat command is executed on the NIM server while the NIM client is performing a NIM operation involving NFS service requests.

Example 5-19 Non-reserved ports usage

```
(root@lpar2):/ # netstat -na | grep 10.1.1.70
tcp4  0 101040  10.1.1.22.2049  10.1.1.70.32786  ESTABLISHED
```

The NIM clients already installed before enabling usage of NIM reserved ports should change their settings following the procedures shown in “Enabling NFS reserved ports on a NIM client already installed” on page 445.
After usage of NFS reserved ports is enabled, NIM clients use reserved ports for NFS traffic as shown in Example 5-20.

**Example 5-20  Reserved ports usage**

```
(root@lpar2):/ # netstat -na | grep 10.1.1.70
tcp4  0    0 10.1.1.22.2049          10.1.1.70.1021     ESTABLISHED
...```

---

**Enabling NFS reserved ports on the NIM master**

This section describes how to enable NFS reserved ports on the NIM master.

**Within a NIM environment**

Through this procedure you change the NIM master database to set that any client installed with this option sets the `nfs_reserved_ports` parameter to 1 and uses NFS reserved ports.

Follow these steps to configure NFS reserved ports usage within a NIM environment:

- Enter the `smitty nim_global_nfs` fastpath in the NIM master.
- Select **enable** as the value for the option **Enable/Disable Global Usage of NFS Reserved Ports?**.

Example 5-21 shows the SMIT panel used to enable usage of NFS reserved ports.

**Example 5-21  Enabling usage of NFS reserved ports**

Manage NFS Client Communication

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

```
[Entry Fields]
* Enable/Disable Global Usage of NFS Reserved Ports?  [enable]  +
* Allow NIM to enable port-checking on NIM master?  [no]  +
```

F1=Help   F2=Refresh   F3=Cancel   F4=List
F5=Reset  F6=Command   F7=Edit     F8=Image
F9=Shell  F10=Exit     Enter=Do
In Example 5-22, we see the attribute nfs_reserved_port set to yes to enable usage of NIM reserved port.

**Example 5-22  NIM master attributes**

(root@lpard):/ # lsnim -l master
master:
  class               = machines
  type                = master
  max_nimesis_threads = 20
  if_defined          = chrp.mp.ent
  comments            = machine which controls the NIM environment
  platform            = chrp
  netboot_kernel      = mp
  if1                 = ent-Network1 lpar2 00096B4EAD9C
  cable_type1         = N/A
  Cstate              = ready for a NIM operation
  prev_state          = ready for a NIM operation
  Mstate              = currently running
  serves              = LPP_5305
  serves              = SEC_ADAPTR
  serves              = SPOT_5305
  serves              = boot
  serves              = nim_script
  master_port         = 1058
  registration_port   = 1059
  reserved            = yes
  ssl_support         = yes
  nfs_reserved_port   = yes

---

**For a single NIM client**

Use the following steps to configure the usage of NIM reserved ports between the NIM master and a specific client:

- Enter the `smitty nim_chmac` fastpath in the NIM master.
- Select the NIM client in which you want to configure the usage of NIM reserved ports.
- Select **yes** for the option NFS Client Reserved Ports.

In Example 5-23 we see the SMIT panel used to set NFS client reserved ports values.

**Example 5-23  Setting NFS client reserved ports values**

<table>
<thead>
<tr>
<th>Machine Name</th>
<th>[VLPAR3_p5]</th>
</tr>
</thead>
<tbody>
<tr>
<td>* Hardware Platform Type</td>
<td>[chrp] +</td>
</tr>
<tr>
<td>* Kernel to use for Network Boot</td>
<td>[mp] +</td>
</tr>
</tbody>
</table>
Use the `lsnim` command to verify that the `nfs_reserved_port` value is set to `yes` for a NIM client in the NIM master database as shown in Example 5-24.

Example 5-24 Checking NFS reserved ports values

```
(root@lpar2):/ # lsnim -l VLPAR3_p5
VLPAR3_p5:
  class = machines
  type = standalone
  connect = shell
  platform = chrp
  netboot_kernel = mp
  if1 = ent-Network2 vlpar3_p5 0
  cable_type1 = bnc
  Cstate = ready for a NIM operation
  prev_state = ready for a NIM operation
  Mstate = currently running
  cpuid = 00CC544E4C00
  nfs_reserved_port = yes
```

Note: You can use various combinations for NFS reserved ports; for example:

- You can have NFS reserved ports enabled for your NIM environment, and select NIM clients using non-reserved ports.
- Also, you can have NFS reserved ports disabled for the NIM environment, and select clients using reserved ports for the NFS communication.
Enabling NFS reserved ports on a NIM client already installed

If the NIM client is installed prior to setting usage of NFS reserved ports, then you must execute some changes in order to have the client start using reserved ports for NFS operations. You must recreate the /etc/niminfo file to reflect the changes on the NIM master regarding usage of NFS reserved ports.

You can recreate the /etc/niminfo file by using one of the following methods:

- You can rebuild the file from the NIM master.
- You can rebuild the file from the NIM client.

We describe each method in the following sections.

Rebuilding the NIM client /etc/niminfo file from the NIM master

To rebuild the NIM client /etc/niminfo file from the NIM master, follow these steps.

1. Type the `smitty nim_switch_master` fastpath on the NIM master.
2. Select the Machine Name for the NIM client in which you want to rebuild the /etc/niminfo file.
3. Select the Host Name of Network Install Master using the same host name as the actual one.

In Example 5-25 we show the SMIT panel used to rebuild the /etc/niminfo file on the NIM client named VLPAR3_p5 from the NIM master lpar2, introducing the Host Name lpar2 for the value of Host Name of Network Install Master.

Example 5-25   Rebuilding the NIM client /etc/niminfo file from the NIM master

<table>
<thead>
<tr>
<th>Machine Name</th>
<th>[VLPAR3_p5]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Host Name of Network Install Master</td>
<td>[lpar2]</td>
</tr>
<tr>
<td>Force</td>
<td>no +</td>
</tr>
</tbody>
</table>

In Example 5-26, we can see that the /etc/niminfo file on the NIM client has been updated with the changes regarding usage of NFS reserved ports. A new variable is added to the file. The variable is called NFS_RESERVED_PORT, and the value for this variable is yes, because usage of NFS reserved ports is enabled on the NIM master.

Example 5-26   New /etc/niminfo file

```bash
# cat /etc/niminfo
#------------------ Network Install Manager ------------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
export NIM_NAME=VLPAR3_p5
export NIM_HOSTNAME=vlpar3_p5
export NIM_CONFIGURATION=standalone
```
export NIM_MASTER_HOSTNAME=lpard2
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS=" 10.1.1.70:vlpar3_p5  10.1.1.22:lpard2 "
export NIM_MOUNTS=""
export NFS_RESERVED_PORT=yes
export ROUTES=" default:0:10.1.1.1 

Rebuilding the NIM client /etc/niminfo file from the NIM client

To rebuild the NIM client /etc/niminfo file from the NIM client proceed, as follows:

- Rename the /etc/niminfo file to another name (you also can delete it, but renaming it allows you to keep a copy if you should need it for some reason).
- Enter the smitty niminit fastpath on the NIM client.
- Select the Machine Name. This is the name of the client on the NIM master. This name is already defined on the NIM master, because this client is already registered on the NIM master.
- Select the Primary Network Install Interface for the NIM client.
- Select the Host Name of Network Install Master. This is the NIM master that you are already using.

Example 5-27 shows the SMIT panel used to rebuild the /etc/niminfo on the NIM client in the preceding scenario. The /etc/niminfo file is rebuilt on the NIM client VLPAR3_p5, from the NIM master lpar2.

Example 5-27 Rebuilding the NIM client /etc/niminfo file from the NIM client

<table>
<thead>
<tr>
<th>Machine Name</th>
<th>[VLPAR3_p5]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Primary Network Install Interface</td>
<td>[en0]</td>
</tr>
<tr>
<td>Host Name of Network Install Master</td>
<td>[lpar2]</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Hardware Platform Type</th>
<th>chrp</th>
</tr>
</thead>
<tbody>
<tr>
<td>Kernel to use for Network Boot</td>
<td>[mp]</td>
</tr>
<tr>
<td>Communication Protocol used by client</td>
<td>[]</td>
</tr>
<tr>
<td>Ethernet Interface Options</td>
<td></td>
</tr>
<tr>
<td>Network Speed Setting</td>
<td>[]</td>
</tr>
<tr>
<td>Network Duplex Setting</td>
<td>[]</td>
</tr>
<tr>
<td>Comments</td>
<td>[]</td>
</tr>
</tbody>
</table>

Alternate Port Numbers for Network Communications
(reserved values will be used if left blank)

| Client Registration | []          |
| Client Communications| []         |
Disabling use of NFS reserved ports
The following sections show how to disable the usage of NFS reserved ports.

Disabling use of NFS reserved ports for the NIM environment
Follow these steps to disable the usage of NFS reserved ports for the entire NIM environment.

1. On the NIM master, execute the `nim` command by using the change operation to change the nfs_reserved_port attribute to no for the NIM machine object corresponding to the NIM master, as shown in Example 5-28. In the example, `master` is the name of the NIM machine object for the NIM master.

2. Rebuild the `/etc/niminfo` file on the NIM clients. For information about how to rebuild the `/etc/niminfo` file on the NIM client, refer to “Rebuilding the NIM client `/etc/niminfo` file from the NIM master” on page 445 or “Rebuilding the NIM client `/etc/niminfo` file from the NIM client” on page 446.

Example 5-28   Disabling usage of NFS reserved ports on the NIM environment
(root@lpar2):/ # nim -o change -a nfs_reserved_port=no master
(root@lpar2):/ #

Disabling use of NFS reserved ports for a particular NIM client
Follow these steps to disable the use of NFS reserved ports for a particular NIM client.

1. On the NIM master, execute the `nim` command using the change operation to change the nfs_reserved_port attribute to no for the NIM machine object corresponding to the NIM client on which you are disabling the usage of NFS reserved ports, as shown in Example 5-29. In the example, `VLPAR3_p5` is the name of the NIM machine object for the NIM client.

2. Rebuild the `/etc/niminfo` file on the NIM clients.

   For information about how to rebuild the `/etc/niminfo` file on the NIM client, refer to “Rebuilding the NIM client `/etc/niminfo` file from the NIM master” on page 445 or “Rebuilding the NIM client `/etc/niminfo` file from the NIM client” on page 446.

Example 5-29   Disabling use of NFS reserved ports for a particular NIM client
(root@lpar2):/ # nim -o change -a nfs_reserved_port=no VLPAR3_p5
Enabling the NFS server portcheck option (with nfso)

This option provides a convenient way for users to enable the port-checking that is done by the NFS server. When the nfso portcheck option is enabled, the NFS server checks whether an NFS request has originated from a privileged port; that is, a reserved port (below 1024). The default value of 0 disables port checking by the NFS server. A value of 1 directs the NFS server to do port checking on the incoming NFS requests.

This option does not have to be configured through NIM if resources are being served from a resource server separate from the NIM master. Use the nfso command as shown in Example 5-30 to enable this value on the resource server if the resources are being served from a resource server separate from the NIM master.

Example 5-30 Setting portcheck through the nfso command

(root@lpar2):/ # nfso -o portcheck=1
Setting portcheck to 1

Allowing port-check enablement adds the nfso server option portcheck with a value of 1 to the NIM master. This can be checked by using the nfso command, as shown in Example 5-31.

Example 5-31 Checking portcheck enablement with the nfso command

(root@lpar2):/ # nfso -o portcheck
portcheck = 1

To enable the use of the nfso server portcheck option, follow these steps:

1. Enter the smitty nim_global_nfs fastpath in the NIM master.
2. Select yes as the value for the option Allow NIM to enable port-checking on NIM master?

In Example 5-32 on page 449, we see the SMIT panel used to enable the nfso server portcheck option.
Example 5-32  Enabling nfso server portcheck option

Manage NFS Client Communication

Type or select values in entry fields. Press Enter AFTER making all desired changes.

* Enable/Disable Global Usage of NFS Reserved Ports? [enable] +
* Allow NIM to enable port-checking on NIM master? [no] +

F1=Help F2=Refresh F3=Cancel F4=List
F5=Reset F6=Command F7=Edit F8=Image
F9=Shell F10=Exit Enter=Do

Note: If you enable the nfso server portcheck option, then the NIM clients configured not to use NFS reserved ports fail to perform NIM operations involving NFS traffic. The error displayed is similar to the one shown in Figure 5-3.

Disabling the NFS server portcheck option (with nfso)

Use the nfso command on the NIM master to disable the portcheck option.
Example 5-33 on page 450 shows how to use the nfso command to disable the portcheck option.
Example 5-33  Disabling the nfso portcheck option

(root@lpar2):/ # nfso -o portcheck=0
Setting portcheck to 0

5.3.10 Firewall considerations

NIM makes use of several protocols that are generally considered risky services on firewall machines. It is recommended that users who desire firewall protection within their NIM environment follow these rules:

- The NFS program usually runs at port 2049, which is outside the privileged port space. Normally, access to port mapper (port 111) is needed to find which port this service runs on, but because most installations run NFS on this port, hackers can bypass NFS and try this port directly.

NFS was designed as a LAN service and contains numerous security vulnerabilities when used over the Internet. NFS services should not be run on firewall machines; if a NIM master resides on a firewall machine, then resources should reside on another client because clients may also be used as resource servers in a NIM environment (refer to 4.3.1, “Configuring a resource server” on page 144 for more information about this topic).

- If possible, TFTP servers should not be placed on firewall machines because no authentication is needed when requesting service. The TFTP protocol does allow for denying access based on entries contained in /etc/tftpaccess.ctl. NIM manages access to files in /tftpboot only, so all other directory locations should be off limits. When managed properly, TFTP access can be viewed as acceptable in the NIM environment.

- Because rsh is the standard method of client control, clients participating in the NIM environment must allow shell service (514), enable NIMSH for client communication, or enable Kerberos in the NIM environment per client. In order to reduce the amount of open ports in the NIM environment, the following rules may be applied:
  - For every NIM communication using rsh, leave five (5) ports open starting at 1023 and decremented from there. So if a client is communicating in the NIM environment, the client should leave open ports (1023-1019) and the master should leave open ports (1023-1019). Note that this is an estimate and may not work in all environments, because other services may call reservport() prior to, or during, NIM operations. When monitored, this approach should work fine in small environments because access to ports in the privileged space are restricted to super-user access only.
  - Users may also add secondary interfaces for each client participating in the NIM environment. The additional interfaces should be packet-filtered.
When NIM clients no longer participate in the NIM environment, or are temporarily removed from the NIM environment, users should disable rsh services on client machines by removing ~/.rhosts or removing rshd service.

5.4 Cloning NIM clients using mksysb

This section describes how to clone a client using an existing mksysb image and Network Installation Manager (NIM) procedures.

5.4.1 Using a mksysb image to clone NIM Client

An mksysb image is a backup of the operating system (that is, the root volume group). This backup can be used to reinstall a system to its original state, if needed. It also can be used to clone the machine from which the mksysb image has been taken to another machine.

Another usage of this image may be to customize your environment, creating an installable image of AIX 5L or AIX 4.3 containing the customizations and products that best fit your requirements and using it to install the clients. However, the target systems might not contain the same hardware devices or adapters, or require the same kernel (uniprocessor or multiprocessor).

These procedures are intended to be used to clone NIM clients. For information about how to back up and restore a NIM master, refer to 5.10, “Backing up and reinstalling a NIM master” on page 537.

Because NIM configures TCP/IP at the end of an installation, it is recommended that a bosinst_data resource be allocated for cloning mksysb installations with the RECOVER_DEVICES field set to no. This will prevent the BOS installation process from attempting to reconfigure the devices as they were on the source mksysb image.

**Note:** Starting in AIX 5L V5.2, devices are not recovered if the mksysb image that is being installed was not created on the same system.
5.4.2 Prerequisites

In order to restore an mksysb image using NIM, the following prerequisites must be met:

- The NIM master must be configured, and SPOT and mksysb resources must be defined.
- The NIM client to be installed must already exist in the NIM environment.
- The mksysb must be available on the hard disk of the NIM master or a running NIM client, or the mksysb image is created during this procedure from either the NIM master or a running NIM client.
- The SPOT and mksysb resources should be at the same level of AIX when used for NIM BOS installations.
- Many applications, particularly databases, maintain data in sparse files. A sparse file is one with empty space, or gaps, left open for the future addition of data. If the empty spaces are filled with the ASCII null character and the spaces are large enough, the file will be sparse, and disk blocks will not be allocated to it.

This situation creates an exposure in that a large file will be created, but the disk blocks will not be allocated. As data is then added to the file, the disk blocks will be allocated, but there may not be enough free disk blocks in the file system. The file system can become full, and writes to any file in the file system will fail. It is recommended that you either have no sparse files on your system, or that you ensure you have enough free space in the file system for future allocation of the blocks.

**Important:** If the system you have cloned is using OpenGL or graPHIGS, there may be some device filesets from these LPPs that must be installed after a clone. OpenGL and graPHIGS have graphics adapter-specific filesets, so if you cloned onto a system with a different graphics adapter, you will need to create a bundle as follows:

```bash
echo OpenGL.OpenGL_X.dev > /usr/sys/inst.data/user_bundles/graphic_dev.bnd
```

```bash
echo PEX_PHIGS.dev >> /usr/sys/inst.data/user_bundles/graphic_dev.bnd
```

You can allocate this bundle when you install the mksysb, and the device filesets will be installed automatically if OpenGL and graPHIGS are in your lpp_source.
If you are cloning machines that have different hardware, you need to have a LPP_SOURCE in order to be able to install the additional filesets to support the new hardware (support for the new hardware (device filesets) might not be available in the mksysb image).

### 5.4.3 mksysb image installation on a NIM Client

There are three ways to perform the tasks required to install a mksysb image on a NIM client:

- Web-Based System Management
- SMIT
- Command line

In this section, we use SMIT to perform the tasks. For information about how to perform these tasks using Web-Based System Management or the command line, refer to *AIX 5L V5.3 Installation and Migration*, SC23-4887.

At this point, we assume that the NIM master has been configured, a SPOT resource has been defined, and that the NIM client to be installed already exists in the NIM environment. For this example we use a NIM master (and resource server) named “master”, and a client named VLPAR3_p5. The mksysb image does not exist as a resource on the NIM master; it is created when the mksysb resource is defined.

#### 5.4.4 Mksysb resource creation

The first step is to create a mksysb resource. The following procedure lead us to accomplish the task:

1. Enter the `smitty nim_mkres` fastpath.
2. Select mksysb from the list of resource types that can be defined.
3. In the displayed dialogs, supply the values for the required fields. Use the help information and the LIST option to help you specify the correct values for defining your mksysb resource. The option `CREATE system backup image?` has been set to yes in order to create a system image.

Example 5-34 shows the input values for the creation of the mksysb resource in our environment.

*Resource Name* | [MKSYSB_VLPAR5_p5]
---|---
*Resource Type* | mksysb
*Server of Resource* | [master] +
*Location of Resource* | [/mksysb/VLPAR5] /
Example 5-35 shows the output for the creation of the mksysb resource. In this case, the output includes the output for the creation of the mksysb because we choose to create the mksysb at the moment of creation of the mksysb resource.

**Example 5-35 Output of the mksysb resource creation**

```
+--------------------------------------------------------+
<p>|                   System Backup Image Space Information   |</p>
<table>
<thead>
<tr>
<th>(Sizes are displayed in 1024-byte blocks.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Required = 730240 (713 MB)   Available = 2096504 (2047 MB)</td>
</tr>
</tbody>
</table>
```

Data compression will be used by the system backup utilities which create the system backup image. This may reduce the required space by up to 50 percent.
5.4.5 Correlating mksysb and SPOT resources

A SPOT resource must be allocated to the client to restore the mksysb. Note that mksysb and SPOT resources must be at the same level. The level of the SPOT NIM resource can be checked using the nim command, giving the SPOT resource name to the command with the options shown in Example 5-36.

Example 5-36   Checking SPOT level

{nimmast}:/etc # nim -o fix_query SPOT_53_ML4 | grep ML
   All filesets for 5300-02_AIX_ML were found.
   All filesets for 5.3.0.0_AIX_ML were found.
   All filesets for 5300-01_AIX_ML were found.
   All filesets for 5300-03_AIX_ML were found.
   All filesets for 5300-04_AIX_ML were found.

The lsnim command can also be used to check the SPOT level as shown in Example 5-37. The oslevel_r attribute shows the SPOT level.

Example 5-37   Checking SPOT level using the lsnim command

{nimmast}:/ # lsnim -l SPOT_53_ML4
SPOT_53_ML4:
   class         = resources
   type          = spot
   plat_defined  = chrp
   arch          = power
   bos_license   = yes
   Rstate        = ready for use
   prev_state    = ready for use
   location      = /AIX53ML4/SPOT_53_ML4/usr/SPOT_53_ML4/usr
   version       = 5
   release       = 3
   mod           = 0
   oslevel_r     = 5300-04
   alloc_count   = 0
   server        = master
   if_supported  = chrp.mp ent
   Rstate_result = success
The level of the mksysb can be checked using the **nim** command with the options shown in Example 5-38 on the value of `oslevel_r`.

**Example 5-38  Checking the mksysb level**

```
{nimmast}:/etc # lsnim -l MKSYSB_VLPAR5_p5
MKSYSB_VLPAR5_p5:
   class          = resources
   type           = mksysb
   arch           = power
   Rstate         = ready for use
   prev_state     = unavailable for use
   location       = /mksysb/VLPAR5
   version        = 5
   release        = 3
   mod            = 0
   oslevel_r      = 5300-04
   alloc_count    = 0
   server         = master
   extracted_spot = SPOT_PRUEBA
```

### 5.4.6 SPOT creation from an existing mksysb

There are several reasons why there may be differences between an SPOT and a mksysb resource. For instance, the mksysb may have been taken from another machine which is not in the NIM environment, or the machine from which the mksysb was taken may have been updated without updating the SPOT. For such cases, you need to create an SPOT from an existing mksysb.

Follow these steps to create a SPOT starting from an existing mksysb:

1. Enter **smitty nim_mkres** on the NIM master.
2. Select **SPOT** as the Resource Type.
3. Enter the values required to define the resource. For the value **Source of Install Images**, select the mksysb resource that you want to use to create the SPOT.

Example 5-39 shows the smitty options used to create an SPOT using a mksysb NIM resource as the source for the creation.

**Example 5-39  SPOT creation from a mksysb**

```
* Resource Name                                      [SPOT_VLPAR_p5]
* Resource Type                                       spot
* Server of Resource                                  [master] +
* Source of Install Images                            [MKSYSB_VLPAR5] +
* Location of Resource                                [/export/spot] /
```
5.4.7 mksysb installation

After you create the mksysb resource and take a mksysb image, you can to restore the mksysb in another machine (or in the same machine). To restore the mksysb, follow these steps:

1. Enter the smit nim_bosinst fast path.
2. Select a TARGET for the operation. This is the partition where the restoring of the mksysb takes place.
3. Select mksysb as the installation TYPE.
4. Select the MKSYSB to use for the installation.
5. Select the SPOT to use for the installation.
6. In the displayed dialog fields, supply the correct values for the installation options or accept the default values. You can use the help information or the LIST option for assistance.
7. Run the SMIT dialog to install the NIM client.

If the client machine being installed is not already a running configured NIM client, NIM will not automatically reboot the machine over the network for installation. If that is the case, supply the boot_client=no attribute to the bos_inst command. If the boot_client attribute value is not specified, it defaults to boot_client=yes.

If the client was not rebooted automatically from SMIT, initiate a network boot from the client to install it. Example 5-40 shows the SMIT panel and values to restore the mksysb.

Example 5-40  Restoring the mksysb

<table>
<thead>
<tr>
<th>* Installation Target</th>
<th>VLPAR3_p5</th>
</tr>
</thead>
<tbody>
<tr>
<td>* Installation TYPE</td>
<td>mksysb</td>
</tr>
<tr>
<td>* SPOT</td>
<td>SPOT_53_ML4</td>
</tr>
<tr>
<td>LPP_SOURCE</td>
<td>[]</td>
</tr>
<tr>
<td>MKSYSB</td>
<td>MKSYSB_VLPAR5_p5</td>
</tr>
</tbody>
</table>
BOSINST_DATA to use during installation [] +
IMAGE_DATA to use during installation [] +
RESOLV_CONF to use for network configuration [] +
Customization SCRIPT to run after installation [] +
Customization FB Script to run at first reboot [] +
ACCEPT new license agreements? [no] +
Remain NIM client after install? [yes] +
PRESERVE NIM definitions for resources on this target?
FORCE PUSH the installation? [no] +
Initiate reboot and installation now? [yes] +
-OR-
Set bootlist for installation at the next reboot? [no] +
Additional BUNDLES to install [] +
-OR-
Additional FILESETS to install [] + (bundles will be ignored)
installp Flags
COMMIT software updates? [yes] +
SAVE replaced files? [no] +
AUTOMATICALLY install requisite software? [yes] +
EXTEND filesystems if space needed? [yes] +
OVERWRITE same or newer versions? [no] +
VERIFY install and check file sizes? [no] +
ACCEPT new license agreements? [no] +
(AIX V5 and higher machines and resources)
Preview new LICENSE agreements? [no] +
Group controls (only valid for group targets):
   Number of concurrent operations [] #
   Time limit (hours) [] #
Schedule a Job [no] +
YEAR [] #
MONTH [] ++
DAY (1-31) [] ++
HOUR (0-23) [] ++
MINUTES (0-59) [55] ++

In our scenario, the client where we are restoring the mksysb resets and the restore begins.
5.4.8 Monitoring the mksysb installation

You can monitor the restore process by either opening a console to the machine, or by using NIM commands used on the master. The `lsnim` command provides information about the status of the client.

Example 4-7 shows the output of the `lsnim` command used with different parameters to monitor the restore process.

Example 5-41 Monitoring mksysb restore

```
{nimmast}:/ # lsnim -l VLPAR3_p5
VLPAR3_p5:
  class     = machines
  type      = standalone
  connect   =nimsh
  platform  = chrp
  netboot_kernel = mp
  if1       = NET_EN1 VLPAR3_p5 0
  cable_type1 = N/A
  Cstate    = Base Operating System installation is being performed
  prev_state = BOS installation has been enabled
  Mstate    = in the process of booting
  info      = BOS install 16% complete : 12% of mksysb data restored.
  boot      = boot
  mksysb    = MKSYSB_VLPAR5_p5
  nim_script = nim_script
  spot      = SPOT_53_ML4
  cpuid     = 00CC544E4C00
  control   = master
  Cstate_result = success
```

Tip: The `lsnim` command flag `-a` can be used to display a particular attribute. This can be used to display only the attribute info, as shown in Example 5-42.

Using this into a loop, you can automatically monitor the process.

Important: If the mksysb that you are restoring comes from a different machine than the one on which you are restoring it, there may be some additional software which needs to be installed (for example, device drivers). In that case you need to allocate a LPP_SOURCE resource to supply the required filesets.
Example 5-42  Displaying the info attribute

{nimmast}: / # lsnim -a info VLPAR3_p5
VLPAR3_p5:
info = BOS install 16% complete : 12% of mksysb data restored.

When the restore process completes, the `lsnim` command displays output similar to Example 5-43. The value for the attribute Cstate must be ready for a NIM operation.

Example 5-43  Restore process completed

{nimmast}: / # lsnim -1 VLPAR3_p5
VLPAR3_p5:
  class = machines
type = standalone
connect = nimsh
platform = chrp
netboot_kernel = mp
if1 = NET_EN1 VLPAR3_p5 0
cable_type1 = N/A
Cstate = ready for a NIM operation
prev_state = not running
Mstate = currently running
cpuid = 00CC544E4C00
Cstate_result = success

Also check that there is no link in the /tftpboot directory for any of the resources previously assigned to restore the mksysb, and that there is no entry in the file /etc/bootptab for the machine where the mksysb is restored.

5.5 Using NIM to migrate systems to new hardware

In this section, we briefly discuss how to use the Network Installation Manager (NIM) to move systems to new hardware whether that hardware resides in the same site or in a remote site. By “new hardware”, we mean both moving to similar hardware (for example, from POWER4 to POWER4) and also moving to a different platform (for example, POWER4 to POWER5).

We cover the following topics here:

- Migrating an LPAR to another managed system using NIM
- Relocating an LPAR to a remote location via NIM
- Migrating to new hardware utilizing custom bosinst.data and image.data files with NIM
5.5.1 Migrating the image of an LPAR to another system using NIM

You migrate the image of an LPAR from one managed system to another by using a mksysb image to clone a system (see 5.4, “Cloning NIM clients using mksysb” on page 451). An example of this would be if your current managed system is a System p 650 (POWER4) and you want to “move” an LPAR from this system to a different LPAR on an IBM System p 595 (POWER5). Using mksysb cloning makes this task fairly simple. However, you need to consider the following before proceeding:

- What version of AIX is the source system running? This is very important because not all versions of AIX will run on newer IBM System p hardware. For example, AIX 5L V5.1 systems will not run on POWER5, so the system must migrate to AIX 5L V5.3 or be migrated using the new mksysb migration procedure (see 4.5, “NIM mksysb migration and nim_move_up POWER5 tools” on page 205). Verify that your AIX version and target hardware platform are compatible; you can find this information in the AIX release notes:


- If the hardware type and configuration of the source and target systems are very different, then you need to ensure that you have all the correct device support in an lpp_source with an updated SPOT. For example, migrating a system from a p660 (POWER3™ RS64) to a p595 (POWER5) will require additional device support for the POWER5 hardware.

- Create a new NIM client machine definition for the target LPAR. This will be used as the target of the mksysb cloning.

- Verify that the new hardware is ready to accept the source system. Before attempting to clone the source image to the new LPAR, first create the new LPAR definition on the target system with all the necessary disk, CPU, memory and adapters (Fibre Channel, SCSI, Ethernet, and so on). Any cabling required for network or storage (FC) connections should also be completed and verified. An IP address should also be assigned for the target LPAR (unless the source system is going to be decommissioned after the move and the target system is going to reuse its IP address).

  After the new LPAR definition is ready, perform a NIM rte installation of AIX for this LPAR. Performing this step will allow you to verify that the LPAR configuration is valid and that all the necessary adapters, processors, memory, network/storage connectivity and other devices are valid before attempting the move of the source system.

  Running cfgmgr at this point is also recommended so that if there are any devices that cannot be configured because of missing device filesets, cfgmgr will display a message outlining which filesets are required. For information
about moving LPARs via SAN zoning, refer to 5.6, “Using SAN zoning for cloning LPARs” on page 475.

- Ensure that the microcode on the target system’s adapters, managed system, and HMC are up-to-date before attempting a hardware migration. Ensure that all necessary device support is available.

- When moving an LPAR to a managed system that is connected to a different HMC, the mksysb cloning operation will recreate the RMC (part of RSCT) access control lists (ACLs, /var/ct/cfg/ctrmc.acls). This is done to allow the target LPAR’s HMC to identify and manage the new LPAR. For detailed information about recreating the RMC ACLs, refer to 5.6, “Using SAN zoning for cloning LPARs” on page 475.

A related topic regarding DLPAR and cloning via alt_disk_install may arise: after cloning, the /etc/ct_node_id file has the same contents as the source LPAR, so RSCT does not detect the LPAR to manage. As a workaround, run the following commands after the first boot of the new LPAR, followed by a reboot:

```
# /usr/sbin/rsct/install/bin/uncfgct -n
# /usr/sbin/rsct/install/bin/cfgct
```

**Note:** NIM rte installations avoid this issue by creating a unique /etc/ct_node_id file.

- Your NIM master must be configured with the latest level of AIX code, and must include all the necessary device filesets to support the target system. The lpp_source must contain the filesets and the corresponding SPOT must be updated; refer to 5.1, “Updating the NIM environment (lpp_source, SPOT)” on page 410 for more information about this topic.

  - For example, if you are moving an LPAR from a System p650 to a System p595, it is most likely that the adapter types will be different between the two systems. On your System p650 you may have 6228 Fibre Channel (FC) adapters, but the target system has 5716 FC adapters, requiring a different device driver.

  For a smooth hardware migration, you will need to ensure that all device filesets are available in your lpp_source to support the 5716 adapter. Otherwise, you may find that some devices will be in an unconfigured state after the move. Or, if your system is booting from the SAN, then you may not be able to perform the cloning operation because it may not be able to detect the SAN-attached disk or it may fail when trying to access the disks.
Starting with AIX 5L V5.2, an lpp_source is no longer a prerequisite for a mksysb installation; that is, when installing AIX 5L V5.2, by default all device support files are also installed, so installing a mksysb from such a system would not require an lpp_source. However, when moving a system image to a different hardware platform, we recommend that you allocate an lpp_source.

- Also, if the correct disk device support is not available during the mksysb cloning, the install may appear to work successfully but when the client boots for the first time it, may fail with LED code 554 (554=The boot device could not be opened or read). This situation may occur when moving a system that boots from a SCSI disk to one that boots from a SAN-attached disk, and the necessary device filesets are not available (or the administrator did not allocate an lpp_source for the mksysb installation).

- Another possibility you may encounter if you do not have all the required device support in your lpp_source and an up-to-date SPOT is when network-booting the client. If the required device support is not on your NIM master for the target system's network adapter (from which you are trying to network-boot), then you will be unable to start the cloning operation because the client will be unable to configure the network boot adapter. You will see LED code 605 (605=Configuration of physical network boot device failed).

► When moving a system via NIM mksysb cloning, it is desirable to check that the source system’s devices are not recovered during the cloning operation. Letting a mksysb restore to recreate the source system's devices could lead to duplicate IP addresses on your network. Unless the source system is on a different network, you should choose no to recovering devices. How you do this depends on how you are moving. For example, if you manually boot the client and enter details in the BOS installation menu, you can select no to Recover Devices. If booting automatically, you can use a custom bosinst.data file (with RECOVER DEVICES = no).

**Note:** When a mksysb image is created, the CPU ID is saved. If you are reinstalling the same system, then the device information is recovered; for example, RECOVER DEVICES is automatically set to yes.

If the mksysb image is used to install another system, device information is not recovered from the mksysb image; for example, RECOVER DEVICES = Default (no).
5.5.2 Relocating the image of an LPAR to a remote location

If you have a requirement to move a NIM client to a remote location, you can use NIM to assist in this task. Using a mksysb image of the remote client will allow you to “move” it to your local site without the need for tapes or relocating the hardware. However, in order for this approach to be successful there must be a high-speed network link between both sites. Then all that is required is to export your NIM master’s mksysb directory (for example, /export/images, with enough free space for the image).

NFS-mount the export from the client, perform a mksysb to the mount, and then install the mksysb image onto the new (target) system, as described in this example:

- We need to relocate an AIX 5L V5.2 LPAR running on a System p650 (lpar1) from Paris to Montpellier. This is our remote (source) system.
- The target system is an LPAR on a System p595 (lpar1_p5). This is our local (target) system. The NIM master (montpnim) is also located at the local site in Montpellier.
- A high-speed network link exists between the two sites.
- First, we create a mksysb image of the remote system which will be written to our local NIM master's mksysb directory via NFS:
  
  ```
  <remote_server> # mount <montpnim>:/export/images /mnt
  <remote_server> # mksysb -i /mnt/lpar1-mksysb.5205.14Jun2006
  ```
- We also perform a `savevg` of the remote system's data volume group to the mksysb directory. Depending on the size of your data volume group this may not be possible. (For example, a 1 TB volume group backed up over a network via NFS is not the best approach.) We need to check that we have enough free space on NIM master for this backup. Our data volume group was only 5 GB in size, so we shut down all applications on the system before performing the `savevg`, as follows:
  
  ```
  <remote_server> # savevg -f /mnt/lpar1-datavg.savevg.14Jun2006 datavg
  <remote_server> # cd / ; umount /mnt
  ```
- Now we have a mksysb image and savevg images of our remote system. We can install the mksysb image onto the new p595 LPAR (lpar1_p5). We restore with `RECOVER_DEVICES` set to no. Refer to 5.4, “Cloning NIM clients using mksysb” on page 451 for details about cloning via a mksysb image.

After this step is complete, we can configure lpar1_p5 with new IP details (gateways, DNS servers, and so on) for the local site and reconfigure devices such disk, adapters and so on. The new site also uses Tivoli Storage Manager for backup, so we install the TSM client and configure it so the new system can be backed up. We also verify that the AIX level is correct.
(oslevel) and that all the filesets are consistent (lppchk). The data volume group is then restored (restvg) and verified.

The system is now ready for application testing, and if that is successful, the relocation is complete. Further (site-specific) customization may be required to suit the new environment (for example, mksysb/savevg scripts, hosts file, print queues, security settings, and so on).

If you need to relocate a system but a network link does not exist between the sites, you can try the following alternative (this procedure assumes there are tapes drives, of similar type, available at both sites):

- Perform a mksysb of the remote system to tape. Send the tape to the destination site.
- Using a suitable tape drive attached to your NIM master, extract the mksysb image. You will need enough free space in a file system to restore the image.
  
  ```
  # tctl -l /dev/rmt0 rewind
  # tctl -f /dev/rmt0.1 fsf 3
  # cd /migrate/restore
  # dd if=/dev/rmt0.1 of=/migrate/restore/lpar1-dd-mksysb-image-file
  ```
- You will now have a mksysb image that you can use with NIM to install onto the target LPAR at the local site. In the following section, we describe how to extract a mksysb from tape.

### 5.5.3 Migrating to new hardware utilizing custom bosint.data and image.data files

In this section, we investigate a specific example of using a custom bosint.data and image.data file when migrating to new hardware. For example, the mksysb image comes from a mirrored rootvg and the target server has only one disk allocated for rootvg—or the mksysb image is from the tape media, instead of an image file.

Here we describe how to the NIM environment to resolve these issues. First, we need access to the mksysb image, the bosinst.data, and image.data files. This section explains how to extract the mksysb image from the tape media; customize the bosinst.data and image.data file to suit the new server (target hardware); and then perform a BOS installation.
Extracting mksysb image file from a tape media

If the mksysb image is on a tape media, we first need to extract the mksysb image from this tape media by following these steps:

1. Determine the tape blocksize.
   
   ```
   # tcopy /dev/rmt0
   ```
   
   The output of the `tcopy` command is a list of all the files found on the media, along with byte count and the block size used, as shown by the values highlighted in bold in Example 5-44 (this command may take a while to complete).

```
Example 5-44  The tcopy command to determine the tape blocksize

# tcopy /dev/rmt0

tcopy : Tape File: 1; Records: 1 to 7179 ; size:512

tcopy : Tape File: 1; End of file after :7179 records; 3675648 bytes

tcopy : Tape File: 2; Records: 1 to 2900 ; size:512

tcopy : Tape File: 2; End of file after 2900 records, 76890 bytes
...
```

2. Change the blocksize of the tape drive.

   ```
   # chdev -l rmt0 -a block_size=512
   ```

3. Rewind the tape media (/dev/rmt0) to the beginning.

   ```
   # tctl -f /dev/rmt0 rewind
   ```

4. Move the tape forward to the beginning of the fourth tape marker.

   ```
   # tctl -f /dev/rmt0.1 fsf 3
   ```

5. Copy the mksysb image to a directory (for example, copy mksysb of node1 to /export/images directory).

   ```
   # dd if=/dev/rmt0.1 of=/export/images/Node1.mksysb ibs=1024 obs=1024 conv=sync
   ```

After the mksysb image is extracted from the tape, we can create the NIM mksysb resource (see Example 5-45).

   ```
   # smitty nim_mkres
   ```

   Select “mksysb = a mksysb image”

```
Example 5-45  Define a NIM mksysb resource

Define a Resource

Type or select values in entry fields.
Press Enter AFTER making all desired changes.
The bosinst.data file

The bosinst.data file contains information for the BOS installation program. For example, the BOS installation program looks for information in the bosinst.data file to find out which target disk to install the rootvg as well as whether to install. It also updates any devices in the target server, and so on.

The BOS installation program looks for the information from the /bosinst.data in the mksysb image. If the BOS installation program cannot obtain all the information that it requires, it will prompt the user to manually specify the information through the console.

The bosinst.data file is usually used in a NIM environment when you need a no-prompt installation. This can be done by prior specification of the bosinst_data resource. The bosinst.data file should contain all the necessary information needed by the BOS installation program.

There are many parameters in the bosinst.data file. You can find the detailed information in the /usr/lpp/bosinst/bosinst.template.README file. If you need to install a mksysb image to another server (different hardware), the following list highlights important parameters that you must specify.

- **EXISTING_SYSTEM_OVERWRITE**

  This parameter specifies which disks can be overwritten during the BOS install. This variable is applicable only for a non-prompted overwrite installation.

  If the target_disk_data stanza has no field values, then the EXISTING_SYSTEM_OVERWRITE field is used to determine which disks to install on.

  If EXISTING_SYSTEM_OVERWRITE is set to 'any', it means that any disk can be used for the install.
If EXISTING_SYSTEM_OVERWRITE is set to 'no', it means that only disks that contain no volume group can be used during the install.

If EXISTING_SYSTEM_OVERWRITE is set to 'yes', it means that disks which contain the existing root volume group will be used first, and if additional disks are needed, those containing no volume group can be used.

▶ **RECOVER_DEVICES**

If this parameter is set to Default, the install process will determine whether you are installing to the same machine or not, based on the CPU ID and LPAR nodeid.

If you are reinstalling a system backup to the same machine, then RECOVER_DEVICES will be set to yes. Otherwise, it is set to no. This field may also set directly to yes or no.

▶ **INSTALL_DEVICES_AND_UPDATES**

When installing a mksysb image to a system with a different hardware configuration, you boot from product media in order to obtain any missing device drivers installed, if all devices and kernels were not installed prior to creating the mksysb image. In our case, it is the lpp_source rather than the product media. In addition, if the product media is a later level of AIX than the mksysb, software in the mksysb image will be updated.

To prevent either of these additional installs from occurring, set this field to 'no'. The default is 'yes'.

**Note:** If none of the new devices are required for disk/boot support, we recommend that you set INSTALL_DEVICES_AND_UPDATES to no. Then manually update the system (after the mksysb is installed) using the correct level if CD media / lpp_source.

However, if the new devices are required by disk/boot support, you need to set INSTALL_DEVICES_AND_UPDATES to yes. Be aware that the devices will be updated if the lpp_source used during the mksysb installation is of a higher level, and be prepared for that fact.

The ALL_DEVICES KERNELS parameter is not required in this case. Specify ALL_DEVICES KERNELS only if you are performing new system installs (overwrite, preservation, or migration); do not specify it for mksysb install.

▶ **ENABLE_64BIT_KERNEL and CREATE_JFS2_FS fields**

If the system is model IBM eServer™ p5 or BladeCenter® JS20 or later, the default for ENABLE_64BIT KERNEL and for CREATE_JFS2_FS will be yes, otherwise, it will be no.
If either of these fields is set to a value other than Default, that value will be used. If blank, the value Default will be assumed. On any system, JFS2 file systems can be selected with either the 64-bit kernel or the 32-bit kernel.

**TARGET DISK DATA**

There can be multiple target_disk_data stanzas. They define which disks will contain the root volume group. Only one field (PVID, PHYSICAL_LOCATION, SAN_DISKID, CONNECTION, LOCATION, SIZE_MB, HDISKNAME) must be non-null in order for BOS install to choose a disk.

The order of precedence is listed here; you can refer to the /usr/lpp/bosinst/bosinst.template.README for more details about the precedence information.

- PVID (Physical Volume ID), then
- PHYSICAL_LOCATION
- SAN_DISKID
- CONNECTION(parent attribute//connwhere attribute)
- LOCATION
- SIZE_MB
- HDISKNAME

If the BOS installation is no-prompt and you leave the target_disk_stanza empty, then the BOS installation program will check on the EXISTING_SYSTEM_OVERWRITE field.

Now that we have a good understanding of the parameters in the bosinst.data file, we can edit this file to suit the target server’s environment.

There are two approaches to perform this task: with source server running, or without the source server running:

- If the source server is running, you can edit the /bosinst.data file directly from the server. As of AIX 4.3.3 and later versions, the mksysb command always updates the target_disk_data stanzas in /bosinst.data to match the disks currently in the root volume group of the system where the mksysb is running.

  We need to create a /save_bosinst.data_file file to avoid overwriting the edited/customized /bosinst.data file during the mksysb backup. You can just touch a file with the file name as save_bosinst.data_file.

  **Note:** Ensure that the edited/customized /bosinst.data file is not updated after the mksysb command is run.

- If the source server is not running, we can extract the bosinst.data file from the mksysb image.
In our scenario, we do not have the source server running, only its mksysb image. We extract bosinst.data file from the mksysb image and create a NIM bosinst_data resource, ready for our NIM operation. We follow these steps:

1. Extract the bosinst.data file from mksysb image file.

Assume we are extracting the bosinst.data file from the /export/images/Node1.mksysb and placing it in /other_res directory in the NIM master.

```
# cd /other_res
# restore -xvqf /export/images/Node1.mksysb ./bosinst.data
```

In your case, you can rename this bosinst.data file to bosinst.data.Node1 to denote that this file is used for the Node1. Change the parameter fields shown in step one in the bosinst.data.Node1 file. Then create a NIM bosinst_data resource:

```
# mv bosinst.data bosinst.data.Node1
```

2. Create a NIM bosinst_data resource; see Example 5-46.

```
# smitty nim_mkres
```

Select “bosinst_data = config file used during base system installation”

```
Example 5-46 Define NIM bosinst_data resource
```

```
| Type or select values in entry fields. Press Enter AFTER making all desired changes. |
|-----------------------------------|-----------------------------------------------------------------|
| Resource Name                     | [BID_NODE1]                                                     |
| Resource Type                     | bosinst_data                                                   |
| Server of Resource                | [master] +                                                      |
| Location of Resource              | [/other_res/bosinst.data.Node1]                                |
| Comments                          | []                                                              |
| Source for Replication            | [] +                                                            |
```

**image.data file**

The image.data file contains information required by the BOS installation program. This file describes how physical disks, volumes groups, logical volumes, file systems and paging space should be configured in the root volume group during installation. This file is generated whenever you run a mksysb -i or the mkszfile command.

In our scenario, we are restoring the mksysb image with a mirrored rootvg to another server that has only one disk for the rootvg. We need to edit the image.data file to change the LV_SOURCE_DISK_LIST, COPIES and the PP
parameters in order to reflect one copy of rootvg; see Example 5-47. We change
the `LV_SOURCE_DISK_LIST`, `COPIES` and the `PP` parameters, as highlighted
in the example with an arrow and bold font.

**Note:** Example 5-47 on page 471 shows only the changes on hd2. You
need to perform the changes for all the other LVs in the rootvg.

There are two approaches to working on the image.data file: with the source
server running, or without the source server running, as explained here:

- If the source server is still running, you can edit the image.data file in the
server, as shown in Example 5-47. Then perform a mksysb without
generating a new image.data (mksysb without the `-i` option). However, you
must ensure that the edited/customized image.data file is not overwritten after
a mksysb command.

- If the source server is already down and you only have its mksysb image, you
can extract the image.data file from the mksysb image.

In our scenario, we do not have the source server running, only its mksysb
image. Here are the steps to extract the image.data file from the mksysb image,
edit the necessary parameters, and create a NIM image_data resource that is
ready for NIM operation.

1. Extract the image.data file from the mksysb image
   `/export/images/Node1.mksysb`, and edit the file.

   ```
   # cd /other_res
   # restore -xvqf /export/images/node1.mksysb ./image.data
   ```

   Rename this image.data file to image.data.Node1 to denote that this file is for
target Node1.

   ```
   # mv image.data image.data.Node1
   ```

   Edit image.data.Node1 file to be able to restore with one copy of rootvg on the
target server, as shown in Example 5-47.

**Example 5-47**  Edit image.data.Node1 file to install one copy of rootvg

```makefile
lv_data:

lv_data:

VOLUME_GROUP= rootvg

```
STALE_PPs= 0
INTER_POLICY= minimum
INTRA_POLICY= center
MOUNT_POINT= /usr
MIRROR_WRITE_CONSISTENCY= on/ACTIVE
LV_SEPARATE_PV= yes
PERMISSION= read/write
LV_STATE= opened/syncd
WRITE_VERIFY= off
PP_SIZE= 8
SCHED_POLICY= parallel

==> PP= 140  <-- change this
BB_POLICY= relocatable
RELOCATABLE= yes
UPPER_BOUND= 32
LABEL= /usr
MAPFILE=
LV_MIN_LPS= 83
STRIPE_WIDTH=
STRIPE_SIZE=
SERIALIZE_IO= no
FS_TAG=

To verify the changes on the image.data.Node1 file, refer to Example 5-48.

Example 5-48  Updated image.data.Node1 file

```bash
lv_data:
VOLUME_GROUP= rootvg
==> LV_SOURCE_DISK_LIST= hdisk0
LV_IDENTIFIER= 00cc544e00004c000000010bec51e388.5
LOGICAL_VOLUME= hd2
VG_STAT= active/complete
TYPE= jfs2
MAX_LPS= 32512
==> COPIES= 1
LPS= 70
STALE_PPs= 0
INTER_POLICY= minimum
INTRA_POLICY= center
MOUNT_POINT= /usr
MIRROR_WRITE_CONSISTENCY= on/ACTIVE
LV_SEPARATE_PV= yes
PERMISSION= read/write
LV_STATE= opened/syncd
WRITE_VERIFY= off
PP_SIZE= 8
SCHED_POLICY= parallel
==> PP= 70
```
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BB_POLICY = relocatable
RELOCATABLE = yes
UPPER_BOUND = 32
LABEL = /usr
MAPFILE =
LV_MIN_LPS = 83
STRIPE_WIDTH =
STRIPE_SIZE =
SERIALIZE_IO = no
FS_TAG =

2. Create a NIM image_data resource.

After changing the parameters in the image.data.Node1 file, create a NIM image_data resource as shown in Example 5-49.

# smitty nim_mkres
   Select “image_data = config file used during base system installation”

Example 5-49 Define NIM image_data resource

Performing BOS installation
After we have the mksysb, bosinst_data and image_data resources defined in our NIM master, we need to define a NIM client machine to our NIM master. With all these in place, we can start the BOS installation on the target server.

There are certain considerations to take care of when executing a “push” installation with the no-prompt option. If the target server is not already a NIM client defined to the NIM master, we need to assign the /etc/niminfo file to the target server so that this server knows who the NIM master is. Otherwise, we will need to perform a push installation with a Force option.
1. Assign the /etc/niminfo file to the target server.

After the NIM client machine has been defined in the NIM master, we assign the /etc/niminfo file to the target server by specifying a new master to the client machine. Follow the smit steps.

```bash
# smitty nim_mac
   Specify New Master for Client Machine
   Select the NIM client machine

Or use the SMIT smitty nim_switch_master fast path, as shown in Example 5-50.

Example 5-50   Specify a NIM master for a client machine

<table>
<thead>
<tr>
<th>Entry Fields</th>
</tr>
</thead>
<tbody>
<tr>
<td>Machine Name</td>
</tr>
<tr>
<td>Host Name of Network Install Master</td>
</tr>
<tr>
<td>Force</td>
</tr>
</tbody>
</table>
```

2. Forcing a NIM push installation.

After allocating the necessary NIM resources (smitty nim_mac_res), perform the SMIT steps to enable a NIM push installation with a Force option. This operation will update the /etc/niminfo file to the target server.

```bash
# smitty nim_mac_op
   Select the NIM client
   Select “bos_inst = perform a BOS installation”
   Change the “Source for BOS runtimes file” to mksysb;
   “Force Unattended Installation Enablement?” to yes
   “ACCEPT new license agreements?” to yes

See Example 5-51.

Example 5-51   Perform NIM PUSH installation with a Force option

<table>
<thead>
<tr>
<th>Entry Fields</th>
</tr>
</thead>
<tbody>
<tr>
<td>Perform a Network Install</td>
</tr>
</tbody>
</table>
```

Note: In order to perform either action, the target server must be contactable through remote shell, so include the NIM master hostname in the target server's ~/.rhosts file.
Target Name | NODE1
---|---
Source for BOS Runtime Files | mksysb +
installp Flags | [-agX]
Fileset Names |[
Remain NIM client after install? | yes +
Initiate Boot Operation on Client? | yes +
Set Boot List if Boot not Initiated on Client? | no +
Force Unattended Installation Enablement? | yes +
ACCEPT new license agreements? | [yes] +

As an alternative, use the command `smitty nim_bosinst` to perform the BOS installation. Select the target machine, the mksysb, and the SPOT. Set the option FORCE PUSH the installation? to yes, and set the option ACCEPT new license agreements? to yes.

5.6 Using SAN zoning for cloning LPARs

This procedure is useful if you want to deploy and install AIX onto LPARs in a production environment, but do not want to perform a NIM installation over the production network.

In this case, you can deploy the operating system image via NIM on LPARs in a test environment, then simply move the LUNs from the test environment to the production environment and activate the LPARs in the production environment. This can be achieved via SAN zoning and LUN masking, with minimal changes when you activate the LPARs in the production environment.

To move an LPAR from one physical machine to another, when all disks (including rootvg) are available via SAN, the supported methods are:

- Reinstall the LPAR from scratch
- Create an mksysb image from the running LPAR and reinstall it on the target LPAR.

These are also the supported procedures for LPARs running in a Virtual I/O Server (VIOS) environment (even though you can use other means, such as the `dd` command to copy virtual disks between logical volumes in the VIOS).

It is also possible to use SAN zoning to move SAN-based rootvg disks (logical units, or LUs) from one LPAR to another LPAR in another physical machine, assuming both LPARs are connected to the same SAN fabric, and that the operating system level is supported by the destination physical machine.
Both LPARs should be configured with the same type of physical machine, with the same number and type of adapters, and are not restricted to VIOS resources.

The general steps for SAN zoning of an LPAR’s rootvg LUNs are:

1. **Document**
2. **Plan**
3. **Verify**
4. **Execute**

**Document**
Document the LPAR environment, such as (but not limited to) LPAR profiles, HMCs involved, NIM servers, IP addresses, gateways, DNS servers, NTP servers, and LDAP servers.

**Plan**
Decide when the zoning can be implemented, who needs to be involved, the exact steps to verify the SAN, LAN and AIX, and define a rollback plan.

**Verify**
Zone a new rootvg disk to the target LPAR and perform a basic rte installation from NIM to the target LPAR, to make sure all adapters are properly allocated and working with the new IP settings.

**Execute**
Open the SAN zone for the originating LPAR’s SAN disks to the new destination LPAR. Then stop the running LPAR, start the target LPAR, change the IP settings and change the HMC and RSCT settings for the LPAR. After functional verification, remove the originating LPAR from the SAN zone.

**Note:** Depending on your particular changes after a SAN zoning (such as changes to the hostname, node id or IP addresses), consult the IBM product documentation and verify the appropriate command sequence for your specific level of AIX and HMC software. Refer to *Hardware Management Console for pSeries Installation and Operations Guide*, SA38-0590, for more information.

If you change the HMC that manages the physical machine during the SAN zoning, you need also to change the /var/ct/cfg/ctrmc.acls file to allow the target LPAR’s HMC to manage the new LPAR. When moving an LPAR using mksysb cloning, the HMC connections are recreated.
To determine whether you have this case, use the `lsrsrc` command as shown in Example 5-52.

**Example 5-52  Correct output from the lsrsrc IBM.ManagementServer command**

```
root@lpar55:/: lsrsrc IBM.ManagementServer
Resource Persistent Attributes for IBM.ManagementServer
resource 1:
    Name       = "10.1.1.100"
    Hostname   = "10.1.1.100"
    ManagerType = "HMC"
    LocalHostname = "lpar5"
    ClusterTM   = "9078-160"
    ClusterSNum = ""
    ActivePeerDomain = ""
    nodeNameList = {"lpar55"}
```

Also verify the output from the `ctsthl` command on the originating LPAR as shown in Example 5-53. In this case, verify the output from the default cluster security services trusted host list for the node (`/var/ct.cfg/ct_has.thl`).

**Example 5-53  Output from the ctsthl command**

```
root@lpar55:/: ctsthl -l
ctsthl: Contents of trusted host list file:
---------------------
Host Identity: 10.1.1.100
Identifier Generation Method: rsa512
Identifier Value:
1202009bedb21d54f57d2c217f46f3b1352a30317e87dac7cb2d593582159e0cab3bc5a3e211b606e2fd94a05520f0c81d36e333e346bc56781o3d8de8e44327ae3110103
---------------------
Host Identity: loopback
Identifier Generation Method: rsa512
Identifier Value:
120200ca6e9e199d8177b0ede67ec30fb4abaaacb56779decea348bca7aae904485e5f0cc284e2017e3f295a75ac8038b6332477a8f530ff9240a0fa3f5a9e917c0b0103
---------------------
Host Identity: 127.0.0.1
Identifier Generation Method: rsa512
Identifier Value:
120200ca6e9e199d8177b0ede67ec30fb4abaaacb56779decea348bca7aae904485e5f0cc284e2017e3f295a75ac8038b6332477a8f530ff9240a0fa3f5a9e917c0b0103
---------------------
Host Identity: 10.1.1.55
Identifier Generation Method: rsa512
Identifier Value:
120200ca6e9e199d8177b0ede67ec30fb4abaaacb56779decea348bca7aae904485e5f0cc284e2017e3f295a75ac8038b6332477a8f530ff9240a0fa3f5a9e917c0b0103
```

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After moving the LPAR, the new HMC's IP address in our examples is 10.1.2.100. On the LPAR and on the HMC, the respective node identifier is stored in the /etc/ct_node_id file. This identifier is used to grant access from the HMC to the LPAR, specified in the /var/ct/cfg/ctrmc.acls file. The ctrmc.acls file contains a node's resource monitoring and control (RMC) access control list (ACL).

Example 5-54 shows the /etc/ct_node_id file of the current HMC and the destination HMC.

Example 5-54 ct_node_id from HMCs

```
root@lpar55:/: ssh hscroot@10.1.1.100 head -1 /etc/ct_node_id
9bfc2ff2c7b3fb7

root@lpar55:/: ssh hscroot@10.1.2.100 head -1 /etc/ct_node_id
c75d71c5f7b9279a
```

The ctskeygen command is used to update the RMC security files ct_has.pkf (public key file), ct_has.qkf (private key file), ct_has.thl (trusted host list file). Example 5-55 displays the current public key value for the local system.

Example 5-55 Output from the ctskeygen command

```
root@lpar55:/: /usr/sbin/rsct/bin/ctskeygen -d
120200ca6e9e199d8177b0ede67ec30fb4abaaacb56779dece348b7cc7a7ae904485e5f0cc284e0717e3f295a75ac8b038b6332477a8f530ff92400fa3f5a9e917c0b010
```

5.7 System maintenance for NIM clients

Performing proactive system maintenance for NIM clients is important in order to keep systems stable and up-to-date. System maintenance includes installing software fixes or updates, verifying installed software, reviewing installed software and operating system levels, and performing hardware maintenance and diagnostics. You can use NIM to perform all of these maintenance activities in a very fast and efficient way. You can perform maintenance on a single system
or a group of systems, thus reducing the time and effort required to keep your systems updated.

In this section, we discuss the following topics:

- Software maintenance approach
- Creating a mksysb backup of a NIM client
- Performing software maintenance on NIM clients
- Booting a NIM client in maintenance and diagnostic mode

### 5.7.1 Software maintenance approach

Software maintenance is an important task for any AIX or NIM administrator. By “software maintenance”, we mean applying AIX PTFs, APARs, Service Packs, Concluding Service Packs (CSPs) and Technology Levels (TLs) on a NIM client. It is generally a good idea to keep your NIM environment running at the latest and most stable release of AIX code. This will ensure that your systems can exploit the latest features and enhancements for AIX. Develop a maintenance strategy that is most appropriate for your environment. IBM introduced a new service strategy for AIX 5L in early 2006. This strategy offers several maintenance models but the one that will meet the needs of most sites is the “maximum stability” model.

**Maximum stability maintenance model**

The maximum stability maintenance strategy is designed for sites that would like to adopt a new TL every six to eight months and take advantage of the latest group of PTFs available in a Concluding Service Pack. By this we mean that a system that is currently running TL4 would wait for TL5 and its CSP to be released before applying the software. In between TLs, the site could also install Interim Fixes (IFs) to address security and other issues that may be required before the latest TL and CSP is available. For more information, refer to *AIX 5L Service Strategy and Best Practices: AIX 5L Service Scenarios and Tools*, which is available at the following Web site:


**Software maintenance on the NIM master**

Before you can apply maintenance to a NIM client, you must make sure that your NIM master has been updated with the highest level of code. But you must first obtain the software in some form. The latest TLs, SPs and CSPs can be downloaded from the IBM fix central Web site:

http://www.ibm.com/eserver/support/fixes/fcgui.jsp
However, we recommend that you use the Service Update Management Assistant (SUMA) in conjunction with NIM to download and manage the latest fixes. Create a new file system to which SUMA can download the TL and CSP filesets. A new lpp_source should also be created for the new TL/CSP, which initially only contains the base level code. This new lpp_source will be updated with the fixes downloaded via SUMA (for example, Base+TL+CSP).

Create a new SPOT from the new lpp_source and update it each time the lpp_source is updated. Refer to 4.10, “NIM and Service Update Management Assistant” on page 319, for additional information about using NIM and SUMA. For more information about updating software in a NIM environment, refer to 5.1, “Updating the NIM environment (lpp_source, SPOT)” on page 410.

**Using NIM to perform software maintenance on NIM clients**

Prior to applying the latest TL on a NIM client, it is desirable to test the code on a non-critical system. This will allow you to verify the code and refine your installation procedures before applying it to any production system.

The current level of your client can be determined with the `oslevel` command. The `-s` flag shows the current Service Pack level, and the `-r` flag displays the current Technology Level, as shown in Example 5-56.

**Example 5-56   Using the oslevel command**

```
{nimmast}:/ # rsh lpar4 oslevel -r
5300-04
{nimmast}:/ # rsh lpar4 oslevel -s
5300-04-03
```

Always create a mksysb backup of the client before performing any type of software maintenance task. As shown in Example 5-57, you can use NIM to back up the client from the master (or you can use a script that runs on the client to back up to the NIM master).

**Example 5-57   Creating a mksysb of a NIM client from the NIM master**

```
{nimmast}:/ # nim -o define -t mksysb -a server=master -a source=LPAR4 -a mk_image=yes -a location=/export/images/mksysb.lpar4.5303.Fri lpar4-mksysb
+---------------------------------------------------------------------+
<p>| System Backup Image Space Information                               |</p>
<table>
<thead>
<tr>
<th>(Sizes are displayed in 1024-byte blocks.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Required = 1072580 (1047 MB) Available = 1691148 (1652 MB)</td>
</tr>
</tbody>
</table>
+---------------------------------------------------------------------+
```
Data compression will be used by the system backup utilities which create the system backup image. This may reduce the required space by up to 50 percent.

Creating information file (/image.data) for rootvg..

Creating list of files to back up.
Backing up 26669 files.....
26669 of 26669 files (100%)
0512-038 savevg: Backup Completed Successfully.

{nimmast}:/ # lsnim -t mksysb
lpar1nim-mksysb resources mksysb
MK_LPAR6_AIX530403 resources mksysb
MKSYSB_VIO12_53_ML3 resources mksysb
MK_AIX5104 resources mksysb
mksysb_1par5c resources mksysb
mksysb_1par5d resources mksysb
mksysb_vpar1 resources mksysb
MK_VIO1 resources mksysb
VLPAR3_phys_mksysb resources mksysb
MK_MST_53ML4 resources mksysb
VLPAR3_p5_mksysb resources mksysb
MK_MST_15JUIN06 resources mksysb
MKSYSB_VLPAR5_p5 resources mksysb
lpar4-mksysb resources mksysb

{nimmast}:/ # lsnim -l lpar4-mksysb
lpar4-mksysb:
    class       = resources
    type        = mksysb
    arch        = power
    Rstate      = ready for use
    prev_state  = unavailable for use
    location    = /export/images/mksysb.lpar4.5300.Fri
    version     = 5
    release     = 3
    mod         = 0
    oslevel_r   = 5300-03
    alloc_count = 0
    server      = master

You can perform software maintenance tasks on one or more NIM clients concurrently. If you have defined a NIM machine group, you can choose to perform an operation on the machine group and update all the group members (clients) at the same time. Depending on the size and type of your environment,
you may only need to update on a per-client basis, but the flexibility to manage multiple clients exists.

As shown in the following examples, we perform software maintenance on a NIM client via the NIM master. Our task is to apply the latest maintenance to our client. After this is completed our client, which was running AIX 5L V5.3 ML3 (5300-03), will be updated to AIX 5L V5.3 TL4 SP3 (5300-04-03).

We will perform the following tasks:

- Commit any software in an applied state. There may be software in an applied state from a previous maintenance task.
- Apply software via a NIM (cust) update_all operation.
- LPAR4 is the NIM client.
- The lpp_source name is LPP_53_ML4.
- COMMIT software updates? No.
- SAVE replaced file? Yes.
- Accept new license agreements? Yes.
- Verify that the oslevel and instfix commands display the correct TL and SP information. Verify the filesets installed from the NIM master via the NIM lppchk and showlog operation. Also perform a fix_query NIM operation on the NIM client.

We chose not to commit the software updates or save the replaced files. This will allow us to reject a fileset (or filesets) if there are issues after the update. This is called applying software updates. We can choose to commit the updates later, which will remove the saved files from the system.

**Important:** Try to avoid rejecting an entire Technology Level after it has been applied to an AIX 5L V5.3 system. TLs are usually quite large in terms of the number of filesets updated. It is faster and less risky to fall back to the previous level using other methods such as alt_disk_install, multiboot, or a mksysb restore via NIM.

As shown in Example 5-58 on page 483, and because we are applying a new TL, we perform a PREVIEW first in order to review what will actually be installed and to check for any missing prerequisites. In most cases when applying a new TL, you will be asked to update the bos.rte.install fileset first. All other filesets are deferred until it is updated. After it is updated, you will be able to apply the remaining filesets.
Also, ensure that you have taken a backup of any other data volume groups (non-rootvg volume groups). We recommend that all your applications be shut down and all users logged off the system before you apply any AIX operating system maintenance. Also check the AIX error report before and after to see whether there are any issues (hardware or otherwise) with the system.

It may also be worth cleaning up your old SMIT log files beforehand. This will make reviewing the logs much less confusing after the maintenance has been applied; see Example 5-58.

**Example 5-58   bos.rte.install must be updated first when applying a TL**

```
{nimmast}:/# smit nim_task_maint
Commit Applied Software Updates (Remove Saved Files)
LPAR4       machines       standalone

        Commit Applied Software Updates (Remove Saved Files)

        * Target                                              LPAR4
        * Software Names                                       [all] +
                  Force                                           no +
                  PREVIEW only?                                  [no] +
                  COMMIT requisites?                            [yes] +

{nimmast}:/# smit nim_task_inst

Update Installed Software to Latest Level (Update All)
LPAR4       machines       standalone
LPP_53_ML4   resources       lpp_source

Update Installed Software to Latest Level (Update All)

        * Installation Target                                 LPAR4
        * LPP_SOURCE                                           LPP_53_ML4
        Software to Install                                    update_all

        Customization SCRIPT to run after installation       [] +
                  (not applicable to SPOTs)

        Force                                                 no +

installp Flags
        PREVIEW only?                                      [yes] +
        COMMIT software updates?                          [no] +
        SAVE replaced files?                               [yes] +
        AUTOMATICALLY install requisite software?           [yes] +
        EXTEND filesystems if space needed?                [yes] +
```
OVERWRITE same or newer versions? [no] +
VERIFY install and check file sizes? [no] +
ACCEPT new license agreements? [yes] +

(AIX V5 and higher machines and resources)
Preview new LICENSE agreements? [no] +

Group controls (only valid for group targets):
Number of concurrent operations []
Time limit (hours) []

Schedule a Job [no] +
YEAR [] #
MONTH [] +#
DAY (1-31) [] +#
HOUR (0-23) [] +#
MINUTES (0-59) [] +#

COMMAND STATUS
Command: OK stdout: yes stderr: no

Before command completion, additional instructions may appear below.

[TOP]

*******************************************************************************
installp PREVIEW: installation will not actually occur.
*******************************************************************************

+-----------------------------------------------------------------------------+
Pre-installation Verification...
+-----------------------------------------------------------------------------+
Verifying selections...done
Verifying requisites...done
Results...

SUCCESSES
Filesets listed in this section passed pre-installation verification and will be installed.

Mandatory Fileset Updates
(being installed automatically due to their importance)
bos.rte.install 5.2.0.41  # LPP Install Commands

<< End of Success Section >>
FILESET STATISTICS
------------------
41  Selected to be installed, of which:
    1  Passed pre-installation verification
    40  Deferred (see *NOTE below)
----
1  Total to be installed

After bos.rte.install is updated, we are able to apply TL4 to our NIM client, LPAR4, as shown in Example 5-59.

Example 5-59  Applying a TL on a NIM client
{nimmast}:/ # smit nim_task_inst
Update Installed Software to Latest Level (Update All)
  LPAR4  machines  standalone
  LPP_53_ML4  resources  lpp_source

Update Installed Software to Latest Level (Update All)

  * Installation Target  LPAR4
  * LPP_SOURCE  LPP_53_ML4
  Software to Install  update_all

  Customization SCRIPT to run after installation  [] +
  (not applicable to SPOTs)

  Force  no +

  installp Flags
    PREVIEW only?  [no] +
    COMMIT software updates?  [no] +
    SAVE replaced files?  [yes] +
    AUTOMATICALLY install requisite software?  [yes] +
    EXTEND filesystems if space needed?  [yes] +
    OVERWRITE same or newer versions?  [no] +
    VERIFY install and check file sizes?  [no] +
    ACCEPT new license agreements?  [yes] +
    (AIX V5 and higher machines and resources)
    Preview new LICENSE agreements?  [no] +

  Group controls (only valid for group targets):
    Number of concurrent operations  [] #
    Time limit (hours)  [] #

  Schedule a Job  [no] +
  YEAR  [] #
We verify the installed filesets by running an lppchk operation on the NIM client from the NIM master. We also review the installp log with the showlog operation; see Example 5-60.

Example 5-60  Running an lppchk and showlog operation after the TL is applied

{nimmast}:/# nim -o lppchk -a lppchk_flags="-c -m3" LPAR4
/usr/bin/lppchk: 0504-230  8367 files have been checked.
/usr/bin/lppchk: 0504-230  13186 files have been checked.
/usr/bin/lppchk: 0504-230  14798 files have been checked.
/usr/bin/lppchk: 0504-230  561 files have been checked.
/usr/bin/lppchk: 0504-230  377 files have been checked.

{nimmast}:/# nim -o showlog -a log_type=niminst LPAR4
Command line is:
/usr/sbin/installp -acgXY -e /var/adm/ras/nim.installp -f /
/tmp/genlib.installp.list.548880-d /tmp/_nim_dir_557166/mnt0
+-----------------------------------------------------------------------------+
Pre-installation Verification...
+-----------------------------------------------------------------------------+
done

SUCCESSES

Filesets listed in this section passed pre-installation verification and will be installed.

Selected Filesets

Java14.sdk 1.4.2.75
X11.adt.include 5.3.0.50
X11.apps.aixterm 5.3.0.50
X11.apps.config 5.3.0.50
X11.apps.xdm 5.3.0.50
X11.base.lib 5.3.0.50
X11.base.rte 5.3.0.50
bos.rte.libpthreads 5.3.0.50
bos.rte.serv_aid 5.3.0.50
rsct.core.utils 2.4.5.2

# Java SDK 32-bit
# AIXwindows Application Devel...
# AIXwindows aixterm Application
# AIXwindows Configuration App...
# AIXwindows xdm Application
# AIXwindows Runtime Libraries
# AIXwindows Runtime Environment

USR   COMMIT   SUCCESS
USR   COMMIT   SUCCESS
ROOT  COMMIT   SUCCESS
USR   COMMIT   SUCCESS
ROOT  COMMIT   SUCCESS
installp:  * * *  A T T E N T I O N ! ! !
Software changes processed during this session require this system and any of its diskless/dataless clients to be rebooted in order for the changes to be made effective.

END:Tue Jul  4 22:08:05 2006

Using rsh from the NIM master, we run the oslevel and instfix commands on the NIM client to verify that the correct AIX level is shown and that all filesets have been updated correctly. We then run a fix_query operation from the master, which is the same as running the instfix command on the client, as shown in Example 5-61.

Example 5-61  oslevel, instfix commands and fix_query operation

```
{nimmast}:/ # rsh lpar4 instfix -icqk 5300-04_AIX_ML | grep ":-:"
{nimmast}:/ # rsh lpar4 instfix | grep AIX
    All filesets for 5300-02_AIX_ML were found.
    All filesets for 5.3.0.0_AIX_ML were found.
    All filesets for 5300-01_AIX_ML were found.
    All filesets for 5300-03_AIX_ML were found.
    All filesets for 5300-04_AIX_ML were found.
{nimmast}:/ # rsh lpar4 oslevel -r
5300-04
{nimmast}:/ # rsh lpar4 oslevel -s
5300-04-03
{nimmast}:/ # nim -o fix_query LPAR4 | grep AIX
    All filesets for 5300-02_AIX_ML were found.
    All filesets for 5.3.0.0_AIX_ML were found.
    All filesets for 5300-01_AIX_ML were found.
    All filesets for 5300-03_AIX_ML were found.
    All filesets for 5300-04_AIX_ML were found.
```

In Example 5-62 on page 488, we perform software maintenance on a NIM machine group. We install the bos.alt_disk_install filesets on all members of the group NIM_MAC_GRP_1.
Example 5-62  Performing software maintenance on a NIM machine group

{nimmast}:/ # lsnim -t mac_group
LPAR123456  groups       mac_group
nimgrp      groups       mac_group
NIM_MAC_GRP_1 groups       mac_group

{nimmast}:/ # lsnim -l NIM_MAC_GRP_1
NIM_MAC_GRP_1:
class    = groups
type     = mac_group
comments = NIM Machine Group One.
member1  = LPAR4
member2  = LPAR5

{nimmast}:/ # smit nim_task_inst
Install and Update from ALL Available Software
NIM_MAC_GRP_1 groups          mac_group
LPP_53_ML4 resources       lpp_source

Install and Update from ALL Available Software

* Installation Target                NIM_MAC_GRP_1
* LPP_SOURCE                          LPP_53_ML4
* Software to Install                [bos.alt_disk_install] +

Customization SCRIPT to run after installation  [] +
(not applicable to SPOTs)

Force                    no +

installp Flags
PREVIEW only?            [no] +
COMMIT software updates? [yes] +
SAVE replaced files?     [no] +
AUTOMATICALLY install requisite software? [yes] +
EXTEND filesystems if space needed?  [yes] +
OVERWRITE same or newer versions?  [no] +
VERIFY install and check file sizes? [no] +
ACCEPT new license agreements?
   (AIX V5 and higher machines and resources) [no] +
Preview new LICENSE agreements?

Group controls (only valid for group targets):
   Number of concurrent operations  [] #
   Time limit (hours)               [] #
   Schedule a Job                   [no] +
   YEAR                              [] #
   MONTH                             [] +#
Before command completion, additional instructions may appear below.

+-----------------------------------------------------------------------------+
| Initiating "cust" Operation                                                  |
+-----------------------------------------------------------------------------+
Allocating resources ...

Initiating the cust operation on machine 1 of 2: LPAR4 ...

Initiating the cust operation on machine 2 of 2: LPAR5 ...

+-----------------------------------------------------------------------------+
| "cust" Operation Summary                                                     |
| Target                  Result                 |
| -------                -------                 |
| LPAR4                   INITIATED          |
| LPAR5                   INITIATED          |

Note: Use the lsnim command to monitor progress of "INITIATED" targets by viewing their NIM database definition.

Operations performed on machine groups are by default performed asynchronously on members of the group, as shown in Example 5-62 on page 488. NIM does not wait for an operation to complete on one group member before initiating the operation on the next member.

When performing operations asynchronously, it is not possible for NIM to display all the output as it occurs on each client. Therefore, use the lsnim command to check the states of the group members to determine how far, and how successfully, the operations have executed (see Example 5-64 on page 491).

If errors do occur, you can view the log files on client machines by using the NIM showlog operation. To change the behavior of NIM group operations from asynchronous to synchronous, use the async=no attribute when running the nim command.
The number of machines permitted in a machine group is not explicitly limited by NIM. However, the following factors limit the number for practical reasons:

▶ The operation being performed

Operations that are not resource-intensive (such as the `maint` or `showlog` operations) may be performed on a group containing any number of machines. Operations that are resource-intensive (such as `cust` or `bos_inst`) are limited by the throughput of the network, the disk access throughput of the installation servers, and the platform type of servers.

▶ NFS export limitations

The maximum number of hosts to which a file or directory may be exported with root permissions is limited by NFS to 256. Also, the length of a line in an exports file has an upper limit, which could determine the maximum number of machines permitted in a group.

For information about how to increase the number of machines to which a resource can be allocated, refer to “Exporting NIM resources globally” in AIX 5L V5.3 Installation and Migration, SC23-4887.

**Example 5-63  Displaying the installation log for a NIM machine group**

```
{nimmast}:/ # smit nim_grp_op
NIM_MAC_GRP_1 groups mac_group
showlog = display a log in the NIM environment

Display Installation Log

* Target Name                                         NIM_MAC_GRP_1
  Log Type                                           [niminst] +
  Only Show Last Entry in Log?                        yes +

COMMAND STATUS

Command: OK                      stdout: yes           stderr: no

Before command completion, additional instructions may appear below.

[TOP]
+-------------------------------------------------------------+
| Performing "showlog" Operation                             |
+-------------------------------------------------------------+
| Performing showlog operation on machine 1 of 2: LPAR4 ...   |

BEGIN:Fri Jun 16 15:02:48 2006:061613024806
Command line is:
/usr/sbin/installp -acNgX -e /var/adm/ras/nim.installp -f \
/tmp/.genlib.installp.list.323610-d /tmp/_nim_dir_307446/mnt0
```
Pre-installation Verification...

---

Filesets listed in this section passed pre-installation verification and will be installed.

Selected Filesets

bos.alt_disk_install.boot_images 5.3.0.30 # Alternate Disk Installation ...
bos.alt_disk_install.boot_images 5.3.0.40 # Alternate Disk Installation ...
bos.alt_disk_install.rte 5.3.0.30 # Alternate Disk Installation ...
bos.alt_disk_install.rte 5.3.0.40 # Alternate Disk Installation ...

<< End of Success Section >>

FILESET STATISTICS

4 Selected to be installed, of which:
4 Passed pre-installation verification

---

If there are any issues with a software maintenance task, you will see that the Cstate and prev_state information will reflect the status of the operations that are running or have run. In Example 5-64 we can see that the prev_state for LPAR4 was lppchk operation being performed and the prev_state for LPAR5 was customization is being performed. Their current state is ready for a NIM operation, so no problems were encountered in any of the previous NIM operations on these clients.

Example 5-64 Displaying NIM client Cstate and prev_state information

{nimmast}:/ # lsnim -1 LPAR4 LPAR5

LPAR4:
  class = machines
  type = standalone
  connect = shell
  platform = chrp
  netboot_kernel = mp
  if1 = NET_EN1 lpar4 0
  cable_type1 = tp
  Cstate = ready for a NIM operation
  prev_state = lppchk operation is being performed
  Mstate = currently running
  cpuid = 001A85D24C00
Cstate_result = success
current_master = nimmast
sync_required = yes

LPAR5:
class = machines
type = standalone
connect = shell
platform = chrp
netboot_kernel = mp
if1 = NET_EN1 LPAR5 0
cable_type1 = N/A
Cstate = ready for a NIM operation
prev_state = customization is being performed
Mstate = currently running
cpuid = 00CC544E4C00
Cstate_result = success

The output from the installp process is also logged on the NIM client to /var/adm/ras/nim.installp.

You can also perform other software maintenance-related tasks with NIM (via SMIT), as shown in Example 5-65.

Example 5-65 NIM software maintenance tasks

{nimmast}:/ # smit nim_task_maint
   Software Maintenance and Utilities

   Commit Applied Software Updates (Remove Saved Files)
   Reject Applied Software Updates (Use Previous Version)
   Remove Installed Software
   Copy Software to Hard Disk for Future Installation
   Add Software to an lpp_source
   Remove Software from an lpp_source
   Eliminate Unnecessary Software Images in an lpp_source
   Check Software File Sizes After Installation
   Verify Software Installation and Requisites
   Clean Up After Failed or Interrupted Installation

For example, you can list installed software, checking for installed fixes and committing applied filesets.

Example 5-66 NIM software listing and related tasks

{nimmast}:/ # smit nim_task_maint
The **nim** command can also be used from the NIM master to perform several software maintenance tasks:

- **Querying installed software** (**lslpp**) on a client (or clients) and a machine group:
  
  ```
  {nimmast}:/ # nim -o lslpp LPAR4
  {nimmast}:/ # nim -o lslpp LPAR4 LPAR5
  {nimmast}:/ # nim -o lslpp NIM_MAC_GRP_1
  ```

- **Querying installed fixes** on a client:
  
  ```
  {nimmast}:/ # nim -o fix_query LPAR4 | grep AIX
  ```

- **Previewing the installation** of the **bos.alt_disk_install** filesets on a NIM client:
  
  ```
  {nimmast}:/ # nim -o cust -a lpp_source=LPP_53_ML4 -a 
  installp_flags="-pacgXY" -a filesets=bos.alt_disk_install LPAR4
  ```

- **Performing an installation** of the **bos.alt_disk_install** filesets on a NIM client:
  
  ```
  {nimmast}:/ # nim -o cust -a lpp_source=LPP_53_ML4 -a 
  installp_flags="-acgXY" -a filesets=bos.alt_disk_install LPAR4
  ```

- **Previewing the removal** of the **bos.alt_disk_install** filesets on a NIM client:
  
  ```
  {nimmast}:/ # nim -o cust -a lpp_source=LPP_53_ML4 -a 
  installp_flags="-pug" -a filesets=bos.alt_disk_install LPAR4
  ```

- **Performing a removal** of the **bos.alt_disk_install** filesets on a NIM client:
  
  ```
  {nimmast}:/ # nim -o cust -a lpp_source=LPP_53_ML4 -a 
  installp_flags="-ug" -a filesets=bos.alt_disk_install LPAR4
  ```

- **Displaying the installp log** for a NIM client:
  
  ```
  {nimmast}:/ # nim -o showlog -a log_type=niminst LPAR4
  ```

- **Previewing an update_all** on a NIM client:
  
  ```
  {nimmast}:/ # nim -o cust -a lpp_source=LPP_53_ML4 -a 
  installp_flags="-pacgXY" -a fixes=update_all LPAR4
  ```

- **Performing an update_all** on a NIM client (installing the **bos.rte.install** fileset first):
  
  ```
  {nimmast}:/ # nim -o cust -a lpp_source=LPP_53_ML4 -a 
  installp_flags="-acgXY" -a filesets=bos.rte.install LPAR4
  ```
Performing an update_all on a NIM machine group, as shown in Example 5-67:

```
{nimmast}:/ # nim -o cust -a lpp_source=LPP_53_ML4 -a \nfixes=update_all LPAR4
```

Example 5-67   Performing an update_all on a NIM machine group

```
{nimmast}:/ # nim -o cust -a lpp_source=LPP_53_ML4 -a fixes=update_all
NIM_MAC_GRP_1
+-----------------------------------------------------------------------------+
Initiating "cust" Operation
+-----------------------------------------------------------------------------+
Allocating resources ...
Initiating the cust operation on machine 1 of 2: LPAR4 ...
Initiating the cust operation on machine 2 of 2: LPAR5 ...
+-----------------------------------------------------------------------------+
"cust" Operation Summary
+-----------------------------------------------------------------------------+
Target                  Result
-----                  ------
LPAR4                   INITIATED
LPAR5                   INITIATED
```

**Note:** Use the `lsnim` command to monitor progress of INITIATED targets by viewing their NIM database definition.

Performing an installation of filesets and RPMs on a NIM client:

In Example 5-68, we install the OpenSSH and OpenSSL software. Note that both software packages are located in our `lpp_source` directory. However, the RPMs (OpenSSL) are located in the RPMS/ppc directory.

The `geninstall` command will find and install the RPMs from that location. The OpenSSH filesets are located in `installp/ppc`.

```
Example 5-68   Installing the OpenSSH and OpenSSL software
{nimmast}:/ #nim -o cust -a lpp_source=lpp5305 -a installp_flags=agXY -a \nfilesets="openssl-0.9.7d-2 openssh.base" LPAR4
```

Validating RPM package selections ...
openssl

Pre-installation Verification...

Verifying selections...done
Verifying requisites...done
Results...

SUCCESSES

Filesets listed in this section passed pre-installation verification and will be installed.

Selected Filesets

openssh.base.client 4.1.0.5301  # Open Secure Shell Commands
openssh.base.server 4.1.0.5301  # Open Secure Shell Server

<< End of Success Section >>

FILESET STATISTICS

2  Selected to be installed, of which:
   2  Passed pre-installation verification
----
   2  Total to be installed

Installing Software...

installp: APPLYING software for:
   openssh.base.client 4.1.0.5301
   openssh.base.server 4.1.0.5301

Installation Summary

<table>
<thead>
<tr>
<th>Name</th>
<th>Level</th>
<th>Part</th>
<th>Event</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>openssh.base.client</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>openssh.base.server</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

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Tip: It is possible to install RPMs using FTP via the NIM master. For example, the following command will download the openssl rpm from the NIM master and install it on lpar4.

```
{lpar4}:/# rpm -i ftp://root@nimmast/AIX53ML4/LPP_53_ML4/RPMS/ppc/
openssl-0.9.7g-1.aix5.1.ppc.rpm
Password for root@nimmast:
{lpar4}:/# rpm -qa
cdrecord-1.9-4
mkisofs-1.13-4
AIX-rpm-5.2.0.50-1
openssl-0.9.7g-1
{lpar4}:/#
```

Client-initiated software maintenance tasks ("pull")
There are several NIM operations related to software maintenance that the client can initiate via the nimclient command. Note that the client can perform operations upon itself only.

- Listing all available resources for the client:
  ```bash
  {lpar4}:/# nimclient -l -L LPAR4
  ```

- Allocating an lpp_source to the client:
  ```bash
  {lpar4}:/# nimclient -o allocate -a lpp_source=lpp5305
  ```

- Deallocate a resource from the client:
  ```bash
  {lpar4}:/# nimclient -o deallocate -a lpp_source=lpp5305
  ```

- Show allocated resources for the client:
  ```bash
  {lpar4}:/# nimclient -l -c resources LPAR4
  lpp5305 lpp_source
  ```

- Starting a BOS installation from the client (lpp_source and SPOT allocated first; accept_licenses set to yes):
  ```bash
  {lpar4}:/# nimclient -o allocate -a lpp_source=LPP_53_ML4 -a spot=SPOT_53_ML4
  {lpar4}:/# nimclient -o bos_inst -a accept_licenses=yes
  ```

  Broadcast message from root@lpar4 (tty) at 10:21:57 ...
NIM has initiated a bos installation operation on this machine. Automatic reboot and reinstallation will follow shortly...

Performing an update_all (cust) operation from the client:

```
{lpar4}:/ # nimclient -o cust -a lpp_source=lpp5305 -a fixes=update_all
Command line is:
/usr/sbin/installp -agQX -e /var/adm/ras/nim.installp -f /
/tmp/.genlib.installp.list.270544-d /tmp/_nim_dir_327922/mnt0
Pre-installation Verification...
Output removed.
```

Resetting the NIM client state:

```
{LPAR5}:/ # nimclient -Fo reset
```

Setting the date and time to that of the NIM master:

```
{LPAR5}:/ # nimclient -d
```

### 5.7.2 Booting in maint_boot and diag modes

This section provides information about booting a NIM client in maintenance mode. If you need to perform maintenance on a NIM client, you can enter maintenance mode directly by enabling the `maint_boot` operation for a NIM standalone machine.

**Booting in maintenance mode**

Follow this procedure to initiate the maint_boot operation from the NIM master; see Example 5-69:

#### Example 5-69  Enabling maintenance boot for a NIM client

```
{nimmast}:/ # smit nim_mac_op
LPARS machines standalone
maint_boot = enable a machine to boot in maintenance mode
```

Enable Maintenance Boot

Type or select values in entry fields.
Press Enter AFTER making all desired changes.
1. Enter the smit nim_mac_op fast path.
2. Select the client’s machine object.
3. Select the `maint_boot` operation.
4. Select the SPOT to be used for the operation.
5. Press Enter to enable the client for maintenance boot.
6. Verify the NIM client state is now set to maintenance boot has been enabled.
7. Network-boot the client. It will boot from the SPOT in maintenance mode.
8. You are presented with a menu for performing various maintenance activities, as shown in Example 5-70.

In our scenario, we access a root volume group. This is useful if you are troubleshooting a system that does not boot normally (for example, because of file system or JFS log corruption).

9. We are presented with a maintenance shell.
10. When we are finished, we can halt the machine and restart it.
11. We reset the NIM client. Its Cstate (as shown in Example 5-71 on page 500) is now set to: ready for a NIM operation.
Type the number of your choice and press Enter.

>>> 1 Access a Root Volume Group
  2 Copy a System Dump to Removable Media
  3 Access Advanced Maintenance Functions
  4 Erase Disks

88  Help ?
99  Previous Menu

>>> Choice [1]:

Warning:

If you choose to access a root volume group, you will NOT be able to return to
the Base Operating System Installation menus without rebooting.

Type the number of your choice and press Enter.

0 Continue

88  Help ?
>>> 99  Previous Menu

>>> Choice [99]:0

Access a Root Volume Group
Type the number for a volume group to display the logical volume information
and press Enter.

1)Volume Group 00cc544e00004c0000000010bcc5a1e11 contains these disks:
   hdisk0  10240   vscsi

Choice:1

Volume Group Information

Volume Group ID 00cc544e00004c0000000010bcc5a1e11 includes the following
logical volumes:

hd5 hd6 hd8 hd4 hd2 hd9var hd3 hd1 hd10opt

Type the number of your choice and press Enter.

1) Access this Volume Group and start a shell
2) Access this Volume Group and start a shell before mounting filesystems

99) Previous Menu

Choice [99]: 1

Importing Volume Group...

rootvg

Checking the / filesystem.

log redo processing for /dev/rhd4
syncpt record at 114d1ac
end of log 117924c
syncpt record at 114d1ac
syncpt address 114ba2c
number of log records = 1551
number of do blocks = 94
number of nodo blocks = 3
/dev/rhd4 (/): ** Unmounted cleanly - Check suppressed

Checking the /usr filesystem.

/dev/rhd2 (/usr): ** Unmounted cleanly - Check suppressed

Saving special files and device configuration information.
Checking and mounting the /tmp filesystem.

/dev/rhd3 (/tmp): ** Unmounted cleanly - Check suppressed

Checking and mounting the /var filesystem.

/dev/rhd9var (/var): ** Unmounted cleanly - Check suppressed

Filesystems mounted for maintenance work.

#

Resetting the NIM client after a maintenance boot is shown in Example 5-71.

**Example 5-71 Resetting a NIM client after a maintenance boot**

{nimmast}:/> # smit nim_mac_op

LPAR5      machines       standalone
reset       = reset an object's NIM state
Reset the NIM State of a Machine

Target Name: LPAR5
Deallocation All Resources? yes +
(replaces all root data for diskless/dataless clients)
Force: yes +

{nimmast}:/ # lsnim -l LPAR5
LPAR5:
class = machines
type = standalone
connect = shell
platform = chrp
netboot_kernel = mp
if1 = NET_EN1 LPAR5 0
cable_type1 = N/A
\textit{Cstate} = \textit{ready for a NIM operation}
prev_state = maintenance boot has been enabled
Mstate = currently running
\textit{Cstate\_result} = reset

It is also possible for the client to configure itself for a maintenance mode boot:

{LPAR5}:/ # nimclient -o maint\_boot -a spot=SPOT\_53\_ML4

\textbf{Performing boot diagnostics on NIM clients}

This section provides information about performing hardware diagnostics on a NIM client. Hardware diagnostics can be performed on all NIM clients using a diagnostic boot image from the NIM master, rather than booting from a diagnostic tape or CD-ROM. This is useful for standalone clients because the diagnostics do not have to be installed on the local disk. Diagnostic support comes from a SPOT resource.

Follow these steps to initiate the \texttt{diag} operation from the master:

1. Enter the \texttt{smit nim\_mac\_op} fastpath as shown in Example 5-72 on page 502.
2. Select the machine object.
3. Select the \texttt{diag} operation from the list of operations.
4. Verify that the NIM client state is now set to: diagnostic boot has been enabled.
5. Network-boot the client in service mode. It will boot from the SPOT in diagnostic mode, as shown in Example 5-73 on page 502.
6. The diagnostic menu appears. Various hardware diagnostic activities can be performed.

7. When finished, halt the machine and restart it.

8. Reset the NIM client. Its Cstate is now set to: ready for a NIM operation; see Example 5-71 on page 500.

Example 5-72  Enabling diagnostics boot for a NIM client

```
{nimmast}:/ # smit nim_mac_op
LPAR5     machines       standalone
diag             = enable a machine to boot a diagnostic image

Enable Diagnostic Boot

Target Name                                         LPAR5
* SPOT                                               

{nimmast}:/ # lsnim -l LPAR5
LPAR5:                                               
class          = machines                          LPAR5
  type           = standalone                        [SPOT_53_ML4]
cconnect        = shell                             
cplatform       = chrp                              
cnetboot_kernel = mp                                
if1            = NET_EN1 LPAR5 0                   
cable_type1    = N/A                                
Cstate         = diagnostic boot has been enabled    
prev_state     = ready for a NIM operation
Mstate         = currently running                   
boot           = boot                                
spot           = SPOT_53_ML4                         
control        = master                             
Cstate_result  = reset                             
```

You will be prompted to define the system console when booting in diagnostic mode.

Example 5-73  Booting the client in diag mode

```
******* Please define the System Console. *******

Type a 1 and press Enter to use this terminal as the system console.
Pour definir ce terminal comme console systeme, appuyez sur 1 puis sur Entree.
Taste 1 und anschliessend die Eingabetaste druecken, um diese Datenstation als Systemkonsole zu verwenden.
```
Starting errdemon
Starting Diagnostics

DIAGNOSTIC OPERATING INSTRUCTIONS VERSION 5.3.0.40

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These programs contain diagnostics, service aids, and tasks for
the system. These procedures should be used whenever problems
with the system occur which have not been corrected by any
software application procedures available.

In general, the procedures will run automatically. However,
sometimes you will be required to select options, inform the
system when to continue, and do simple tasks.

Several keys are used to control the procedures:
- The Enter key continues the procedure or performs an action.
- The Backspace key allows keying errors to be corrected.
- The cursor keys are used to select an option.

To continue, press Enter.

FUNCTION SELECTION

1 Diagnostic Routines
   This selection will test the machine hardware. Wrap plugs and
   other advanced functions will not be used.
2 Advanced Diagnostics Routines
   This selection will test the machine hardware. Wrap plugs and
   other advanced functions will be used.
3 Task Selection (Diagnostics, Advanced Diagnostics, Service Aids, etc.)
   This selection will list the tasks supported by these procedures.
   Once a task is selected, a resource menu may be presented showing
   all resources supported by the task.
4 Resource Selection

This selection will list the resources in the system that are supported by these procedures. Once a resource is selected, a task menu will be presented showing all tasks that can be run on the resource(s).

99 Exit Diagnostics

NOTE: The terminal is not properly initialized. You will be prompted to initialize the terminal after selecting one of the above options.

To make a selection, type the number and press Enter. [1]

To make a selection, type the number and press Enter. [99]

SHUTDOWN

A system shutdown is about to occur.

Type 99 again and press <Enter> to continue the shutdown process.
--or--
Press the <Enter> key to abort the shutdown and return to Diagnostics.

99
....Halt completed....

It is also possible for the client to configure itself for a diagnostic boot:

{LPAR5}:/# nimclient -o diag -a spot=SPOT_53_ML4

5.8 Automatic scripts

This section describes how to use automatic scripts to perform system customization after a Basic Operating System (BOS) mksysb installation.

It covers the following topics:

- Customizing using a NIM script resource
- Customizing using a NIM bosinst_data resource
- Customizing using a NIM fb_script resource
5.8.1 Install time customization

When installing an AIX LPAR or physical machine, with either a Basic Operating System (BOS) installation or a mksysb image file, there are several ways to provide installation time customization.

Customization for BOS installations (NIM bos_inst operations using source=rte or source=spot), can be performed in one or more of the following ways:

- Using NIM script resources to provide command line and script customization - during installation and NIM cust operations
- Using NIM bosinst_data resources to provide command line and script customization - during installation
- Using SPOT modified /usr file system files - during installation
- Using installable filesets and scripts customization - any time after the first boot
- Using automated remote commands (rsh/ssh) from scripts run from another system - any time after the first boot
- Using manually executed commands - any time after the first boot
- Using a NIM fb_script resource script to be executed - at the end of the first boot

Customization of mksysb installations (NIM mksysb), in addition to the BOS installation described here, can also be performed in the following way:

- Modifying files on the source system before creating a NIM mksysb image file
- In the following sections, we explain these topics in greater detail.

5.8.2 Customization for BOS installations

Here we describe how to create and use:

- NIM script resources
- NIM bosinst_data CUSTOMIZATION_FILE attribute script
- NIM fb_script resource

Creating installable filesets and customization scripts is described in 4.12, “Creating bundles, BFF, and RPM packages” on page 354. To run remote commands from another node, such as the NIM master, you can use commands such as rsh or ssh.
Using NIM script resources
A NIM script resource represents a file that is an user-created shell script that can be allocated to a NIM machine, after it is defined.

The NIM script resources are always run by NIM after software installation are performed during bos_inst operations, or during cust operations. Multiple script resources can be allocated to be executed, but the order in which the scripts will be run is unpredictable.

Use the NIM script resources in this sequence:
1. Create a shell script.
2. Define the NIM script resource pointing to the shell script.
3. Allocate the NIM script resource for a cust or bos_inst operation to one or more NIM clients or NIM groups.
4. Execute the cust or bos_inst operation on one or more NIM clients or NIM groups.

Example 5-74 shows a simple shell script that performs some customization on a NIM client. First it acquires the /etc/motd file from the NIM master, then it customizes the login herald, sets the time zone, and specifies the resolve order for hostname and IP-address.

Example 5-74  Example NIM script, node_cust, for cust of bos_inst operation

```bash
#!/bin/ksh
# node_cust
# Synopsis........%M%
# Author..........User01
# Created.........2006
# Version.........%Z% %M% %I% (%E% %U%) %Q%
# Description.....N/A
# Input...........N/A
# Output.........Perform Node Customization.
# Algorithm.......N/A
#----------------------------------------------------------------------
#
# Redirect STDOUT and STDERR to a logfile
#
exe 1>/tmp/${0##*/}.log
exe 2>&1
#
# Acquiring the /etc/motd file from the NIM master...
#
if [[ "$NIM_SHELL" = "shell" ]];then
   if [[ "$NIM_MASTER_HOSTNAME" != "" ]];then
      ping -c 1 -w 1 $NIM_MASTER_HOSTNAME >dev/null 2>&1
   if [[ $? -eq 0 ]];then
```

506  NIM from A to Z in AIX 5L
In our case, we check the script for syntax errors by running it without execution. The script name in our examples is node_cust:

```
ksh -xvn node_cust
```

After this step completes successfully, run the script manually on a test system to verify that it works as desired. After verifying that the script works properly, it can be defined as a NIM script resource as shown in Example 5-75. In this case, we use the /export/scripts directory.

**Example 5-75 Creating a NIM script resource**

```
root@master:/: nim -o define -t script -a server=master
-a location=/export/scripts/node_cust node_cust

root@master:/: lsnim -l node_cust
node_cust:
    class       = resources
    type        = script
    Rstate      = ready for use
    prev_state  = unavailable for use
    location    = /export/scripts/node_cust
```
alloc_count = 0
server      = master

Now, when the NIM script has been defined, you can use the nim command to view the content of the script file itself:

    nim -o showres node_cust

The node_cust NIM script resource is now ready for use, and can be allocated and executed during cust or bos_inst operations. You can allocate the script to a NIM standalone machine or NIM group as shown in Example 5-76. In this case, the NIM machine is LPAR55.

**Example 5-76  Allocate a NIM script to a NIM standalone machine or NIM group**

    root@master:/: nim -o allocate -a script=node_cust LPAR55

To execute the script on a running NIM client, use the cust operation as shown in Example 5-77.

**Example 5-77  Run a NIM script on a running NIM client or NIM group**

    root@master:/: nim -o cust LPAR55

```
+-----------------------------------------------------------------------------+
| Initiating "cust" Operation                                                  |
+-----------------------------------------------------------------------------+
Allocating resources ...

Initiating the cust operation on machine 1 of 1: LPAR55 ...

+-----------------------------------------------------------------------------+
| "cust" Operation Summary                                                    |
+-----------------------------------------------------------------------------+
| Target                  Result                                      |
|------                  ------                                      |
| LPAR55                  INITIATED                                  |
```

Note: Use the lsnim command to monitor progress of "INITIATED" targets by viewing their NIM database definition.

Each NIM script will be run with the name script on the NIM client, after being copied to a separate and temporary directory in the /tmp file system. Thus our debug output redirection, in the beginning of the script, will create a log file in the /tmp directory named “script.log”.

    exec 1>/tmp/${0##*/}.log
    exec 2>&1
To monitor the progress of the NIM cust operation, use the `lsnim` command:

```
lsnim -l <NIM machine name>
```

In our case, the command is:

```
lsnim -l LPAR55
```

When the installation (bos_inst) or customization (cust) is finished, the actions specified in the NIM script customization script have been performed. In the even of problems, check the output of the NIM script execution, as shown in Example 5-78.

**Example 5-78  Debug output of NIM script execution during cust operation**

```
+ [[ shell = shell ]]
+ [[ nimmast != ]] 
+ ping -c 1 -w 1 nimmast 1> /dev/null 2>& 1
+ [[ 0 -eq 0 ]]
+ date +%j
+ cp /etc/motd /etc/motd~172
+ rcp nimmast:/etc/motd /etc
+ /usr/bin/chsec -f /etc/security/login.cfg -s default -a herald="This computer is the property of Our Company. Unauthorized access is prohibited. If you are not authorized to have access to this computer, leave now. All sessions on this computer can and may be monitored."
+ /usr/bin/chtz UTC-1UTC-2,M3.5.0/02:00:00,M10.5.0/03:00:00
+ echo NSORDER=local,bind >> /etc/environment
```

**Note:** The script resources must not point to files that reside in the `/export/nim/scripts` directory. This directory is used for the `nim_script` resource that is managed by NIM. NFS restrictions prevent defining multiple resources in the same location.

**Using NIM bosinst_data resources**

When using a NIM bosinst_data resource during a bos_inst operation on a NIM client, you can specify the path to a script for the `CUSTOMIZATION_FILE` attribute, in the file pointed to by the bosinst_data resource.

This script is started at the end of the main installation program, by the `/usr/lpp/bosinst/bi_main program. For spot installations, it will occur after approximately 90% of the total installation process. For rte installations, it will occur after approximately 95% of the total installation process.
Example 5-79 is a simple shell script that performs some customization on a NIM client. In this case, it overwrites the /etc/motd (message of the day) file.

Example 5-79  Example CUSTOMIZATION_FILE script, node_bosinst

#!/bin/ksh
# node_bosinst
# Synopsis........%M%
# Author..........User01
# Created........2006
# Version.........%Z% %M% %I% (%E% %U%) %Q%
# Description.....N/A
# Input...........N/A
# Output.........Perform Node Customization during bosinst.
# Algorithm.......N/A
#-------------------------------------------------------------
#
# Redirect STDOUT and STDERR to a logfile
#
exec 1>/usr/local/bosinst/node_bosinst.log
exec 2>&1

cat <<EOF > /etc/motd
This computer is the property of Our Company.
Unauthorized access is prohibited. If you are not authorized
to have access to this computer, leave now.
All sessions on this computer can and may be monitored.
Violations will be punished to the full extent of the LAW.

EOF

We check the script for syntax errors by running it without execution. The script name is node_bosinst:

    ksh -xvn node_bosinst

After this step completes successfully, run the script manually on a test system to verify that it works as desired. After verifying that the script works properly, it can be copied to a directory on the SPOT that will be used during installation. In our case, we create and use the /usr/local/bosinst directory in the SPOT for our script, because the SPOT will be mounted over the RAM-/usr file system.

Note: This method has been available to use with mksysb since the early 1990s with AIX 3.1. With NIM, you can use the NIM script resources instead, which is usually more efficient. However, tape, DVD or similar mksysb media can still make use of this method.
The full path to the customization script on our NIM master will then be /export/spot/spot5305/usr/local/bosinst/node_bosinst.

**Note:** The path name specified for the CUSTOMIZATION_FILE attribute must be the path as known to the installation process during installation.

Example 5-80 is a simple bosinst_data resource specification file for automated installation. It should not require any user input unless something goes wrong during the installation process.

```plaintext
Example 5-80   Example bosinst_data resource specification file

control_flow:

CONSOLE = Default
INSTALL_METHOD = overwrite
PROMPT = no
EXISTING_SYSTEM_OVERWRITE = yes
INSTALL_X_IF_ADAPTER = no
RUN_STARTUP = no
CUSTOMIZATION_FILE = /usr/local/bosinst/node_bosinst
ACCEPT_LICENSES = yes
DESKTOP = NONE
INSTALL_DEVICES_AND_UPDATES = yes
ENABLE_64BIT_KERNEL = yes
CREATE_JFS2_FS = yes
ALL_DEVICES_KERNELS = no
GRAPHICS_BUNDLE = no
MOZILLA_BUNDLE = no
KERBEROS_5_BUNDLE = no
SERVER_BUNDLE = no
REMOVE_JAVA_118 = no
HARDWARE_DUMP = yes
ADD_CDE = no
ADD_GNOME = no
ADD_KDE = no

target_disk_data:

LOCATION =
SIZE_MB =
HDISKNAME =

locale:

BOSINST_LANG =
CULTURAL_CONVENTION =
MESSAGES =
```
To check the contents of your customized bosinst_data resource file, use the `bicheck` command as follows:

```
/usr/lpp/bosinst/bicheck <filename>
```

In our case:

```
/usr/lpp/bosinst/bicheck bosinst_group55
```

The `bicheck` command will verify the existence of the control_flow, target_disk_data, and locale stanzas, as needed.

The value for each field (if given) will be confirmed to match an allowable value, or other limitations, if they exist. If a non-prompted install is specified, the existence of values for required fields will be confirmed.

The command will not stop after the first error, but will continue as far as possible to indicate all problems with the bosinst.data file. If the return code is 1 (failed), an error message to standard error will name the stanzas and fields that have incorrect values.

**Note:** The `bicheck` command will not issue errors for misspelled attributes. For example, attributes such as CONSOLE should be in capital letters, and are *not* recognized if they are not.

When both the customization script and the specification file are working as desired, define the NIM bosinst_data resource as shown in Example 5-81. In this case, we use the `/export/scripts` directory for the bosinst_data specification file.

**Example 5-81  Creating a NIM bosinst_data resource**

```
root@master:/: nim -o define -t bosinst_data -a server=master -a
location=/export/scripts/bosinst_group55 bosinst_group55
```

For our purposes, we use a SPOT cloning during which our customization script will be used. In Example 5-82 on page 513, we use one NIM group with one NIM standalone machine.
Example 5-82  Creating a NIM machine group resource

root@master:/: nim -o define -t mac_group -a add_member=LPAR55 group55

The lpp_source needs to be allocated in case additional device drivers are needed, as shown in Example 5-83. To prevent this from happening, set the ALL_DEVICES KERNELS and INSTALL_DEVICES_AND_UPDATES attributes to no in the bosinst_data resource specification file.

Example 5-83  Allocating SPOT, lpp_source and bosinst_data for SPOT cloning

root@master:/: nim -o allocate -a spot=spot5305 -a lpp_source=lpp5305 -a bosinst_data=bosinst_group55 group55

Now we can initiate the actual installation process. In this case we specify the installation source to be the allocated SPOT resource spot5305, as shown in Example 5-84.

Example 5-84  Activating the SPOT cloning

root@master:/: nim -o bos_inst -a source=spot -a installp_flags=agX group55

Initiating the bos_inst operation on machine 1 of 1: LPAR55 ...

Target Result
------ ----- 
LPAR55 INITIATED

Note: Use the lsnim command to monitor progress of "INITIATED" targets by viewing their NIM database definition.

The installation process screen will show SPOT data being copied; see Figure 5-4 on page 514.
Using the CUSTOMIZATION_FILE with mksysb image files

Instead of updating the SPOT file tree, copy the customization file to the system to be cloned. In our example, we put it under the /usr/local/bosinst directory.

Perform cleanup and additional customization needed on the system prior to creating the mksysb image file for cloning purposes, as shown in Example 5-85. For more information about cloning using the mksysb command, see 5.4, “Cloning NIM clients using mksysb” on page 451.

Example 5-85  Creating a mksysb with the CUSTOMIZATION_FILE script

```
root@master:/: nim -o define -t mksysb -a server=master -a mk_image=yes -a source=LPAR55 -a mksysb_flags=i -a location=/export/images/mksysb_lpar55 mksysb_lpar55
```

<table>
<thead>
<tr>
<th>Approximate % tasks complete</th>
<th>Elapsed time (in minutes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>18</td>
<td>3</td>
</tr>
</tbody>
</table>

19% of SPOT data copied.

Creating information file (/image.data) for rootvg..

Creating list of files to back up.
Back up 20141 files..................
20141 of 20141 files backed up (100%)

Figure 5-4  Point-in-time screenshot of SPOT cloning
Then activate the installation of the newly created mksysb. In this case, we install it on the NIM client LPAR66, as shown in Example 5-86.

**Example 5-86 Installing allocated mksysb**

```bash
root@master:/: nim -o bos_inst -a source=mksysb LPAR66
```

+-----------------------------------------------------------------------------+
| Initiating "bos_inst" Operation                                                |
| Allocating resources ...                                                     |
| Initiating the bos_inst operation on machine 1 of 1: LPAR66 ...               |
+-----------------------------------------------------------------------------+

```
<table>
<thead>
<tr>
<th>Target</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>LPAR66</td>
<td>INITIATED</td>
</tr>
</tbody>
</table>
```

Note: Use the lsnim command to monitor progress of "INITIATED" targets by viewing their NIM database definition.

The installation process screen will show mksysb data being restored; see Figure 5-5.

```
<table>
<thead>
<tr>
<th>Approximate % tasks complete</th>
<th>Elapsed time (in minutes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>20</td>
<td>2</td>
</tr>
</tbody>
</table>

17% of mksysb data restored.
```

*Figure 5-5 Point-in-time screen shot of mksysb restore*
Using NIM fb_script script resources
A NIM fb_script resource represents a file that is a user-created shell script and can be allocated to a NIM machine, after it is defined. The BOS installation process creates a script in the /etc directory named firstboot, containing the content of the allocated NIM fb_script resource.

When a client is booted, the /usr/sbin/fbcheck script command checks for the existence of the /etc/firstboot file. If it exists, it renames it to a script in the /etc directory prefixed with fb_. This script is then executed.

The fbcheck command is run by init master process according to the entry in /etc/inittab. This allows the fb_script to perform configuration processing on the client after all the software is installed, but before it has finished the first startup in multi-user mode.

Use NIM fb_script resources in the following sequence:
1. Create a shell script.
2. Define the NIM fb_script resource pointing to the shell script.
3. Allocate the NIM fb_script resource for a bos_inst operation, to one or more NIM clients or NIM groups.
4. Execute the bos_inst operation on one or more NIM clients or NIM groups.

Example 5-87 is a simple shell script that performs some customization on a NIM client. It creates a few file systems.

```
Example 5-87 Example NIM fb_script, node_firstboot, for bos_inst operation
#
# node_firstboot
# Synopsis........%M%
# Author..........User01
# Created........2006
# Version........%Z% %M% %I% (%E% %U%) %Q%
# Description.....N/A
# Input...........N/A
# Output.........Perform First Boot Node Customization.
# Algorithm......N/A
#---------------------------------------------------------------
#
# Redirect STDOUT and STDERR to a logfile
#
exec 1>/tmp/${0##*/}.log
exec 2>&1
#
# Create /local JFS2 filesystem with 1PP size, mount it, create a directory and
# add the directory path to the root users KornShell .profile
```
We check the script for syntax errors by running it without execution. The script
name is node_firstboot:

```
ksh -xvn node_firstboot
```

After this step completes successfully, run the script manually on a test system to
verify that it works as desired. After it works properly, it can be defined as a NIM
fb_script resource as shown in Example 5-88. In this case, we use the
/export/scripts directory.

```
Example 5-88 Creating a NIM fb_script resource
```

```
root@master:/: nim -o define -t fb_script -a server=master
    -a location=/export/scripts/node_firstboot node_firstboot

root@master:/: lsnim -l node_cust
node_firstboot:
    class       = resources
    type        = fb_script
    Rstate      = ready for use
    prev_state  = unavailable for use
    location    = /export/scripts/node_firstboot
    alloc_count = 1
    server      = master
```

Now when the NIM fb_script has been defined, you can use the nim command
to view the content of the script file itself:

```
nim -o showres node_firstboot
```

The node_firstboot NIM fb_script resource is now ready for use, and can be
allocated and used for bos_inst operations. Allocate the script to a NIM
standalone machine or NIM group. In this case the NIM machine is LPAR55, as
shown in Example 5-89 on page 518.
Example 5-89  fb_script for a standalone or a group of machines

root@master:/: nim -o allocate -a spot=spot5305 -a lpp_source=lpp5305 -a bosinst_data=bosinst_group55 -a fb_script=node_firstboot LPAR55

Now we can initiate the actual installation process. In this case, we specify the installation source to be the allocated NIM lpp_source resource lpp5305, using the source attribute keyword rte, as shown in Example 5-90.

Example 5-90  Activating the installation with firstboot fb_script customization

root@master:/: nim -o bos_inst -a source=rte -a installp_flags=agX group55

+-----------------------------------------------------------------------------+
| Initiating "bos_inst" Operation                                              |
+-----------------------------------------------------------------------------+
Allocating resources ...

Initiating the bos_inst operation on machine 1 of 1: LPAR55 ...

+-----------------------------------------------------------------------------+
| "bos_inst" Operation Summary                                                |
+-----------------------------------------------------------------------------+
Target          Result
------          ------
LPAR55          INITIATED

Note: Use the lsnim command to monitor progress of "INITIATED" targets by viewing their NIM database definition.

The installation process screen will display the message: Installing additional software. Then software installation using the installp command will commence, as shown in Figure 5-6 on page 519.
5.9 Implementing a standard operating environment for AIX 5L V5.3 systems with NIM

This section describes practices for implementing a standard operating environment (SOE) for AIX systems with NIM. It is intended as an example-based guide that explains how to install AIX systems in a repeatable and consistent way, with the objective of reducing the associated system management and administration overhead.

The practices described here may not be suitable for all environments, so use your best judgment and take only what you consider can be applied to your site in keeping with the overall recommendations. The list of recommendations is not exhaustive; instead it is a starting point for developing a standard operating environment (SOE) for AIX in a NIM environment.

We discuss the following topics:

- Do you need an SOE for your AIX systems
- What is an SOE for AIX systems
- What is the purpose of the SOE image
- Using NIM to install and manage the SOE environment
5.9.1 Do you need an SOE for your AIX systems

If you manage one or more AIX systems, then an SOE may be useful. If you have a NIM master and you need to manage five or more AIX system images in a consistent and standard way, an SOE can offer many advantages.

5.9.2 What is an SOE for AIX systems

An SOE for AIX systems is a set of best practices, procedures, documents, standards, conventions, tools, and utilities with which you install and administer an AIX server. Administration tasks within the SOE are performed via NIM. All this information would be outlined in an SOE document. This document would include (but is not limited to) the following:

1. Guidelines for installing new hardware within your data center; for example, hardware delivery, cabling for network and storage, how and where to record hardware serial numbers and model types, location of pSeries hardware environment diagrams, and so on.

2. A list of standard filesets included (or that should be included) for installation in the AIX SOE image. This includes AIX filesets, storage device drivers and software (for example, SDD, SDDPCM), and so on.

3. AIX installation and management procedures via NIM. A standard image will be used to install all new NIM clients. This image would reside in /export/images on the NIM master and would be named so as to identify its purpose; for example, soe_mksysb - /export/images/AIX5304_64bit_SOE_V1-mksysb. The latest Technology Level would be applied to this image regularly.

4. NIM standards such as naming conventions for NIM clients, SPOTs, lpp_source resources and standard locations for NIM resources, and so on (for more information about this topic, refer to 2.3, “Planning for your NIM environment” on page 45).

Here are some examples:

– A NIM client machine name consists of the hostname with nim appended to it (such as uataix01nim).

– NIM client mksysb backups are performed from the client via a script from root's crontab; such a script could be executed from root's crontab, for example, twice a week.

– NIM client mksysb resource names format, such as hostname-mksysb.AIXV.Day (where hostname is the name of the system, AIXV is the AIX version, and Day is the day of the week that the backup was created). For example: uataix01nim-mksysb.530401.Mon.

– NIM client mksysb images are stored in /export/images.
– NIM lpp_source resource names and locations will be lpp_sourceaixVERSION, /export/lpp_source/lpp_sourceaixVERSION (where VERSION is the AIX version). For example, lpp_sourceaix5304 - /export/lpp_source/lpp_sourceaix5304.

– NIM SPOT resource names and location will be spotaixVERSION and /export/spot/spotaixVERSION (where VERSION is the AIX version). For example, spotaix5304 - /export/spot/spotaix5304.

– /tftpboot is created as a separate file system; for example, not in / (root). This prevents the root file system from filling in the event that many boot images are created.

– Location of other software that may need to be installed on the system. For example, a separate file system is created which will hold other software (for example, DB2, Oracle®, TSM, controlm, installp bundles and RPMs, and so on.). Refer to 4.12, “Creating bundles, BFF, and RPM packages” on page 354 for use with NIM.

– Location of SOE materials. For example, a file system (/software/soe), would contain SOE only-related software such as SOE scripts, tools, utilities, installp bundles, RPMs, and so on.

– Location of custom/firstboot NIM scripts. For example, the /export/scripts file system would contain firstboot and customization scripts that could be used as NIM resources during an installation.

– Location of other custom NIM resource files. For example, /export/etc would contain custom NIM resource configuration files like bosinst.data and nimbclient.defs.

5. Network configuration. For example, a separate VLAN for administration exists within the data center network. This VLAN is used only for administration and backup tasks. You create a new VLAN that will be used exclusively by NIM (and CSM and TSM, or CSM or TSM) network traffic that is completely isolated from any production network. Each host has at least two network adapters, with at least one interface connected to the administration and management VLAN.

6. LPAR configuration standards such as profile names, LPAR names, recommended LPAR profile settings (CPU, memory min/des/max and adapter layout), special settings (such as Small Real Mode Address Region, Allowed Shared Processor Pool Utilization Authority, Enable Connection Monitoring, and so on). For example:

– Profile name = normal

– The partition name will be the same as the hostname.

– The partition minimum and desired settings will be the same.
– The partitions should be configured for Dynamic LPAR, for example CPU min=1, Des=1, Max=4.
– Where possible, spread adapters over different I/O drawers and halves of the drawers, for redundancy.
– All partitions have a minimum of two Ethernet adapters and two Fibre Channel adapters.

7. Hostname standards and naming conventions, such as uataix01, where u=UNIX, a=AIX, t=Test (p=Production, d=Development, and so on). aix is a three-letter label indicating the system’s purpose (for example, sap, db2, ora, and so on). 01 (for example, 02, 03, 04, and so on) indicates the unique number of this type of server.

8. Volume group, logical volume and file system naming standards or conventions. For example, all VGs and LVs will have vg/lv appended, such as datavg and usrlv. All file systems within rootvg should be of type JFS. All file systems within non-rootvg file systems should be of type JFS2.

9. Paging space and dump space considerations and sizing. For example, true paging space sizing will depend on application requirements. But as a starting point, set paging space to at least the same (or twice the) size of real memory (on small memory systems). A separate LV for system dump space should be created, for example, hd7. Use the dumpcheck/sysdumpdev -e commands to ensure it is large enough.

10. AIX customization, such as TCB, kernel type, syslog configuration, TZ, LANG, AIX licenses, tuning recommendations, sendmail configuration, NTP settings, /etc/motd, and so on. For example:
– TCB should be enabled.
– 64-bit kernel should be installed.
– LANG=en_US.
– AIX licenses set to 1000 (not an issue with AIX 5L V5.3).
– sys0 attributes, for example maxuproc, iostat, cpuguard and fullcore.
– Syslog configuration; for example:

```
mail.debug /var/log/maillog    rotate time 7d files 4 compress
*.debug;mail.none /var/log/syslog rotate time 7d files 4 compress
```

11. Disk configuration, such as bootlist, mirrored rootvg, SDD, SDDPCM. System boot type will also be defined: boot from SAN or boot from SCSI disk. For example, rootvg should be mirrored when using SCSI disks, or if using SDDPCM and DS8300 disk (SAN boot MPIO), then rootvg will not be mirrored.
12. Network settings. For example, hardcode speed and duplex (where appropriate), use DNS (/etc/resolv.conf, /etc/netsvc.conf). The resolv.conf is contained within the image so we do not need to use a resolv_conf NIM resource.

13. Security settings (site-specific); for example, user attributes, password attributes, disabling unnecessary users and groups, disabling unnecessary services (telnet, ftp, sendmail, and so on).


15. Root account settings and restrictions. For example, no direct login; only via console (rlogin=false); use of sudo; allow only system administrators that are part of the system group to su to root.

16. Common set of system services and tools on all systems; for example: OpenSSH, OpenSSL, Isof, nmon, topas, sudo, pstree, tcsh, vim, logrotate, websm, nimsh, TSM client, and so on.

17. Backup strategy for all AIX systems. For example, sysbtonim and skelvg scripts to perform mksysb to NIM master and backup data volume group structure; TSM client used to back up the entire system.

18. Local custom scripts for administration tasks; for example, backup, nmon data collection, and so on. These scripts would typically reside in /usr/local/bin (a separate file system, /usr/local, would be created for this purpose).


20. Standard for /etc/rc.local. Any local startup scripts should be placed in rc.local and an entry created in inittab for rc.local.

21. AIX error report and SMIT log management. For example, to retain any information in the AIX error report and the SMIT logs, you could run some scripts to redirect or copy the information to a file for later reference. The following simple scripts are examples only, as shown in Example 5-91.

Example 5-91 Sample AIX error report and SMIT log cleanup scripts

```
clean_errpt.ksh:
  thedate=`date +%d%b%Y`
  varerr=/var/log/errpt
  errnm=errpt
  errpt >> $varerr/$errnm.$thedate
  errpt -a >> $varerr/$errnm.$thedate
  echo "Written $varerr/$errnm.$thedate"
  errclear 0
  echo "Cleared Error Report."

clean_smit.ksh:
  thedate=`date +%d%b%Y`
```
varsmit=/var/log/smit
cp -p /smit.log $varsmit/smit.log.$thedate
cp -p /smit.script $varsmit/smit.script.$thedate
cp -p /smit.transaction $varsmit/smit.transaction.$thedate
echo "Written $varsmit/smit.log.$thedate"
echo "Written $varsmit/smit.script.$thedate"
echo "Written $varsmit/smit.transaction.$thedate"
>/smit.log
>/smit.script
>/smit.transaction
echo "Cleared SMIT log."

# /var/log/errpt/clean_errpt.ksh
Written /var/log/errpt/errpt.27Jun2006
Cleared Error Report.

# /var/log/smit/clean_smit.ksh
Written /var/log/smit/smit.log.27Jun2006
Written /var/log/smit/smit.script.27Jun2006
Written /var/log/smit/smit.transaction.27Jun2006
Cleared SMIT log.

22. Setup for AIX systems within a DMZ; for example, special network tuning options required to secure AIX network connections. If the system is within a DMZ, then there may be VLAN restrictions imposed upon the system that may impact its ability to be administered via NIM. Refer to 5.3, “NIMSH, OpenSSL and firewall considerations” on page 424 for more details about this topic.

If you have a requirement to only administer a DMZ system infrequently, then you can consider using a “floating network adapter” for installs and temporary administration work. For example, assuming the system is an LPAR, you could configure and cable a network adapter on the managed system that is connected to your administration VLAN. When you need to perform a task on the DMZ LPAR, you can use DLPAR to assign the adapter, configure it and then perform the task. When the task is finished you could then unconfigure it and unassign it from the DMZ system.

Another consideration is how to create a mksysb backup of the client to the NIM master from the DMZ. One way is via scp. You can write a small script to perform a mksysb to a local file system, and then use scp (secure copy) to copy the image to the NIM master. A sample script (sysbtofs) is provided in Appendix D, “Additional material” on page 643.

23. Steps to verify and hand over an AIX system; for example, SOE verification and system peer review and Quality Assurance would be performed prior to application installation. Custom scripts can be used to perform this task.
24. Documenting the system configuration; for example, a system support pack would be created that outlined how the system was configured and why.

25. Administration tasks. Where possible, all systems should be administered from the NIM master. Tasks such as software maintenance can be performed with NIM quickly and efficiently (refer to 5.7, “System maintenance for NIM clients” on page 478 for more information about this topic).

Also, commands such as `dsh/dcp` (CSM tools) make administration easier because they will allow you to run commands on many systems at once. CSM is capable of much more in terms of administering your systems; for details refer to 6.1, “Overview of Cluster Systems Management” on page 560.

It is possible to install the `csm.dsh` fileset and run the `dsh/dcp` commands but it is not supported. If you do not have CSM within in your environment but would like a dsh-like command, one alternative is `pdsh` (Public Domain Korn Shell):

```
http://www.llnl.gov/linux/pdsh/pdsh.html
```

The purpose of the SOE image

In order to maintain a consistent image across all your AIX systems, an SOE mksysb image is created. This mksysb image contains the following:

- A standard set of AIX filesets such as `bos.net*`, `devices.fcp*` and much more.
- A standard set of AIX tools and utilities. These may be open source tools or those provided by IBM such as `topas`, `lparstat`, `mpstat`, `nmon`, `lsof`, and others.
- Preferred kernel and device support such as 64-bit, jfs file systems for rootvg, and so on.
- Standard user accounts, for example, for system administrators.
- Scripts for system administration.
- Backup tools, for example, TSM client.

To keep the SOE image as clean and as small as possible, rootvg only contains AIX operating system-related software and tools. Applications, databases and other software are never installed into rootvg.

A separate volume group is created for any additional (non-standard) software outside of the SOE. This will keep rootvg and the mksysb small, and helps to reduce the time required to install and restore the image and manage the root volume group.
How an SOE image is created

The SOE image is created by a base install of AIX, which is then customized and a mksysb image created. If you want to create an SOE image, first install AIX 5L V5.3 (via NIM rte install) onto a test system. When performing the installation, ensure that you have selected the desired configuration for your SOE image (that is, kernel type, TCB on or off, all kernel/device support yes or no, language, and other AIX OS filesets).

All devices on this system should be unconfigured (for example, no network settings). After AIX has been installed, then install all of the tools and utilities you would like to include in your SOE image, create any file systems you need (for example, /usr/local), and add scripts and configuration files required, and so on.

When the system is fully configured to your SOE design, perform a mksysb of the system to a local file system. For example, create a /mksysb file system within rootvg and perform a mksysb to it (# mksysb -i /mksysb/soe_image_mksysb). After you have a “gold” image of your SOE, you can configure IP on this system and transfer it to your NIM master’s mksysb directory (/export/images) ready for installation.

To update your SOE in the future, if you need to add, change or remove any of its components, you can use the same procedure as described. But instead of installing base AIX, you would install your SOE image onto an unconfigured test system, perform the updates, and then create a new mksysb image as before.

An alternative way to update your SOE is by assigning an LUN as your SOE disk. This disk can be assigned to an LPAR. You install the SOE onto this disk and then perform your updates. This LUN could be permanently assigned to a small micro-partition “SOE server” using virtual I/O (VIO) devices. You would install the VIO client using your SOE image and then perform the updates.

Another way of easily deploying your SOE is via alt_disk_install. If you have a spare disk within your pSeries environment, either an internal SCSI disk or a small LUN on your SAN disk device (for example, ESS800, DS8300) you can use this disk to update your SOE quickly. For example, you could install your SOE image onto a system that boots from SAN disk. This SOE LUN could be assigned temporarily to any test system that you will use for the SOE update. You then perform any updates required to your SOE image.

After the system is up and running, you could assign another LUN (Clone LUN) and use alt_disk_install to clone the disk. The LUN could be unassigned from the SOE server and then assigned to the new LPAR you are attempting to install. The new LPAR can boot from this disk and would then be running the SOE image. Refer to 5.6, “Using SAN zoning for cloning LPARs” on page 475 for more detailed information about this topic.
It is important to keep your lpp_source and SPOT up-to-date, and to have all the available device and kernel support within these resources. If you have several types of System p hardware (p660, p650, p690, p570, p595, and so on) within the environment where you intend to install your SOE, you need to ensure that all required device (and other) filesets be in the lpp_source for the SOE to be installed on many types of pSeries hardware. Refer to 5.5, “Using NIM to migrate systems to new hardware” on page 460 for further information.

Using NIM to install and manage the SOE environment

After the SOE image is created, it can be used to install new systems with standard NIM cloning techniques (refer to 5.4, “Cloning NIM clients using mksysb” on page 451). However, a standard set of procedures for creating and installing the client will exist in an SOE environment. Hostnames and mksysb images will be named according to this standards.

In larger AIX environments that need to install multiple clients at once, the nimdefs command will be used to predefine all the NIM clients that need to be created. Once created, the clients are then installed at the same time via a NIM bos_int operation on a NIM machine group.

Note: An example of a nimdef stanza file is located in /usr/samples/nim/client.defs.

What follows is a short example of using the nimdefs command to quickly define six new NIM clients to our NIM environment. Having an SOE in place makes this process simple, because we already know what the hostnames will be and which network (VLAN) to use.

The client.defs file begins with some default values for our environment, such as the machine type, subnet mask, gateway, platform (chrp), kernel type (mp) and the machine group for the new clients.

The NIM client definitions follow next and contain the network type, cable type and a comment. We could have included just the comment because the network type and cable type are already defined in the default stanza. We are defining six clients, uataix01nim through to uataix06nim.

The NIM master’s /etc/hosts file is updated with the IP addresses of the new NIM clients:

10.1.1.91  uataix01nim
10.1.1.92  uataix02nim
10.1.1.93  uataix03nim
10.1.1.94  uataix04nim
10.1.1.95  uataix05nim
We update our /export/etc/client.defs file with the new client definitions, as shown in Example 5-92.

Example 5-92  Updating the /export/etc/client.defs file

```
# cat /export/etc/client.defs
# set default values
default:
    machine_type = standalone
    subnet_mask  = 255.255.255.0
    gateway      = 10.1.1.1
    network_type = ent
    cable_type   = tp
    platform     = chrp
    netboot_kernel = mp
    machine_group = nimgrpl

# Define uataix01, uataix02, uataix03, uataix04, uataix05, uataix06
uataix01nim:
    network_type = ent
    cable_type   = tp
    comment      = "Test AIX LPAR number 1"

uataix02nim:
    network_type = ent
    cable_type   = tp
    comment      = "Test AIX LPAR number 2"

uataix03nim:
    network_type = ent
    cable_type   = tp
    comment      = "Test AIX LPAR number 3"

uataix04nim:
    network_type = ent
    cable_type   = tp
    comment      = "Test AIX LPAR number 4"

uataix05nim:
    network_type = ent
    cable_type   = tp
    comment      = "Test AIX LPAR number 5"

uataix06nim:
    network_type = ent
    cable_type   = tp
```
Creating the client.defs file can be also be streamlined by writing a small script to generate a client.defs based on a list of new NIM client names. For example, the script in Example 5-93 will create a new client.defs file in /export/etc/client.defs based on the list of NIM client names in the file /export/etc/newclients.list.

Example 5-93 Automating the creation of the client.defs file

```
# cat /export/scripts/cr_cldef
#!/usr/bin/ksh
#
# Script to create a new client.def file based on newclients.list file.
#
client=$(</export/etc/newclients.list)

if [ "$client" = "" ] ; then
  echo "Please add new clients to /export/etc/newclients.list e.g.
  uataix01nim
  uataix02nim
  etc......
  "
  exit 1
fi

echo '# set default values
default:
  machine_type = standalone
  subnet_mask = 255.255.255.0
  gateway = 10.1.1.1
  network_type = ent
  cable_type = tp
  platform = chrp
  netboot_kernel = mp
  machine_group = nimgrpl
' > /export/etc/client.defs

for i in $client
do
  echo "$i:
    comment = 'NIM client $i'
  " >> /export/etc/client.defs
done

# cat /export/etc/newclients.list
```
Next, we run the `nimdef` command to preview the client definition file, and also to create a script that we can run to perform the actual creation of the NIM client definitions, as shown in Example 5-94.

**Example 5-94  Running the nimdef command**

```bash
# nimdef -p -f client.defs > /export/scripts/mkcldef
# cat /export/scripts/mkcldef
6 machine definitions are complete. The following machines will be added to the NIM environment:

uataix01nim:
  hostname=uataix01nim
gateway=10.1.1.1
  subnet_mask=255.255.255.0
  network_type=ent
cable_type=tp
  machine_type=standalone
  platform=chrp
  hostaddr=10.1.1.91
  netaddr=10.1.1.0
  netboot_kernel=mp
  groupname=nimgrp1

uataix02nim:
```
hostname=uataix02nim
gateway=10.1.1.1
subnet_mask=255.255.255.0
network_type=ent
cable_type=tp
machine_type=standalone
platform=chrp
hostaddr=10.1.1.92
netaddr=10.1.1.0
netboot_kernel=mp
groupname=nimgrp1

uataix03nim:
  hostname=uataix03nim
gateway=10.1.1.1
subnet_mask=255.255.255.0
network_type=ent
cable_type=tp
machine_type=standalone
platform=chrp
hostaddr=10.1.1.93
netaddr=10.1.1.0
netboot_kernel=mp
groupname=nimgrp1

uataix04nim:
  hostname=uataix04nim
gateway=10.1.1.1
subnet_mask=255.255.255.0
network_type=ent
cable_type=tp
machine_type=standalone
platform=chrp
hostaddr=10.1.1.94
netaddr=10.1.1.0
netboot_kernel=mp
groupname=nimgrp1

uataix05nim:
  hostname=uataix05nim
gateway=10.1.1.1
subnet_mask=255.255.255.0
network_type=ent
cable_type=tp
machine_type=standalone
platform=chrp
hostaddr=10.1.1.95
netaddr=10.1.1.0
netboot_kernel=mp
groupname=nimgrp1

uataix06nim:
  hostname=uataix06nim
gateway=10.1.1.1
subnet_mask=255.255.255.0
network_type=ent
cable_type=tp
machine_type=standalone
platform=chrp
hostaddr=10.1.1.96
netaddr=10.1.1.0
netboot_kernel=mp
groupname=nimgrp1

1 machine group will be created with new members.

nimgrp1:
machine_type=standalone
member=uataix01nim
member=uataix02nim
member=uataix03nim
member=uataix04nim
member=uataix05nim
member=uataix06nim

1 network in the NIM environment will have new machine interfaces added.

NET1:
  network_type=ent
  address=10.1.1.0
  subnet=255.255.255.0
  hostname=uataix01nim
  hostname=uataix02nim
  hostname=uataix03nim
  hostname=uataix04nim
  hostname=uataix05nim
  hostname=uataix06nim

Summary

6  Machines will be added to the NIM environment.
1  Machine group will be created with new members.
1  Network will have new NIM machine interfaces added.

#########################################################################
# Commands to define new machines in the NIM environment.
##########################################################################
nim -o define -t standalone -a if1="find_net uataix01nim 0 ent" -a cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1.1" -a netboot_kernel=mp -a platform=chrp uataix01nim

nim -o define -t standalone -a if1="find_net uataix02nim 0 ent" -a cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1.1" -a netboot_kernel=mp -a platform=chrp uataix02nim

nim -o define -t standalone -a if1="find_net uataix03nim 0 ent" -a cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1.1" -a netboot_kernel=mp -a platform=chrp uataix03nim

nim -o define -t standalone -a if1="find_net uataix04nim 0 ent" -a cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1.1" -a netboot_kernel=mp -a platform=chrp uataix04nim

nim -o define -t standalone -a if1="find_net uataix05nim 0 ent" -a cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1.1" -a netboot_kernel=mp -a platform=chrp uataix05nim

nim -o define -t standalone -a if1="find_net uataix06nim 0 ent" -a cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1.1" -a netboot_kernel=mp -a platform=chrp uataix06nim

# Commands to define new groups and members in the NIM environment.

nim -o define -t mac_group -a add_member=uataix01nim -a add_member=uataix02nim -a add_member=uataix03nim -a add_member=uataix04nim -a add_member=uataix05nim -a add_member=uataix06nim nimgrp1

We can now run the mkcldef script to define the clients. We remove everything except the lines that contain the commands to define the clients and machine groups, as shown in Example 5-95.

Example 5-95  Defining the machines in the new environment

nim -o define -t standalone -a if1="find_net uataix01nim 0 ent" -a cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1.1" -a netboot_kernel=mp -a platform=chrp uataix01nim
nim -o define -t standalone -a if1="find_net uataix02nim 0 ent" -a
cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1
.1 " -a netboot_kernel=mp -a platform=chrp uataix02nim

nim -o define -t standalone -a if1="find_net uataix03nim 0 ent" -a
cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1
.1 " -a netboot_kernel=mp -a platform=chrp uataix03nim

nim -o define -t standalone -a if1="find_net uataix04nim 0 ent" -a
cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1
.1 " -a netboot_kernel=mp -a platform=chrp uataix04nim

nim -o define -t standalone -a if1="find_net uataix05nim 0 ent" -a
cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1
.1 " -a netboot_kernel=mp -a platform=chrp uataix05nim

nim -o define -t standalone -a if1="find_net uataix06nim 0 ent" -a
cable_type1=tp -a net_definition="ent 255.255.255.0 10.1.1
.1 " -a netboot_kernel=mp -a platform=chrp uataix06nim

########################################################################
# Commands to add new members to existing groups in the NIM environment.
#
########################################################################
nim -o change -a add_member=uataix01nim -a add_member=uataix02nim -a
add_member=uataix03nim -a add_member=uataix04nim -a add_
member=uataix05nim -a add_member=uataix06nim nimgrp1

# ksh /export/scripts/mkcldef

Our six new NIM clients are now defined:

# lsnim -t standalone
uataix01nim     machines       standalone
uataix02nim     machines       standalone
uataix03nim     machines       standalone
uataix04nim     machines       standalone
uataix05nim     machines       standalone
uataix06nim     machines       standalone

To automate the SOE installation process, a custom bosinst.data and first boot
script resource is created to support an unattended installation and automatic
customization of the system.
A NIM bosinst_data resource is created for the SOE bosinst.data:

```bash
# lsnim -t bosinst_data
soe_bosinst_data resources bosinst_data

# lsnim -l soe_bosinst_data
soe_bosinst_data:
    class       = resources
    type        = bosinst_data
    Rstate      = ready for use
    prev_state  = unavailable for use
    location    = /export/etc/soe.bosinst.data
    alloc_count = 1
    server      = master
```

In particular, the following entries will be changed in the bosinst.data file, as shown in Example 5-96.

**Example 5-96  Example SOE bosinst.data customizations**

```plaintext
INSTALL_METHOD = overwrite
PROMPT = no
EXISTING_SYSTEM_OVERWRITE = yes
TCB = yes
RECOVER_DEVICES = no
ACCEPT_LICENSES = yes
ALL_DEVICES_KERNELS = no
ENABLE_64BIT_KERNEL = yes
ALT_DISK_INSTALL_BUNDLE = yes
locale:
    BOSINST_LANG = en_US
    CULTURAL_CONVENTION = en_US
    MESSAGES = en_US
    KEYBOARD = en_US

target_disk_data:
    HDISKNAME = hdisk0
```

If you need to install the SOE image onto several different LPARs on several different managed systems, you may find it more convenient to use a single NIM client definition for the mksysb install. For example, you may create a new NIM...
client definition named uataixinst, which is used only for installing the SOE on several LPARs.

**Note:** If you plan to use a single NIM client to install many systems, consider disabling CPU ID validation on the NIM master. Refer to 4.5, “NIM mksysb migration and nim_move_up POWER5 tools” on page 205 and 4.6, “NIM alternate disk migration” on page 261, for more information about Managing client CPU ID validation.

A first boot script is also used to perform any additional customization required upon the client’s first boot (for example, setting the hostname, configuring additional adapters, changing network settings, modifying .profile/.kshrc files, and so on). This is generally not required because the SOE is already heavily customized for all of these, but there may be circumstances where it is required when the SOE must change to meet a new requirement. Refer to 5.8, “Automatic scripts” on page 504 for more information on scripting NIM automation.

The BOS installation process adds the content of the fb_script resource to the /etc/firstboot file, which is run the first time that a client is booted (fbcheck from inittab). See Example 5-97 for a sample first boot script (fbscript) NIM resource.

**Example 5-97   Sample first boot script**

```
# lsnim -l soe_fbscript
soe_fbscript:
  class       = resources
  type        = fb_script
  Rstate      = ready for use
  prev_state  = unavailable for use
  location    = /export/scripts/soe_fbscript.ksh
  alloc_count = 1
  server      = master
```

When installing the SOE onto a new LPAR, we use the following NIM resources:

- An AIX 5L V5.3 lpp_source: *LPP_53_ML4*.
- An AIX 5L V5.3 SPOT resource: *SPOT_53_ML4*.
- An SOE first boot script resource: *soe_fbscript*.
- The SOE mksysb image resource: *soe_mksysb*
- The SOE bosinst_data resource: *soe_bosinst_data*

To install the SOE image onto all clients in the *nimgrp1* machine group, we would perform the following:

```
# nim -o bos_inst -a source=mksysb -a spot=SPOT_53_ML4 -a lpp_source=LPP_53_ML4 -a mksysb=soe_mksysb -a bosinst_data=soe_bosinst_data -a fb_script=soe_fbscript -a
```
accept_licenses=yes -a installp_flags=-acNgX -a no_client_boot=yes -a preserve_res=yes nimgrp1

After the SOE mksysb installation is complete, there is little left to do (in terms of AIX installation and configuration), except to verify that the install completed successfully and that the system conforms to our SOE design. At the end of the firstboot script, we ran a script on the system after the installation. This script checks the system against our predefined SOE configuration and reports on anything that may be different from what we expect to find in our SOE image.

Before installing any applications on the system, we recommend that you have the build reviewed by another technical resource to check for any oversights in the system's configuration. If everything is OK, then the system's current configuration should be documented. The new AIX system is now ready for use.

In summary, using NIM and our SOE image allows us to ensure that:

- All of our AIX installations are consistent and adhere to standards set out for our environment.
- That the time-consuming and tedious post-operating system installation tasks are reduced significantly (if not removed altogether).

NIM (and the SOE image) reduced the administration and management overhead associated with installing and then customizing an AIX system.

## 5.10 Backing up and reinstalling a NIM master

In this section, we present three methods (described in scenarios) for backing up and restoring a NIM master with as little effort and as automatically as possible.

Keeping an up-to-date image of your NIM master machine or NIM master machines is an important task that a NIM administrator should perform, for several reasons. For example, it helps to protect your NIM environment in case of a hardware or software failure, or when you are using several complex NIM environments with several NIM master machines.

For two of the three methods, we use a mksysb tape already created. For the third method, we use NIM.

**Note:** For detailed information about how to create and install system backups, refer to *AIX 5L Version 5.3: Installation Guide and Reference*, SC23-4887.
5.10.1 Scenario 1: Back up and restore a NIM master on the same machine using a tape

As a starting point, we assume we have a mksysb tape of our NIM master. The file bosinst.data, which is included into the mksysb image, must have the parameter RECOVER_DEVICES = yes, as shown in Example 5-98. This parameter is used to specify whether the devices will be recreated as they were on the source system. Practically, this avoids having to reconfigure the network adapter.

Example 5-98  The bosinst.data file with RECOVER_DEVICES value

```
control_flow:
    CONSOLE = /dev/lft0
    INSTALL_METHOD = overwrite
    PROMPT = no
    EXISTING_SYSTEM_OVERWRITE = yes
    SWITCH_TO_PRODUCT_TAPE =
    RECOVER_DEVICES = yes
    BOSINST_DEBUG = no
    ACCEPT_LICENSES = yes

......................

target_disk_data:
    PVID = 00554d4ab6bb3366
    PHYSICAL_LOCATION = U0.1-P2/Z1-A8
    CONNECTION = scsi0//8,0
    LOCATION = 1S-08-00-8,0
    SIZE_MB = 17357
    HDISKNAME = hdisk0

locale:
    BOSINST_LANG = en_US
    CULTURAL_CONVENTION = en_US
    MESSAGES = en_US
    KEYBOARD = en_US
```

There is no particular difficulty in performing this task: to initiate mksysb restore, go into SMS mode and select the appropriate boot device (in this case, the tape).

5.10.2 Scenario 2: Back up and restore a NIM master on a different machine using a tape

The starting point is the same as for the Scenario 1: we assume we have a mksysb tape of our NIM master. This image contains the same bosinst.data file as shown in Example 5-98.
The target machine is different (hardware configuration) than the source machine, thus some additional work must be done after the installation itself:

1. Change network definition.
2. Change the hostname of the new master stored into the NIM database and the related hardware address.

**Note:** If the machine we want to reinstall does not have the same hardware as the one which served to create the mksysb image, we need to use CDs to boot properly.

There is no specific additional work compared to the restore of a standard mksysb. We need to follow the basic steps:

1. Go to SMS mode.
2. Select the right device you want to boot from (either a tape or a CD) depending on whether the target machine has the same hardware or not as the source machine.
3. Follow the menus to restore from tape.

After the machine has rebooted, two actions must be taken: change the network definition and master hostname, and save its related hardware address into the NIM database.

To perform the first step (Network definition change), run the following command:

```
/usr/sbin/mktcpip -h'cev223' -a'129.1.2.23' -m'255.255.255.0' -i'en0' -A'no' -t'N/A'
```

where:

- cev223 is the new hostname.
- 129.1.2.23 is the new IP address.
- 255.255.255.0 is the new mask.
- en0 is the interface name.

A best practice is to check the result of the work. We suggest running the following command:

```
netstat -in
```

Example 5-99 gives the output of the `netstat` command. This output also gives the hardware address (0002554F2693, in our case) used in the second step.

**Example 5-99  Output of netstat -in command**

<table>
<thead>
<tr>
<th>Name</th>
<th>Mtu</th>
<th>Network</th>
<th>Address</th>
<th>Ipkts</th>
<th>Ierrs</th>
<th>Opkts</th>
<th>Oerrs</th>
<th>Coll</th>
</tr>
</thead>
<tbody>
<tr>
<td>en0</td>
<td>1500</td>
<td>link#2</td>
<td>0.2.55.4f.26.93</td>
<td>884</td>
<td>0</td>
<td>562</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>
To perform the second step (NIM master hostname and hardware address changes), we use SMIT by running the command:

```
smitty nim
```

Select the following sub-panels in order:

- Perform NIM Administration Tasks
- Manage Machines
- Change/Show Characteristics of a Machine
- Chose master

After these choices are made, the SMIT menu shown in Example 5-100 is launched. Change the HostName value and the Network Adapter Hardware Address by the appropriate values, then press Enter for execution.

**Example 5-100   SMIT panel to change master hostname and hardware address**

Change/Show Characteristics of a Machine

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

```
[TOP]                                                   [Entry Fields]
  Machine Name                                       [master]
*  Hardware Platform Type                             [chrp]  +
*  Kernel to use for Network Boot                     [mp]  +
  Machine Type                                       master
Network Install Machine State                       currently running
Network Install Control State                       ready for a NIM opera>
Primary Network Install Interface
  Network Name                                       NET_EN0
  Host Name                                           [cev223]
  Network Adapter Hardware Address                   [0002554F2693]
  Network Adapter Logical Device Name                [ent]
  Cable Type                                         N/A  +
  Network Speed Setting                               []  +
```

```
A best practice is to check the result of the work by running the following command:

```
lsnim -l master
```

Example 5-101 gives the output of the `lsnim` command.

```
Example 5-101   Output of lsnim -l master command

{cev223}:/ # lsnim -l master
master:
  class               = machines
  type                = master
  max_nimesis_threads = 20
  comments            = machine which controls the NIM environment
  platform            = chrp
  netboot_kernel      = mp
  if1                 = NET_ENO cev223 0002554F2693
  cable_type1         = N/A
  Cstate              = ready for a NIM operation
  prev_state          = ready for a NIM operation
  Mstate              = currently running
  serves              = BID_NP_HD0
  serves              = LPP_53_ML3
  serves              = SPOT_53_ML3
  serves              = boot
  serves              = nim_script
  master_port         = 1058
  registration_port   = 1059
  reserved            = yes
{cev223}:/ #
```

### 5.10.3 Scenario 3: Back up and restore a NIM master using another NIM master

Basically, even if a mksysb image of one NIM master is available, when restoring it using NIM, this machine becomes a simple client. In effect, several specific and important NIM scripts are used in the network boot process. One of them is:

```
/SPOT/usr/lpp/bos.sysmgmt/nim/methods/c_mk_nimclient
```

This is used if `no_nim_client=no`, or is not specified. If it is set to `yes`, then this script does not get called. This variable tells the NIM master if the currently installed machine is going to remain (or not) a NIM client to that master after install.
The script performs the following tasks:

- It will install bos.sysmgt.nim.client and bos.net*.client.
- It will deinstall the bos.sysmgt.nim.master if it is present.
- It invokes mktcip to configure the network on the installed machine.
- It populates the new /etc/hosts file with values from the $NIM_HOSTS from /etc/niminfo (created by $NIM_BOSINST-RECOVER in the previous bi_main step).
- It adds routes as specified in $ROUTES from /etc/niminfo.

In most cases, we want this machine be part of our NIM environment after the installation. Thus, the value of no_nim_client must be to no. This is done when you start an operation on the client. Example 5-102 shows the appropriate SMIT panel.

Example 5-102   Start an operation on a NIM client

Install the Base Operating System on Standalone Clients

Type or select values in entry fields.
Press Enter AFTER making all desired changes.

[MORE...1]          [Entry Fields]
* Installation TYPE  mksysb
  * SPOT             SPOT_53_ML4
    LPP_SOURCE       [] +
    MKSYSB           MK_MST_53ML4

BOSINST_DATA to use during installation [] +
IMAGE_DATA to use during installation [] +
RESOLV_CONF to use for network configuration [] +
Customization SCRIPT to run after installation [] +
Customization FB Script to run at first reboot [] +
ACCEPT new license agreements? [no] +
Remain NIM client after install? [yes] +
PRESERVE NIM definitions for resources on [yes] +
[MORE...35]

Thus, after the installation is finished, this machine has all the information needed to be reconfigured as a NIM master, but is not used. What are the three things that are missing to have this machine back as a NIM master?

- Installation of nim.master fileset, because this fileset has been uninstalled through the script:
  /SPOT/usr/lpp/bos.sysmgt/nim/methods/c_mk_nimclient
- NIM database restoration
Modification of the hostname and the hardware address

To revert this machine into a NIM master we use a fb_script resource to run the necessary commands, as shown in Example 5-103.

Example 5-103  Script to reconfigure the machine as a NIM master

```
{nimmast}:/JMB/scripts # cat nimmast.script
#!/bin/ksh
#    JM BERAIL          June, 15th 2006
#
#    PHASE 1:   Installation of nim.master fileset from the lpp_source
#               included into the mksysb image
#
/usr/lib/instl/sm_inst installp_cmd -a -Q -d '/AIX53ML4/LPP_53_ML4' -f '+
5.3.0.40  Network Install Manager - Master Tools
@@S:bos.sysmgt.nim.master 5.3.0.40' '-c' '-N' '-g' '-X' '-G'
#
#    PHASE 2:   NIM database restoration
#
#        A NIM database backup has been made before the mksysb creation
#        and it has been included onto the mksysb image.
#        In our case, the NIM database backup file name is
#        nimdb.backup.15jun06
#        and it is located into the /tmp directory
#
/usr/lpp/bos.sysmgt/nim/methods/m_restore_db /tmp/nimdb.backup.15jun06
#
#    PHASE 3:   Modification of the hostname related to the master.
#               Because the mksysb restoration can occur on a different
#               machine
#               than the one that has been used for the mksysb creation,
#               we need to be sure that the hostname of the master machine
#               stored
#               onto the NIM database is the same than the hostname of the
#               machine used for the restauration. To fix this problem,
#               we need to run the nim -o change command with the appropriate
#               parameters.
#
```
MAC=$(lscfg -vl $(netstat -i | grep $(uname -n) | awk '{print $1}'} | sed -e 's/en/ent/') | grep 'Network Address')

nim -o change -a if1="NET_EN0 $(uname -n) $MAC" -a platform=chrp \
-a netboot_kernel=mp master

NIM from A to Z in AIX 5L

Note: The values shown in bold font in the figure (such as the lpp_source
name directory, the backup file name of the NIM database, and the network
class name) must be adapted to your environment.

5.10.4 Changing the NIM master hostname

In order to change the hostname for the NIM master, follow these steps. They
are explained in more detail throughout the section.

1. Update the name resolution (for the NIM master and the NIM clients), keeping
   the old names.
2. Change the hostname on the NIM database.
3. Remove the old name from name resolution.

Scenario
Here we use two machines, configuring one as a NIM master and the other as a
NIM client. The NIM master name is changed and the change is reflected to the
NIM client.

Updating name resolution
Name resolution must be updated for the NIM master and the NIM client. The old
name must be kept in order to be able to communicate to the NIM clients to
update the /etc/niminfo files with the new name.

Note: If /etc/hosts is being used for the name resolution, the new name for the
NIM master on the NIM client has to be added at the end of the corresponding
entry. Using a different order may cause the update from the NIM master to fail.
In our scenario, the NIM master name is lpar2. Example 5-104 shows the output for the `lsnim` command. The value for if1 shows that the hostname on the NIM database is lpar2.

**Example 5-104  Host name on the NIM database**

```
(root@lpar2):/ # lsnim -l master
master:
  class           = machines
  type            = master
  max_nimesis_threads = 20
  if_defined      = chrp.mp.ent
  comments        = machine which controls the NIM environment
  platform        = chrp
  netboot_kernel  = mp
  if1             = NET_EN1 lpar2 00096B4EAD9C
  cable_type1     = N/A
  Cstate          = ready for a NIM operation
  prev_state      = ready for a NIM operation
  Mstate          = currently running
  serves          = LPP_PRUEBA
  serves          = SEC_ADAPTR
  serves          = boot
  serves          = nim_script
  master_port     = 1058
  registration_port = 1059
  reserved        = yes
  ssl_support     = yes
```

The new name for the NIM master is nimmast. Example 5-105 shows how the name resolution is updated for the NIM master.

**Example 5-105  /etc/hosts on NIM master**

```
(root@lpar2):/ # cat /etc/hosts
............
10.1.1.22       lpar2 nimmast
............
```

Example 5-106 shows how the name resolution is updated for the NIM client.

**Example 5-106  /etc/hosts on NIM client**

```
# more /etc/hosts
............
10.1.1.22       lpar2 nimmast
............
```
Example 5-107 shows the contents of the /etc/niminfo file for the NIM client. Check that the value for NIM_MASTER_HOSTNAME is lpar2.

```
Example 5-107 /etc/niminfo on the NIM client

# cat /etc/niminfo
#------------------ Network Install Manager ------------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
export NIM_NAME=VLPAR3_p5
export NIM_HOSTNAME=vlpar3_p5
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=lpar2
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS=" 10.1.1.70:vlpar3_p5  10.1.1.22:lpar2 ">
export NIM_MOUNTS=""
export ROUTES=" default:0:10.1.1.1 ">
```

**Changing the hostname in the NIM database**

This task changes the hostname on the NIM database and reflects the change on the NIM client's configuration.

To perform the change, follow these steps:

1. Type the `smitty nim_ch_if1 fastpath` on the NIM master.
2. Select the proper values for the SMIT panel. If there is an existing NIM network referring to the hostname that is being changed, choose it in order to reflect the changes.

Example 5-108 shows the panel and values used to change the hostname for the NIM master on the database.

```
Example 5-108 Changing the hostname using smit

New Host Information (Optional)

<table>
<thead>
<tr>
<th>New Host Name</th>
<th>[nimmast]</th>
</tr>
</thead>
<tbody>
<tr>
<td>New Cable Type</td>
<td>[ ]</td>
</tr>
<tr>
<td>+</td>
<td></td>
</tr>
</tbody>
</table>

New Network Information

<table>
<thead>
<tr>
<th>Existing NIM Network Name</th>
<th>[NET_EN1]</th>
</tr>
</thead>
<tbody>
<tr>
<td>-OR-</td>
<td></td>
</tr>
<tr>
<td>New NIM Network Type</td>
<td>[ ]</td>
</tr>
<tr>
<td>+</td>
<td></td>
</tr>
</tbody>
</table>
```
The output for the operation is shown in Example 5-109 showing that the NIM clients are updated.

**Example 5-109  Hostname change output**

```
Switching master on NIM clients
  changed master for vlpar3_p5
Finished switching master on NIM clients
```

Example 5-110 shows the output for the `lsnim` command on the NIM server. This output shows that `master` is the new hostname on the NIM server, and that the new hostname is propagated to the NIM client (vlpar3_p5).

**Example 5-110  lsnim command output**

```
(root@lpar2):/ # lsnim -l master
master:
  class = machines
  type = master
  max_nimesis_threads = 20
  if_defined = chrp.mp.ent
  comments = machine which controls the NIM environment
  platform = chrp
  netboot_kernel = mp
  if1 = NET_EN1 nimmast 00096B4EAD9C
  cable_type1 = N/A
  Cstate = ready for a NIM operation
  prev_state = ready for a NIM operation
  Mstate = currently running
  serves = LPP_PRUEBA
  serves = SEC_ADAPTR
  serves = boot
  serves = nim_script
  master_port = 1058
  registration_port = 1059
  reserved = yes
  ssl_support = yes
```

On the NIM client, the `/etc/niminfo` file is updated with the new hostname as shown in Example 5-111 on page 548.
**Example 5-111  /etc/niminfo updates**

```bash
# cat /etc/niminfo
#------------------ Network Install Manager ------------------
# warning - this file contains NIM configuration information
# and should only be updated by NIM
export NIM_NAME=VLPAR3_p5
export NIM_HOSTNAME=vlpar3_p5
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=nimmast
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="shell"
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS=" 10.1.1.70:vlpar3_p5  10.1.1.22:nimmast ">
export NIM_MOUNTS=""
export ROUTES=" default:0:10.1.1.1 "
```

**Removing old names from name resolution**

At this point the old names can be removed from the name resolution. Example 5-112 shows the content of the /etc/hosts file on the NIM master after removing the old name.

**Example 5-112  /etc/hosts on the NIM master**

```
(root@lpar2):/ # cat /etc/hosts
...........
10.1.1.22  nimmast
...........
```

Example 5-113 shows the content of the /etc/hosts file on the NIM client after removing the old name.

**Example 5-113  /etc/hosts on the NIM client**

```
# cat /etc/hosts
...........
10.1.1.22  nimmast
...........
```

**5.10.5 Changing the NIM master IP address**

**Important:** Perform a NIM DB backup before changing NIM master object attributes.
To change the IP address for the NIM master, follow these steps. They are explained in more detail throughout the section.

1. Change the IP address for the NIM master.
2. Update name resolution (for the NIM master and the NIM clients).
3. Update the NIM networks object.
   a. Remove all client NIM objects.
   b. Recover the NIM master.
   c. Remove old NIM networks object and rename the new one.
   d. Check for new NIM networks.
   e. Recreate the NIM clients.

**Scenario**
Here we are using three machines. One machine is configured as a NIM master, and the second machine is configured as a NIM client. The third machine is configured as a gateway, routing network traffic through different network subnets.

Initially, the NIM master and the NIM client are on the same subnet. In this example we are moving the NIM master to other subnet and showing how to reconfigure the NIM environment to reflect the new environment.

Figure 5-7 on page 550 shows the initial and the final stages of the environment, when changing the IP address for the NIM master to a new IP address on a different subnet than the NIM client’s subnet.
Changing the IP address for the NIM master
At this stage the NIM master IP is changed. The actual IP is 10.1.1.22 using 255.255.255.0 for the network mask. We change the IP to 10.1.2.22 for the NIM master. The NIM client remains on the 10.1.1 subnet, using the 10.1.1.70 IP address.

For more detailed information about how to change the IP address, refer to *AIX 5L Version 5.3 System Management Guide: Networks and Communications Management*, SC23-5203.

Updating the name resolution
The name resolution must be updated for the NIM server and the NIM client. There is no need to keep the old names for this procedure.
Updating the NIM networks object

We need to reflect the IP address change to the NIM database. To reflect the change, we need to remove all the NIM clients objects and recover the NIM master using a NIM method. This method creates a new NIM network object. The old NIM network object must be removed, and the new one is renamed to the old NIM network object.

Removing all client NIM objects

In this example we only have one client, which is named VLPAR3_p5 as seen in Example 5-114. The master machine shown in Example 5-114 is the NIM master itself.

Example 5-114   List of clients

```
(root@lpar2):/ # lsnim -c machines
master       machines       master
VLPAR3_p5    machines       standalone
```

Now we proceed to delete the client, as shown in Example 5-115.

Example 5-115   Client removal

```
(root@lpar2):/ # nim -o remove VLPAR3_p5
```

Example 5-116 shows that the client is removed.

Example 5-116   List of NIM machines

```
(root@lpar2):/ # lsnim -c machines
master       machines       master
```

In Example 5-117, we can see the NIM attributes for the master machine.

Example 5-117   Master properties

```
(root@lpar2):/ # lsnim -l master
master:
  class               = machines
  type                = master
  max_nimesis_threads = 20
  if_defined          = chrp.mp.ent
  comments            = machine which controls the NIM environment
  platform            = chrp
  netboot_kernel      = mp
  if1                 = NET_EN1 lpar2 00096B4EAD9C
  cable_type1         = N/A
  Cstate              = ready for a NIM operation
  prev_state          = ready for a NIM operation
```
Example 5-118 shows the properties for the NIM network object named NET_EN1.

**Example 5-118  NIM network object attributes**

```
(root@lpar2):/ # lsnim -l NET_EN1
NET_EN1:
  class      = networks
  type       = ent
  comments   = Generated during definition of lpar2
  Nstate     = ready for use
  prev_state = ready for use
  net_addr   = 10.1.1.0
  snm        = 255.255.255.0
  routing1   = default 10.1.1.1
```

There is only one NIM network object for this NIM environment. The next stage is to recover the NIM master.

**Recovering the NIM master**

To recover the NIM master, we use a NIM method. NIM methods are located under /usr/lpp/bos.sysmgt/nim/methods. The method that we use to recover the NIM master is the `nim_master_recover`.

The network interface is given to the method as a parameter. This method creates a new NIM network object named ent-Network1 with the new network address. Example 5-119 shows the execution of the method.

**Example 5-119  NIM master recovery**

```
(root@lpar2):/ # /usr/lpp/bos.sysmgt/nim/methods/nim_master_recover -i en1 -S
error retrieving nim name, defaulting to host name.
Updating master definition
  Updated master attribute platform to chrp
  Updated master attribute netboot_kernel to mp
  Updated master attribute if1 to ent-Network1 lpar2 00096B4EAD9C
  Updated master attribute cable_type1 to N/A
```
Updated ent-Network1 routing1 to default 10.1.2.1
Finished updating master definition
Resetting machines
  Reset master
Finished resetting machines
Resetting NIM resources
Finished resetting NIM resources
Checking NIM resources
Keeping LPP_PRUEBA
  Keeping SEC_ADAPTR
Finished checking NIM resources
nim_master_recover Complete

Example 5-120 shows that a new NIM network object named ent-Network1 is created.

Example 5-120  NIM network objects

(root@lpar2):/ # lsnim -c networks
ent-Network1     networks       ent
NET_EN1          networks       ent

Example 5-121 shows the attributes for the ent-Network1 NIM network object. Information for the new IP address is added to the ent-Network1 NIM network object.

Example 5-121  NIM network object attributes

(root@lpar2):/ # lsnim -l ent-Network1
ent-Network1:                          
  class      = networks
  type       = ent
  comments   = Generated during definition of lpar2
  Nstate     = ready for use
  prev_state = ready for use
  net_addr   = 10.1.2.0
  snm        = 255.255.255.0
  routing1   = default 10.1.2.1

Note: If the new IP address is configured on the same subnet as the old one, there is no need to create a new NIM network object. The nim_master_recover method does not create a new NIM network object; instead, it updates the old NIM network object.

Example 5-122 on page 554 shows the attributes for the NIM master. The if1 attribute is changed to the NIM network object generated through the nim_master_recover method.
Example 5-122  NIM master attributes

```
(root@lpar2):/ # lsnim -l master
master:
  class       = machines
  type        = master
  max_nimesis_threads = 20
  if_defined  = chrp.mp.ent
  comments    = machine which controls the NIM environment
  platform    = chrp
  netboot_kernel = mp
  if1         = ent-Network1 lpar2 00096B4EAD9C
  cable_type1 = N/A
  Cstate      = ready for a NIM operation
  prev_state  = ready for a NIM operation
  Mstate      = currently running
  serves      = LPP_PRUEBA
  serves      = SEC_ADAPTR
  serves      = boot
  serves      = nim_script
  master_port = 1058
  registration_port = 1059
  reserved    = yes
  ssl_support = yes
```

Removing the old NIM network object and renaming the new object

The ent-Network1 NIM network object has the information for the new IP address. The NIM network object keeping information about the old IP address must be removed, and the ent-Network1 NIM network objects must be renamed to the original NIM network object.

In our scenario, we have two NIM network objects:

- NET_EN1, which contains information about the old IP address and network
- ent-Network1, which is generated through nim_master_recover and contains information about the new IP address and network

Example 5-123 shows the defined NIM network objects.

Example 5-123  NIM network objects

```
(root@lpar2):/ # lsnim -c networks
ent-Network1     networks       ent
NET_EN1          networks       ent
```

Example 5-124 on page 555 illustrates the removal of the NET_EN1 NIM network object. The nim command is used to remove the NIM network object.
**Example 5-124  NET_EN1 removal**

(root@lpar2):/ # nim -o remove NET_EN1

The only NIM network object defined in the NIM master is the one created through the `nim_master_recover` method, as shown in Example 5-125.

**Example 5-125  NIM network objects**

(root@lpar2):/ # lsnim -c networks
ent-Network1     networks       ent

The next step is to rename, using the `nim` command, the ent-Network1 NIM network object to the original NIM network object named NET_EN1. This step is shown in Example 5-126.

**Example 5-126  Renaming the NIM network object**

(root@lpar2):/ # nim -o change -a new_name=NET_EN1 ent-Network1

Example 5-127 shows how the name change is reflected to the NIM master attributes. The if1 attribute is changed to reflect the new name for the NIM network object.

**Example 5-127  NIM master attributes**

(root@lpar2):/ # lsnim -l master
master:
class               = machines
type                = master
max_nimesis_threads = 20
if_defined          = chrp.mp.ent
comments            = machine which controls the NIM environment
platform            = chrp
netboot_kernel      = mp
if1                 = NET_EN1 lpar2 00096B4EAD9C
cable_type1         = N/A
Cstate              = ready for a NIM operation
prev_state          = ready for a NIM operation
Mstate              = currently running
serves              = LPP_PRUEBA
serves              = SEC_ADAPTR
serves              = boot
serves              = nim_script
master_port         = 1058
registration_port   = 1059
reserved            = yes
ssl_support         = yes
**Checking for new NIM networks**

The NIM master and NIM client are now in different subnets. The NIM master needs information about how to communicate to the NIM client, so we must define a new NIM network.

An additional NIM network can be defined by the NIM administrator, or it can be added automatically when defining the client.

In our scenario, we need an additional network to allow the client (which is in the 10.1.1 subnet) to communicate with the NIM server (which is in the 10.1.2 subnet). Here we illustrate two ways of creating the new NIM network object: manually, or automatically.

To create a NIM network object manually, follow these steps:
1. Type the `smitty nim_net` fastpath on the NIM server.
2. Select **Define a Network** from the SMIT menu.
3. Select the network type.
4. Complete the values required to define the NIM network.

Example 5-128 shows the SMIT panel and the values entered to define the proper network, in order to allow communication between the NIM server and the NIM client.

**Example 5-128  NIM network creation**

<table>
<thead>
<tr>
<th>* Network Name</th>
<th>[NET_EN2]</th>
</tr>
</thead>
<tbody>
<tr>
<td>* Network Type</td>
<td>ent</td>
</tr>
<tr>
<td>* Ethernet Type</td>
<td>Standard +</td>
</tr>
<tr>
<td>* Network IP Address</td>
<td>[10.1.1.0]</td>
</tr>
<tr>
<td>* Subnetmask</td>
<td>[255.255.255.0]</td>
</tr>
<tr>
<td>Default Gateway for this Network</td>
<td>[10.1.1.12]</td>
</tr>
<tr>
<td>Other Network Type</td>
<td>+</td>
</tr>
<tr>
<td>Comments</td>
<td>[]</td>
</tr>
</tbody>
</table>

Another option is to create the client from the master and fill the required values to automatically create the NIM network needed to communicate the NIM master with the NIM client.

To create a NIM client object and automatically the NIM network object, follow these steps:
1. Type the `smitty nim_mkmac` fastpath on the NIM master.
2. Enter the hostname for the NIM client.
3. Select the network type.
4. Select the proper values for the network.

Example 5-129 shows the SMIT panel and values entered to define the NIM client, along with the NIM network object. In this example, the VLPAR3_p5 NIM client object and the NET_EN2 network object are created.

```
Example 5-129   SMIT panel to define the NIM client and NIM network object

* NIM Machine Name                                   [VLPAR3_p5]
* Machine Type                                       [standalone]            +
* Hardware Platform Type                             [chrp]                  +
  Kernel to use for Network Boot                     [mp]                    +
  Communication Protocol used by client              []                      +
  Primary Network Install Interface
    * Cable Type                                        bnc                    +
    Network Speed Setting                            []                      +
    Network Duplex Setting                           []                      +
  NIM Network                                        [NET_EN2]
    * Network Type                                    ent              +
    * Ethernet Type                                   Standard               +
    Subnetmask                                        [255.255.255.0]
    Default Gateway Used by Machine                  [10.1.1.12]           +
    Default Gateway Used by Master                    [10.1.2.1]           +
    Host Name                                         vlpar3_p5
    Network Adapter Hardware Address                 [0]
    Network Adapter Logical Device Name              []                      +
    IPL ROM Emulation Device                         []                      +/
    CPU Id                                             []                      +
    Machine Group                                      []                      +
    Comments                                           []                      +
```

Recreating the NIM clients
The NIM clients must be recreated. For information about how to recreate the NIM clients, refer to “Defining NIM clients” on page 79.

Rebuilding the /etc/niminfo file on the NIM clients
The /etc/niminfo file on the NIM clients must be rebuilt.
Cluster Systems Management and Network Installation Manager

This chapter provides a general description of Cluster Systems Management (CSM). It also explains how CSM uses Network Installation Manager (NIM) to perform its node installation.

For more detailed information about CSM you can refer to CSM documentation, which is available at the following site:


The chapter covers the following topics:

- Overview of CSM
- The management server (MS)
- NIM and CSM - how NIM operates in a CSM environment
6.1 Overview of Cluster Systems Management

A *cluster* is a set of two or more networked connected computers. A specific system management tool is required to manage this set of computers. This was formerly the role of Parallel Systems Support Programs (PSSP), which has been replaced by Cluster Systems Management (CSM).

As previously mentioned, NIM can perform the installation, maintenance, updating and backup tasks for the participants in the cluster. The basic challenges of CSM are to monitor, remotely access, and diagnose the problems that can arise during installation and maintenance of the operating systems on the machines in the cluster.

Figure 6-1 shows the CSM cluster environment.

![Figure 6-1 CSM cluster overview](image)

### 6.1.1 The management server

The management server (MS) is a specific machine running AIX 5L and CSM server code. Although providing a detailed explanation about how to configure
CSM is beyond the scope of this book, the basic steps involved in how an AIX 5L machine becomes a management servers are listed here:

**Step 1: Choosing the MS machine**
Among the AIX running machines, choosing the one that is going to become the management server (MS) is not difficult; you must know whether this machine will also be the NIM master. If it will be the NIM master, then refer to 2.3.1, “Choosing your NIM master” on page 45 for information related to the choice of a NIM master.

**Step 2: Run some checks on the AIX machine**
For instance, check the level of AIX, the level of the Reliable Scalable Clustering Technology (RSCT) product, the network configuration and so forth.

**Step 3: Install CSM package**
 Basically, the CSM client is automatically installed with AIX, thus the AIX machine is cluster-ready as a managed node. However, you will need to install the CSM server code. A license is required in order to use this product. A 60-day trial licence is included in the AIX 5L package. After this period, a license fee is required.

**Step 4: Configure the CSM cluster**
 Using several CSM tools, information related to the nodes are gathered to populate the CSM database.

**Step 5: Check the CSM cluster data**
 By running some CSM commands, verify whether the content of the CSM database is what has been planned.

**Step 6: Work with CSM**
 Using the CSM tools, you can install the nodes with NIM, and control and manage the AIX 5L cluster nodes with CSM.

**The nodes**
The nodes are the other managed machines in the cluster. AIX may or may not have already been installed on these nodes. If AIX has already been installed, a minimum CSM layer is necessary to join the cluster.

If AIX has not already been installed, then it first needs to be installed. Then the CSM layer has to be configured to have the node join the CSM cluster.

Note that the AIX installation (from a mksysb or from filesets) is not the responsibility of CSM: it is the role of NIM. CSM is not designed to install or maintain a machine. CSM can help NIM to fill the client definitions of the
machines objects after the NIM master configuration has been made and the resources created.

Another characteristic of a CSM cluster is that the management server is an AIX machine. However, you can have a mix of AIX 5L nodes and Linux nodes. In this case, the MS can control and monitor the Linux nodes only if Linux is already installed.

At the time of writing there are no defined procedures to use NIM to automatically install Linux on machines except for some manual operations, as detailed in 4.2, “Using the OS_install command” on page 137.

6.1.2 NIM and CSM

PSSP provides the setup_server tool to set up the NIM environment (from the NIM configuration to the different NIM operations, such as installation or migration of a node).

In CSM, however, there is no tool or script to perform these steps. Thus, the cluster administrator must separately build the CSM cluster and the NIM environment. For more details about how to set up a CSM cluster, refer to the CSM documentation:


Basically, the different machines making up the cluster are seen as nodes for CSM and clients for NIM. These machines are the same, and the majority of their characteristics are similar in both the CSM and NIM databases.

To save time in building the NIM database, particularly when defining the clients, there is a tool part of the CSM package that allows system administrators to get node information from the CSM database and put the related client NIM information into the NIM database. In fact, two commands are available: one for managing individual nodes (csm2nimnodes) and one for machine groups (sm2nimgrps).

Figure 6-2 on page 563 gives an overview of the relationship between the two databases: CSM registry and NIM ODM classes.
As shown in Figure 6-2, the `csm2nimnodes` and `csm2nimgrps` commands link the CSM database to the NIM database, although each program has its particular set of tools for node creation, modification, or removal.

The `csmsetupnim` command performs tasks on both databases which ensure that the node will automatically be part of the cluster, for management purposes, when the installation completes.
Basic NIM problem determination and tuning

This chapter describes basic NIM problem determination, solutions for network boot problems, and procedures for producing debug output for NIM base operating system (BOS) installations.

It also discusses the approach that is used to identify and correct problems involved with NIM operations. It covers the following topics:

- Troubleshooting methodologies
- LEDs
- Network File System (NFS) usage
- Booting issues
- Log files
- Case study: NIM server performance
- Multi-threaded NIM nimesis daemon
7.1 Troubleshooting methodologies

First, we describe an approach to manage NIM troubleshooting. NIM bases its operations on two major components: the network and the operating system. Troubleshooting NIM consists of identifying the cause of the problem, and then determining whether it is a NIM-related problem, a network-related problem, or an AIX problem.

Tip: After you identify the component that is causing the problem, you can correct the problem by executing the appropriate action. Keep in mind, however, that with any troubleshooting methodology, often the simplest solution is all that is needed. So be sure to examine the basics before delving into the more complex reasons behind an issue.

For instance, if you cannot ping a NIM client, first verify that the network cable is connected before examining icmp packets with tcpdump. This “back to basics” approach can often speed up problem resolution.

There are several operations that are performed by NIM through all its functions. Network boot, for example, covers many of the operations performed by NIM. In the following section we describe troubleshooting a network boot problem. The troubleshooting procedure is illustrated through the flowcharts presented here.

7.1.1 Troubleshooting a network boot problem

In this scenario, we work with two machines. One machine is configured as a NIM master/server and the other is configured as a NIM client.

The client has been booted to the SMS menu to configure a network install boot operation in order to install the client. Remote IPL values have been entered in the client SMS configuration.

On the master side, lpp_source and Shared Product Object Tree (SPOT) resources have been allocated to the client and a network install operation has been initiated. A problem has been detected while performing the network boot, and the client is unable to boot from the server.

We follow the flowchart illustrated in Figure 7-1 on page 567 to solve the problem presented in this scenario.
Network communications

As a starting point, we try to determine whether IP communication between machines can be established (client and server). To do this, we perform a ping test from the client's SMS menu, trying to ping our NIM master as shown in Example 7-1.

Example 7-1  SMS ping menu

Version SF240_202
SMS 1.6 (c) Copyright IBM Corp. 2000,2005 All rights reserved.

Ping Test
Interpartition Logical LAN: U9111.520.65C544E-V8-C3-T1
Speed, Duplex: auto,auto
Client IP Address: 10.1.1.70
Server IP Address: 10.1.1.1
Gateway IP Address: 000.000.000.000
Subnet Mask: 255.255.255.000
Spanning Tree Enabled: 1
Connector Type: none

1. Execute Ping Test

If the ping test fails, we verify that the client, server, gateway addresses and network mask are specified correctly. We also verify that the adapter configuration (network speed setting and duplex) are specified correctly.

If all settings are correct, we try to ping the server from another machine. We try to ping another machine from the client in an attempt to separate a network problem on the client from a network problem on the server.

If the server can be pinged from another machine, or if other machines cannot be pinged from the client, it may mean that the network adapter on the boot client is faulty, or that there is a problem with the switch port, the cables or the VLAN.

Obtaining the boot image from the server
At this point we have verified the communication between the NIM master/server and the NIM client. The next stage in the network install operation is obtaining the boot image from the server. When a network boot is initiated on a client, a bootp request packet is sent from the client to the server. The server then replies with a packet to the client, specifying the image to be loaded by the client. The client machine displays the number of packets sent and received for the bootp request, as shown in Example 7-2.

Example 7-2  BOOTP request success

| BOOTP R = 1 | BOOTP S = 2 |

If a packet is sent from the client, but none is received, another packet will be sent. Example 7-3 on page 569 shows the output for a system that is not able to obtain a response packet from the server.
Example 7-3  BOOTP request failure

BOOTP: BOOTP request fail: 0

If bootp packets continue to be sent but no response is received, the boot server may not be responding to the request. Verify that the correct entry exists in the /etc/bootptab file on the server for the selected client.

The /etc/bootptab file contains entries, one for each client ready to perform a network boot operation, with the following information:

- hostname_of_client
- bf=boot_file
- ip=client_ip_address
- ht=network_type
- sa=boot_server_address
- sm=client_subnet_mask
- ha=network_adapter_hardware_address (required only if bootp requests are sent by broadcasting)

These entries are created at the moment that NIM configures the client machine for the operation. Example 7-4 shows the content for the /etc/bootptab file in our environment.

Example 7-4  The /etc/bootptab content

VLPAR3_p5:bf=/tftpboot/VLPAR3_p5:ip=10.1.1.70:ht=ethernet:sa=10.1.1.1:sm=255.255.255.0:

If an entry does not exist, it means that either the NIM command used to set up the current operation failed, or the machine was reset before the boot operation could occur. In this case we can rerun the NIM bos_inst, diag, or maint_boot operation to prepare the server for the client boot request.

If the entry exists in /etc/bootptab, we verify that the specified data is correct. If a field contains incorrect data, the information that was used to define the machine or network in the NIM database was probably incorrect. We can correct this problem by performing a NIM reset operation on the client machine, correcting the invalid data in the client or network definition, retrying the NIM operation, and rebooting the client.

Verifying inetd

If the /etc/bootptab file is correct, we proceed to troubleshooting inetd by following the flowchart illustrated in Figure 7-2.
We verify that the inetd daemon is running, as shown in Example 7-5. If it is not running, we start it and retry the network boot from the client. If the inetd daemon is running, it should automatically start the bootpd daemon when the bootp request is received at the server.

Example 7-5  The inetd status verification

<table>
<thead>
<tr>
<th>Subsystem</th>
<th>Group</th>
<th>PID</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>inetd</td>
<td>tcpip</td>
<td>102520</td>
<td>active</td>
</tr>
</tbody>
</table>

If the bootpd daemon is not started, we verify that the bootps entry in the /etc/inetd.conf file is not commented out. If it is commented out, we uncomment it.
and restart inetd with the `refresh -s inetd` command. Then we retry the network boot from the client.

The `/etc/inetd.conf` file should contain a line similar to the one shown in Example 7-6.

**Example 7-6** The `bootps` entry

```
# cat /etc/inetd.conf
........
bootps dgram udp wait root /usr/sbin/bootpd bootpd /etc/bootptab
........
```

If a bootp reply is still not received at the client, we manually start the bootpd daemon in debug mode. To manually start the bootpd daemon in debug mode we follow these steps:

1. Comment out the `bootps` entry from the `/etc/inetd.conf` file on the server.
2. Stop all running bootpd processes.
3. Restart inetd using the `refresh -s inetd` command.
4. Start bootpd from the command line, using the following command:

   ```
   /usr/sbin/bootpd -s -d -d -d
   ```

We then retry the network boot from the client. If no output is displayed from the running `bootpd` command, it means that the client bootp request is not reaching the server.

Example 7-7 shows the output of the `bootpd` command running on the server in debug mode at the moment of receiving a bootpd request.

**Example 7-7** `Bootpd` output

```
# /usr/sbin/bootpd -s -d -d -d
BOOTPD: bootptab mtime is Mon Jun 19 14:41:44 2006
BOOTPD: reading "/etc/bootptab"
BOOTPD: read 1 entries from "/etc/bootptab"
BOOTPD: dumped 1 entries to "/etc/bootpd.dump".
BOOTPD: bootptab mtime is Mon Jun 19 14:47:36 2006
BOOTPD: reading new "/etc/bootptab"
BOOTPD: read 1 entries from "/etc/bootptab"
BOOTPD: Received boot request.
BOOTPD: request from IP addr 10.1.1.70
BOOTPD: found 10.1.1.70 VLPAR3_p5
BOOTPD: bootstrap = /tftpboot/VLPAR3_p5
BOOTPD: vendor magic field is 99.130.83.99
BOOTPD: RFC1048 vendor data ( bp_vend[64] )
```
If the server receives the client bootp request, the running `bootpd` command displays output matching the client data in the `/etc/bootptab` file. We verify that the specified addresses are correct. This information is sent back to the client in the bootp reply.

If the client is still not receiving the bootp reply, we perform network debugging procedures to determine why the reply packet is not reaching the client.

**Verifying tftp**

After the client receives the bootp reply, the next stage is transferring the boot image to the client. At this stage the boot image is transferred from the server to the client through `tftp`.

The boot image is located in the server under the `/tftpboot` directory as a link to the file containing the boot image. The name of the link is the same as the name of the client machine. Under this directory there is also another file related to the operation, which name is the name of the client machine plus `.info`. It stores configuration information used by the Network Install Manager (NIM). This file and the link to the boot image are created at the moment when the client machine is configured for the operation.

Example 7-8 shows the content of the `/tftpboot` directory.

```
Example 7-8   The tftpboot directory content

# ls -l /tftpboot
total 120624
........
-rw-r--r-- 1 root system 12211712 Jun 19 16:24 SPOT_53_ML4.chrp.mp.ent
lrwxrwxrwx 1 root system 33 Jun 19 16:42 VLPAR3_p5 ->
/tftpboot/SPOT_53_ML4.chrp.mp.ent
-rw-r--r-- 1 root system 1066 Jun 19 16:42 VLPAR3_p5.info
........
```

Example 7-9 on page 573 shows the content of the `.info` file.
Example 7-9  The .info file content

```bash
# cat VLPAR3_p5.info
#
#------------------ Network Install Manager ---------------
# warning - this file contains NIM configuration information
#     and should only be updated by NIM
export NIM_NAME=VLPAR3_p5
export NIM_HOSTNAME=VLPAR3_p5
export NIM_CONFIGURATION=standalone
export NIM_MASTER_HOSTNAME=nimmast
export NIM_MASTER_PORT=1058
export NIM_REGISTRATION_PORT=1059
export NIM_SHELL="nimsh"
export NIM_MASTERID=0061703A4C00
export NIM_LICENSE_ACCEPT=yes
export RC_CONFIG=rc.bos_inst
export NIM_BOSINST_ENV="/..SPOT/usr/lpp/bos.sysmgt/nim/methods/c_bosinst_env"
export NIM_BOSINST_RECOVER="/..SPOT/usr/lpp/bos.sysmgt/nim/methods/c_bosinst_env -a
hostname=VLPAR
3_p5"
export SPOT=nimmast:/AIX53ML4/SPOT_53_ML4/usr
export NIM_CUSTOM="/..SPOT/usr/lpp/bos.sysmgt/nim/methods/c_script -a
location=nimmast:/export/nim
/scripts/VLPAR3_p5.script"
export NIM_BOS_IMAGE=/SPOT/usr/sys/inst.images/installp/ppc/bos
export NIM_BOS_FORMAT=rte
export NIM_HOSTS=" 10.1.1.70:VLPAR3_p5  10.1.1.1:nimmast 
"export NIM_MOUNTS=" nimmast:/AIX53ML4/LPP_53_ML4:/SPOT/usr/sys/inst.images:dir 
"
```

Figure 7-3 on page 574 shows the flowchart used for troubleshooting tftp.
Figure 7-3  Troubleshooting tftp

The number of tftp packets transferred to the client will be displayed at the client machine as shown in Example 7-10.

**Example 7-10  The tftp packet count**

<table>
<thead>
<tr>
<th>FILE: /tftpboot/VLPAR3_p5</th>
<th>FINAL Packet Count = 23852</th>
</tr>
</thead>
<tbody>
<tr>
<td>FINAL File Size = 12211712 bytes.</td>
<td></td>
</tr>
</tbody>
</table>

When the LED displays 299 (or, on the machines of other platforms, when the bottom third of the screen turns gray), it means that the boot image has been successfully retrieved at the client machine.
If the tftp of the boot image does not complete successfully, it means that the client may be trying to get the wrong boot image. We verify that the client definition in the NIM database shows the correct platform and kernel type. If the data is incorrect then we correct it, reset the client machine, rerun the NIM operation, and reboot the client over the network.

We verify that the /tftpboot directory on the boot server contains a link with the client name to the correct boot image. If the link does not exist, we reset the client machine, rerun the NIM operation, and reboot the client over the network.

The response for the tftp server and the NIM server can also be tested from another machine by using the `tftp` command. Using this command, we can retrieve information about the content of the tftpboot directory on the server, testing the response of the tftp server.

Example 7-11 shows the execution of the `tftp -g - <tftp_server_name> /tftpboot` command.

Example 7-11  A tftp server test

```bash
# tftp -g - nimmast /tftpboot
...SPOT_53_ML4.chspotaix5204.chspotaix5104.chSPOT_PRUEBA.chAIX53_ML04_debSPOT-VIO.chrp.spotaix5205.chrp.mp.ent SPOT_53_ML4.chrp.mp.ent SPOT_PRUEBA.chrp.mp.ent spotaix5104.chrp.mp.ent spotaix5204.chrp.mp.ent spotaix5205.chrp.mp.ent
```

We get a list of the contents of the directory when we execute `echo *` for the /tftpboot directory on the server, as shown in Example 7-12.

Example 7-12  Directory listing on the server

```bash
{nimmast}:/tftpboot # echo *
AIX53_ML04_debug.chrp.mp.ent SPOT-VIO.chrp.mp.ent SPOT_53_ML4.chrp.mp.ent SPOT_PRUEBA.chrp.mp.ent spotaix5104.chrp.mp.ent spotaix5204.chrp.mp.ent spotaix5205.chrp.mp.ent
```

If the link with the client name is pointing to the correct boot image but the tftp of the boot image does not complete successfully, it means that the boot image may be corrupted. We recreate the boot image by performing a NIM check operation with the force flag on the SPOT. We also verify that the client has the latest version of the firmware installed.

**Note:** The final file size value shown by the tftp transfer must be the same as the size of the boot image file, as displayed in Example 7-8 on page 572 and Example 7-10 on page 574.
We also check that the duplex settings for the network adapters in the server and the client are correct, and that the switch ports where they are connected are correct. If one of the duplex settings for the adapters is incorrectly set, bootp may work but tftp may develop problems when transferring the boot image. Note that tftp may also fail due to an MTU size mismatch between the NIM master network and the NIM client network.

### 7.1.2 Debugging NIM BOS installations

Clients may fail to boot or install properly because of problems in the network or in the NIM configuration. If this happens, it may be necessary to obtain debug information to determine the cause of the problem.

For further information regarding debugging NIM BOS installations, refer to the section “Obtaining debug output for NIM BOS Installations” in *AIX 5L V5.3 Installation and Migration, SC23-4887*.

### 7.1.3 Recreating the SPOT from an existing directory

Rebuilding the NIM database during system recovery implies defining a SPOT. Defining a SPOT may be a lengthy process if you are using the install media (CD). However, if the NIM database was lost and the files for the previously-defined SPOT are valid, you can use this operation to recreate the SPOT, thus avoiding the need for a fresh build.

After redefining the NIM master, one of the NIM methods is used to recreate the SPOT. The method is /usr/lpp/bos.sysmgmt/nim/methods/m_mkspot. The server name, the SPOT location, and the SPOT name must be given to the method.

Example 7-13 shows the recreation of the SPOT that is named SPOT_TEST, located in the /SPOT_TEST directory, in the server named master. Note the selected option `source=no` for the method. This option tells the method not to rebuild the files again.

**Example 7-13 Re-creating an SPOT**

```bash
{nimmast}:/ # lsnim -l SPOT_TEST
0042-053 lsnim: there is no NIM object named "SPOT_TEST"
{nimmast}:/ # ls -l /SPOT_TEST/SPOT_TEST
     total 72
-r-xr-xr-x   1 root     system         5670 Jun 14 2005     bosinst.data
-r-xr-xr-x   1 root     system        14262 Jun 08 2005     image.data
-r-xr-xr-x   1 root     system         5173 Aug 26 2005     lpp_name
  drwxr-xr-x  24 bin      bin            4096 Jun 22 16:56     usr
{nimmast}:/ # /usr/lpp/bos.sysmgmt/nim/methods/m_mkspot -o -a server=master -a location=/SPOT_TEST -a source=no SPOT_TEST
```
As you can see in Example 7-13 on page 576, there was no SPOT in the NIM environment (shown on the first `lsnim` command execution), although the files that used to belong to an SPOT are still there (shown on the `ls` command execution). After using the method execution to recreate the SPOT, we verify that the SPOT has been created by executing the `lsnim` command.

### 7.2 LEDs

If your system has an LED display, the three-digit LED shows values during NIM operations. These values are useful to understand which stage of the operation is being performed and, if the operation fails, in which stage the failure occurred. In the following section we list the values for the three-digit LED output.

#### 7.2.1 LED values during NIM operations

In the following list, the values shown at the first level of indentation are the normal values displayed during normal performance of the operations. The values shown at the second level are failure indicators.

---

Note: If resources have been deleted using NIM commands, they cannot be recovered without recreating them.
The values are presented in the order in which they are displayed in the three-digit LED:

- 299 Boot image successfully received at the NIM client.
- 600 Starting network boot (portion of /sbin/rc.boot).
- 602 Configuring network parent devices.
  - 603 Script defsys, cfgsys, or cfgbus located in /usr/lib/methods/ failed.
- 604 Configuring physical network boot device.
  - 605 Configuration physical network boot device failed.
- 606 Running /usr/sbin/ifconfig on logical network boot devices.
  - 607 /usr/sbin/ifconfig failed.
- 608 Attempting to retrieve the client.info file with tftp from the SPOT server.
  - 609 The client.info file does not exist or could not be accessed, or it is zero length.
- 610 Attempting to mount a remote file system using NFS.
  - 611 The client is unable to mount a remote file system (NIM resource) using NFS.
- 612 Accessing remote files. Unconfiguring network boot devices.
  - 613 The route command failed.
- 614 Configuration of logical paging devices.
  - 615 Configuration of logical paging device failed.
- 616 Converting from diskless to dataless configuration.
  - 617 Diskless to dataless configuration failed.
- 618 Configuring remote (NFS) paging device.
  - 619 Configuration of remote (NFS) paging space failed.
- 620 Updating special device files and ODM in permanent file system.
- 622 Control returned to the /sbin/rc.boot program.
  - 623 The BOS installation program has encountered a fatal error.
- 624 Control passed to the BOS installation Program.
- c40 Extracting data files from media.
- c42 Extracting data files from diskette.
- c44 Initializing install data base with target disk information.
- c46 Normal install processing.
- c48 Prompting user for input.
- c50 Creating root volume group on target disks.
- c52 Changing from RAM environment to disk environment.
- c54 Installing either BOS or additional packages.
- c56 Running user-defined customization.
- c58 Displaying message to turn key.
  - c41 Could not determine boot type or device.
  - c43 Could not access boot/install tape.
  - c45 Cannot configure console.
  - c47 Could not create pvid on disk.
  - c49 Could not create or form the jfs log.
  - c51 No paging devices found.
  - c53 Not enough space in /tmp to do preservation install.
  - c55 Could not remove the specified logical volume in a preservation install.
  - c57 Failure to restore BOS.
  - c59 Could not copy either device special files, device ODM, or vg information from RAM to disk.
  - c61 Failed to create boot image. Ensure enough space in /tmp.

Using the values displayed in the three-digit LED, you can determine which operation failed and perform the proper actions to solve the problem.

Some of the most common errors encountered after the client machine has successfully received the boot image from the server are hangs with the LED displaying the values 608, 611, or 613. We examine these problems in more detail in the following sections.

608 - tftp retrieve of client info file failure

If a 608 hang is encountered, we verify that the ClientName.info file exists in the /tftpboot directory. If it does not exist, we retry the NIM operation to create it. If it does exist, we verify that tftp access to the /tftpboot directory is not restricted in the /etc/tftpaccess.ctl file.

It is also possible that the network adapter was not configured properly in the boot environment. In this case, we use debug-enabled network boot images to look for errors in the boot environment.
611 - Remote mount of NFS file system failure
LED 611 hangs occur when the client machine is unable to mount a resource from the NIM master/resource server. First ensure that NFS is running on the master/resource server. We verify that the resources specified for the operation are exported properly by checking the /etc/exports and /etc/xtab files on the server. Also, we confirm that the resources have permissions set correctly for reading. Debug-enabled network boot images can also be used to determine exactly which mount command is failing on the client. We can also check the value of the nfso server portcheck option and usage of NFS reserved ports.

For further information about the use of NFS reserved ports and the nfso server portcheck option, refer to 5.3.9, “NFS reserved ports” on page 441.

613 - Failure setting up route tables
613 hangs usually occur because a route is incorrectly defined for a network in the NIM database. We verify that the correct gateways are specified between networks, and all gateways are functional. We use debug-enabled network boot images to determine which routes could not be defined.

7.2.2 Hang on LED 611 - NFS mount problem
In this case, during bootup, the system hangs on LED 611. This may result from a shortened domain name. To show the exported lines for the lpp_source and spot, we execute:

```
# lsnim -Fl <client>
```

We ensure that every directory added to the exports list uses the fully qualified domain name (for example, client.xyz.com). A common problem is having just the term “client” in the fields HOSTS allowed root access and HOSTS & NETGROUPS allowed client access instead of the fully qualified domain name.

To verify if a fully qualified domain name is needed, we run:

```
# host <client>
```

The output should read <client>.xyz.com is <ip address>. Then we run:

```
# host <ip address>
```

If it returns <client>xyz.com is <ip address>, then we use the fully qualified domain name. The NIM master should be configured to use DNS in this case.
7.2.3 NIM installation hangs on LED 613

After initiating the rte installation, we look at the client.info file in the /tftpboot directory to see if there is an incorrect default route set there. If there is, we either remove the NIM default route or add the correct default route. (If both the client and the master are on the same network, you should not need any routes.)

To modify the client’s network route in NIM:

```
# nim -Fo reset <client>
# nim -o deallocate -a subclass=all <client>
# lsnim -l <client> ==> if1 = <client_net> <client_hostname> <mac_addr>
```

Look for `<client_net>` and make note of this name, for example:

```
if1            = NET2  LPAR7  22338000C003 ent
```

Then remove the route, run:

```
# smitty nim_rmroute
```

Select the client_net and select the route to remove.

To change the route, run:

```
# smitty nim_chroute
```

Select the `<client_net>` and change the route. After the route is changed, re-initiate the install.

7.3 Network File System (NFS) usage

When resources are allocated for use during NIM operations, they are NFS-exported to the client machines where the operations will be performed. If operations are performed simultaneously on many different clients, the /etc/exports and /etc/xtab files may become very large on the resource servers. This may cause size limits to be exceeded in the files, and it may also negatively affect NIM performance as the files are locked and modified for each resource allocation or deallocation.

The option to globally export the resources may be set in environments where administrators are not concerned about who has access to the NIM resources. This prevents repeated updates to the /etc/exports and /etc/xtab files. Setting global export of a NIM resource will make it readable by any machine in the network, not just those in the NIM environment. The resource will be globally exported as long as it is allocated to any client. When the resource is deallocated from all clients, it is unexported.
7.3.1 Exporting NIM resources globally

NIM resources can be exported globally using Web-Based System Manager, SMIT or the command line.

Using Web-Based System Manager
Follow these steps to enable global export of NIM resources using Web-Based System Manager:

- From the NIM menu, select **Advanced Configuration. Export NIM Resources Globally.**
- Use the dialog to complete the task.

Using SMIT
Follow these steps to enable global export of NIM resources using SMIT:

- Type the smit nim_global_export fastpath on the NIM Server.
- Select **enable** for the value: Enable/Disable Global Exporting of NIM Resources?

Example 7-14 shows the SMIT panel used when enabling global exports of NIM resources.

Example 7-14   Enabling global exports of NIM resources using SMIT

To disable global exports of NIM resources using SMIT, proceed as follows:

- Type the smit nim_global_export fastpath on the NIM Server.

**Note:** Resources that are used exclusively by diskless and dataless clients may not be globally exported.
Select **disable** for the value: Enable/Disable Global Exporting of NIM Resources?

**Using the command line**

To enable global exporting of NIM resources, set the attribute `global_export=yes` on the NIM master:

```
nim -o change -a global_export=yes master
```

Example 7-15 shows the output generated by the `nim` command when enabling global exports of NIM resources.

**Example 7-15   Enabling global exports of NIM resources using the command line**

```
{nimmast}:/# nim -o change -a global_export=yes master
{nimmast}:/# lsnim -l master
master:
   class       = machines
   type        = master
   max_nimesis_threads = 20
   if_defined    = chrp.mp.ent
   comments     = machine which controls the NIM environment - code:524288
   global_export = yes
   platform     = chrp
```

To disable global exporting of NIM resources, remove the `global_export` attribute from the master by setting it to no:

```
nim -o change -a global_export=no master
```

Example 7-16 shows the output from the `nim` command when disabling global exports of NIM resources.

**Example 7-16   Disabling global exports of NIM resources using the command line**

```
{nimmast}:/# nim -o change -a global_export=no master
{nimmast}:/# lsnim -l master | grep glob
{nimmast}:/#
```

Enabling or disabling global exports while there are resources allocated to clients could lead to situations where resources are exported with incorrect permissions. In order to change the `global_export` value, all NIM operations should be completed and resources deallocated. The `nim` command fails to change the `global_exports` value if resources are currently allocated to clients.
Checking global export of NIM resources enablement

The `lsnim` command can be used to check whether global export of NIM resources is enabled.

- The `global_export` value is set to yes if global export of NIM resources is enabled.
- It is not set if global export of NIM resources is disabled.

Example 7-17 shows the output for a NIM master where global export of NIM resources is enabled. Refer to Example 7-16 on page 583 to see how to check whether global export of NIM resources is disabled.

```
Example 7-17 lsnim output

{nimmast}:/{ # lsnim -l master
master:
  class = machines
  type = master
  max_nimesis_threads = 20
  if_defined = chrp.mp.ent
  comments = machine which controls the NIM environment - code:524288
  global_export = yes
  platform = chrp
  netboot_kernel = mp
```

Network performance is conditional on several factors that are beyond the scope of this publication. For further information regarding network tuning and NFS performance refer to *AIX 5L Practical Performance Tools and Tuning Guide*, SG24-6478, and *AIX 5L Version 5.3 Performance Management Guide*, SC23-4905.

### 7.4 Booting issues

This section explains how to troubleshoot a network boot problem.

#### 7.4.1 Booting

We explain all the stages of a network boot process in 7.1.1, “Troubleshooting a network boot problem” on page 566. When troubleshooting a NIM client that is having problems in some of these stages, you may need to check the packets exchange between the NIM master and NIM client. For that reason, here we take a look at the network traffic between a NIM master and a NIM client.
In this scenario we have two machines, one configured as a NIM master/server and the other configured as a NIM client. Both machines are in the same subnet. The NIM server is named lpar2, and the NIM client is named vlpar3_p5. The results for the following examples are taken on the NIM master by running the command:

```
(root@lpar2):/ # tcpdump -a 'host lpar2 and vlpar3_p5'
```

The `tcpdump` command with the arguments shown here extracts the traffic between the hosts lpar2 and vlpar3_p5.

**Pinging the NIM server**

In this example, we ping the NIM server from the NIM client SMS menu. The ping is successful, as shown in Example 7-18.

**Example 7-18 Successful ping to the NIM master**

<table>
<thead>
<tr>
<th>Time</th>
<th>Source</th>
<th>Destination</th>
<th>Protocol</th>
<th>Sequence</th>
<th>Length</th>
</tr>
</thead>
<tbody>
<tr>
<td>13:48:11.755361</td>
<td>arp who-has lpar2 tell vlpar3_p5</td>
<td>vlpar3_p5</td>
<td>arp</td>
<td></td>
<td>short</td>
</tr>
<tr>
<td>13:48:11.755376</td>
<td>arp reply lpar2 is-at</td>
<td>lpar2</td>
<td>arp</td>
<td></td>
<td>short</td>
</tr>
<tr>
<td>13:48:11.757767</td>
<td>IP vlpar3_p5 &gt; lpar2: icmp 12: echo request seq 22136</td>
<td>vlpar3_p5</td>
<td>ip</td>
<td>22136</td>
<td>12</td>
</tr>
</tbody>
</table>

In this example the packets are reaching the NIM server and the reply is sent by the NIM server.

However, if the ping on the SMS menu of the NIM client reports the ping as unsuccessful, there may be two possible reasons for this result:

- The packages are not reaching the NIM server, in which case the tcpdump does not show any output.
- The reply is sent by the NIM master but does not reach the NIM client, in which case we see the reply going out of the NIM server but the NIM client SMS menu shows an unsuccessful ping.

**Bootp**

Example 7-19 shows a successful exchange of packets between the NIM master and the NIM client during the bootp stage.

**Example 7-19 Successful bootp**

<table>
<thead>
<tr>
<th>Time</th>
<th>Source</th>
<th>Destination</th>
<th>Protocol</th>
<th>Sequence</th>
<th>Length</th>
</tr>
</thead>
<tbody>
<tr>
<td>14:35:52.162643</td>
<td>IP vlpar3_p5.bootpc &gt; lpar2.bootps: BOOTP/DHCP, Request from 22:33:80:00:80:03, length: 300</td>
<td>vlpar3_p5</td>
<td>ip</td>
<td>22136</td>
<td>12</td>
</tr>
<tr>
<td>14:35:52.174248</td>
<td>IP lpar2.bootps &gt; vlpar3_p5.bootpc: BOOTP/DHCP, Reply, length: 300</td>
<td>lpar2</td>
<td>ip</td>
<td>22136</td>
<td>12</td>
</tr>
</tbody>
</table>

Example 7-20 on page 586 shows the network traffic during an unsuccessful bootp. The packets reach the NIM master, but the reply is not sent by the NIM.
master to the NIM client. The problem to be resolved here is the response from
the bootp. Refer to “Obtaining the boot image from the server” on page 568 for
more information about resolving this problem.

Example 7-20  Bootp failure

13:54:21.860380 arp who-has lpar2 tell vlpar3_p5
13:54:21.860390 arp reply lpar2 is-at
13:54:21.870376 IP vlpar3_p5.bootpc > lpar2.bootps: BOOTP/DHCP, Request from 22:33:80:00:80:03,
length: 300
13:54:22.889784 IP vlpar3_p5.bootpc > lpar2.bootps: BOOTP/DHCP, Request from 22:33:80:00:80:03,
length: 300
13:54:24.909032 IP vlpar3_p5.bootpc > lpar2.bootps: BOOTP/DHCP, Request from 22:33:80:00:80:03,
length: 300
13:54:28.918683 IP vlpar3_p5.bootpc > lpar2.bootps: BOOTP/DHCP, Request from 22:33:80:00:80:03,
length: 300

Example 7-21   Successful tftp

14:35:52.182347 IP vlpar3_p5.4463 > lpar2.tftp:  28 RRQ "/tftpboot/vlpar3_p5" octet
14:35:52.183812 IP lpar2.33444 > vlpar3_p5.4463: udp 516
14:35:52.341956 IP vlpar3_p5.4463 > lpar2.33444: udp 4
14:35:52.342017 IP lpar2.33444 > vlpar3_p5.4463: udp 516
14:35:52.351681 IP vlpar3_p5.4463 > lpar2.33444: udp 4
14:35:52.351731 IP lpar2.33444 > vlpar3_p5.4463: udp 516
14:35:52.352386 IP vlpar3_p5.4463 > lpar2.33444: udp 4
14:35:52.352423 IP lpar2.33444 > vlpar3_p5.4463: udp 516
14:35:52.361754 IP vlpar3_p5.4463 > lpar2.33444: udp 4
14:35:52.361800 IP lpar2.33444 > vlpar3_p5.4463: udp 516
14:35:52.362371 IP vlpar3_p5.4463 > lpar2.33444: udp 4
14:38:04.485501 IP lpar2.33444 > vlpar3_p5.4463: udp 516
14:38:04.494802 IP vlpar3_p5.4463 > lpar2.33444: udp 4
14:38:04.494835 IP lpar2.33444 > vlpar3_p5.4463: udp 4
14:38:04.495221 IP vlpar3_p5.4463 > lpar2.33444: udp 4
14:38:04.504244 IP lpar2.33444 > vlpar3_p5.4463: udp 4
14:38:04.504298 IP lpar2 > vlpar3_p5: icmp 36: lpar2 udp port 33444 unreachable
14:38:26.504145 IP lpar2.1023 > vlpar3_p5.shell: S 29956891:29956891(0) win 16384 <mss 1460>
14:38:27.503954 IP lpar2.1023 > vlpar3_p5.shell: S 29956891:29956891(0) win 16384 <mss 1460>
14:38:30.504795 IP lpar2.1023 > vlpar3_p5.shell: S 29956891:29956891(0) win 16384 <mss 1460>
7.5 Log files

This section provides information about files related to NIM operations. (There are also other processes involved in NIM operations, so there are other log files that you should be checking; as mentioned in 5.3.8, “NIM communication within a firewall environment” on page 437, rsh, bootp, tftp and nfs are involved in NIM operations.)

7.5.1, “NIM-related files” on page 587, lists files from which you can gather information about NIM and related processes that may help you when troubleshooting a NIM environment.

7.5.1 NIM-related files

NIM creates and modifies a set of files and logs during installation and during operation. You can use these files to determine where problems are occurring for the installation that you are trying to perform. The format of the files is either text or alog.

The text file content can be displayed with your favorite text editor or command. For alog files, you must use the alog command (as shown in Example 7-23 on page 588) for the /var/adm/ras/bosinstlog file.
Example 7-23  alog command execution

```
# alog -o -f /var/adm/ras/bosinstlog | pg
Preparing target disks.
rootvg
Making boot logical volume.
hd5
Making paging logical volumes.
hd6
Making logical volumes.
...........
```

Table 7-1 lists the files and logs created and modified by NIM.

**Table 7-1  NIM logs**

<table>
<thead>
<tr>
<th>File</th>
<th>Content</th>
<th>Text file</th>
<th>Alog file</th>
</tr>
</thead>
<tbody>
<tr>
<td>/var/log/nimol.log</td>
<td>Installation output from the nimol_install command on the NIMOL server.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/devinst.log</td>
<td>Log information from the BOS Installation.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/emgr.log</td>
<td>Log information from the emgr command execution.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/bosinstlog</td>
<td>Log information from the BOS Installation.</td>
<td></td>
<td>X</td>
</tr>
<tr>
<td>/var/adm/ras/nim.alt_disk_install</td>
<td>Debug information from the alt_disk_install command execution on the client, if debug option has been selected.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/alt_disk_inst.log</td>
<td>Output from the alt_disk_install command execution on the client, if verbose option has been selected.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/nimsh.log</td>
<td>Output from the nimsh daemon.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/nim.installp</td>
<td>Log information from the installp operation execution.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/install_all_updates.log</td>
<td>Log information from the install_all_updates command execution.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/nim.update</td>
<td>Log information from the nim_update_all command execution.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/nim.setup</td>
<td>Log information from nim_master_setup command execution.</td>
<td>X</td>
<td></td>
</tr>
</tbody>
</table>
### 7.5.2 RSH-related files

Table 7-2 lists the files related to rsh.

**Table 7-2 rsh files**

<table>
<thead>
<tr>
<th>File</th>
<th>Content</th>
<th>Text file</th>
<th>Alog file</th>
</tr>
</thead>
<tbody>
<tr>
<td>/var/adm/ras/nim.script</td>
<td>Log information from a NIM script execution.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/eznim.cfg</td>
<td>Keeps a list of which resources are currently defined in the resource group used in the eznim environment.</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>/var/adm/ras/nimlog</td>
<td>Log for console messages printed to stderr during a NIM operation.</td>
<td></td>
<td>X</td>
</tr>
</tbody>
</table>

Table 7-3 lists the files related to rshd. The rshd daemon is the server that provides the function for remote command execution.

**Table 7-3 rshd files**

<table>
<thead>
<tr>
<th>File</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>$HOME/.klogin</td>
<td>Specifies remote users that can use a local user account.</td>
</tr>
<tr>
<td>/usr/lppssp/rcmd/bin/rsh</td>
<td>Link to AIX Secure /usr/bin/rsh that calls the SP Kerberos 4 rsh routine, if applicable.</td>
</tr>
<tr>
<td>/usr/lppssp/rcmd/bin/remsh</td>
<td>Link to AIX Secure /usr/bin/rsh that calls the SP Kerberos 4 rsh routine, if applicable.</td>
</tr>
<tr>
<td>$HOME/.rhosts</td>
<td>Specifies remote users that can use a local user account on a network.</td>
</tr>
<tr>
<td>/etc/hosts.equiv</td>
<td>Specifies remote systems that can execute commands on the local system.</td>
</tr>
<tr>
<td>/etc/inetd.conf</td>
<td>Defines how the inetd daemon handles Internet service requests.</td>
</tr>
<tr>
<td>/etc/services</td>
<td>Defines the sockets and protocols used for Internet services.</td>
</tr>
</tbody>
</table>
Information is logged also to the syslogd log file. Refer to “Enabling syslogd daemon logging” for information regarding to how to enable syslogd daemon logging.

**Enabling syslogd daemon logging**

To enable the syslogd daemon logging (if it is not already enabled), follow these steps.

- Edit the `/etc/syslog.conf` file.
- Add a line with the message priority and destination file. Your line should look similar to the following:
  ```
  *.debug               /tmp/syslog.out
  ```
- Create the empty log file using for example the `touch` command.
- Start the syslogd daemon (if not already running), or refresh the daemon if running using src commands, as follows:
  - If syslogd daemon is already running:
    ```
    refresh -s syslogd
    ```
  - If syslogd daemon is not running:
    ```
    startsrc -s syslogd
    ```

Then you are able to monitor the output to find messages related to the failing component. Example 7-24 shows a line from the syslogd log file related to an rsh authentication failure.

**Example 7-24  syslogd log content**

```
..........
Jun 22 10:52:05 VLPAR3_p5 daemon:warn|warning rshd[311496]: Failed rsh authentication from nimmast for local user root via remote user root
...............```

### 7.5.3 BOOTP-related files

Table 7-4 on page 591 lists the files related to bootpd. This daemon sets up the Internet Boot Protocol server. When a bootp request arrives, inetd starts the bootpd daemon. These are text files.
Table 7-4  bootp files

<table>
<thead>
<tr>
<th>File</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>/etc/services</td>
<td>Defines the sockets and protocols used for Internet services.</td>
</tr>
<tr>
<td>/etc/bootptab</td>
<td>Default configuration file.</td>
</tr>
<tr>
<td>/etc/bootpd.dump</td>
<td>Default dump file.</td>
</tr>
<tr>
<td>/etc/inetd.conf</td>
<td>Contains the configuration information for the inetd daemon.</td>
</tr>
</tbody>
</table>

Bootpd also logs information through the syslogd daemon. See 7.5.2, “RSH-related files” on page 589 for information about how to enable syslogd logging.

### 7.5.4 TFTP-related files

Table 7-5 shows the files related to tftp and tftpd. The tftpd daemon is the server that provides the function for the Trivial File Transfer Protocol. These are text files.

Table 7-5  tftp and tftpd files

<table>
<thead>
<tr>
<th>File</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>/etc/tftpaccess.ctl</td>
<td>Allows or denies access to files and directories.</td>
</tr>
<tr>
<td>/etc/inetd.conf</td>
<td>Contains the configuration information for the inetd daemon.</td>
</tr>
<tr>
<td>/etc/services</td>
<td>Defines the sockets and protocols used for Internet services.</td>
</tr>
</tbody>
</table>

The tftpd daemon also can be given the flag -v. With this option, the daemon sends debugging information to the syslog daemon. See 7.5.2, “RSH-related files” on page 589 for information about how to enable syslogd logging.

Example 7-25 shows the content of the syslogd output referring to a tftp transfer.

*Example 7-25  tftpd output to syslogd*

```
............
Jun 22 14:05:18 nimmast daemon:info tftpd[463006]: [00000102] EZZ7044I :
10.1.1.70 RRQ   <file=Received , mode=tftppboot, recognized options: netascii>
```
7.5.5 NFS-related file

Table 7-6 lists the file related to nfs. This is a text file.

Table 7-6  NFS file

<table>
<thead>
<tr>
<th>File</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>/etc/rc.nfs</td>
<td>Contains the startup script for the NFS and NIS daemons.</td>
</tr>
</tbody>
</table>

For further information regarding nfs performance, refer to AIX 5L Practical Performance Tools and Tuning Guide, SG24-6478.

Next, we present practical examples for a NIM environment and a POWER5 case study.

**NIM case study**

Here we work through the performance tuning process for an AIX system that is using the Network Installation Manager (NIM) software. Network Install Manager is a complex application which relies on several subsystems to provide software installation and maintenance in an AIX, or a mixed AIX/Linux environment (from AIX 5L V5.3).

NIM uses a client server model which provides clients with all the necessary resources for booting, installing, maintaining or diagnosing (AIX only) client machines. In a NIM environment, the following subsystems should be considered as candidates for performance tuning: network (TCP/IP), NFS, Virtual Memory Manager, Disk I/O and Logical Volume Manager (LVM).

**POWER5 case study**

This section considers specific POWER5 performance issues. We monitor the CPU performance of a POWER5-based system using a simple case scenario.
7.6 Case study: NIM server performance

In this case study we utilized an IBM eServer pSeries model 690 server that was configured into four separate logical partitions (LPAR). Each partition included one 10/100 Ethernet adapter, one gigabit Ethernet adapter, and one internal SCSI hard disk. Each partition had two processors and 4 GB of RAM. The partition configured as the NIM master (server) also had assigned to it two fibre channel adapters and an additional local SCSI hard disk.

For our first test, we had all partitions using the 10/100 Ethernet adapters, connected to a switch, with effective link parameters of 100 Mbps, full duplex. The NIM server resources were allocated on the second internal SCSI hard disk.

Later we configured NIM to use the gigabit Ethernet (connected to a GbitE switch), and also used the external fibre channel (FC) storage, connected via a Storage Area Network (a FC switch). A diagram of our test environment is presented in Figure 7-4.

![Test environment NIM diagram](image)

7.6.1 Setting up the environment

We installed the NIM master (in our case, LPAR1) from AIX installation CD-ROMs with AIX 5L V5.3. For this purpose, we assigned the CD-ROM drive available in the media drawer to LPAR1.
After installation, we configured the NIM master and defined the resources to be used in our environment. We wanted to install the three remaining LPARs (LPAR2, LPAR3, LPAR4) from the NIM master.

For this purpose, in the initial phase we needed to define the following resources:

1. A NIM repository containing the software packages to be used for installing the clients (similar to the content of the AIX installation CD set). This type of resource is known as lpp_source.

2. A repository containing the binaries (executables) and libraries to be used for executing various operations (programs) during client installation, together with the kernel image used for booting the clients. This is known as Shared Product Object Tree (SPOT), and is a directory similar to the /usr file system.

3. The three clients (LPAR2, LPAR3, LPAR4), which are defined in the NIM environment as standalone machines (after installation they will boot from their own disks and run an independent copy of the operating system).

These machines are defined using the MAC address of the network (Ethernet) adapter to be used for installation and an associated IP address.

We observed that defining the LPPSOURCE- and SPOT-type resources is I/O disk resource-intensive, as explained here:

- Creating the LPPSOURCE consists of copying the necessary Licensed Program Products (LPPs) from the AIX installation CD-ROMs to a designated space on the disk.
- Creating the SPOT is similar to an installation process, where the installation takes place on the defined disk (file system) space.

After these resources were created, we installed the clients. You can install clients in a NIM environment using one of several installation types: SPOT installation; bos rte; or mksysb. During initial client installation (using the bos rte type), the following resources are used:

- The bootp server (to allow clients to boot over the network)
- The tftp server (to transfer the kernel to be loaded by the clients)
- The NFS subsystem (to run the install programs and retrieve the necessary LPPs for installing the client)

Because the NIM software repository resides on a file system, and this file system is NFS-exported to the NIM clients, the following subsystems are also involved during the installation process:

- The Virtual Memory Manager
- The TCP/IP subsystem
- The NFS subsystem
- The Logical Volume Manager
We found useful to tune these subsystems in order to obtain maximum performance for our NIM master. We started by monitoring an idle NIM master, and then gradually tried to identify the bottlenecks during various NIM operations.

### 7.6.2 Monitoring the NIM master using topas

During the client installation process, we began the performance tuning process for the system by monitoring it using **topas**; Example 7-26 shows the output.

#### Example 7-26  topas output for NIM server

<table>
<thead>
<tr>
<th>Topas Monitor for host:</th>
<th>EVENTS/QUEUES</th>
<th>FILE/TTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fri Oct 22 17:23:42 2004</td>
<td>Cswitch 1040</td>
<td>Readch 0</td>
</tr>
<tr>
<td>Interval: 2</td>
<td>Syscall 204</td>
<td>Writech 199</td>
</tr>
<tr>
<td>Kernel 6.2</td>
<td>Reads 0</td>
<td>Rawin 0</td>
</tr>
<tr>
<td>User 0.0</td>
<td>Writes 0</td>
<td>Ttyout 199</td>
</tr>
<tr>
<td>Wait 0.0</td>
<td>Forks 0</td>
<td>Igets 0</td>
</tr>
<tr>
<td>Idle 93.8</td>
<td>Execs 0</td>
<td>Namei 2</td>
</tr>
<tr>
<td></td>
<td>Runqueue 0.0</td>
<td>Dirblk 0</td>
</tr>
<tr>
<td>Network KBPS</td>
<td>KB-In 458.8</td>
<td>KB-Out 22488.2</td>
</tr>
<tr>
<td>en1 11473.5</td>
<td>Waitqueue 0.0</td>
<td></td>
</tr>
<tr>
<td>lo0 0.0</td>
<td>PAGING</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Memory</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Faults 0</td>
<td>Real,MB 4095</td>
</tr>
<tr>
<td>Disk Busy% KBPS TPS KB-Read KB-Writ Steals</td>
<td>% Comp 17.9</td>
<td></td>
</tr>
<tr>
<td>hdisk1 12.5</td>
<td>PgspIn 0</td>
<td>% Noncomp 27.6</td>
</tr>
</tbody>
</table>
| ...(lines omitted)...

As shown in the topas output, the only resource that was running at maximum speed was Ethernet adapter en1. A 10/100 adapter running at 100_Full_Duplex, has a transmit speed limit of approximately 10 Megabytes per second (10 MB/second = 10,000 KB/second). The **topas** output shows en1 at 11,437.5 KB/second.

None of the other devices were overutilized at this point. The direct attached SCSI disk hdisk1, which contained the file systems being used for the NIM resources, is only 12.5% busy.

When a resource is running at its maximum speed, and is the limiting factor in the system, you need to add additional resources. In this case, tuning will not be able to compensate for the device data rate limit of the Ethernet adapter.

To increase the network throughput bandwidth, we allocated a Gigabit Ethernet adapter to the system. A Gigabit Ethernet adapter has a one-direction maximum data rate of 100 Mbytes per second, which is ten times the rate of a 100 Mbit adapter.
Creating a benchmark

One of the difficulties with simply monitoring the NIM server as it handles NIM client requests is that the workload varies. For tuning, it is desirable to have a representative workload that can be used as a benchmark. This benchmark workload can be run before and after tuning to see if any improvement occurs. Note that this approach does not eliminate the need to monitor the system to determine actual workload benefits from tuning, but it does provide a useful way to see if performance tuning is helping a related workload.

Because NIM uses NFS to transfer data between the server and clients, a simple workload is to mount an NFS directory on the clients and generate I/O with the `dd` command. The NIM server can use `rsh` to connect to the NIM clients, which will be useful in automating the workload.

Example 7-27 shows how to export the directory that is being used for NIM resources. Then we used the remote shell (`rsh`) to mount the exported directory on each of the NIM clients.

```
Example 7-27   Setting up for the NIM benchmark run

# exportfs -i -o root=glpar2:glpar3:glpar4 /dasbk
# for i in 2 3 4 ; do
    > rsh glpar$i "mount 192.168.100.71:/dasbk /mnt"
    > done
```

To facilitate the benchmarking effort we created two scripts, one for generating write I/O and one for generating read I/O. Example 7-28 displays the NIM write I/O script.

```
Example 7-28   NIM write I/O benchmark script

#!/usr/bin/ksh

for i in 2 3 4
do
    rsh glpar$i "dd if=/dev/zero of=/mnt/file$i bs=128K count=8000" &
done

#wait command waits for all background processes to finish before continuing wait
```

Example 7-29 displays the NIM read I/O script.

```
Example 7-29   NIM read I/O benchmark script

#!/usr/bin/ksh

for i in 2 3 4
```
do
        rsh glpar$i "dd if=/mnt/file$i of=/dev/null bs=128K count=8000" &
done

#wait command waits for all background processes to finish before continuing
wait

We first execute the `writenim.sh` with the `timex` command to get the total run time of the script.

**Example 7-30  NIM write I/O benchmark script using timex command**

```bash
# timex ./writenim.sh
8000+0 records in
8000+0 records out
8000+0 records in.
8000+0 records out.
8000+0 records in.
8000+0 records out.

real 386.79
user 0.02
sys  0.00
```

We observed that it took 386.79 seconds to write 3000 MB (1000 MB per NIM client). This gives us a throughput of 7.75 MB/second.

We also collected a `topas` screen output, shown in Example 7-31, which showed similar results to the actual workload from Example 7-26 on page 595.

**Example 7-31  The topas output from write I/O benchmark script**

<table>
<thead>
<tr>
<th>Topas Monitor for host:</th>
<th>Hello World</th>
<th>EVENTS/QUEUES</th>
<th>FILE/TTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tue Oct 26 10:19:18 2004</td>
<td>Interval: 2</td>
<td>Cswitch 1750</td>
<td>Readch 0</td>
</tr>
<tr>
<td>Kernel</td>
<td>13.0</td>
<td>Syscall 207</td>
<td>Writech 95</td>
</tr>
<tr>
<td>User</td>
<td>0.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Wait</td>
<td>0.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Idle</td>
<td>87.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Network KBPS I-Pack O-Pack KB-In KB-Out Waitqueue</td>
<td>en1 12011.6 16283.0 1748.0 23809.5 213.7 0.0</td>
<td>en0 0.1 3.0 0.0 0.1 0.0 PAGING</td>
<td>lo0 0.0 0.0 0.0 0.0 0.0 Faults</td>
</tr>
<tr>
<td>Disk Busy% KBPS TPS KB-Read KB-Writ PgspIn PgspOut</td>
<td>hdisk1 84.5 11538.0 358.5 4.0 23072.0</td>
<td>0 % Noncomp 10.7</td>
<td>0 % Client 10.9</td>
</tr>
</tbody>
</table>
To get an accurate result from the read I/O script, we needed to unmount all the related file systems. This was necessary in order to flush the caches (both the file system cache of the NIM server and the NFS client caches of the NIM clients).

**Example 7-32  NIM read I/O benchmark script - unmounting related file systems**

```bash
# umount /dasbk
# mount /dasbk
# for i in 2 3 4 ; do
> rsh glpar$i umount /mnt
> rsh glpar$i mount 192.168.100.71:/dasbk /mnt
> done
# timex ./readnim.sh
8000+0 records in.
8000+0 records out.
8000+0 records in
8000+0 records out
8000+0 records in.
8000+0 records out.

real 268.74
user 0.02
sys  0.00
```

The read benchmark executed in 268.74 seconds, so the read throughput was 11.16 MB/second (3000 MB / 268.74 second).

In Example 7-33 we collected a topas screen output, which indicated that we had reached the limit of hdisk0, as well.

**Example 7-33  The topas output from read I/O benchmark script**

<table>
<thead>
<tr>
<th>Topas Monitor for host:</th>
<th>EVENTS/QUEUES</th>
<th>FILE/TTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tue Oct 26 10:32:38 2004</td>
<td>Interval: 2</td>
<td></td>
</tr>
<tr>
<td>Kernel 10.0</td>
<td>Cswitch 1232</td>
<td>Readch 0</td>
</tr>
<tr>
<td>User 0.0</td>
<td>Syscall 204</td>
<td>Writech 170</td>
</tr>
<tr>
<td>Wait 46.2</td>
<td>Reads 0</td>
<td>Rawin 0</td>
</tr>
<tr>
<td>Idle 43.8</td>
<td>Writes 0</td>
<td>Ttyout 170</td>
</tr>
<tr>
<td>Network en1 11799.0</td>
<td>Forks 0</td>
<td>Igets 0</td>
</tr>
<tr>
<td>en0 0.5</td>
<td>Execs 0</td>
<td>Namei 2</td>
</tr>
<tr>
<td>lo0 0.0</td>
<td>Runqueue 0.0</td>
<td>Dirblk 0</td>
</tr>
<tr>
<td>Disk hdisk1 100.0</td>
<td>I-Pack 11494.0</td>
<td>Waitqueue 3.0</td>
</tr>
<tr>
<td></td>
<td>O-Pack 302.5</td>
<td>MEMORY</td>
</tr>
<tr>
<td></td>
<td>KB-In 22988.0</td>
<td>KBPS 4095</td>
</tr>
<tr>
<td></td>
<td>KB-Out 0.0</td>
<td>TPS 149.0</td>
</tr>
<tr>
<td></td>
<td>Paging 0</td>
<td>KB-Read 197</td>
</tr>
<tr>
<td></td>
<td>Steals 0</td>
<td>KB-Writ 12.8</td>
</tr>
<tr>
<td></td>
<td>Faults 0</td>
<td>PGspIn 0</td>
</tr>
<tr>
<td></td>
<td>% Comp 5.5</td>
<td>% Noncomp 5.5</td>
</tr>
<tr>
<td></td>
<td>Client 5.7</td>
<td>% Client 5.7</td>
</tr>
</tbody>
</table>
7.6.3 Upgrading a NIM environment to Gbit Ethernet

Now that we had a representative workload, we could add the gigabit Ethernet adapter and rerun the benchmark workloads. This would give an idea of what performance increase we might get in the actual workload.

Running the NIM script for write I/O resulted in a time of 260.40 seconds for a throughput of 11.5 MB/second. The execution was identical to Example 7-30 on page 597.

We captured the output from the topas command was captured, as shown in Example 7-34.

Example 7-34  The topas output from write I/O benchmark script

<table>
<thead>
<tr>
<th>Topas Monitor for host:</th>
<th>EVENTS/QUEUES</th>
<th>FILE/TTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tue Oct 26 11:17:07 2004</td>
<td>Cswitch 14586</td>
<td>Readch 0</td>
</tr>
<tr>
<td></td>
<td>Syscall 64</td>
<td>Writtech 148</td>
</tr>
<tr>
<td>Kernel</td>
<td>Reads 0</td>
<td>Rawin 0</td>
</tr>
<tr>
<td>User</td>
<td>Writes 0</td>
<td>Ttyout 148</td>
</tr>
<tr>
<td>Wait</td>
<td>Forks 0</td>
<td>Igets 0</td>
</tr>
<tr>
<td>Idle</td>
<td>Execs 0</td>
<td>Namei 0</td>
</tr>
<tr>
<td></td>
<td>Runqueue 2.5</td>
<td>Dirblk 0</td>
</tr>
<tr>
<td>Network</td>
<td></td>
<td></td>
</tr>
<tr>
<td>en0 72998.9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>en1 0.6 99075.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>lo0 0.0 9752.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Disk</td>
<td></td>
<td></td>
</tr>
<tr>
<td>hdisk1 100.0 42304.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>hdisk3 0.0 0.0</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

As you can see, the network throughput and CPU utilization had increased, but hdisk1 (the actual disk used for NIM repository) was now 100% busy, and was the current bottleneck. Although we increased the throughput of the networking component ten-fold, our benchmark did not see the same amount of performance improvement.

This is typical of the performance tuning process. Increasing one resource often moves the bottleneck to a different component of the system.

Running the NIM script for read I/O resulted in a time of 175.87 seconds for a throughput of 17.1 MB/second. The execution was identical to Example 7-32 on page 598.

We captured the output from the topas command, as shown in Example 7-35 on page 600.
Example 7-35 The topas output from read I/O benchmark script

<table>
<thead>
<tr>
<th>Topas Monitor for host:</th>
<th>p690_lpar1</th>
<th>EVENTS/QUEUEs</th>
<th>FILE/TTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tue Oct 26 11:23:31 2004</td>
<td>Interval: 2</td>
<td>Cswitch 919</td>
<td>Readch 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Syscall 59</td>
<td>Writech 162</td>
</tr>
<tr>
<td>Kernel</td>
<td>5.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>User</td>
<td>0.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Wait</td>
<td>95.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Idle</td>
<td>0.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Network</td>
<td>KBPS</td>
<td>I-Pack</td>
<td></td>
</tr>
<tr>
<td>en0</td>
<td>13896.1</td>
<td>9133.0</td>
<td></td>
</tr>
<tr>
<td></td>
<td>en1</td>
<td>0.6</td>
<td>8.0</td>
</tr>
<tr>
<td></td>
<td>lo0</td>
<td>0.0</td>
<td>0.0</td>
</tr>
<tr>
<td>Disk</td>
<td>Busy%</td>
<td>KBPS</td>
<td></td>
</tr>
<tr>
<td></td>
<td>100.0</td>
<td>13566.0</td>
<td></td>
</tr>
<tr>
<td></td>
<td>0.0</td>
<td>0.0</td>
<td>0.0</td>
</tr>
</tbody>
</table>

The output is similar to what was seen during the benchmark script runs.

NIM workload results with gigabit Ethernet

Utilizing the benchmark script, we saw a performance improvement in both read I/O and write I/O. Next, we wanted to see what kind of improvement occurred when the NIM server handled NIM client requests. So we collected topas output as well as iostat output while three NIM client installs processed simultaneously. Example 7-36 shows the NIM server topas output.

Example 7-36 NIM server topas output

<table>
<thead>
<tr>
<th>Topas Monitor for host:</th>
<th>p690_lpar1</th>
<th>EVENTS/QUEUEs</th>
<th>FILE/TTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tue Oct 26 08:36:13 2004</td>
<td>Interval: 2</td>
<td>Cswitch 2143</td>
<td>Readch 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Syscall 268</td>
<td>Writech 500</td>
</tr>
<tr>
<td>Kernel</td>
<td>15.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>User</td>
<td>0.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Wait</td>
<td>85.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Idle</td>
<td>0.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Network</td>
<td>KBPS</td>
<td>I-Pack</td>
<td></td>
</tr>
<tr>
<td>en0</td>
<td>28098.3</td>
<td>18455.0</td>
<td></td>
</tr>
<tr>
<td></td>
<td>en1</td>
<td>0.5</td>
<td>4.0</td>
</tr>
<tr>
<td></td>
<td>lo0</td>
<td>0.0</td>
<td>0.0</td>
</tr>
<tr>
<td>Disk</td>
<td>Busy%</td>
<td>KBPS</td>
<td></td>
</tr>
<tr>
<td></td>
<td>100.0</td>
<td>27352.0</td>
<td></td>
</tr>
</tbody>
</table>

The output is similar to what was seen during the benchmark script runs. Network throughput had increased, but hdisk1 had become completely busy.
During the NIM client installation process, we collected `iostat` command output, using `iostat 5 >> iostat.out`. This started `iostat` collecting statistics every 5 seconds and saved the output to the file `iostat.out`. After the client installs completed, we stopped the command processing by Ctrl-C.

Example 7-37 shows the NIM server iostat output.

<table>
<thead>
<tr>
<th>tty:</th>
<th>tin</th>
<th>tout</th>
<th>avg-cpu:</th>
<th>% user</th>
<th>% sys</th>
<th>% idle</th>
<th>% iowait</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0.2</td>
<td>275.4</td>
<td>0.0</td>
<td>16.2</td>
<td>0.2</td>
<td>83.6</td>
<td></td>
</tr>
</tbody>
</table>

Disks:  

<table>
<thead>
<tr>
<th></th>
<th>% tm_act</th>
<th>Kbps</th>
<th>tps</th>
<th>Kb_read</th>
<th>Kb_wrtn</th>
</tr>
</thead>
<tbody>
<tr>
<td>hdisk0</td>
<td>0.2</td>
<td>3.2</td>
<td>0.8</td>
<td>0</td>
<td>16</td>
</tr>
<tr>
<td>hdisk1</td>
<td>100.0</td>
<td>27371.2</td>
<td>167.8</td>
<td>136856</td>
<td>0</td>
</tr>
</tbody>
</table>

Example 7-37   NIM server iostat output

tty:  

<table>
<thead>
<tr>
<th>tin</th>
<th>tout</th>
<th>avg-cpu:</th>
<th>% user</th>
<th>% sys</th>
<th>% idle</th>
<th>% iowait</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.0</td>
<td>146.2</td>
<td>0.3</td>
<td>14.6</td>
<td>0.0</td>
<td>85.1</td>
<td></td>
</tr>
</tbody>
</table>

Disks:  

<table>
<thead>
<tr>
<th></th>
<th>% tm_act</th>
<th>Kbps</th>
<th>tps</th>
<th>Kb_read</th>
<th>Kb_wrtn</th>
</tr>
</thead>
<tbody>
<tr>
<td>hdisk0</td>
<td>0.2</td>
<td>4.0</td>
<td>1.2</td>
<td>0</td>
<td>20</td>
</tr>
<tr>
<td>hdisk1</td>
<td>100.0</td>
<td>26365.6</td>
<td>181.0</td>
<td>131828</td>
<td>0</td>
</tr>
</tbody>
</table>

tty:  

<table>
<thead>
<tr>
<th>tin</th>
<th>tout</th>
<th>avg-cpu:</th>
<th>% user</th>
<th>% sys</th>
<th>% idle</th>
<th>% iowait</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.0</td>
<td>224.4</td>
<td>0.2</td>
<td>10.3</td>
<td>0.4</td>
<td>89.1</td>
<td></td>
</tr>
</tbody>
</table>

Disks:  

<table>
<thead>
<tr>
<th></th>
<th>% tm_act</th>
<th>Kbps</th>
<th>tps</th>
<th>Kb_read</th>
<th>Kb_wrtn</th>
</tr>
</thead>
<tbody>
<tr>
<td>hdisk0</td>
<td>0.2</td>
<td>4.0</td>
<td>0.8</td>
<td>0</td>
<td>20</td>
</tr>
<tr>
<td>hdisk1</td>
<td>100.0</td>
<td>22391.2</td>
<td>186.4</td>
<td>111956</td>
<td>0</td>
</tr>
</tbody>
</table>

### 7.6.4 Upgrading the disk storage

Using a single locally attached SCSI drive poses many problems. For example, there is no data redundancy. Also, the performance is insufficient to handle client requests.

We decided to move the NIM server resources to an IBM storage subsystem DS4500 (FASiT 900). We assigned two LUNs to the NIM server. These LUNs resided on separate RAID groups. The RAID groups were comprised of 7 disks each and were configured in RAID5, with a stripe size of 64 KB.

There were many ways of configuring these two DS4500 LUNs. Because the disk subsystem was handling the data redundancy, we did not need to use LVM
mirroring. Our two main choices at this point were to use either a spread logical volume or a striped logical volume, as explained here:

- A spread logical volume (also known as “coarse striping”), alternates data between the hdisk in a volume group on a physical partition level (PP).
- A striped logical volume alternates data between hdisk on a finer basis. With a striped logical volume, you can specify a stripe size from 4KB to 128KB (must be a power of two).

Ultimately we decided to use a JFS2 file system, which gave us additional choices about how to create the JFS2 log (inline, or on a separate logical volume).

**Configuring the LVM**

AIX 5.3 has the device drivers and disk type preloaded for DS4500 disk devices. After configuring the DS4500 storage and assigning the LUNs to the server, the command `cfgmgr` detects the new storage and configures it to the system.

After the disk is configured to the system, it needs to be assigned to a volume group. After being assigned to a volume group, the disk is automatically split into physical partitions. These physical partitions can then be made into logical volumes, and the file system can be configured on the logical volumes.

To start the process we created a new volume group with the DS4500 disk devices. As shown in Example 7-38, we first listed the disks available to the system with the `lsdev` command, then defined the volume group with `mkvg`. Finally, we checked the characteristics of the volume group with `lsvg`.

**Example 7-38  Creating a new volume group**

```
# lsdev -Cc disk
hdisk0 Available 3s-08-00-8,0 16 Bit LVD SCSI Disk Drive
hdisk1 Available 5M-08-00-8,0 16 Bit LVD SCSI Disk Drive
hdisk2 Available 41-08-02  MPIO Other FC SCSI Disk Drive
hdisk3 Available 41-08-02  MPIO Other FC SCSI Disk Drive
hdisk4 Available 41-08-02  1742-900 (900) Disk Array Device
hdisk5 Available 4Q-08-02  1742-900 (900) Disk Array Device

# mkvg -y ds4500vg hdisk4 hdisk5
ds4500vg

# lsvg ds4500vg
VOLUME GROUP:       ds4500vg                 VG IDENTIFIER:
0022be2a00004c000000ff6d6b94f26
VG STATE:           active                   PP SIZE:        32 megabyte(s)
VG PERMISSION:      read/write               TOTAL PPs:      1022 (32704
megabytes)
```
The volume group contained two physical volumes, with a physical partition (PP) size of 32 megabytes. There are a total of 1022 PP, and the volume group has a logical track group (LTG) of 1024 kilobytes.

**Spread versus striped logical volume**

We could not be sure, initially, which type of logical volume would provide the best performance. To help determine which to use, we created both spread logical volumes and striped logical volumes and ran the benchmark script; see Example 7-39.

**Example 7-39  Creating spread logical volumes and stripe logical volumes**

```
# mklv -y'spreadlv' -t'jfs2' -e'x' ds4500vg 120
spreadlv
# mklv -y'stripelv' -t'jfs2' '-S64K' ds4500vg 120 hdisk4 hdisk5
stripelv
```

After the logical volumes were created, we created the jfs2 file systems on these logical volumes.

**Example 7-40  Create and mount file systems**

```
# mklv -y'spreadlv' -t'jfs2' -e'x' ds4500vg 120
spreadlv
# mklv -y'stripelv' -t'jfs2' '-S64K' ds4500vg 120 hdisk4 hdisk5
stripelv
# crfs -v jfs2 -d'spreadlv' -m'/spreadfs' -A'No' -p'rw' -a agblksize='4096'
File system created successfully.
3931836 kilobytes total disk space.
New File System size is 7864320
# crfs -v jfs2 -d'stripelv' -m'/stripefs' -A'No' -p'rw' -a agblksize='4096'
File system created successfully.
3931836 kilobytes total disk space.
New File System size is 7864320
# mount /spreadfs
```
With the file systems mounted, we needed to export the file systems and mount them on the NIM clients, as we did in Example 7-27 on page 596.

Example 7-41  Exporting file systems for benchmark testing

```
# exportfs -i -o root=glpar2:glpar3:glpar4 /spreadfs
# exportfs -i -o root=glpar2:glpar3:glpar4 /stripefs
```

**Benchmarking the spread file system**

With the file systems exported, we mounted one of them and ran the benchmark as shown in Example 7-42.

Example 7-42  Mounting spreadfs on NIM clients

```
# for i in 2 3 4; do
> rsh glpar$i "mount glpar1:/spreadfs /mnt"
> done
```

The hostname `glpar2` is the IP label (as associated in the `/etc/hosts` file) for the LPAR2 Gbit Ethernet interface, and so on (see the IP label assignment in Figure 7-4 on page 593).

With the spreadfs file system NFS mounted on each of the NIM clients, we ran the same script from Example 7-28 on page 596.

Example 7-43  Script for NIM write I/O benchmark - gigabit and DS4500

```
# timex ./writenim.sh
8000+0 records in.
8000+0 records out.
8000+0 records in
8000+0 records out
8000+0 records in.
8000+0 records out.

real 44.99
user 0.02
sys 0.01
```

With both gigabit Ethernet and the DS4500 disk subsystem, the write throughput has increased dramatically to 66.7 MB/second (3000 MB / 44.99 second).

In Example 7-44 on page 605 we show the full `topas` screen output, because there was enough load for the other values to also be of interest.
Example 7-44  The topas output for NIM write benchmark - DS4500 spread and gigabit Ethernet

<table>
<thead>
<tr>
<th>Topas Monitor for host:</th>
<th>EVENTS/QUEUES</th>
<th>FILE/TTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Wed Oct 27 08:59:00 2004</td>
<td>Cswitch 12640</td>
<td>Readch 0</td>
</tr>
<tr>
<td></td>
<td>Syscall 61</td>
<td>Writech 163</td>
</tr>
<tr>
<td>Kernel</td>
<td></td>
<td></td>
</tr>
<tr>
<td>User</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Wait</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Idle</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Network</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Network</th>
<th>KBPS</th>
<th>I-Pack</th>
<th>O-Pack</th>
<th>KB-In</th>
<th>KB-Out</th>
<th>Waitqueue</th>
<th>Memory</th>
</tr>
</thead>
<tbody>
<tr>
<td>en0</td>
<td>110.8K</td>
<td>151.0K</td>
<td>13837.0</td>
<td>219.8K</td>
<td>1861.7</td>
<td>0.0</td>
<td>PAGING</td>
</tr>
<tr>
<td>en1</td>
<td>0.3</td>
<td>3.0</td>
<td>1.0</td>
<td>0.1</td>
<td>0.4</td>
<td></td>
<td>MEMORY</td>
</tr>
<tr>
<td>lo0</td>
<td>0.0</td>
<td>0.0</td>
<td>0.0</td>
<td>0.0</td>
<td>0.0</td>
<td></td>
<td>Faults</td>
</tr>
<tr>
<td>Disk</td>
<td>Busy%</td>
<td>KBPS</td>
<td>TPS</td>
<td>KB-Read</td>
<td>KB-Writ</td>
<td>PgspIn</td>
<td>% Noncomp</td>
</tr>
<tr>
<td>hdisk5</td>
<td>100.0</td>
<td>54720.0</td>
<td>53.5</td>
<td>0.0</td>
<td>106.9K</td>
<td>0 0</td>
<td>50.4</td>
</tr>
<tr>
<td>hdisk4</td>
<td>84.5</td>
<td>59408.0</td>
<td>140.0</td>
<td>0.0</td>
<td>116.0K</td>
<td>0 0</td>
<td>50.4</td>
</tr>
<tr>
<td>hdisk2</td>
<td>0.0</td>
<td>0.0</td>
<td>0.0</td>
<td>0.0</td>
<td>0.0</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Name</th>
<th>PID</th>
<th>CPU%</th>
<th>PgSp</th>
<th>Owner</th>
<th>% Used</th>
<th>1.0</th>
</tr>
</thead>
<tbody>
<tr>
<td>nfsd</td>
<td>409606</td>
<td>50.1</td>
<td>0.8</td>
<td>root</td>
<td>% Free</td>
<td>98.9</td>
</tr>
<tr>
<td>j2pg</td>
<td>147544</td>
<td>0.0</td>
<td>0.2</td>
<td>root</td>
<td>ServerV2</td>
<td>0</td>
</tr>
<tr>
<td>topas</td>
<td>307366</td>
<td>0.0</td>
<td>1.2</td>
<td>root</td>
<td>ClientV2</td>
<td>0</td>
</tr>
<tr>
<td>gil</td>
<td>73764</td>
<td>0.0</td>
<td>0.1</td>
<td>root</td>
<td>ServerV3</td>
<td>3412</td>
</tr>
<tr>
<td>pilegc</td>
<td>61470</td>
<td>0.0</td>
<td>0.2</td>
<td>root</td>
<td>ClientV3</td>
<td>0</td>
</tr>
</tbody>
</table>

The topas output shows that some of the system resources were being fully utilized, which is desirable. The CPU was only 8% idle, but was showing zero wait time. The new disks were fully utilized, but appeared to be slightly imbalanced. And the Gbit Ethernet card throughput (one direction) was close to its maximum of 100 MB/second.

Now we ran the read I/O benchmark, making sure to flush the caches as shown in Example 7-45.

Example 7-45  Script for NIM read I/O benchmark - DS4500 spread and gigabit

```bash
# umount /spreadfs
# mount /spreadfs
# for i in 2 3 4 ; do
> rsh glpar$i umount /mnt
> rsh glpar$i mount glpar1:/spreadfs /mnt
> done
# timex ./readnim.sh
8000+0 records in.
8000+0 records out.
8000+0 records in.
8000+0 records out.
```
8000+0 records in
8000+0 records out

real 30.20
user 0.02
sys  0.00

With both gigabit Ethernet and the DS4500 disk subsystem, the read throughput had increased dramatically to 99.3 MB/second (3000 MB / 30.20 second).

In Example 7-46 we show the full topas screen output, because there was enough load for the other values to also be of interest.

<table>
<thead>
<tr>
<th>Topas Monitor for host:</th>
<th>EVENTS/QUEUES</th>
<th>FILE/TTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>p690_lpar1</td>
<td>Cswitch 6905</td>
<td>Readch 0</td>
</tr>
<tr>
<td>Wed Oct 27 09:04:54 2004</td>
<td>Syscall 53</td>
<td>Writech 185</td>
</tr>
<tr>
<td>Interval: 2</td>
<td>Reads 0</td>
<td>Rawin 0</td>
</tr>
<tr>
<td>Kernel 52.2</td>
<td>Writes 0</td>
<td>Ttyout 185</td>
</tr>
<tr>
<td>User 0.0</td>
<td>Forks 0</td>
<td>Igets 0</td>
</tr>
<tr>
<td>Wait 24.0</td>
<td>Execs 0</td>
<td>Namei 0</td>
</tr>
<tr>
<td>Idle 23.8</td>
<td>Runqueue 2.5</td>
<td>Dirblk 0</td>
</tr>
<tr>
<td>Network KBPS I-Pack O-Pack KB-In KB-Out Waitqueue</td>
<td>PAGING</td>
<td>MEMORY</td>
</tr>
<tr>
<td>en0 102.5K 69925.0 7118.0 4028.4 201.1K</td>
<td></td>
<td></td>
</tr>
<tr>
<td>en1 0.3</td>
<td>Faults 648</td>
<td>Real,MB 4095</td>
</tr>
<tr>
<td>lo0 0.0</td>
<td>steals 0</td>
<td>% Comp 17.2</td>
</tr>
<tr>
<td>Disk Busy% KBPS TPS KB-Read KB-Writ PgspIn % Noncomp</td>
<td>PgspOut % Client</td>
<td></td>
</tr>
<tr>
<td>hdisk4 56.5 53248.0 1524.0 104.0K 0.0</td>
<td>0 38.9</td>
<td></td>
</tr>
<tr>
<td>hdisk5 43.0 49152.0 1360.0 98304.0 0.0</td>
<td>PageIn 25584</td>
<td></td>
</tr>
<tr>
<td>hdisk2 0.0</td>
<td>PageOut 0</td>
<td>PAGING SPACE</td>
</tr>
<tr>
<td>Name PID CPU% PgSp Owner</td>
<td>Sios 25602 Size,MB 512</td>
<td></td>
</tr>
<tr>
<td>nsfd 409606 25.0 0.8 root</td>
<td>NFS (calls/sec) % Free 98.9</td>
<td></td>
</tr>
<tr>
<td>topas 254150 0.0 1.5 root</td>
<td>ServerV2 0</td>
<td></td>
</tr>
<tr>
<td>j2pg 147544 0.0 0.2 root</td>
<td>ClientV2 0 Press:</td>
<td></td>
</tr>
<tr>
<td>gil 73764 0.0 0.1 root</td>
<td>ServerV3 3198 &quot;h&quot; for help</td>
<td></td>
</tr>
<tr>
<td>aixmibd 442596 0.0 0.6 root</td>
<td>ClientV3 0 &quot;q&quot; to quit</td>
<td></td>
</tr>
</tbody>
</table>

Although the read throughput was higher, the resources did not report being as busy as with the write workload. The network adapter was still close to its limit at 100 MB/second.

Now that we had some numbers for a spread file system, we ran the same benchmark for the striped file system.
Benchmarking stripe file system

To prepare for running the same benchmark against the stripe file system, we needed to unmount the spread file system from the NIM clients, and then mount the striped file system and run the script; see Example 7-47.

Example 7-47  Script for NIM write I/O benchmark - gigabit and DS4500 striped

```bash
# for i in 2 3 4 ; do
> rsh glpar$i "umount /mnt"
> rsh glpar$i "mount glpar1:/stripefs /mnt"
> done
# timex ./writenim.sh
8000+0 records in.
8000+0 records out.
8000+0 records in.
8000+0 records out.
8000+0 records in
8000+0 records out

real 98.00
user 0.02
sys 0.00
```

The striped file system finished in 98 seconds, giving a throughput of 30.6 MB/s (3000 MB/98 seconds). This was much slower than the spread file system, which finished in less than half the time at 45 seconds.

This may be a good indication that in our environment we are using large sequential reads and writes (which is a typical NIM environment).

Example 7-48  The topas output for NIM write benchmark - DS4500 stripe and Gigabit Ethernet
As the topas output in Example 7-48 on page 607 shows, Disk Busy% increased but KBPS for the disks was lower. The extra overhead in splitting the I/Os into 64 KB strips between the DS4500 RAID LUNs resulted in decreased write performance. Coarse striping from implementing a spread file system appears to outperform fine striping, as shown in Example 7-49.

After we observed the write performance, it was time to finish the benchmark comparison by running the read I/O script; see Example 7-49.

**Example 7-49 Script for NIM read I/O benchmark - gigabit and DS4500 striped**

```
# umount /stripefs;mount /stripefs
# for i in 2 3 4 ; do
> rsh glpar$i "umount /mnt"
> rsh glpar$i "mount glpar1:/stripefs /mnt"
> done
# timex ./readnim.sh
8000+0 records in.
8000+0 records out.
8000+0 records in.
8000+0 records out.
8000+0 records in
8000+0 records out

real 29.46
user 0.02
sys 0.00
```

Read throughput for the striped file system was comparable and finished less than a second quicker than the spread file system. With both gigabit Ethernet and the DS4500 disk subsystem, the read throughput for the striped file system has increased to 101.8 MB/second (3000 MB/29.46 second).

In Example 7-50 we show the topas screen output for the NIM read benchmark to the striped file system.

**Example 7-50 The topas output for NIM read benchmark - DS4500 stripe and Gigabit Ethernet**
The Disk Busy% was much higher for the striped file system, but the load was better balanced. The rest of the resource utilization was similar to the spread file system.

7.6.5 Real workload with spread file system

Although the striped file system outperformed the spread file system for read operations, the difference was small. The difference between write throughput was significant; the spread file system had more than double the write throughput of the striped file system. Because of these results, we decided to use the spread file system.
With the NIM resources moved to the spread file system, we could then monitor a real workload. For this, we simultaneously restored three NIM clients and monitored the output with `topas`, `iostat`, and `sar` as shown in Example 7-51.

**Example 7-51 The `topas` output after Gigabit Ethernet and DS4500 storage**

<table>
<thead>
<tr>
<th>EVENT/QUEUE</th>
<th>FILE/TTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cswitch 5126</td>
<td>Readch 0</td>
</tr>
<tr>
<td>Syscall 218</td>
<td>Writech 645</td>
</tr>
<tr>
<td>Reads 0</td>
<td>Rawin 0</td>
</tr>
<tr>
<td>Writes 1</td>
<td>Ttyout 189</td>
</tr>
<tr>
<td>Forks 0</td>
<td>Igets 0</td>
</tr>
<tr>
<td>Execs 0</td>
<td>Namei 2</td>
</tr>
<tr>
<td>Runqueue 0.0</td>
<td>Dirblk 0</td>
</tr>
<tr>
<td>Waitqueue 0.0</td>
<td></td>
</tr>
</tbody>
</table>

**Network**

- `en0` KBPS: 73874.8, Pack: 47437.0, Pack: 4809.0, KB-In: 2651.3, KB-Out: 141.7K
- `en1` KBPS: 0.3, Pack: 5.0, Pack: 1.0, Pack: 0.2, Pack: 0.4 PAGING
- `lo0` KBPS: 0.0, Pack: 0.0, Pack: 0.0, Pack: 0.0, Pack: 0.0 Faults: 175, Real,MB: 4095

**Disk**

- `hdisk5` Busy%: 31.0, KBPS: 36776.0, TPS: 261.0, KB-Read: 73552.0, KB-Writ: 0.0 PgsIn: 0, % Noncomp: 37.2
- `hdisk4` Busy%: 28.0, KBPS: 35480.0, TPS: 199.0, KB-Read: 70960.0, KB-Writ: 0.0 PgsOut: 0, % Client: 37.3
- `hdisk2` Busy%: 0.0, KBPS: 0.0, TPS: 0.0, KB-Read: 0.0, KB-Writ: 0.0 PgsIn: 0, % PAGING SPACE
- `sios` Busy%: 18022, KBPS: 512, TPS: 0, KB-Read: 0.0, KB-Writ: 0.0 PgsOut: 0

**Name**

- `nfsd` PID: 409606, CPU%: 0.0, PgSp: 0.8, Owner: root
- `topas` PID: 348170, CPU%: 0.0, PgSp: 1.2, Owner: root
- `sadc` PID: 393360, CPU%: 0.0, PgSp: 0.2, Owner: root
- `nimesis` PID: 262222, CPU%: 0.0, PgSp: 1.4, Owner: root

---

**Important:** Little benefit is gained from performing a similar procedure twice. For example, with database applications, it is good practice to avoid “double buffering”. This term refers to having both the application and the operating system use memory as cache, because this consumes memory that could be used for other operations and wastes CPU cycles by doing redundant caching.

It is a similar case with striping. DS4500 LUNs are already striped across disks, so using LVM striping across DS4500 LUNs results in (for lack of a better term) “double striping”. In effect, the DS4500 controller will receive small stripes alternating between different disk groups, but the extra striping does not benefit the disk subsystem, and could even cause performance degradation.

Therefore, it is important to understand the workload that the application is generating in order to use system resources most efficiently.
As you can see, the three NIM clients definitely made use of the additional network and storage resources. They did not constrain the available resources, based on the benchmark testing.

To collect iostat information we executed the command `iostat 5 60 >> iostat.out`, as shown in Example 7-52. This collected statistics every 5 seconds for 60 intervals, for a total of five minutes. We scanned through the output; Example 7-52 displays the interval where activity was the highest.

Example 7-52 The iostat output after gigabit Ethernet and DS4500 storage

<table>
<thead>
<tr>
<th>tty:</th>
<th>tin</th>
<th>tout</th>
<th>avg-cpu:</th>
<th>% user</th>
<th>% sys</th>
<th>% idle</th>
<th>% iowait</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0.4</td>
<td>80.8</td>
<td>0.2</td>
<td>25.7</td>
<td>73.1</td>
<td>1.0</td>
<td></td>
</tr>
</tbody>
</table>

Disks: % tm_act Kbps tps Kb_read Kb_wrtn
hdisk0 0.0 0.0 0.0 0.0 0.0
hdisk1 0.0 0.0 0.0 0.0 0.0
hdisk3 0.0 0.0 0.0 0.0 0.0
hdisk2 0.0 0.0 0.0 0.0 0.0
dac0 0.0 27161.6 97.4 135808 0
dac0-utm 0.0 0.0 0.0 0.0 0.0
dac1 0.0 25395.2 97.0 126976 0
dac1-utm 0.0 0.0 0.0 0.0 0.0
hdisk4 18.8 27161.6 97.4 135808 0
hdisk5 20.0 25395.2 97.0 126976 0
cd0 0.0 0.0 0.0 0.0 0.0

The dac0 and dac1 items in the Disks: column were the DS4500 controllers. If there were more disks per controller and activity on the disks, the dac0 and dac1 would show a cumulative value. Because there was only one disk per controller in our configuration, the values were the same for the disk and its associated controller.

As shown, the DS4500 system was handling the I/O requests and had some throughput left over. The load was spread quite evenly over the two DS4500 hdisks.

Using the `sar` command is another useful way of collecting disk statistics. To collect the disks statistics shown in Example 7-53, we executed the command `sar -d 5 60 >> sar.out`. We then scanned the output and selected the interval with the highest utilization.

Example 7-53 The sar output after gigabit Ethernet and DS4500 storage

<table>
<thead>
<tr>
<th>117:15:28</th>
<th>device</th>
<th>%busy</th>
<th>avque</th>
<th>r+w/s</th>
<th>Kbs/s</th>
<th>avwait</th>
<th>avserv</th>
</tr>
</thead>
</table>
...(lines omitted)....

dac0      0      0.0      145    33231      0.0      0.0
dac0-utm      0      0.0        0        0      0.0      0.0
dac1      0      0.0      150    32261      0.0      0.0
dac1-utm      0      0.0        0        0      0.0      0.0
hdisk4     24      0.0      145    33231      0.0      0.0
hdisk5     24      0.0      150    32261      0.0      0.0
...(lines omitted)....

The output from \texttt{sar -d} is similar to \texttt{iostat}, but with \texttt{sar} you receive additional values that can be useful.

Zero values for avque, avwait, and avserv are desirable. You should subject non-zero values to further investigation and tuning.

### 7.6.6 Summary

Performance tuning is an iterative process. This case study went through a few basic iterations of the process. It is important to accurately identify system bottlenecks and then make the correct choice regarding whether to add resources, tune resources, or leave the system alone.

Performance tuning on a production system is risky. Therefore, the first step in the performance tuning process is to understand the system workload and the effects of tuning commands. Also, having system backups and system documentation can provide significant assistance in recovering from bad tuning choices.

### 7.6.7 Multi-threaded option for the NIM nimesis daemon

If you are installing a large number of nodes, enable the multi-threaded option on the NIM nimesis daemon by setting the \texttt{max\_nimesis\_threads} value. Setting this value improves the performance of NIM when you are working with large numbers of nodes.

The multi-threaded option provides better handling of the volume of client information change requests and client state changes. Without the use of the multi-threaded option, the NIM master can become overloaded by activity on the NIM database and the number of active processes, resulting in simultaneous failures during the installation of a large number of client machines. The multi-threaded nimesis daemon will serialize and buffer NIM client requests to protect the NIM master from process overload, without causing significant performance degradation.
The number of threads assigned to this daemon determines how many simultaneous NIM client requests can be handled in the NIM environment. Because most of the NIM client requests are processed rapidly, you do not need to have one thread for every client installing.

The number of threads needed to support the activities in a NIM environment depends upon several factors. Keep the following considerations in mind then determining the appropriate number of threads:

- Number of clients that will be operated on at the same time
- Processing capacity of the NIM master machine
- What type of operations are planned

In general, one thread can support two to four clients that are installing BOS at the same time. For example, when installing 150 machines, 50 to 75 threads is sufficient. Be aware that the number of threads is also highly dependent on the processing power of the NIM master machine, and slower master machines may require more threads.

For smaller NIM environments, enabling the multi-threaded daemon can monopolize system resources on the master that will not be used. So, when installing 50 machines simultaneously, 20 to 25 threads or even the single-threaded daemon would suffice.

**Note:** The multi-threaded option alone will not allow more machines to be installed simultaneously. The multi-threaded option should be used in conjunction with global export of NIM resources, distribution of NIM resources throughout the NIM environment (that is, resource servers), and a network environment capable of handling a large volume of throughput.

You can specify a value from 20 to 150 (the default is 20). The general rule is to set it for approximately half the number of nodes on which you are operating simultaneously. For example, if you want to install 100 nodes, set the value to 50. Issue the following command to set the `max_nimesis_threads` value:

```
# nim -o change -a max_nimesis_threads=50 master
```

When resources are allocated for use during NIM operations, they are NFS-exported to the client machines where the operations will be performed. If operations are performed simultaneously on many different clients, the `/etc/exports` and `/etc/xtab` files may become very large on the NIM master. This may cause size limits to be exceeded in the files, and it may also negatively affect NIM performance as the files are locked and modified for each resource allocation or deallocation.
So, if you are installing a large number of nodes, set the `global_exports` attribute to `yes` on the NIM master.

    # nim -o change -a global_export=yes master

It is useful to set this attribute when you are simultaneously running NIM operations to many nodes.
General LPAR sizing and creation with mig2p5 tools

This appendix explains how to perform general LPAR sizing and creating using mig2p5 tools. The mig2p5 tools, which are a set of perl scripts, were developed to provide a set of user-friendly tools that enable you to facilitate the migration of workloads from older AIX machines to POWER5 LPARs (with either dedicated or shared processors). The mig2p5 files were written by the IBM Yorktown research team and were incorporated into the nim_move_up tool written by the STG team in Austin.

The mig2p5 tools have been designed to work with the nim_move_up tool, but can also be used as standalone scripts. In this appendix, we provide a brief introduction about how to use these scripts outside of the nim_move_up environment.

The appendix covers the following topics:

- An overview of the mig2p5 tools
- A description of the standalone mig2p5 tool
- Examples of using the mig2p5 tools from a NIM master
The **mig2p5** tools

The mig2p5 tools are set of perl scripts. These scripts define a process for automating the sizing and creation of POWER5 LPARS. The basic flow of this process is described as follows and is illustrated in Figure A-1.

1. Collect the source LPARs CPU and memory utilization. This task is performed by `getSrcUtil`.
2. Collect the source LPARs hardware configuration. This task is performed by `getSrcCfg`.
3. Capture the target POWER5 machine's hardware configuration. This task is performed by `getTgtRsrc`.
4. Generate the target LPAR’s required configuration, based on the hardware requirements and CPU/memory utilization collected in step one. This task is executed by `TgtCfg`.
5. Create the target LPAR on the POWER5 machine via `createTgtLPAR`.

![mig2p5 Function Flow](image)

*Figure A-1  mig2p5 function flow*
The mig2p5 scripts are listed as follows:

/usr/lpp/bos.sysmgt/nim/methods/getSrcUtil
/usr/lpp/bos.sysmgt/nim/methods/getSrcCfg
/usr/lpp/bos.sysmgt/nim/methods/getTgtRsrc
/usr/lpp/bos.sysmgt/nim/methods/genTgtCfg
/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR

They are incorporated with the nim_move_up utility, but can be used outside of this to size and create new POWER5 LPARs.

/usr/lpp/bos.sysmgt/nim/methods/getSrcUtil

This script generates a file (srcUtil) containing the system's CPU and memory utilization over a period of time (which you can specify). It collects vmstat information that is used by the genTgtCfg script to size the new POWER5 LPAR.

To collect data over a longer period of time, you can adjust the interval and loop count. The following will collect performance data on LPAR4 for a 24-hour period:

{nimmast}:/usr/lpp/bos.sysmgt/nim/methods # ./getSrcUtil -s LPAR4 -o /tmp/mig2p5/lpar4util.out -i 10 -l 9000

/usr/lpp/bos.sysmgt/nim/methods/getSrcCfg

This script generates a file (srcCfg) with the source systems hardware configuration.

/usr/lpp/bos.sysmgt/nim/methods/getTgtRsrc

This script generates a file (tgtRsrc) containing information about hardware resources available on the target POWER5 machine.

/usr/lpp/bos.sysmgt/nim/methods/genTgtCfg

This script generates the new LPAR definition which will be used to create the new LPAR on the POWER5 system. It uses the capEqMap file (/usr/lpp/bos.sysmgt/nim/methods/capEqMaps), and the srcCfg and tgtRsrc files during this process. It creates a file (tgtCfg) that contains the target LPARs configuration.
/usr/lpp/bos.sysmgt/nim/methods/createTgtLPAR

This script creates the new LPAR definition and profile on the POWER5 system, based on the tgtCfg file.

Standalone mig2p5 tool

As shown in Figure A-2 on page 619, the mig2p5 tools can be issued from any standalone AIX 5L V5.3 machine. When issuing the tools from a standalone AIX instance, the following occurs:

1. From the standalone AIX system, getSrcUtil and getSrcCfg connect to the source system (via rsh or ssh) and collect CPU/memory utilization and hardware configuration information. Refer to 4.5, “NIM mksysb migration and nim_move_up POWER5 tools” on page 205 and to the topic “Setting up secure script execution between SSH clients and the HMC” (at the Web site below) for more information about configuring SSH keys for communication between an AIX host and an HMC.

   http://publib.boulder.ibm.com/infocenter/eserver/v1r3s/index.jsp

2. getTgtRsrc connects the POWER5 HMC via ssh and gathers hardware resource information for the POWER5 machine.

3. genTgtCfg generates the target LPAR’s required configuration.

4. The createTgtLPAR script creates the new LPAR definition on the POWER5 machine.
Figure A-2  Using mig2p5 to size and create a POWER5 LPAR

The following are examples of using the mig2p5 tools from a NIM master. These scripts are currently delivered via the bos.sysmgt.nim.master fileset. Note that you can copy these scripts to another AIX system if you want to run them somewhere other than the NIM master.

Get the source LPARs hardware configuration

Example A-1 shows how to get the source LPAR hardware configuration.

Example: A-1  Acquiring the source LPAR hardware configuration

{nimmast}:/usr/lpp/bos.sysmgt/nim/methods # ./getSrcCfg -s lpar4 -o /tmp/mig2p5/lpar4cfg.out -util /tmp/mig2p5/lpar4util.out

INPUT:
Source Hostname = lpar4
File name for source configuration= /tmp/mig2p5/lpar4cfg.out
File containing utilization data = /tmp/mig2p5/lpar4util.out

Getting the type & model of the given source machine............
Getting the info about CPUs and Memory in the source machine.....
-----------------------------------------------------------------
Adding utilization info from the /tmp/mig2p5/lpar4util.out
File.................
-----------------------------------------------------------------
Getting the info about volume groups in the source machine.......
-----------------------------------------------------------------
Getting the info about network adapters in the source machine....

Get the source LPARs CPU and memory utilization

Example A-2 shows how to get the source LPAR hardware configuration.

Example: A-2   Acquiring the source LPAR CPU and memory utilization

{nimmast}:/usr/lpp/bos.sysmgmt/nim/methods # ./getSrcUtil -s LPAR4 -o
/tmp/mig2p5/lpar4util.out -i 10 -l 9000

The number of vmstat loops : 9000
The Average of Active virtual pages: 229 MB
The Average of Size of the free list: 6 MB
The sum of the CPU %idle: 291
The Average of CPU idle: 97.00
The Average of CPU utilization: 3.00

Flags for getSrcCfg command

Example A-3 shows how to get the source LPAR hardware configuration.

Example: A-3   Flags for getSrcCfg command

{nimmast}:/usr/lpp/bos.sysmgmt/nim/methods # ./getSrcCfg

SYNTAX:
getSrcCfg -s <srcHostname> [-o <srcCfgFile>] [-util <utilFile>]
where
<srcHost>: Hostname of the source machine
<utilFile>: File Containing the CPU and Memory utilization
values for the source
<srcCfgFile>: Output file into which the source configuration
will be written
-h : prints this syntax help. This flag cannot be used with other flags.
NOTE: This version only works for <srcHostname> running AIX 5.0
and above (as it uses the lsconf command).
Flags for the getSrcUtil command

Example A-4 shows how to get the source LPAR hardware configuration.

Example: A-4  Flags for the getSrcUtil command

{nimmast}:#/usr/lpp/bos.sysmgmt/nim/methods # ./getSrcUtil

SYNTAX:
getSrcUtil -s <srcHost> [-o <srcUtilFile>] [-i <interval>] [-l <loops>] [-h] [-v]

where flag
- o writes the output to a file. Default file: /tmp/srcUtil
- i denotes the <interval> in # seconds. Default: 1
- l denotes the number of loops; Default: 10
- v Version number

Get the target POWER5 machine resources via its HMC

Example A-5 shows how to get the source LPAR hardware configuration.

Example: A-5  Acquiring the target POWER5 machine resources

{nimmast}/usr/lpp/bos.sysmgmt/nim/methods # ./getTgtRsrc -hmc hmcsark -u hscroot -m SARK-520-65C544E -viosEth VIO2 -viosDisk VIO2 -o /tmp/mig2p5/tgtrsc.out

INPUT:
HMC Host                          = hmcsark
HMC Username                      = hscroot
Managed System name               = SARK-520-65C544E
Ethernet VIO Server(s)            = VIO2
Disk VIO Server(s)                = VIO2
Output file                       = /tmp/mig2p5/tgtrsc.out

-------------------------------------------------------------------------------------------------
Getting the type & model of the given P5 machine..............
cmd = ssh hscroot@hmcsark lssyscfg -m SARK-520-65C544E -r sys -Ftype_model
Type-Model = 9111-520
-------------------------------------------------------------------------------------------------
Getting the number of processing units in the given P5 machine........
cmd = ssh hscroot@hmcsark lshwres -m SARK-520-65C544E --level sys -Fconfigurable_sys_proc_units
available_proc_units = 2.0
-------------------------------------------------------------------------------------------------
Getting the amount of memory in MBs in the given P5 machine......
Configurable Memory = 16384
Available memory = 11648
LMB Size = 64

Getting the available physical I/O slots

Getting the volume groups info in the VIO Disk server(s)
Command:
ssh hscroot@hmcsark viosvrcmd -m SARK-520-65C544E -p VIO2 -c "lsvg"
Command:
ssh hscroot@hmcsark viosvrcmd -m SARK-520-65C544E -p VIO2 -c "lsvg rootvg"
VIO Server = VIO2; VG = rootvg; Size = 41088MB

Getting the available VLANs info in the VIO server(s)
Command:
ssh hscroot@hmcsark lshwres -m SARK-520-65C544E -r virtualio --rsubtype eth --level lpar --filter "lpar_names=VIO2"

Flag name:slot_num:port_vlan_id:is_trunk
VIO Server = VIO2; VLAN Id = 1; Slot number = 30

Flags for the getTgtRsrc command

Example A-6 shows how to get the source LPAR hardware configuration.

Example: A-6  Flags for the getTgtRsrc command

{nimmast}:/usr/lpp/bos.sysmg/nim/methods # ./getTgtRsrc

SYNTAX:
getTgtRsrc -hmc <hmcHost> -u <hmcUser> -m <managedSys> [-viosEth <vioEthServers>] [-viosDisk <vioDiskServers>] -o <outFile>

where
<hmcHost> : Hostname of the target HMC
<hmcUser> : Name of the user on the HMC who can execute Administrative commands
<managedSys> : Name of the target managed system
<vioEthServers> : LPAR names of the VIO servers for Ethernet. If you have multiple VIO server LPARs, separate the names with comma.
<vioDiskServers> : LPAR names of the VIO servers for Hard Disks. If you have multiple VIO server LPARs, separate
the names with comma.

$outFile$    : Name of the file into which the output will be written
-h : Prints this syntax help. Cannot be used with other flags.
E.g.: ./getTgtRsrc -hmc myhmc -u ssh_user1 -m myP5 -vio vioLP1,vioLP2 -o
tgtRsrc

---

Flags for the genTgtCfg command

Example A-7 shows how to get the source LPAR hardware configuration.

Example: A-7   Flags for the genTgtCfg command

{nimmast}:/usr/lpp/bos.sysmgt/nim/methods # ./genTgtCfg

SYNTAX:

genTgtCfg.pl -s $<srcCfgFile> -m $tgtRsrcFile> -e $eqMapsFile>
- lpar $<lparName> -prof $<profileName> -o $tgtLPARFile>
-[-dedCpu] [-dedEth] [-dedDisk]

where

$<srcCfgFile>  : Name of the file containing the source system info
$<tgtRsrcFile> : Name of the file containing the target machine info
$<eqMapsFile>  : Name of the file containing the capicity equivalence info
$<lparName>    : Name of the LPAR to be created in the target machine
$<profileName> : Profile for the above LPAR
$<tgtLPARFile> : Name of the file into which the target LPAR configuration info

will be written.
-[-dedCpu] : Use dedicated CPUs for the target LPAR
-[-dedEth] : Use dedicated Ethernet adapters for the target LPAR
-[-dedDisk] : Use dedicated hard disks for the target LPAR
-[-T] : assess user_defined volume groups other than rootvg from the original

client
-[-h] : Prints this syntax help. This flag cannot be used with other flags.
E.g.: ./genTgtCfg -s srcCfg -m tgtSmpRsrc -e eqMaps -lpar LP1 -prof Profile1 -o
tgtLPARcfg

---

Generate the target LPARs profile information

Example A-8 shows how to get the source LPAR hardware configuration.

Example: A-8   Generate of the target LPAR profile information

{nimmast}:/usr/lpp/bos.sysmgt/nim/methods # ./genTgtCfg -s
/tmp/mig2p5/1par4cfg.out -m /tmp/mig2p5/tgtrsc.out -e
/usr/lpp/bos.sysmg/nim/methods/capEqMaps -lpar newlpar -prof normal -o /tmp/mig2p5/newlparcfg.out

INPUT:
Source Configuration file : /tmp/mig2p5/lpar4cfg.out
Target Machine information file : /tmp/mig2p5/tgtrsc.out
Capacity equivalence maps file : /usr/lpp/bos.sysmg/nim/methods/capEqMaps
Target LPAR name : newlpar
Name of the profile to be created in LPAR: normal
Target LPAR file : /tmp/mig2p5/newlparcfg.out
Use dedicated CPUs? : No
Use dedicated Ethernet adapters? : No
Use dedicated Hard disks? : No

Reading the Source Configure from the given file..............

10002
src_mem_util = 99

Machine Type-model of the source machine = 7040-671
Number of CPUs in the source machine = 2
Amount of memory in the source machine = 1024

Network slots in source machine = 10/100 Mbps Ethernet PCI Adapter II (1410ff01)

Reading the target P5 managed system configuration...........

Available processing units = 2.0
Available memory = 11648


Channel Serial Bus:21030003/none/Empty slot:21040003/none/PCI 1Gbps Ethernet Fiber 2-port

Storage IO slots =

Network IO slots = 21040003/none/PCI 1Gbps Ethernet Fiber 2-port

VIO Volume groups = rootvg,VIO2,41088

VIO Hard disks =

VIO VLANs = 1,VIO2,30
Appendix A. General LPAR sizing and creation with mig2p5 tools

src_freq = 1000, tgt_freq = 1500

Calculating the resource requirements of target LPAR..............

des_procs = 0.1
des_memory = 1024
New Physical io slots =

Creating the target LPAR configuration file......................

---

Generated Target LPAR configuration information

Example A-9 shows how to get the source LPAR hardware configuration.

Example: A-9 Generated target LPAR configuration information

{nimmast}:/tmp/mig2p5 # cat newlparcfg.out
LPAR_NAME = newlpar
PROFILE_NAME = normal
# PROC_UNITS = <min> <desired> <max>
PROC_UNITS = 0.1 0.1 0.2
# MEMORY = <min MB> <desired MB> <max MB>
MEMORY = 512 1024 2048
# VIO_VG_INFO = <vgname_src>,<size in MB>,<vgname_vio>,<lpar_name>
#   Where <vgname_src> is the VG name in source machine, and
#   <vgname_vio> is the VG name in VIO server LPAR
VIO_VG_INFO = rootvg,17344,rootvg,VIO2
# VIO_VLAN_INFO = <vlan id>,<lpar name>,<slot number>
VIO_VLAN_INFO = 1,VIO2,30

---

At this point you can either choose to create the LPAR with the createTgtLPAR script or—if all you require is the sizing information (shown in Example A-9 on the newlparcfg.out file), then you can stop now.

If you want to automate the entire process from sizing to LPAR creation to NIM installation, then use the nim_move_up tool alone.

Create the target LPAR definition on the POWER5 machine

Example A-10 on page 626 shows how to get the source LPAR hardware configuration.
Example: A-10  Creation of the target LPAR definition

{nimmast}:/{usr/lpp/bos.sysmgt/nim/methods # createTgtLPAR -m
/tmp/mig2p5/tgtrsc.out -t /tmp/mig2p5/newlparcfg.out

INPUT:
Target Machine configuration file = /tmp/mig2p5/tgtrsc.out
Target LPAR configuration file    = /tmp/mig2p5/newlparcfg.out
Managed system = SARK-520-65C544E
HMC Hostname = hmcsark
User configured for remote ssh to HMC = hscroot
LPAR name:  newlpar
Profile name: normal
Proc units:  Min=0.6, Desired=1.3, Max=2.0
CPUs:  Min=1, Desired=2, Max=2
Memory:  Min=3520, Desired=7040, Max=14080
Virtual I O VGs:
  rootvg,17344,rootvg,VIO2

Virtual I O VLANs:
  1,VIO2,30

-----------------------------------------------------------------
Creating the target LPAR profile with proc units and memory......
Command:
  ssh hscroot@hmcsark mksyscfg -r lpar -m SARK-520-65C544E -i
    name=newlpar,profile_name=normal,lpar_env=aixlinux,proc_mode=shared,sharing_mod
    e=cap,min_proc_units=0.6,desired_proc_units=1.3,max_proc_units=2
      .0,min_procs=1,desired_procs=2,max_procs=2,min_mem=3520,desired_mem=7040,max_mem
      =14080,boot_mode=norm
-----------------------------------------------------------------
Discovering the LPAR id assigned to the above LPAR..............
Command:
  ssh hscroot@hmcsark lssyscfg -r lpar -m SARK-520-65C544E --filter
    lpar_names=newlpar -F lpar_id
  LPAR ID = 12
-----------------------------------------------------------------
Adding Physical I/O slots to the LPAR profile.....................
......No physical I/O slots to add to the LPAR profile.
-----------------------------------------------------------------
Adding Virtual I/O to the LPAR profile.........................
-----------------------------------------------------------------
Getting the list of existing vscsi devices in the VI0 server.....
Command:
  ssh hscroot@hmcsark viosvrcmd -m SARK-520-65C544E -p VIO2 -c "\lsdev
    -virtual\""
Determining the free virtual slot number in the VIO server......
Command:
```bash
ssh hscroot@hmcsark lshwres -r virtualio --rsubtype slot -m SARK-520-65C544E --level slot --filter "lpar_names=VIO2" -Fslot_num
```

Creating virtual scsi adapter in the VIO server.............
Adding the vscsi adapter to the VIO server using DR operation. 
Command = ssh hscroot@hmcsark chhwres -r virtualio --rsubtype scsi -m SARK-520-65C544E -o a -p VIO2 -s 42 -a

"adapter_type=server,remote_slot_num=2,remote_lpar_name=newlpar"

Getting the default and current profile names of VIO server...
Command:
```bash
ssh hscroot@hmcsark lssyscfg -r lpar -m SARK-520-65C544E --filter "lpar_names=VIO2" -Fdefault_profile:curr_profile
```

Adding the vscsi adapter to the default profile of VIO server....
Command:
```bash
ssh hscroot@hmcsark chsyscfg -r prof -m SARK-520-65C544E -i "name=normal,lpar_name=VIO2, virtual_scsi_adapters+=42/server/12/newlpar/2/1"
```

Configuring the virtual scsi adapter in the VIO server...........
Command:
```bash
ssh hscroot@hmcsark viosvrcmd -m SARK-520-65C544E -p VIO2 -c "\"cfgdev\""
```

Determining the OS-generated vscsi device name for the new adapter....
Command:
```bash
ssh hscroot@hmcsark viosvrcmd -m SARK-520-65C544E -p VIO2 -c "\"lsdev -virtual\""
```

Creating a logical volume in the VIO server..................
Command:
```bash
ssh hscroot@hmcsark viosvrcmd -m SARK-520-65C544E -p VIO2 -c "\"mklv -lv rootvg_12 rootvg 17G\""
```

Attaching the above LV to the vscsi device created earlier....... 
Command:
```bash
ssh hscroot@hmcsark viosvrcmd -m SARK-520-65C544E -p VIO2 -c "\"mkvdev -vdev rootvg_12 -vadapter vhost12 -dev vtscsi12\""
```

Creating the virtual scsi adapter for client LPAR.............
Command:
```bash
ssh hscroot@hmcsark chsyscfg -r prof -m SARK-520-65C544E -i name=normal,lpar_name=newlpar, virtual_scsi_adapters+=2/client//VIO2/42/1"
Creating the virtual ethernet adapters for client LPAR...........
Command:
  ssh hscroot@hmcsark chsyscfg -r prof -m SARK-520-65C544E -i
  name=normal, lpar_name=newlpar, virtual_eth_adapters+=3/0/1/0/1

Flags for the createTgtLPAR command

Example A-11 shows how to get the source LPAR hardware configuration.

Example: A-11 Flags for the create TgtLPAR command

{nimmast}:/usr/lpp/bos.sysmgt/nim/methods # ./createTgtLPAR

SYNTAX:
createTgtLPAR.pl -m <tgtMachFile> -t <tgtCfgFile> -v <vginfo_file> -T
where
  <tgtMachFile> : File containing the information about the target machine
  <tgtCfgFile>  : File containing the description of the target LPAR
  <vginfo_file> : File to which the vhost and slot number of each VG is written

  -T : Create user VGs as well.
  -h : Prints this syntax help. Cannot be used with other flags.
E.g.: ./createTgtLPAR -m myP5 -t myLPAR
Automatic provisioning NIM and Tivoli Provisioning Manager

This appendix describes how to implement NIM as an automated provisioning tool with Tivoli Provisioning Manager. It covers the following topics:

- Overview of Tivoli Provisioning Manager
- Explanation of why to use Tivoli Provisioning Manager
- Description of the architecture
- Explanation of Tivoli Provisioning Manager terminology
- Workflow to define a NIM client
- Automated provisioning scenario
- Ways to automate
Overview of Tivoli Provisioning Manager

IBM Tivoli Provisioning Manager (TPM) provides the capability to automate the provisioning of servers (both real and virtual), software, network connections, and storage.

TPM permits the rapid deployment of resources within your infrastructure. It is an end-to-end automation tool. It captures a customer's existing procedures by linking together their systems management tools and executing them and new processes in a repetitive, error-free manner either within or across organizational boundaries.

Why use Tivoli Provisioning Manager

TPM helps to boost server-to-administrator ratios and reduce human error by automating the manual and repetitive steps required to provision a production server or to update it with the latest fixpack or security patch. By utilizing existing hardware, software, and network devices without rewiring, you can minimize implementation times and achieve a fast return on investment.

In addition, IBM Tivoli Provisioning Manager allows you to create, customize, and use automation workflows. Prebuilt workflows provide control and configuration of major vendors' products, and customized workflows can implement your company's data center best practices and procedures.

You can determine whether TPM is providing the workflows to automate your configuration or installation at a central Web site known as IBM Tivoli Open Process Automation Library (search for terms like “nim”, for example):

http://catalog.lotus.com/wps/portal/tpm/

The architectural picture

This is a global architectural overview that includes Tivoli Intelligent Orchestrator. As shown in Figure B-1 on page 631, TPM is represented by two components: the Deployment Engine, and the Data Center Model.
TPM terminology

In this section we explain the TPM terminology used in this appendix.

Data Center Model

The Data Center Model (DCM) represents physical and logical devices within the infrastructure that can be managed by TPM. Each object has a unique identifier, and this ID is used by the workflows during the provisioning mechanism.

Workflow

It is a usual best practice to complete an activity, for instance, installing an operating system. A workflow is composed of transitions, which are the steps to execute to complete the activity. A step could be a command, a piece of code, or another workflow.
Driver
A driver is a package containing several workflows, documentation, and scripts. TPM provides some drivers for the IBM @server pSeries platform and AIX 5L that contain all the workflows to automate tasks; for example:

- pSeries-Server.tcdriver
- LPAR-cpu.tcdriver
- AIX-Operating-System.tcdriver
- NIM.tcdriver
- AIX-LVM.tcdriver

Boot server
A boot server has the capability to deploy images, install an operating system, and back up images. The Network Installation Manager (NIM) master is considered a boot server.

Software definition
A software definition represents a piece of software and the information required to install and configure it. It acts as a container that brings together all the information about a piece of software.

Software installable
An installable file is the actual software package or image file that is distributed and installed on a target system.

Host platform
A host platform is a hosting server (like a pSeries machine) on which logical partitions can be created. An ESX server is also a host platform because it can host virtual machines.

Server template
A server template contains information about the required characteristics to create a server, such as CPU, memory, disk, and so on. Each value affected to a machine is deducted from the host platform.

Discovery technology
Code is provided within TPM to automatically discover information on many types of hardware, for example, the Hardware Management Console (HMC) for the IBM @server pSeries, IBM Director for xSeries®, and NIM objects.

TPM drivers for NIM
Figure B-1 on page 631 lists all the workflows available for the NIM driver.
### Table B-1 TPM drivers available for NIM

<table>
<thead>
<tr>
<th>File</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>/repository/nim_ckstatus.sh</td>
<td>Script to check NIM installation status using NIM transition.</td>
</tr>
<tr>
<td>/repository/nim_cust.sh</td>
<td>Script to launch a NIM customization operation.</td>
</tr>
<tr>
<td>/repository/nim_define_client.sh</td>
<td>Script to define a server as a client to the NIM master.</td>
</tr>
<tr>
<td>/repository/nim_install.sh</td>
<td>Script to launch a NIM BOS install.</td>
</tr>
<tr>
<td>/repository/nim_mk_clone.sh</td>
<td>Script to create a mksysb.</td>
</tr>
<tr>
<td>/repository/inventory_export.pl</td>
<td>Standalone script used to export NIM inventory for population of DCM.</td>
</tr>
<tr>
<td>/doc/NIM.html</td>
<td>README.doc.</td>
</tr>
<tr>
<td>/workflow/Get_NIM_TimeOut.wkf</td>
<td>Workflow to get the NIM timeout from a device or use default.</td>
</tr>
<tr>
<td>/workflow/Check_NIM_Install_Status.wkf</td>
<td>Workflow to drive the nim_ckstatus.sh script.</td>
</tr>
<tr>
<td>/workflow/Install_NIM_Client.wkf</td>
<td>Workflow to drive the nim_install.sh script.</td>
</tr>
<tr>
<td>/workflow/Customize_a_NIM_Client.wkf</td>
<td>Workflow to drive the nim_cust.sh script.</td>
</tr>
<tr>
<td>/workflow/NIM_Copy_File_from_Local.wkf</td>
<td>Workflow to copy a local file to a server.</td>
</tr>
<tr>
<td>/workflow/NIM_Remote_Remove_File.wkf</td>
<td>Workflow to remove a file from a server.</td>
</tr>
<tr>
<td>/workflow/Get_NIM_Client_Attributes.wkf</td>
<td>Workflow to get NIM client variable information from a server.</td>
</tr>
<tr>
<td>/workflow/Get_NIM_Software_Attributes.wkf</td>
<td>Workflow to get NIM software variable information form a software product or software stack.</td>
</tr>
<tr>
<td>/workflow/NIM_Create_Clone_Image.wkf</td>
<td>Workflow to call nim_mk_clone.sh</td>
</tr>
<tr>
<td>/workflow/Create_Clone_AIX_Image.wkf</td>
<td>Workflow to create a mksysb of a client.</td>
</tr>
<tr>
<td>/workflow/Define_NIM_Client.wkf</td>
<td>Workflow to drive the nim_define_client.sh script.</td>
</tr>
<tr>
<td>/workflow/Define_NIM_Client_from_DCM.wkf</td>
<td>Workflow to define a server as a NIM client to a NIM master.</td>
</tr>
<tr>
<td>/workflow/AIX_Image_Install.wkf</td>
<td>Workflow to BOS install an AIX server.</td>
</tr>
</tbody>
</table>
Workflow to define a NIM client

Example B-1 illustrates the workflow to define a NIM client. Notice all the ids passed as parameters; TPM is an object oriented application and provides a flexible way to write automation code for an activity.

The workflow will retrieve the NIM master name and IP address from the Data Center Model (in which you have to define the “NIM master” boot server. Then the workflow will transfer and execute the script define_nim_client.sh on the NIM master.

Example: B-1  Workflow to define a NIM client

```plaintext
# -----------------------------------------------------------------
# Licensed Materials - Property of IBM
# 5724-F75
# (C) Copyright IBM Corp. 2003, 2004
# All Rights Reserved
# US Government Users Restricted Rights - Use, duplication or disclosure restricted by GSA ADP Schedule Contract with IBM Corp.
#
# Defines a server in the DCM as a NIM client to a specified NIM master
workflow Define_NIM_Client_from_DCM(in NIM_Master_ID, out NIM_name, out Return_code, in Server_ID, out Stderr) LocaleInsensitive
  var Unmanaged_Network_Interface_ID
  var IP_address
  var Unmanaged_Network_NIC_ID
  var NIM_name_key
  var IF_Name
  var Copied_script_location
  var mac_address
  var NIM_masterID_key
  var Server_name
  var Copied_script_name
  NIM_name_key = "NIM.name"
  NIM_masterID_key = "NIM.masterID"
```

<table>
<thead>
<tr>
<th>File</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>/workflow/AIX_Reset_Install.wkf</td>
<td>Workflow to reset a NIM install.</td>
</tr>
<tr>
<td>/workflow/AIX_Software_Install.wkf</td>
<td>Workflow to install software using the NIM management server onto a server.</td>
</tr>
<tr>
<td>/workflow/AIX_Software_Uninstall.wkf</td>
<td>Workflow to uninstall software using the NIM management server from a server.</td>
</tr>
</tbody>
</table>
NIM_name =
DCMQuery(/Server[@id="$Server_ID"]/property[@componentId="5"]/NIM.name)


java:com.thinkdynamics.kanaha.de.javaplugin.datacentermodel.FindNetworkInterface(IP_address, null, null, IF_Name, Unmanaged_Network_Interface_ID, Unmanaged_Network_NIC_ID, null, null)

try
    java:com.thinkdynamics.kanaha.de.javaplugin.datacentermodel.FindNic(null, null, mac_address, null, Unmanaged_Network_NIC_ID, null, null, null, null)
catchall
endtry

# Replace spaces with '_' in Server_name
var Copy_server_name=Jython["""]

java:com.thinkdynamics.kanaha.de.javaplugin.stringoperations.ReplaceAll(Server_name, " ", ", ", Copy_server_name)

Copied_script_name = Jython[ "nim_define_client_" + Copy_server_name + ".sh"
]

NIM_Copy_File_from_Local(NIM_Master_ID, Copied_script_name, "/tmp", Copied_script_location, "nim_define_client.sh")

Define_NIM_Client(IF_Name, IP_address, mac_address, NIM_Master_ID, NIM_name, Return_code, Stderr, NIM_name, Copied_script_location, Server_name)

NIM_Remote_Remove_File(NIM_Master_ID, Copied_script_name, "/tmp")

#Sets the NIM.masterID variable on the server
DCMInsert parent=DCMQuery(/Server[@id="$Server_ID"]/id) <<EOINSERT
    <property component="DEPLOYMENT_ENGINE" name="NIM.masterID" value="$NIM_Master_ID" />
EOINSERT

#Sets the NIM_name variable on the server
DCMInsert parent=DCMQuery(/Server[@id="$Server_ID"]/id) <<EOINSERT
    <property component="DEPLOYMENT_ENGINE" name="NIM.name" value="$NIM_name" />
EOINSERT
After you have defined the NIM client, you can use the AIX_Image_Install workflow to install the operating system on the client partition.

**Automated provisioning scenario**

In this scenario, we describe the process of creating a partition with Tivoli Provisioning Manager, and we explain how the NIM master is used to install the operating system. We also discuss processes you can use to automate such a procedure.

TPM 3.1 provides a driver known as pSeries-Server.tcdriver. It contains a workflow to create a logical partition (LP) on POWER4 or POWER5 technologies.

Before using a workflow within TPM, we have to define the virtual objects that represent the real infrastructure. Thus, we create the following objects:

- A host platform that represents the IBM System p p570. This object is associated with the pSeries-Server.tcdriver.
- A boot server that represents the NIM master.
- A software definition for the AIX 5L operating system.
- A software installable for AIX 5L V5.3 and information for installation, as shown in Figure B-2.

![Figure B-2 Variable in AIX 5L V5.3](image)

**Partition creation**

Every object in TPM has a unique identifier known as a DCM ID. Thus, each of our four required objects has its own id, which will be provided as inputs to the workflow.
A key concept within TPM is the logical operation, as shown in Figure B-3. The workflow is implementing a logical operation called HostPlatform.CreateVirtualServer.

![Figure B-3 Workflows](image)

In this case, we have associated the HostPlatform with our custom workflow. Therefore, when the logical operation HostPlatform.CreateVirtualServer is called with the HostPlatformID as an input parameter, TPM automatically calls the following Implementation:

```
Odina.pBenchLite_pSeries_Create_Virtual_Server(HostPlatformID, ServerTemplateID, Name, out ServerID) implements HostPlatform.CreateVirtualServer
```

After the execution of this workflow, we will have a partition created on the machine and a virtual object in TPM (with an id of ServerID) to execute the other workflows.

### Partition installation

After the partition is created, we use the NIM driver to define the client and install the AIX 5L image. The same principle is applied: the boot server representing the NIM master is associated with a driver that contains implemented workflows. We have the inputs DCM ID of the NIM master and the ServerID that is the output of the previous creation step; for example:

```
Odina.pBenchLite_Define_NIM_Client_from_DCM(NIM_Master_ID, out NIM_name, out Return_code, Server_ID, out Stderr)
```

We have the inputs DCM ID of the NIM master which is the BootServerID, and the one for the SoftwareInstallable which is the SoftwareStackImageID. The ServerID is the DestinationDeviceID; for example:

```
Odina.pBenchLite_AIX_Image_Install(BootServerID, SoftwareStackImageID, DestinationDeviceID) implements BootServer.InstallImage
```
Automation methods (interfaces, command line, Web services)

TPM has the technical workflow to execute commands within the real infrastructure, but you still need to launch the workflows from the TPM Web interface and fill in the right parameters. If you want to automate the execution of workflows, you have several options:

- Using the TPM-provided scheduler.
- Using Tivoli Intelligent Orchestrator to sense the environment (it gets performance information from the servers running the business applications) and give orders to TPM to execute deployments.
- Using scripts associated to a custom scheduler that invoke the TPM command line interface.
- Using TPM exposed Web services to launch workflows from any other application or process.

In the On Demand IN Action Project, we used a Web service approach with a reservation portal as a front end.
NIM and System i operating system installation for an AIX 5L LPAR

This appendix provides an overview describing how NIM runs on a System i machine.
IBM System i operating system installation for an AIX 5L LPAR

IBM System i and IBM System p rely on the same hardware platform and processor (POWER 5). The only differences come from the microcode and the HMC. In fact, after the System i machine has been partitioned, Network Installation Manager (NIM) does not differentiate between an AIX 5L System p partition and an AIX 5L System i partition.

The AIX 5L System i partition can be a NIM master or a NIM client. This partition can also be used as a resource server. Basically there is no difference, from the NIM perspective, between both systems.

Figure 7-5 shows an example of a mixed NIM environment with System p machines and System i machines.
Refer to Chapter 3, “Basic configuration of a Network Installation Manager environment” on page 51 for details about how to configure and use a NIM environment.
Additional material

This book refers to additional material that can be downloaded from the Internet as described below.

Locating the Web material

The Web material associated with this book is available in softcopy on the Internet from the IBM Redbooks Web server. Point your Web browser to:

ftp://www.redbooks.ibm.com/redbooks/SG247296

Alternatively, you can go to the IBM Redbooks Web site at:

ibm.com/redbooks

Select the Additional materials and open the directory that corresponds with the IBM Redbooks form number, SG247296.

Using the Web material

The additional Web material that accompanies this book includes the following files:

<table>
<thead>
<tr>
<th>File name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SG247296.zip</td>
<td>Scripts used in this book</td>
</tr>
</tbody>
</table>
System requirements for downloading the Web material

The following system configuration is recommended:

**Operating system:** AIX

How to use the Web material

Create a subdirectory (folder) on your workstation, and unzip the contents of the Web material zip file into this folder.
## Abbreviations and acronyms

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Description</th>
<th>Abbreviation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AIX</td>
<td>Advanced Interactive Executive</td>
<td>GUI</td>
<td>graphical user interface</td>
</tr>
<tr>
<td>ACL</td>
<td>access control list</td>
<td>HA</td>
<td>High Availability</td>
</tr>
<tr>
<td>APAR</td>
<td>authorized program analysis report</td>
<td>HACMP</td>
<td>High Availability Cluster Multi-Processing</td>
</tr>
<tr>
<td>API</td>
<td>application program interface</td>
<td>HANIM</td>
<td>High Availability NIM</td>
</tr>
<tr>
<td>ARP</td>
<td>Address Resolution Protocol</td>
<td>HBA</td>
<td>Host Bus Adapter</td>
</tr>
<tr>
<td>BFF</td>
<td>Backup File Format</td>
<td>HMC</td>
<td>Hardware Management Console</td>
</tr>
<tr>
<td>BOS</td>
<td>Base Operating System</td>
<td>HTML</td>
<td>HyperText Markup Language</td>
</tr>
<tr>
<td>CDE</td>
<td>Common Desktop Environment</td>
<td>HTTP</td>
<td>HyperText Transfer Protocol</td>
</tr>
<tr>
<td>CEC</td>
<td>Central Electronic Complex</td>
<td>HTTPS</td>
<td>HTTP-Secure</td>
</tr>
<tr>
<td>CHRP</td>
<td>Common Hardware Reference Platform</td>
<td>I/O</td>
<td>input/output</td>
</tr>
<tr>
<td>CLI</td>
<td>Command Line Interface</td>
<td>IBM</td>
<td>International Business Machines Corporation</td>
</tr>
<tr>
<td>CNAME</td>
<td>Canonical Name</td>
<td>IDE</td>
<td>Integrated Development Environment</td>
</tr>
<tr>
<td>COSI</td>
<td>Common OS Image</td>
<td>IP</td>
<td>Internet Protocol</td>
</tr>
<tr>
<td>CPU</td>
<td>central processing unit</td>
<td>IPL</td>
<td>initial program load</td>
</tr>
<tr>
<td>CPUID</td>
<td>CPU Identification</td>
<td>ITSO</td>
<td>International Technical Support Organization</td>
</tr>
<tr>
<td>CSM</td>
<td>Cluster Systems Management</td>
<td>JFS</td>
<td>Journaled File System</td>
</tr>
<tr>
<td>CSP</td>
<td>Concluding Service Pack</td>
<td>LAN</td>
<td>local area network</td>
</tr>
<tr>
<td>DHCP</td>
<td>Dynamic Host Configuration Program</td>
<td>LED</td>
<td>light emitting diode</td>
</tr>
<tr>
<td>DLPAR</td>
<td>Dynamic LPAR</td>
<td>LIC</td>
<td>Licensed Internal Code</td>
</tr>
<tr>
<td>DMZ</td>
<td>Demilitarized Zone</td>
<td>LPAR</td>
<td>logical partition</td>
</tr>
<tr>
<td>DNP</td>
<td>Dynamic Node Priority</td>
<td>LPP</td>
<td>Licensed Program Product</td>
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<tr>
<td>DNS</td>
<td>Dynamic Name Service</td>
<td>LTG</td>
<td>Logical Track Group</td>
</tr>
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<td>FC</td>
<td>Fibre Channel</td>
<td>LUN</td>
<td>logical unit number</td>
</tr>
<tr>
<td>FQDN</td>
<td>Fully Qualified Domain Name</td>
<td>LV</td>
<td>Logical Volume</td>
</tr>
<tr>
<td>FTP</td>
<td>File Transfer Protocol</td>
<td></td>
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<tr>
<td>GSA</td>
<td>Global Storage Architecture</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Abbreviation</td>
<td>Description</td>
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<td></td>
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<tr>
<td>LVD</td>
<td>Low-Voltage Differential (SCSI)</td>
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<tr>
<td>LVM</td>
<td>Logical Volume Manager</td>
<td></td>
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<tr>
<td>MAC</td>
<td>Media Access Card</td>
<td></td>
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<tr>
<td>ML</td>
<td>Maintenance Level</td>
<td></td>
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<tr>
<td>MPIO</td>
<td>Multi-Path I/O</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MTU</td>
<td>Maximum Transfer Unit</td>
<td></td>
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<tr>
<td>NFS</td>
<td>Network File System</td>
<td></td>
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</tr>
<tr>
<td>NIC</td>
<td>Network Interface Card</td>
<td></td>
<td></td>
</tr>
<tr>
<td>NIM</td>
<td>Network Install Manager</td>
<td></td>
<td></td>
</tr>
<tr>
<td>NIMSH</td>
<td>NIM Service Handler</td>
<td></td>
<td></td>
</tr>
<tr>
<td>NIS</td>
<td>Network Information Service</td>
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<tr>
<td>NTP</td>
<td>Network Time Protocol</td>
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<tr>
<td>ODM</td>
<td>Object Data Manager</td>
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<tr>
<td>PC</td>
<td>personal computer</td>
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<tr>
<td>PCI</td>
<td>Peripheral Component Interconnect</td>
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<tr>
<td>PCI-X</td>
<td>PCI-Extended</td>
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<tr>
<td>PCM</td>
<td>Path Control Module</td>
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<tr>
<td>PID</td>
<td>Process ID</td>
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<tr>
<td>PP</td>
<td>physical partition</td>
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<tr>
<td>PSSSP</td>
<td>Parallel Systems Support Program</td>
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<tr>
<td>PTF</td>
<td>Program Temporary Fix</td>
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<tr>
<td>PVID</td>
<td>Physical Volume ID</td>
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<tr>
<td>PXE</td>
<td>Pre-boot eXecution Environment</td>
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<tr>
<td>RAID</td>
<td>Redundant Array of Independent Disks</td>
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<tr>
<td>RAM</td>
<td>Random Access Memory</td>
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<tr>
<td>RAS</td>
<td>Reliably Availability Serviceability</td>
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<tr>
<td>RFC</td>
<td>Request For Comment</td>
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<tr>
<td>RHE</td>
<td>RedHat Enterprise Linux</td>
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<tr>
<td>RM</td>
<td>Resource Manager</td>
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<tr>
<td>RMC</td>
<td>Resource Monitoring and Control</td>
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<tr>
<td>ROM</td>
<td>Read-Only Memory</td>
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<tr>
<td>RPC</td>
<td>Remote Procedure Call</td>
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<tr>
<td>RPD</td>
<td>RSCT Peer Domain</td>
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<tr>
<td>RPM</td>
<td>RPM Package Manager</td>
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<tr>
<td>RSA</td>
<td>Remote Supervisor Adapter</td>
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<tr>
<td>RSCT</td>
<td>Reliable Scalable Clustering Technology</td>
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<tr>
<td>RSH</td>
<td>Remote Shell</td>
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<tr>
<td>SAN</td>
<td>Storage Area Network</td>
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<tr>
<td>SCSI</td>
<td>Small Computer Systems Interface</td>
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<tr>
<td>SDD</td>
<td>Subsystem Device Driver</td>
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<td>SDDPCM</td>
<td>SDD Path Control Module</td>
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<tr>
<td>SDK</td>
<td>Systems Development Kit</td>
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<td>SLES</td>
<td>SUSE Linux Enterprise Server</td>
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<tr>
<td>SME</td>
<td>Systems Management Environment</td>
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<tr>
<td>SMIT</td>
<td>System Management Interface Tool</td>
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<tr>
<td>SMS</td>
<td>System management Services</td>
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<tr>
<td>SOE</td>
<td>Standard Operating Environment</td>
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<tr>
<td>SPOC</td>
<td>single point of control</td>
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<tr>
<td>SPOT</td>
<td>Shared Product Object Tree</td>
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<tr>
<td>SRC</td>
<td>System Resource Controller</td>
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<tr>
<td>SRPM</td>
<td>Source RPM</td>
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<tr>
<td>SSH</td>
<td>Secure Shell</td>
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<tr>
<td>SSL</td>
<td>Secure Socket Layer</td>
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<tr>
<td>SUMA</td>
<td>Service Update Management Assistant</td>
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<tr>
<td>TCB</td>
<td>Trusted Computing Base</td>
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<tr>
<td>TCP</td>
<td>Transmission Control Protocol</td>
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<tr>
<td>TCP/IP</td>
<td>Transmission Control Protocol/Internet Protocol</td>
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<tr>
<td>TFTP</td>
<td>Trivial File Transfer Protocol</td>
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<tr>
<td>Abbreviation</td>
<td>Description</td>
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<tr>
<td>TID</td>
<td>Thread ID</td>
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<tr>
<td>TL</td>
<td>Technology Level</td>
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<td>TOC</td>
<td>table of contents</td>
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<tr>
<td>TPM</td>
<td>Tivoli Provisioning Manager</td>
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<tr>
<td>TPS</td>
<td>Transactions Processing System</td>
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<tr>
<td>TSM</td>
<td>Tivoli Storage Manager</td>
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<tr>
<td>UDP</td>
<td>Universal Datagram Protocol</td>
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<tr>
<td>URL</td>
<td>Universal Resource Locator</td>
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<tr>
<td>VG</td>
<td>Volume Group</td>
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<tr>
<td>VIO</td>
<td>virtual I/O</td>
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<td>VIOS</td>
<td>VIO Server</td>
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<tr>
<td>VIPA</td>
<td>Virtual IP Address</td>
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<tr>
<td>VLAN</td>
<td>Virtual LAN</td>
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<tr>
<td>VLSI</td>
<td>Very Large Scale Integration</td>
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<tr>
<td>VSCSI</td>
<td>Virtual SCSI</td>
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<tr>
<td>XML</td>
<td>eXtended Markup Language</td>
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</table>
Related publications

The publications listed in this section are considered particularly suitable for a more detailed discussion of the topics covered in this book.

IBM Redbooks

For information on ordering these publications, see “How to get IBM Redbooks” on page 650. Note that some of the documents referenced here may be available in softcopy only.

- *Linux Applications on pSeries*, SG24-6033
- *AIX 5L Practical Performance Tools and Tuning Guide*, SG24-6478
- *Advanced POWER Virtualization on IBM System p5*, SG24-7940
- *NIM From A to Z in AIX 4.3*, SG24-5524

Other publications

This publication is also relevant as a further information source:

- *AIX 5L V5.3 Installation and Migration*, SC23-4887
- *AIX 5L Version 5.3 Commands Reference, Volume 3*, SC23-4890
- *General Programming Concepts: Writing and Debugging Programs*, SC23-4896

Online resources

These Web sites and URLs are also relevant as further information sources:

- SUMA is a complement to the UNIX servers product family portion of the IBM Support Fix Central
  

- RPM Package Manager
  
- AIX 5.3 TL4 Release Notes
- VIO Server documentation
  [http://publib.boulder.ibm.com/infocenter/eserver/v1r3s/topic/iphb1/iphb1kickoff.htm](http://publib.boulder.ibm.com/infocenter/eserver/v1r3s/topic/iphb1/iphb1kickoff.htm)
- SUMA white paper
- IBM AIX 5L Service Strategy
- CSM documentation

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NIM from A to Z in AIX 5L

Configuring NIM - illustrated

Sample best practices

NIM case scenarios

This IBM Redbooks publication will help the AIX 5L technical community, and in particular system administrators who are well versed in the concepts and terminology of the AIX operating system, to understand the benefits of implementing a Network Installation Manager (NIM) environment in their data center. The book applies to AIX 5L V5.3 Technology Level 5, Cluster Systems Management (CSM) V1.5.1, and IBM Director V5.1.

The concept of a cluster (that is, at least two IBM System p machines connected through a network) presents the challenge of installing, maintaining, updating and backing up the various participants in the cluster. NIM, a critical feature of AIX, can perform these tasks for your System p server farm. Using NIM, you can install or upgrade many IBM System p machines and LPARs with the same (or different) images at the same time.

This publication complements the information found in IBM technical AIX 5L manuals, and will be most useful as a reference guide.